Determining the Effect of Acoustic Coupling on Advanced LIGO

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Overview

- PEM at LIGO
- 2. Creating a Program to Calculate Environmental Effects
- 3. Acoustic Coupling
- 4. Acoustic Coupling Studies
- 5. Flexure Damping Studies
- 6. Conclusions
- 7. Acknowledgements

PEM at LIGO

- Advanced LIGO is designed to be sensitive to movements of the test mass as low as $10^{-20} m/\sqrt{Hz}$
- Many other signals other than gravitational waves can be detected
- PEM team responsible for environmental sensors including:
 - Microphones
 - Magnetometers
 - Accelerometers
 - Seismometers
 - Radio Receivers

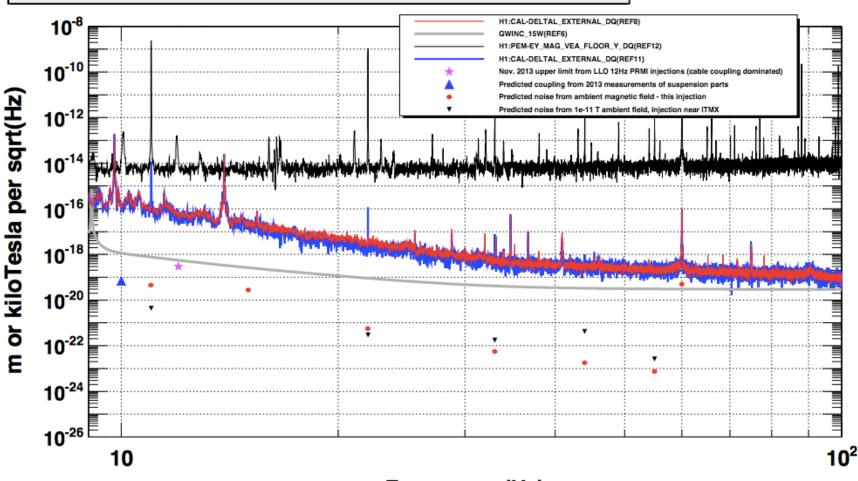






PEM Injections

Estimation of noise from 1e-11 T/sqrt(Hz) magnetic field: RED dots and BLACK triangles: near-chamber magnetic injection at ETMY, and ITMX, respectively



Frequency (Hz)

A Program to Calculate Environmental Effects

- Program developed in Python
- Utilizes exported DTT text files
- Requires an ambient spectrum and an injection spectrum
- Assumes linearity
- Only calculates effect if signal is 10 times larger than background and DARM is 1.5 times larger than background
- Calculates the upper limit of coupling when injections do not produce peaks in DARM
- Outputs text files with coupling factors and noise estimates
- Final program allows for signals from up to 7 different sensors
- Option to produce a file with only data in rank (highest, lowest, etc.) or median of all data at each frequency

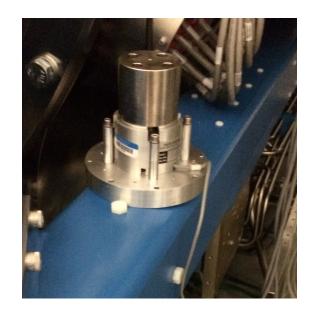
Acoustic Coupling: What is it?

- When sound travels it creates pressure change in the air
- Ways acoustic pressure fluctuations can affect DARM:
 - Shakes vacuum chamber walls: modulates the tiny fraction of scattered light that hits the walls and returns to the beam
 - Shakes external parts of the seismic isolation system: vibrations travel through the isolation system and shake the mirrors in vacuum that the laser beam hits, shaking the beam and producing noise in DARM
 - Shakes mirrors and optics directly in air: the shaking produces noise in DARM

Acoustic Coupling Injections

- 1. Speakers used to test entire system
- Shakers placed on single HAMs or BSCs
- 3. Reaching into HAM and plucking flexure





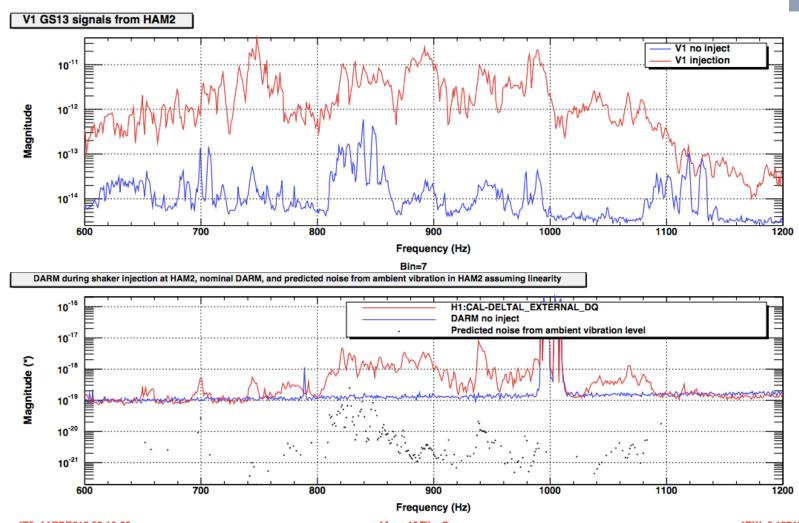


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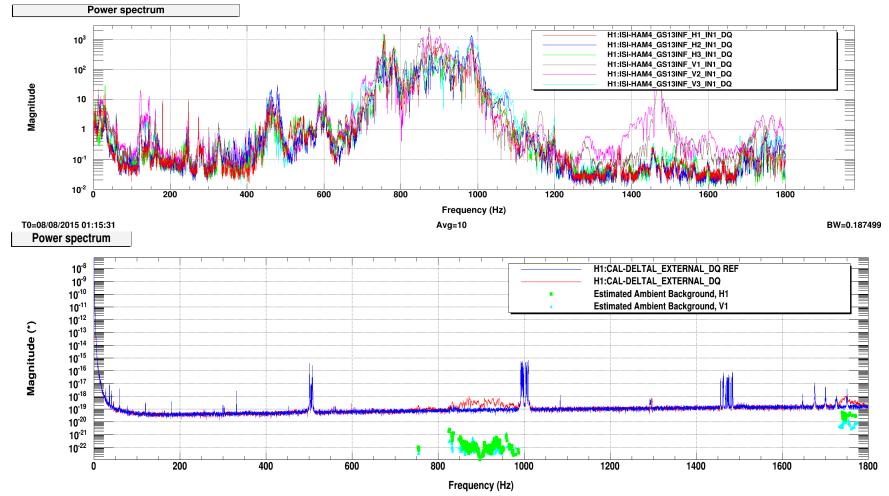
Acoustic Coupling Testing Progress

- Shaker tests on all HAMs and BSCs
- Analyzing data to calculate estimated effect from environmental signal and upper limits of non-peaks
- Creating a ranking of chambers most affected by acoustic coupling

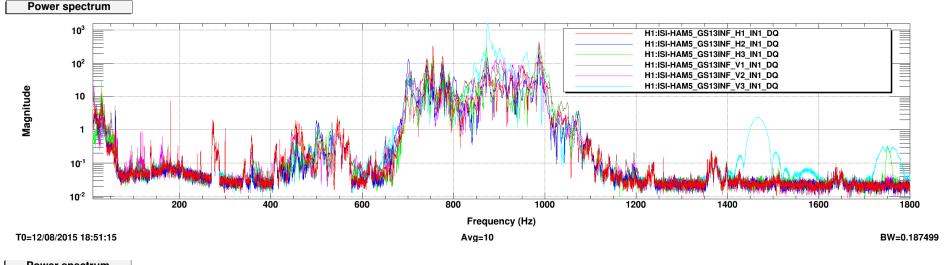
- Large area of raised DARM signal
- Average high estimate between 10^-19 and 10^-20 m/\sqrt{Hz}

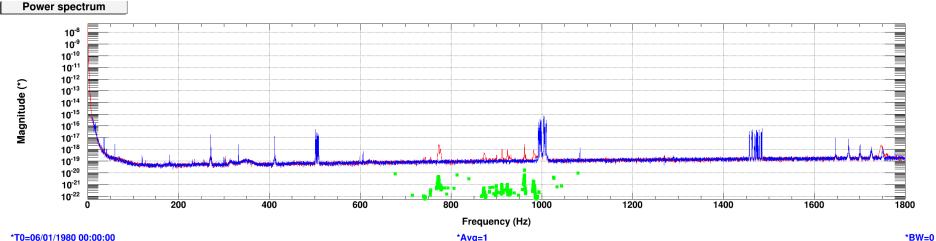


- Created increase in DARM between 800 and 1000 Hz
- Signs of upconversion
- Average estimates around $10^{-21} m/\sqrt{Hz}$

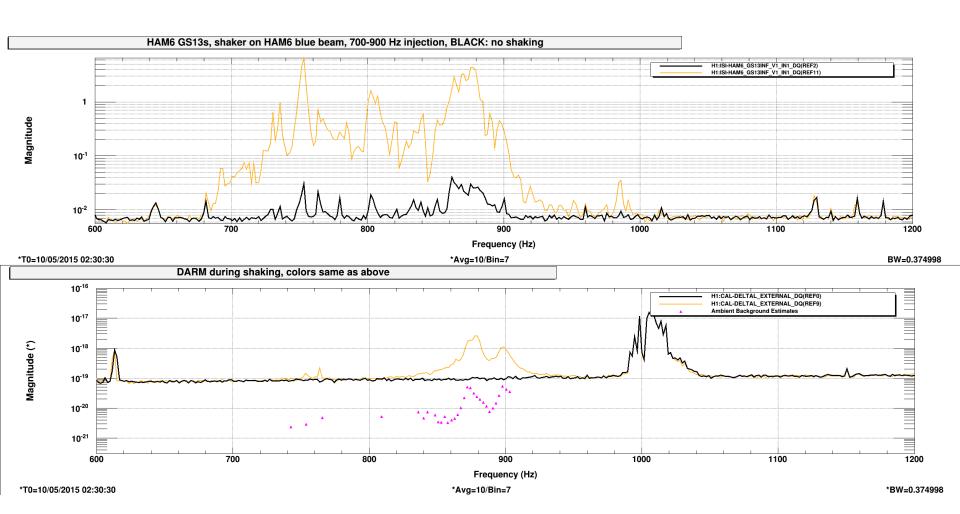


- Few small peaks created in DARM
- Average high estimate between 10^-20 and 10^-21 m/\sqrt{Hz}





- Few peaks produced in DARM
- Average estimates between 10^-19 and 10^-20 m/\sqrt{Hz}



Other HAMS

HAM 1:

- No geophones within chamber
- No noticeable change in DARM occurred during injection

■ HAM 3:

- No noticeable change in DARM occurred during injection
- When calculated by the program, no estimated values were produced

HAM Ranking

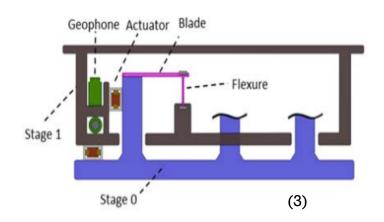
- 1. HAM 2
- 2. HAM 6
- 3. **HAM** 5
- 4. HAM 4
- 5. HAMs 1 and 3

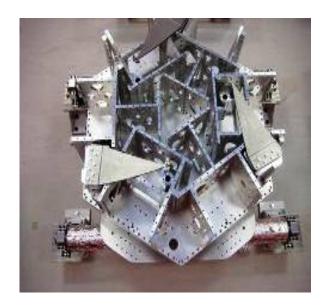
HAM 6 Flexure Testing

- 3 Flexures inside HAM connect the two stages
- When HAM 6 was shaken, peaks appeared
- Possibly the result of flexures vibrating at natural frequencies
- Testing with Viton lined clamps to damp



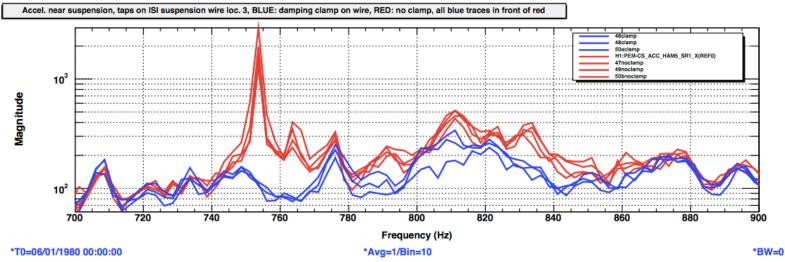




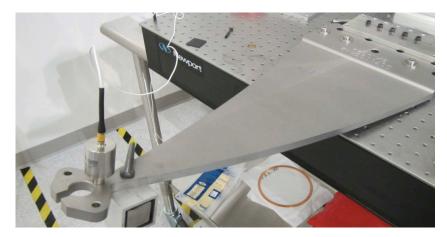


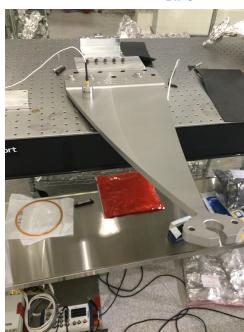
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HAM 6 Flexure Testing



Testing in progress on best way to damp the flexure and blade spring





Conclusions

- Program handled data analysis well
- Shaking tests on HAMs revealed sites of acoustic coupling
- BSC data still needs to be analyzed
- Future work:
 - Testing in end stations
 - How to limit acoustic coupling?

Thank you for an exciting and rewarding experience at LIGO!



Acknowledgements:

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References

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