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# Noise hunting in Advanced LIGO

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*LIGO - T1600159-v1*

# Improving LIGO's sensitivity

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- Characterizing sources of noise allows for improvements in:
  - » SENSITIVITY
  - » STABILITY
  - » DETECTION RATE

# Examples of noise sources

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- Fundamental

- » Shot noise (dominates high frequencies)
- » Suspension thermal noise
- » Test mass thermal noise
- » Seismic Noise (dominates lower frequencies)

- Environmental

- » Wind
- » Ground Motion
- » Magnetic field variations
- » Acoustic disturbances

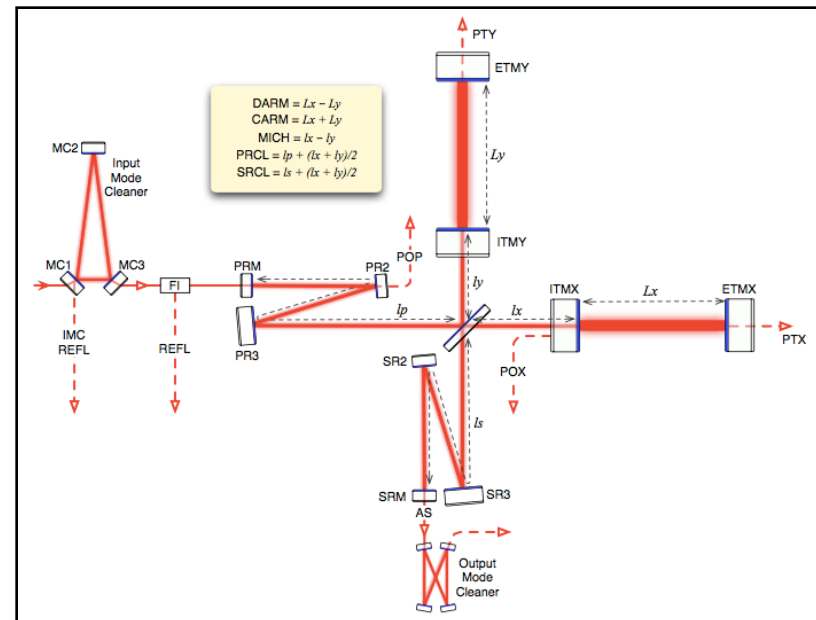
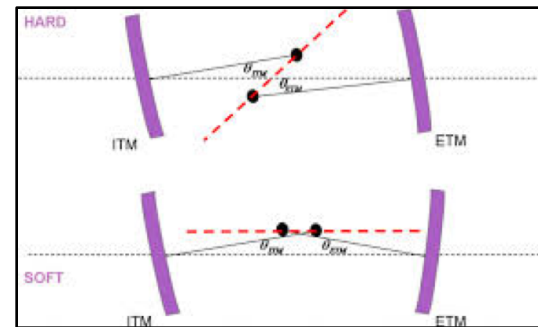
# Wind as a source of noise

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- Hanford: high winds are frequent
- Can cause optics to drift and result in 'lock loss'
  - » Instrument is locked when light is resonating in all cavities
- Can cause light to scatter
- If scattered light were to recombine with main beam, its phase will be shifted

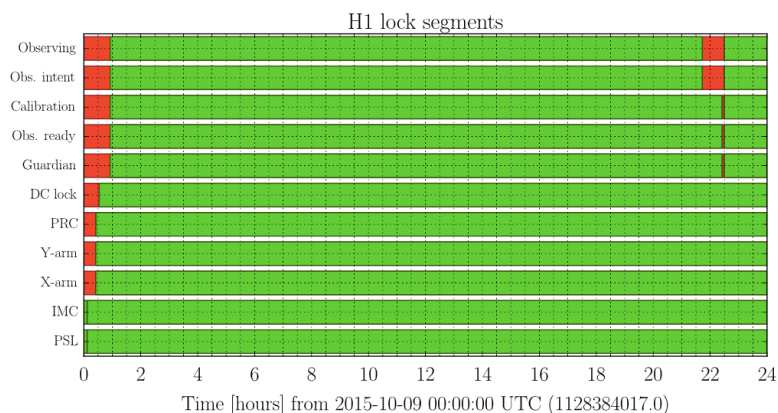
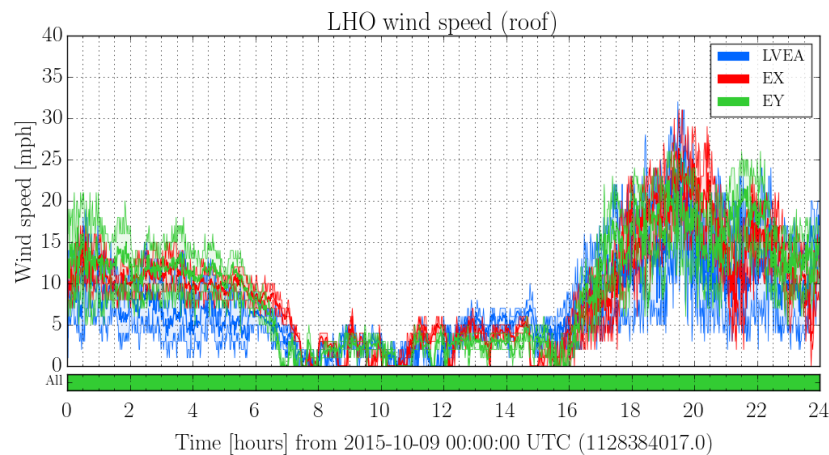
# Alignment sensing and control (ASC) channels

- Look at CARM and DARM for both SOFT and HARD modes and both pitch and yaw angular motion
- Look at transmitted power at photodiodes at end stations for both X and Y arms
- Any angular displacement will be problematic at higher laser power – photon pressure vs actuators' restoring force



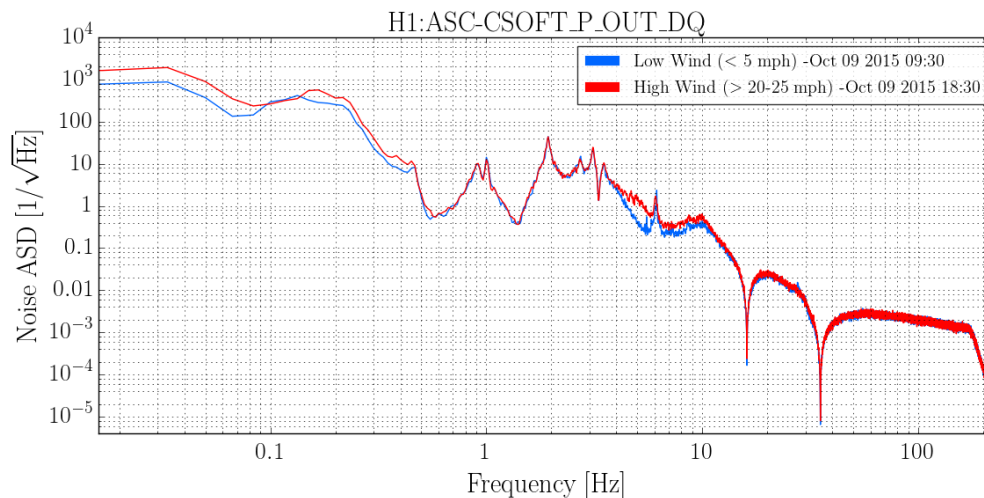
# Identifying useful lock stretches

- Summary pages were used to identify lock stretches that coincided with periods of both high and low wind
- High wind  $> 20$  mph
- Low wind  $< 5$  mph
- All the cavities need to be resonant



# ASD for ASC channels

- Time series is converted to frequency domain
- Useful to look at how power is distributed in different frequency bins
- Excursions are indicative of excess control applied to optics



- Three frequency bands stood out: 0-1 Hz, 4-20 Hz, 20-40 Hz (last one only for transmitted power at end stations)

# ASD for ASC control loops 0-1 Hz

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- [https://dcc.ligo.org/DocDB/0126/T1600159/001/0\\_1\\_Hz\\_ASD.gif](https://dcc.ligo.org/DocDB/0126/T1600159/001/0_1_Hz_ASD.gif)



# ASD for ASC control loops 4-20 Hz

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- [https://dcc.ligo.org/DocDB/0126/T1600159/001/4\\_20\\_Hz\\_ASD.gif](https://dcc.ligo.org/DocDB/0126/T1600159/001/4_20_Hz_ASD.gif)

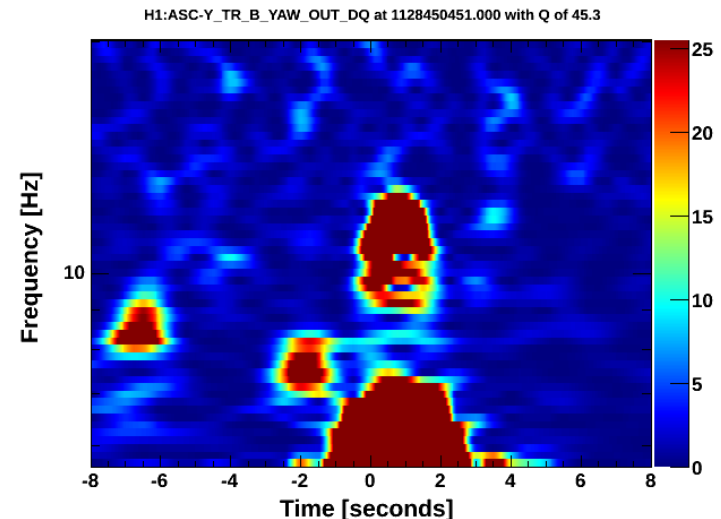
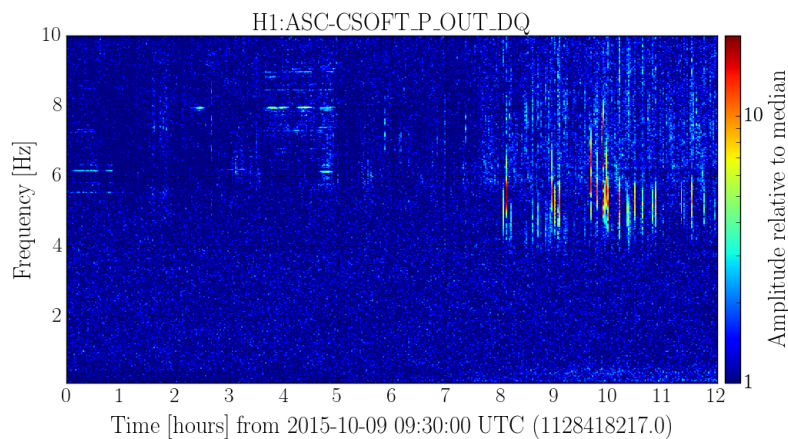
# ASD for ASC control loops 20-40 Hz

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- [https://dcc.ligo.org/DocDB/0126/T1600159/001/20\\_40\\_Hz\\_ASD.gif](https://dcc.ligo.org/DocDB/0126/T1600159/001/20_40_Hz_ASD.gif)

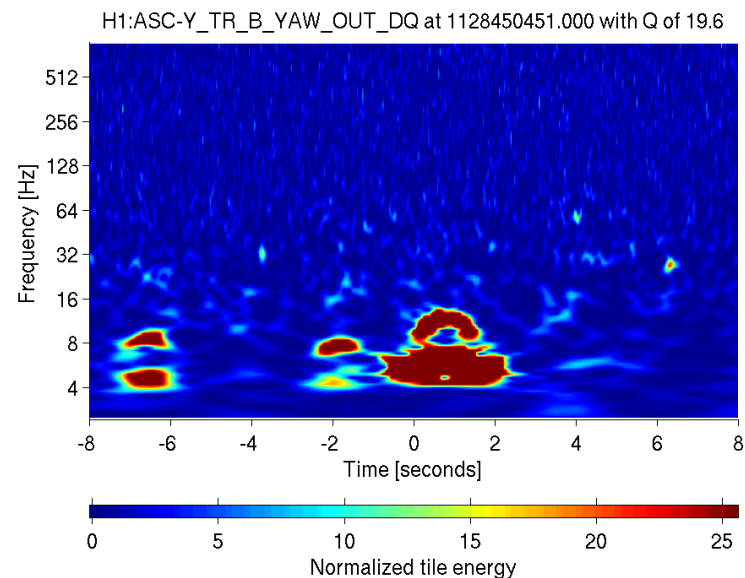
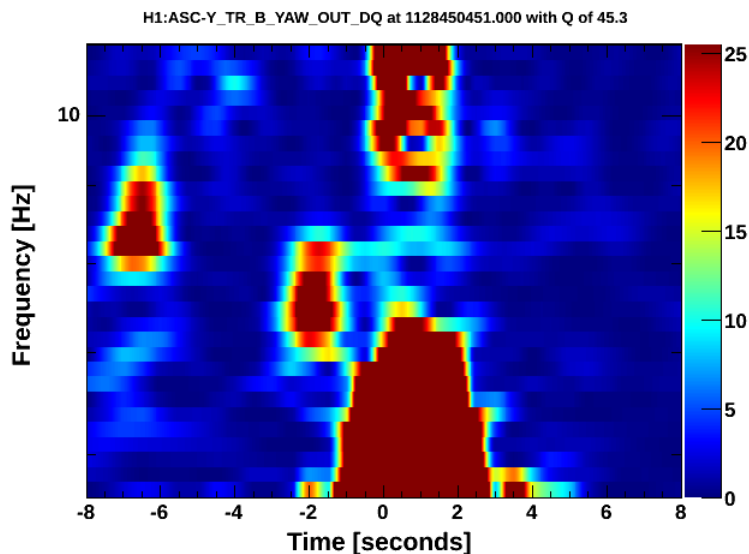
# Glitches in ASC control loops

- Spectrogram using Gwpy
- Glitch for CSOFT\_P
- Spectrograms using OmegaScan
- Glitch for Y\_TR\_B\_YAW

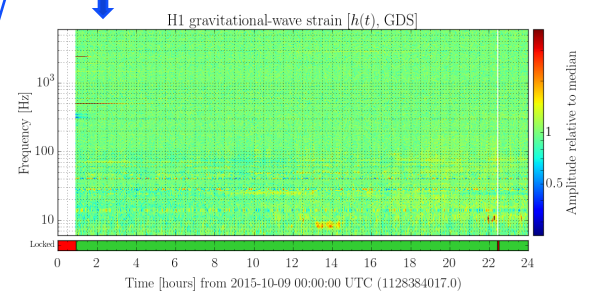
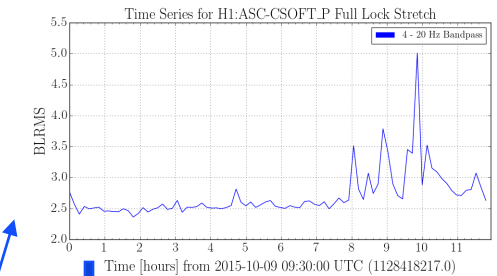
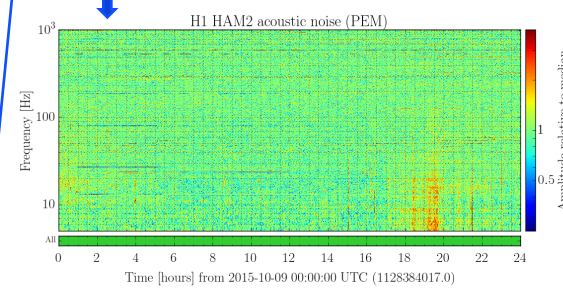
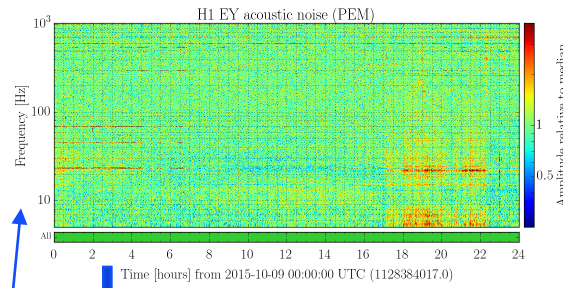
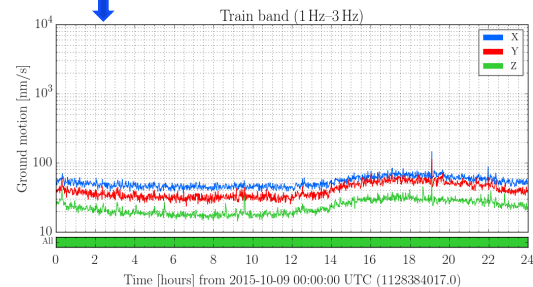
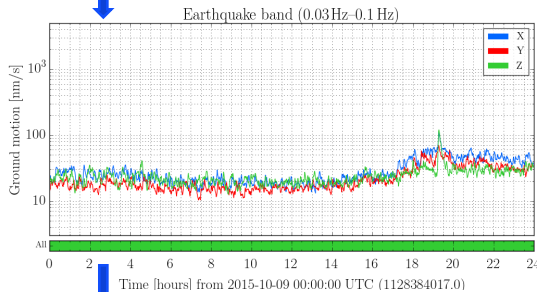
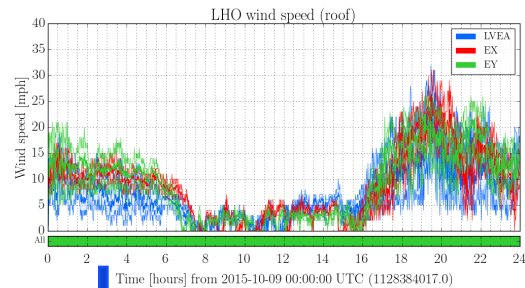


# Glitch due to scattered light

- 5 Hz for Y\_TR\_B\_YAW with a Q of 45.3
- 5 Hz for Y\_TR\_B\_YAW with a Q of 19.6



# Coupling through acoustic noise vs ground motion



- Coupling mechanism is still unknown !

# Are glitches prevalent during extended periods of low wind?

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- 12 lock stretches were observed
- Those that showed glitches coincided with periods of elevated ground motion:
  - » 0.03 – 0.1 Hz (Earthquake Band)
  - » 1 – 3 Hz (Train Band)
  - » 3 – 10 Hz
- No elevated noise was observed in acoustic PEM channels

# Effect of seismic motion on PRCL, SRCL and SRC2

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- Lock stretches in O1 with elevated ground motion were identified
- ASD indicate elevated noise levels for lower frequencies
- Glitches occur with a central frequency around 10 Hz
- Pitch vs yaw for alignment degree of freedom (SRC2) that controls SR2 show an increase in drift of optic

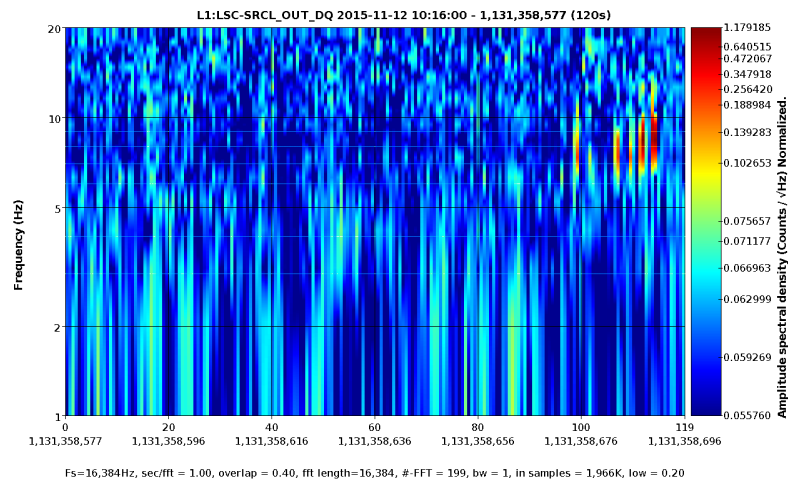
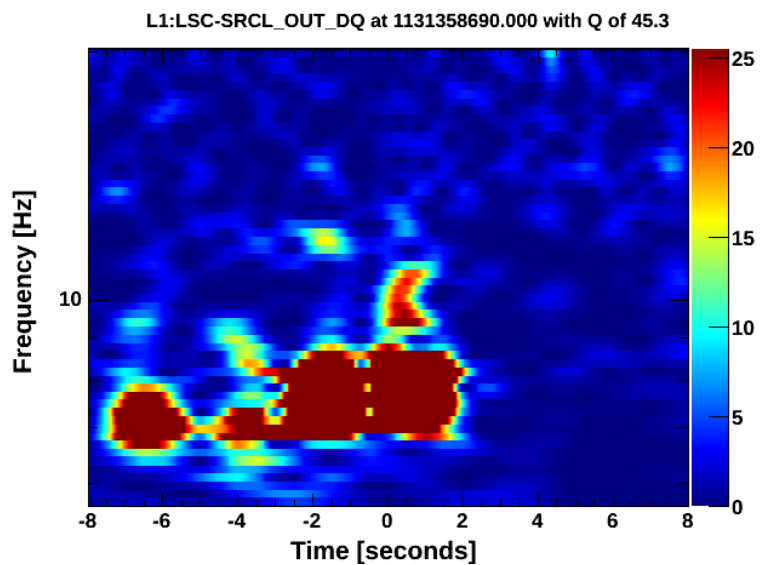
# Effect of Seismic Motion on PRCL, SRCL and SRC2

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- [https://dcc.ligo.org/DocDB/0126/T1600159/001/pitch\\_yaw\\_11\\_06\\_2015\\_v2.mp4](https://dcc.ligo.org/DocDB/0126/T1600159/001/pitch_yaw_11_06_2015_v2.mp4)
- Excess control applied to SR2 occurs at 01:50 (UTC)
- Glitch is seen at around 10 Hz
- ASD are averaged over 15 minute periods



# 10 Hz Glitch



# Summary and conclusion

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- Wind and ground motion cause elevated noise levels and glitching with a central frequency of 5 Hz and 10 Hz
- This will be more problematic at a higher laser power
- Understanding increase in noise levels is important in order to find ways to mitigate them
- Help focus on tuning ASC control loops in order to better mitigate noise during high wind periods

# Future Work

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- Further look into 10 Hz glitches and if they occur for other stretches with elevated ground motion
- Conduct full OmegaScans for a time when the 10 Hz glitch is present
- Use OmegaScan to look for time differences in glitches in order to resolve how a disturbance caused by wind is propagating through the interferometer
- Look at acoustic spectrograms and look at acoustic injection studies to see if 5 Hz glitching appears



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<https://ldas-jobs.ligo-la.caltech.edu/~detchar/summary/>
- [8] Images for slide 6 obtained from: B.P. Abbott et al. (LIGO Scientific Collaboration and Virgo Collaboration). Observation of Gravitational Waves from a Binary Black Hole Merger. *Phys. Rev. Lett.* 116. 061102 (2016)
- [9] GWpy codes and documentation created by Duncan Macleod

# APPENDIX: ASC CHANELS

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H1:ASC-CHARD\_P\_OUT\_DQ  
H1:ASC-CHARD\_Y\_OUT\_DQ  
H1:ASC-DHARD\_P\_OUT\_DQ  
H1:ASC-DHARD\_Y\_OUT\_DQ  
H1:ASC-CSOFT\_P\_OUT\_DQ  
H1:ASC-CSOFT\_Y\_OUT\_DQ  
H1:ASC-DSOFT\_P\_OUT\_DQ  
H1:ASC-DSOFT\_Y\_OUT\_DQ  
H1:ASC-X\_TR\_A\_PIT\_OUT\_DQ  
H1:ASC-X\_TR\_A\_YAW\_OUT\_DQ  
H1:ASC-X\_TR\_B\_PIT\_OUT\_DQ  
H1:ASC-X\_TR\_B\_YAW\_OUT\_DQ  
H1:ASC-Y\_TR\_A\_PIT\_OUT\_DQ  
H1:ASC-Y\_TR\_A\_YAW\_OUT\_DQ  
H1:ASC-Y\_TR\_B\_PIT\_OUT\_DQ  
H1:ASC-Y\_TR\_B\_YAW\_OUT\_DQ