Computing Requirements in the 3G Era

Ed Porter APC / CNRS Dawn IV, Amsterdam, 30-31 August, 2018





Introduction

- Primer on GW data analysis
- Hardware concerns
- Software concerns
- For the future...
- Conclusion





Disclaimer

- Most of what follows are personal musings!
- There will be NO concrete proposals!!
- There will be many more questions than answers!!!
- I might even get somethings right!!!!



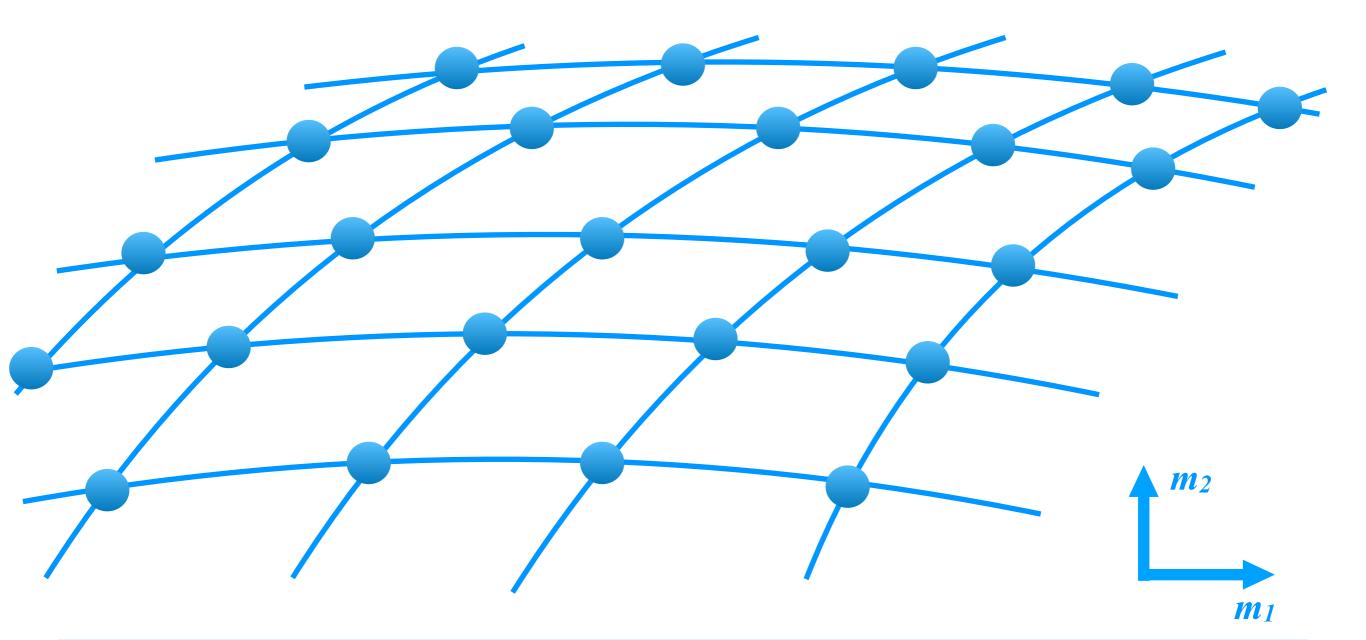


- Two parts:
 - Detection
 - Parameter estimation (Bayesian inference)





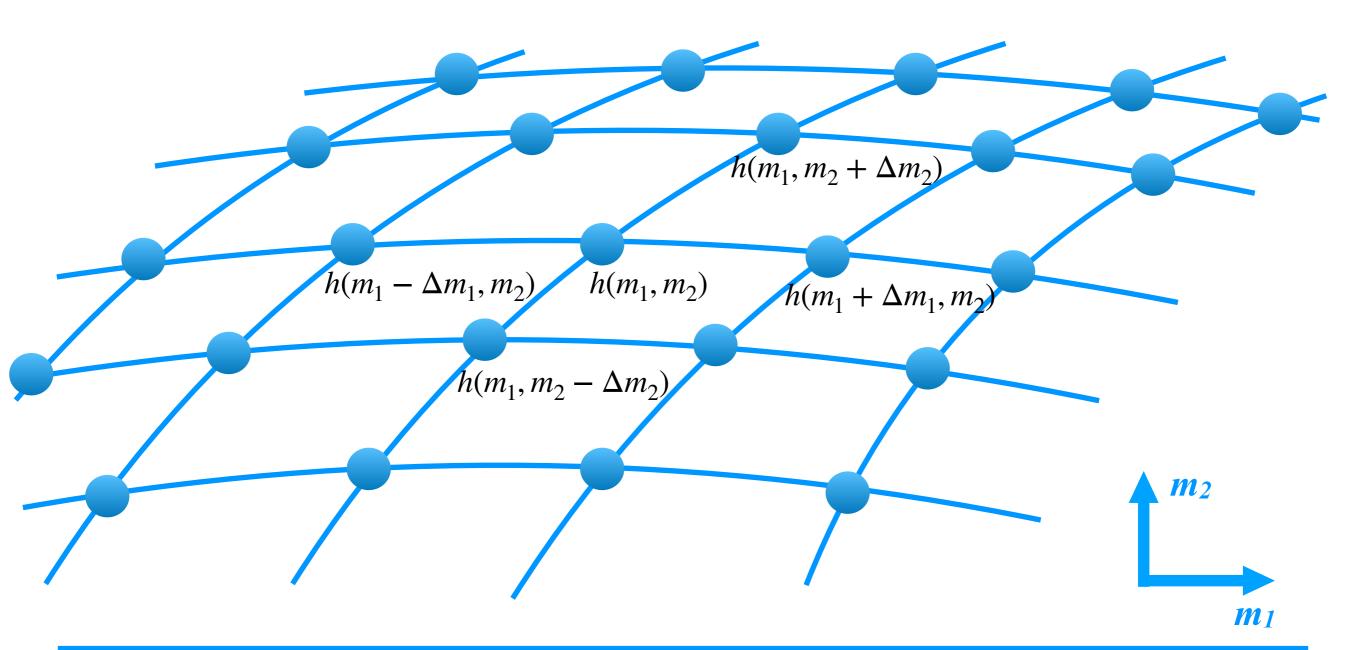
• Template Grid : assume 2D







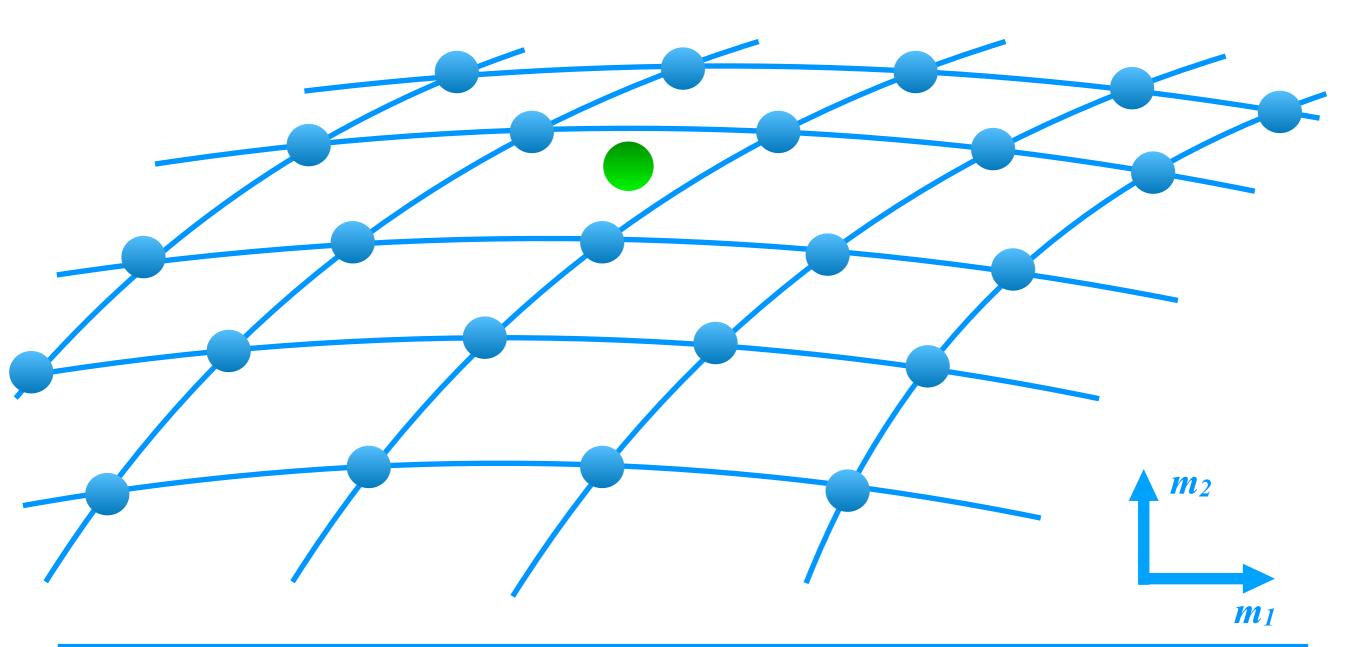
• Template Grid







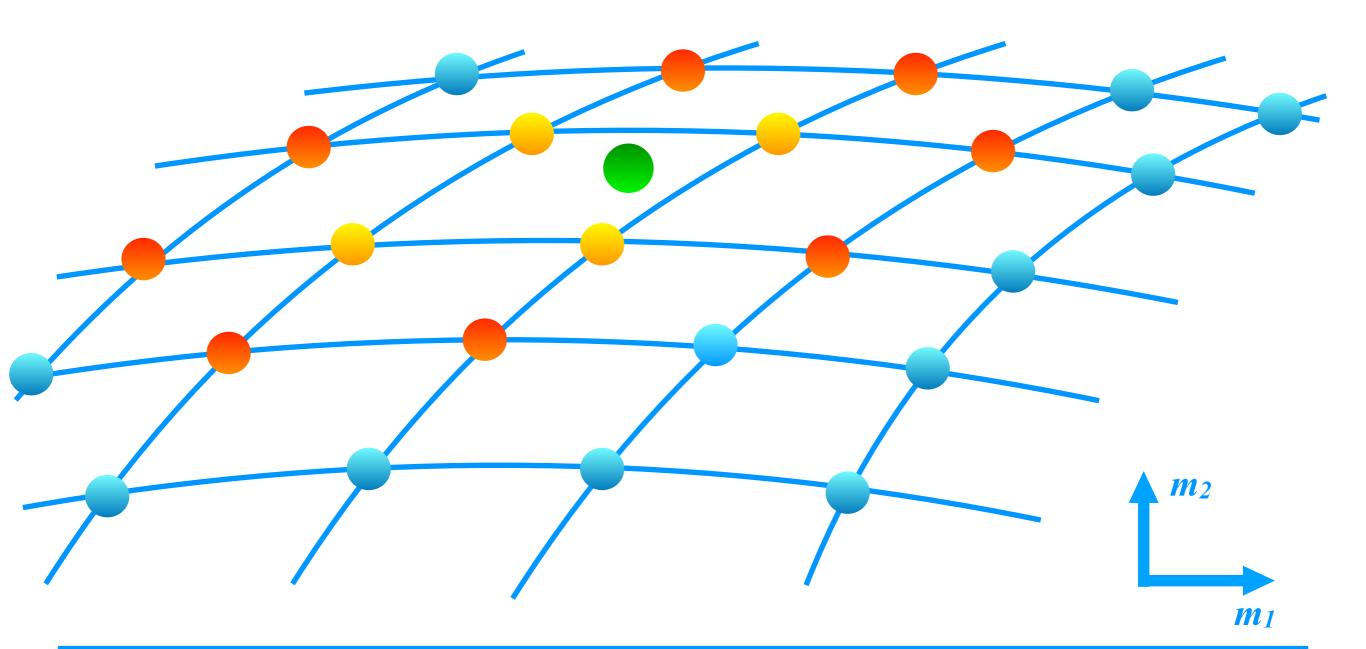
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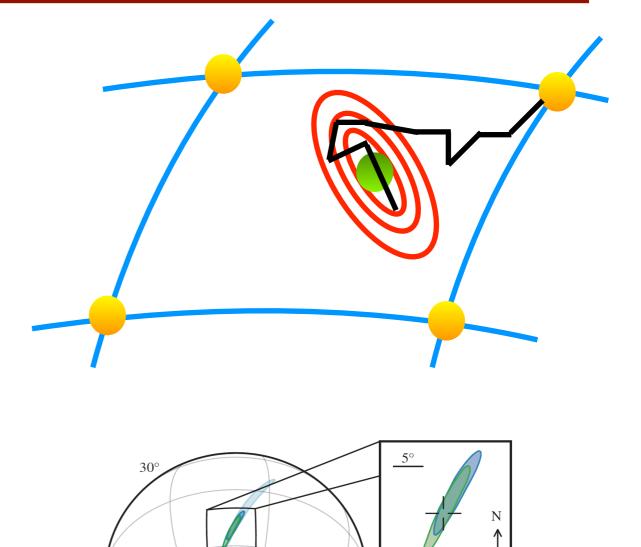






Bayesian Inference

- Extract astrophysical parameters
- Provide posterior distributions...
- ...and confidence intervals



GW170817, B. Abbott et al, PRL 119, 161101 (2017)

25

50

Mpc

75

0



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0°

-30°

15h

12h



Detection

- Get the data
- Generate a bank of N templates
- Cross-correlate the templates with the data
- Find template with parameters closest to signal

Bayesian Inference

- Get the data
- Start with parameters of best-match template
- Use a stochastic sampler requiring M templates
- Extract posterior distributions





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The problem is that N and M are big!!!





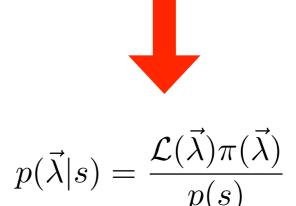
• More mathematically

Detection $s(t) = h(t; \vec{\lambda}^*) + n(t)$ $ds^2 = g_{\mu\nu} dx^{\mu} dx^{\nu}$ $g_{\mu\nu} = \frac{1}{2} \Gamma_{\mu\nu} = \frac{1}{2} < \partial_{\mu} h |\partial_{\nu} h >$

 $\mathcal{L}(\vec{\lambda}) = \langle s - h | s - h \rangle$

Bayesian Inference

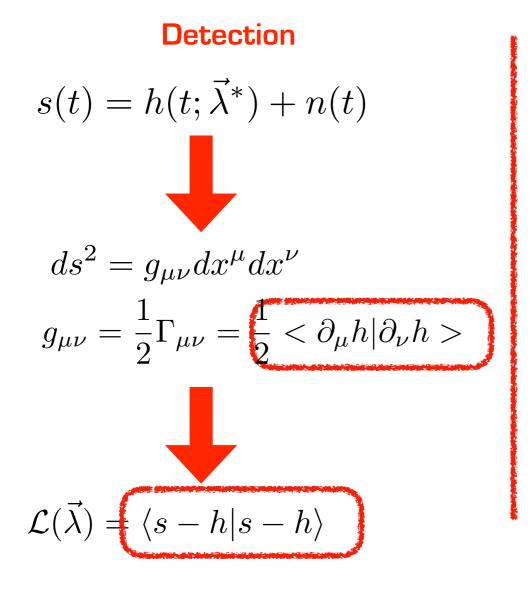
$$s(t) = h(t; \vec{\lambda}^*) + n(t)$$





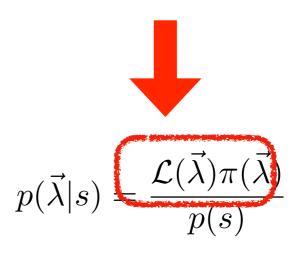


• More mathematically



Bayesian Inference

$$s(t) = h(t; \vec{\lambda}^*) + n(t)$$







• The noise-weighted inner product

$$< h|s> = 2 \int_{f_{low}}^{f_{high}} \frac{df}{S_n(f)} \tilde{h}(f) \tilde{s}^*(f) + c.c.$$

• And because we are using computers, the discretized version is

$$< h|s> = 4 \sum_{k=0}^{n/2} h_k s_k^* / S_k$$

- Each evaluation requires a template generation.
- Each search / inference run can require millions tens of millions of template generations
- *n* can be very large causing both hardware and software problems (more later)





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So, our question is quite simple...how do we accelerate the generation of templates and the evaluation of the inner product?





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Turns out that the solution is not so simple!!!!





Hardware concerns

- So, we just wait for better computers
- I mean, computers in the 3G era will be awesome!!







- Gordon Moore (Intel, 1965)
- Number of components on an integrated circuit would double every year
- Revised in 1975 to every two years
- Intel (2015) : 22nm \Rightarrow 14nm (2.5 years)

 $14nm \Rightarrow 10nm$ (3 years)

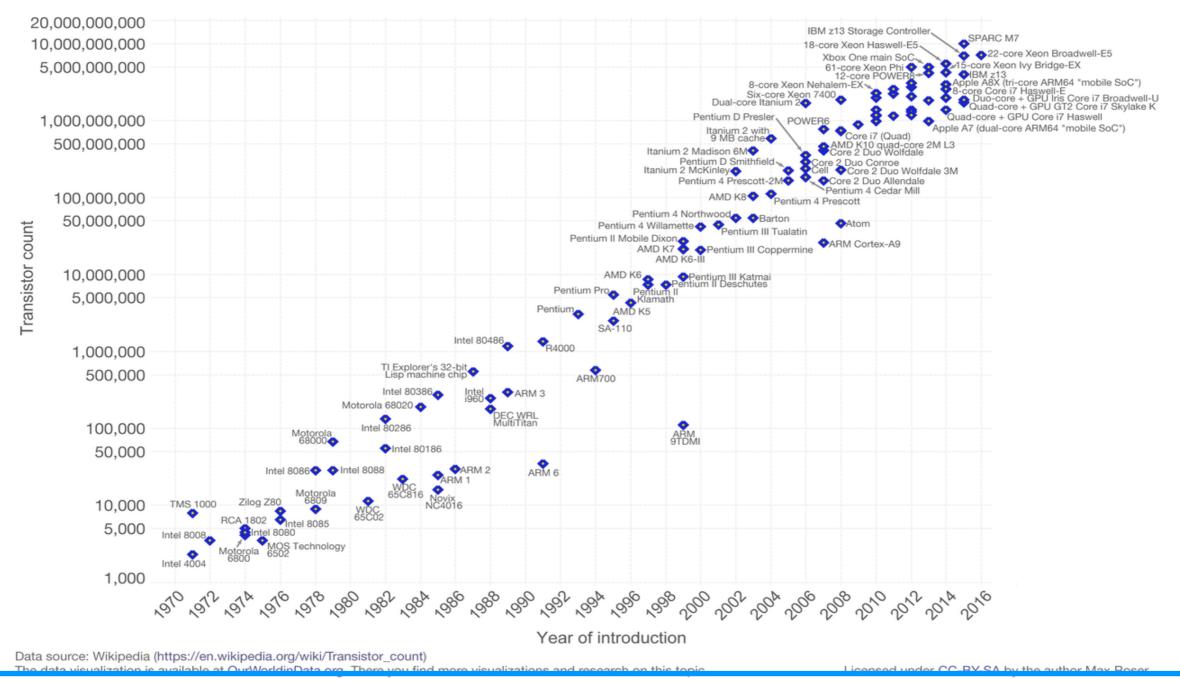
• Believed that Moore's law will end around 2025 (G. Moore, 2015)





Moore's Law – The number of transistors on integrated circuit chips (1971-2016) Our World in Data

Moore's law describes the empirical regularity that the number of transistors on integrated circuits doubles approximately every two years. This advancement is important as other aspects of technological progress – such as processing speed or the price of electronic products – are strongly linked to Moore's law.

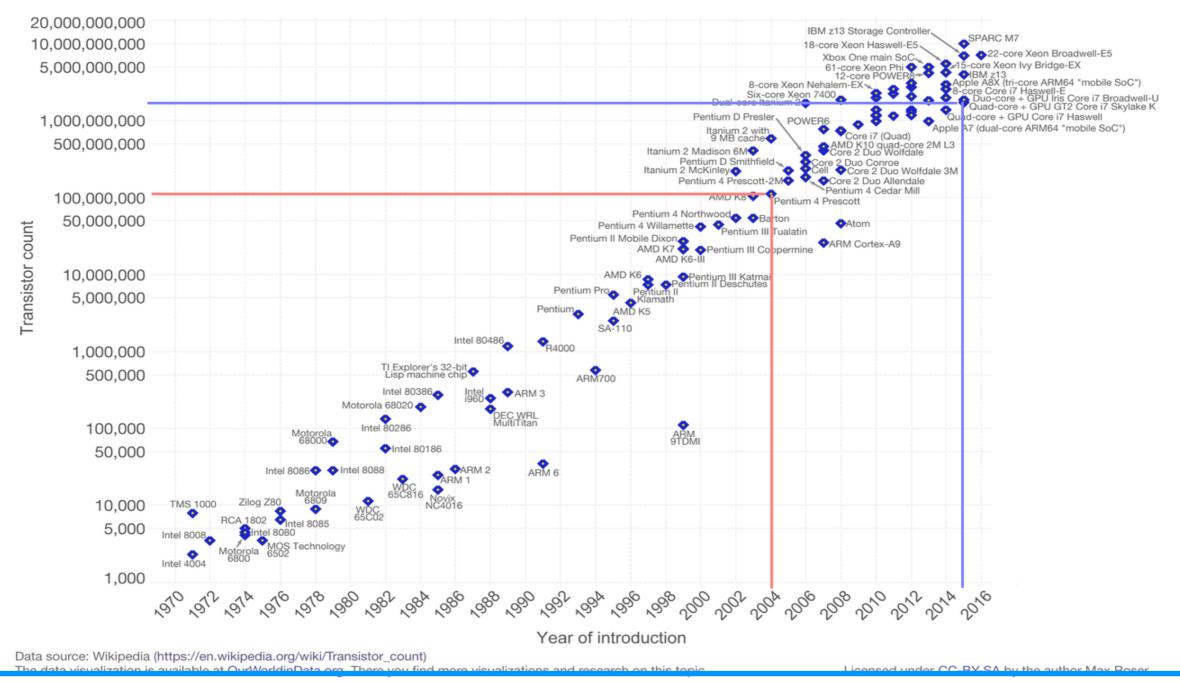






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• 2006 : Bayesian inference of SMBHB for LISA (Cornish & Porter, CQG23, S761 (2006)). $10^7-10^6 M_{\odot}$ (a) z = 1. $t_c = 0.49$ yr; $T_{obs} = 0.5$ yr: $n = 16384 = 2^{14}$. Runtime for a 8x10⁶ MCMC on a Dell desktop with a 2GHz Pentium 4 processor: 8 days





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- 2018 : Same source. Runtime on a 2017 13" Macbook Pro with a 2.9 GHz i5 processor: 44 hours
- Jumping from 100x10⁶ to 2x10⁹ transistors gives a speed-up of x4.4??
- Not very impressive...so what's going on???





Wirth's/Gate's/May's Law

- Also known as "software bloat"!!
- Successive generations of software offset the gains given by Moore's law: commercial software slows by 50% every 18 months
- Office 2007 performed the same task on a typical year-2007 computer at half the speed of Office 2000 on a typical year-2000 computer (Randall Kennedy, Intel, 2008)
- Intel/AMD now prefer multicore chips using multi-threading. As a consequence, the software has to be written in a multi-threaded manner to take advantage of the hardware
- MCMC is a sequential algorithm that uses a single thread...hence the reason for the modest improvement.
- So, to take advantage of multithread technology, I need to write my MCMC code in a multithread fashion....except....I won't!!!!









- As we approach 5nm, physics becomes a problem
- gate design using Si is an issue at this level
- Research has started into alternative materials, e.g. InGaAs, Graphene
- No current estimates on success!!







- The cost of a silicon chip fabrication plant doubles in price every 4 years
- Improvements will only continue as long as profit > cost







Sofware concerns

Template Banks

- The big question is will be able to continue using template banks in 3G?
- Different problem, but, for LISA we demonstrated that a template bank search would require 10¹² templates for SMBHBs (Cornish & Porter, 2005), 10^{7-10¹¹} templates for GBs (Cornish and Porter, 2005) and 10⁴⁰ templates for EMRIs (Gair et al, 2004)
- 3G ground-based template banks will be smaller, but will still be big!
- Given that it is possible that there will be source confusion, and that template banks will be to costly, more stochastic search methods may be needed (Bosi & Porter, 2011)
- But, let's imagine we can use template banks....



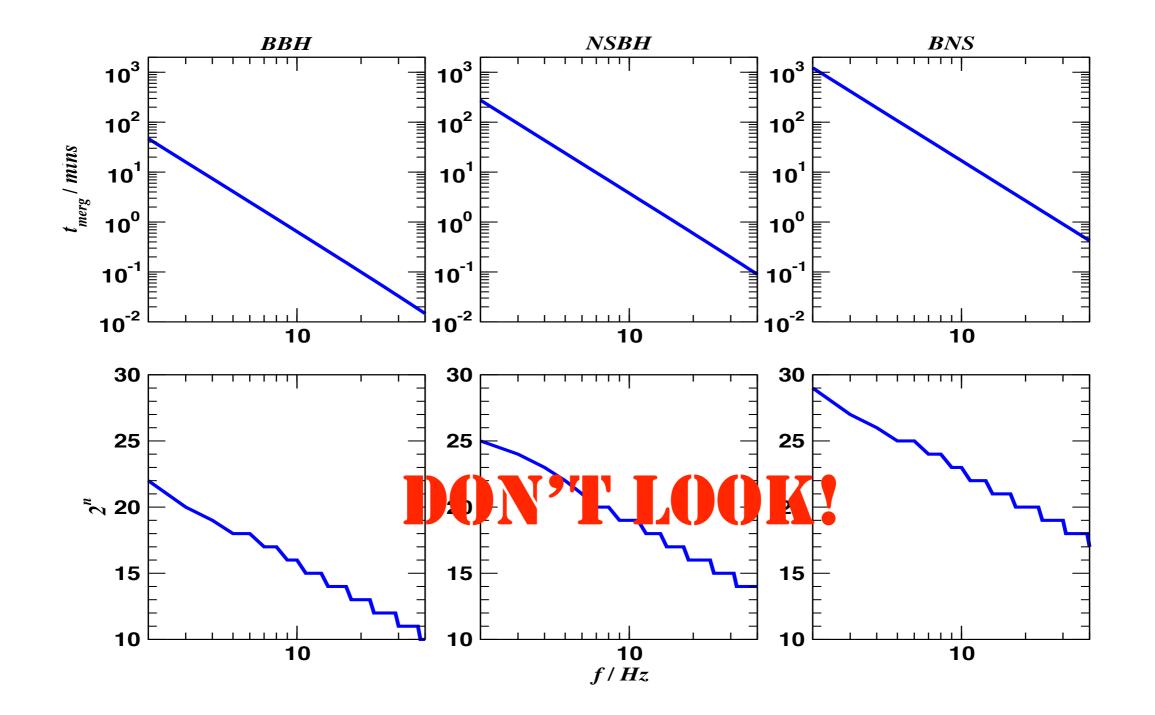


Template Length

- Assume we are are going to target BBH, BNS and NSBH systems separately
- Assume a minimum mass of 1 M_{\odot} for a NS and 5 M_{\odot} for a BH
- Assume the longest template in any search/PE is equal mass
- Use a 3.5PN chirp time to calculate template duration
- Assume each template has a sampling frequency of $2f_{Nyq}$, where the Nyquist frequency assumes minimum total masses of 2, 6 and 10 M_{\odot} for each search







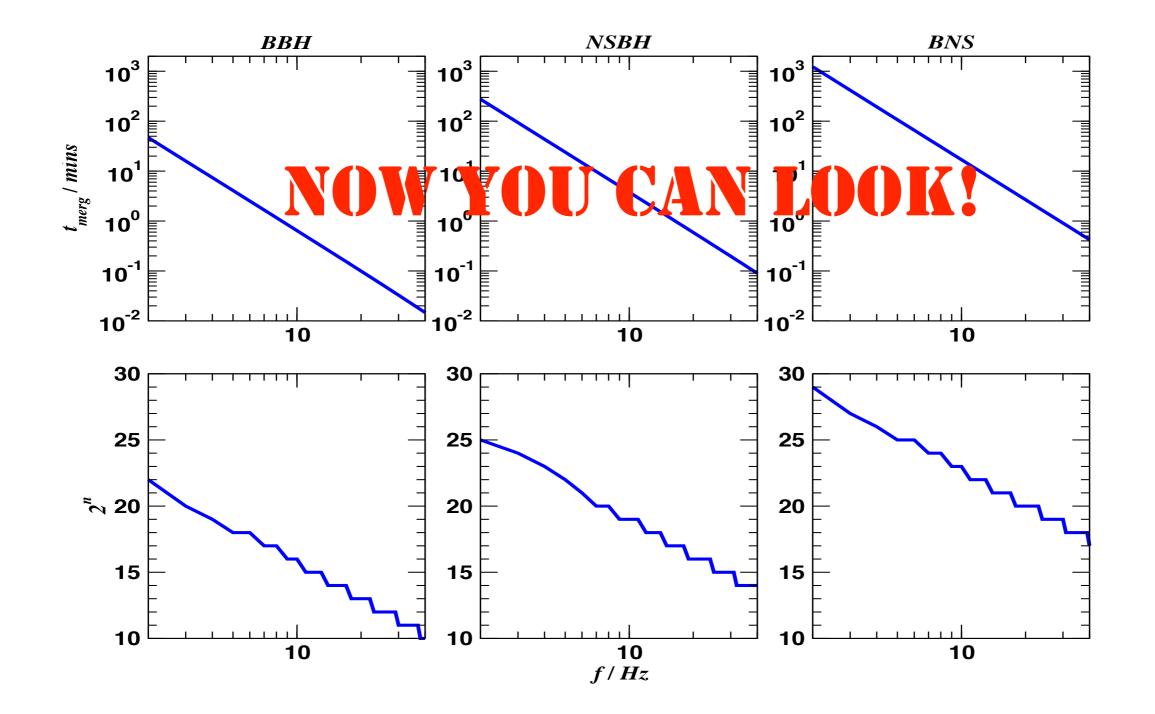




f / Hz	BBH	NSBH	BNS
30	2 secs	12 secs	1 min
20	6 secs	36 secs	3 min
15	13 secs	76 secs	6 min
10	40 secs	4 min	17 min
9	50 secs	5 min	22 min
8	70 secs	7 min	30 min
7	1.5 min	10 min	45 min
6	2.5 min	15 min	1 hr
5	4 min	25 min	1.75 hr
4	8 min	45 min	3 hr
3	16 min	1.5 hr	7 hr
2	45 min	5 hr	20 hr

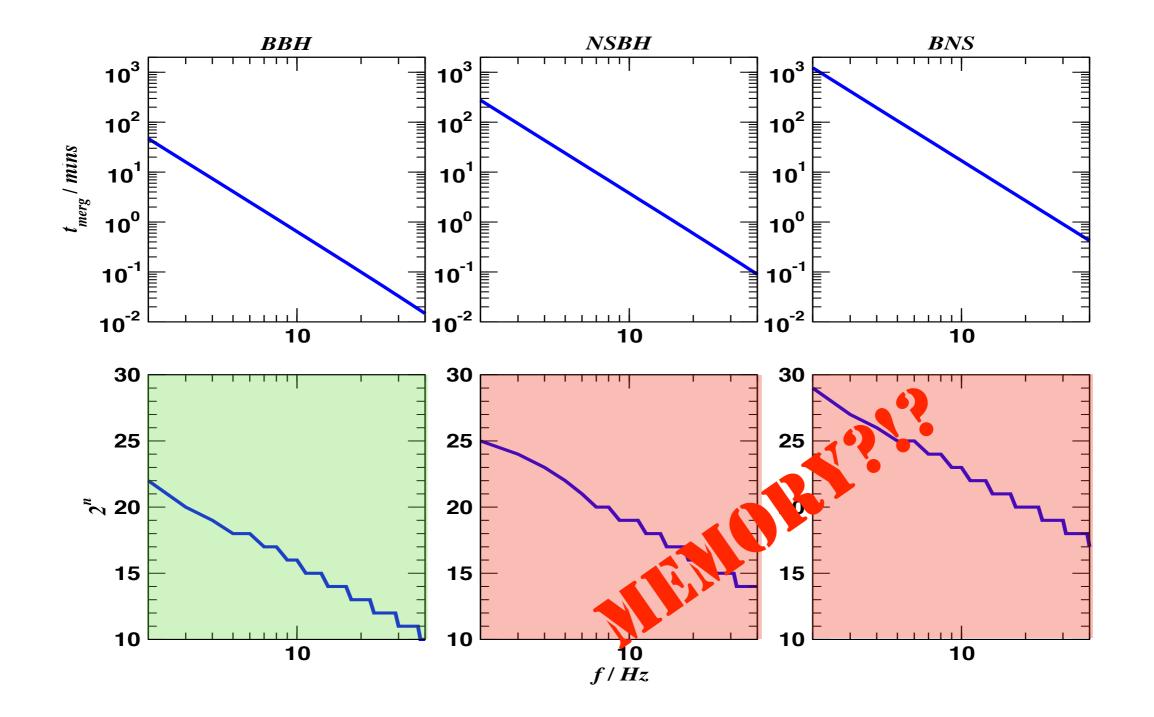
















Computational Power

- To get an idea of the necessary computational power (Schutz, 1989)
- To filter N templates of length F through the data, where F is given by

$$F = \frac{5}{32} f_{Nyq} \left(\pi f_{low}\right)^{-8/3} \left(2GM_{min}/c^3\right)^{-5/3}$$

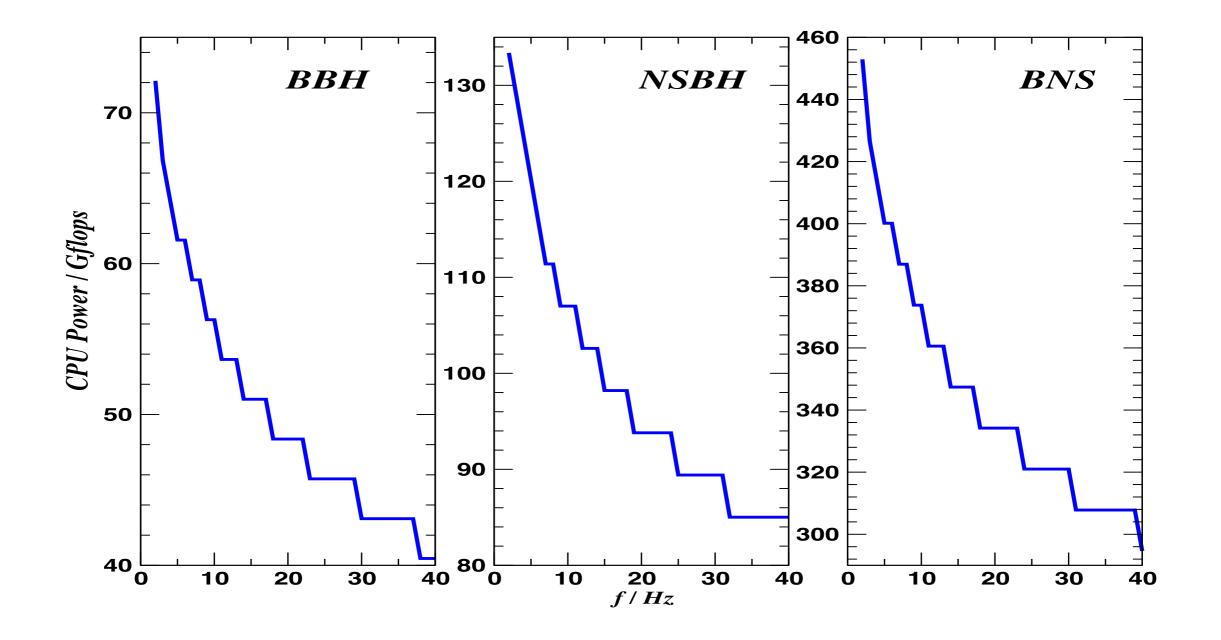
• requires a computational power, in flops, of

$$P \approx N f_{Nyq} \left(32 + 6 \log_2 F \right)$$

- assuming M_{min} has $\eta = 1/4$, and $f_{samp} = 2 f_{Nyq}$
- Assume my template bank requires 10⁶ templates







N.B.: CPU power scales linearly with template number





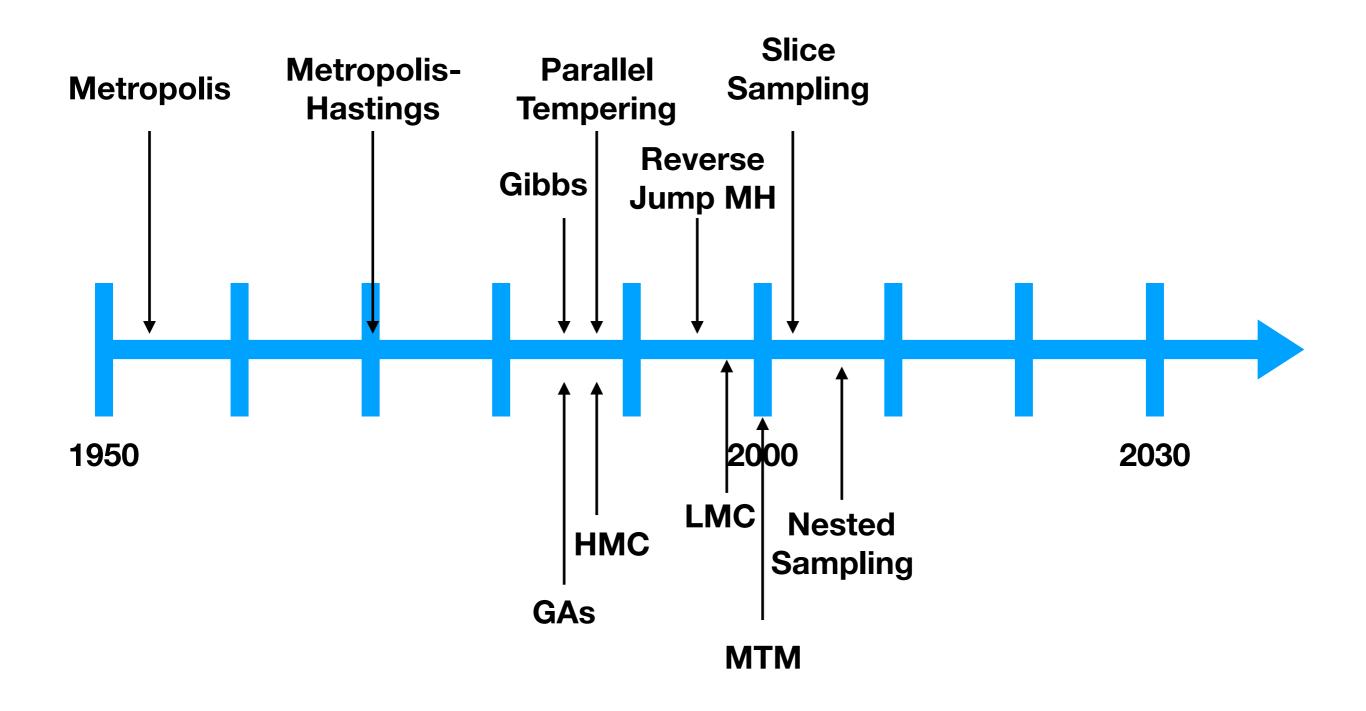
Solution 2:

- We just use better algorithms
- There must be many to choose from..
- Bayesian inference is used in so many fields, e.g. economics, air traffic control, biology, astronomy, computer chess, computational music etc
- I mean, let's face it, everyone is a Bayesian these days!!!
- Well.....



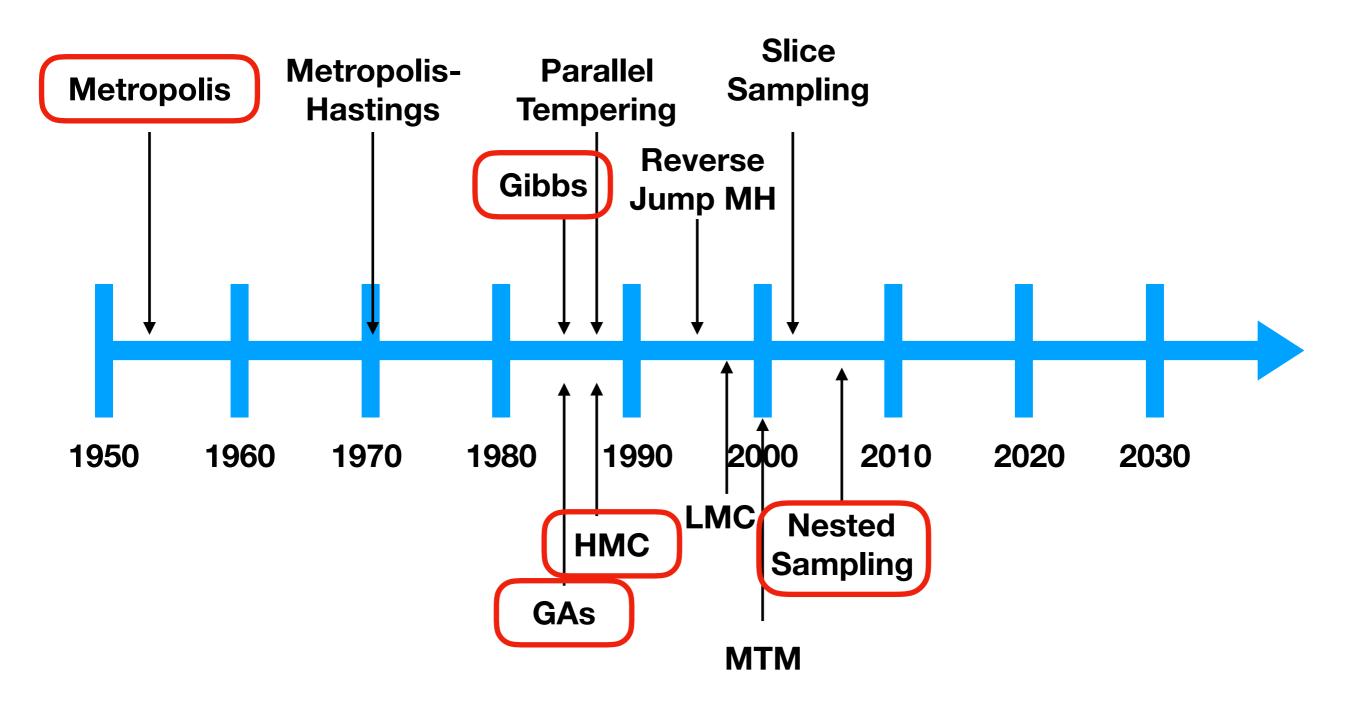






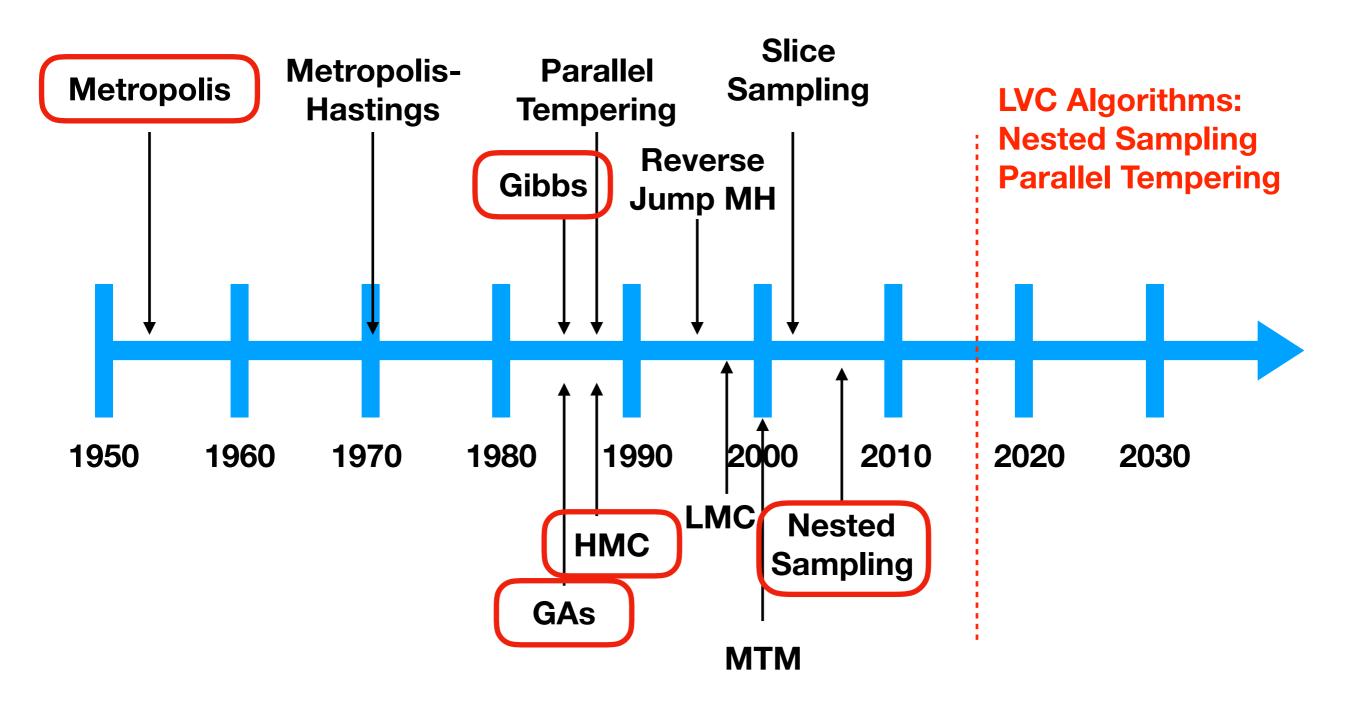
















- Development of a new algorithm is not trivial
- In most cases, "off the shelf" algorithms do not work for your problem
- That means the development of GW-specific algorithms
- Have to solve efficiency and convergence issues
- Difficult to do while analysing data
- Even today, we require 10s of millions of likelihood evaluations to achieve an acceptable number of SISs







For the future...



Look before you jump....





Remember...the PS3??

- Released in 2006-7 with a 6/8 core processor
- You could install Linux/Unix
- It was going to revolutionise scientific computing
- We were all going to build PS3 clusters...
- ...except you couldn't keep them cool enough...
- ...and in 2010, citing security concerns, Sony removed the ability to install other OSs









or the GPU??

- Who needs a 2-4 core CPU, when I can have a 512-1024 core GPU
- It was going to revolutionise scientific computing
- We were all going to build GPU clusters
- Except you don't really know which language to use...
- You have to solve the IO problem...
- To get maximum benefit, you have to program to the hardware requirements...









But we can use the cloud!!

- Don't need to invest in hardware
- Can build virtual clusters
- Can use the "cloudburst" feature
- It'll revolutionise scientific computing!!!
- Big question : will the cloud still be there in the 3G era?
- From "talking with people"...doubtful!! Will be replaced with something else in the next decade!!

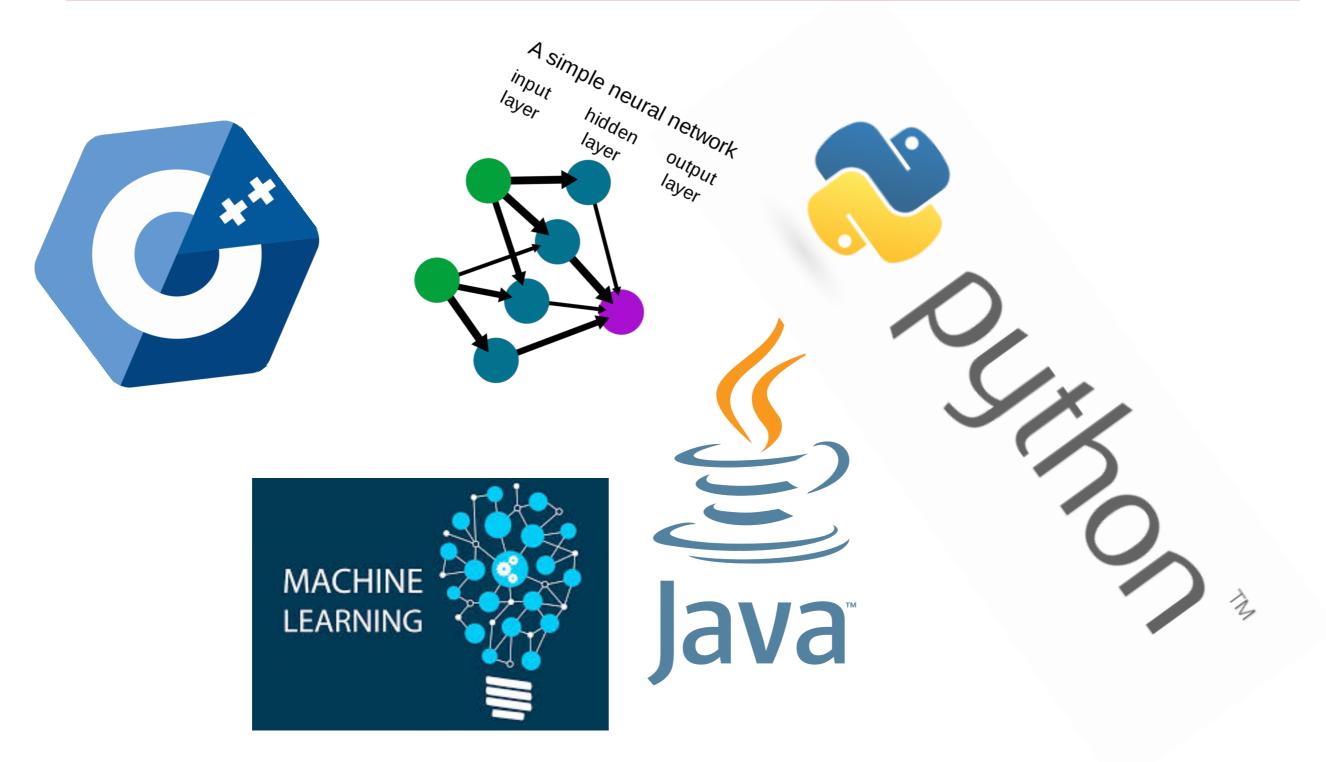








But, things are easier with software...









On a serious note...

- Hardware:
 - Agency/University clusters
 - GRID
 - Laptops/Desktops
 - task force investigating new technology?
 - Cost/benefit analysis?
- Software:
 - Do we need to move beyond scientist developing codes?
 - Computer scientists / professional programmers for profiling / optimisation
 - Investigation and benchmarking of new methods (+ development)
 - Cost/benefit analysis?
 - We will still use externally developed code, e.g. FFTW, astropy, numpy, BLAS, gsl





Conclusion

- GW data analysis will become more difficult and demanding
- Storage will become an issue
- Performance will be an issue depending on how low-latency we want to be
- It may require an investment in computing that frees up the scientists to do science
- We need to keep an eye on emerging technologies...but resist jumping into them too early
- Not everything that's useful, is useful for GW astronomy





