*LIGO Laboratory / LIGO Scientific Collaboration*

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**Single Pendulum Parameter Descriptions and Naming Convention**

Jeffrey Kissel and Mark Barton

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| **California Institute of Technology**  **LIGO Project – MS 18-34**  **1200 E. California Blvd.**  **Pasadena, CA 91125**  Phone (626) 395-2129  Fax (626) 304-9834  E-mail: [info@ligo.caltech.edu](mailto:info@ligo.caltech.edu) | **Massachusetts Institute of Technology**  **LIGO Project – NW22-295**  **185 Albany St**  **Cambridge, MA 02139**  Phone (617) 253-4824  Fax (617) 253-7014  E-mail: info@ligo.mit.edu |
| **LIGO Hanford Observatory**  **P.O. Box 1970**  **Mail Stop S9-02**  **Richland WA 99352**  Phone 509-372-8106  Fax 509-372-8137 | **LIGO Livingston Observatory**  **P.O. Box 940**  **Livingston, LA 70754**  Phone 225-686-3100  Fax 225-686-7189 |

http://www.ligo.caltech.edu/

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# Introduction

## Purpose and Scope

Describes the parameter names used in the Mathematica and Matlab single pendulum dynamics models used for HAUX, HTTS and OFIS.

## References

LIGO-T1400446: [aLIGO SUS Pendulum Dynamics Modeling](https://dcc.ligo.org/LIGO-T1400446)

LIGO-T020205: [Models of the Advanced LIGO Suspensions in Mathematica™](https://dcc.ligo.org/LIGO-T020205)

LIGO-T080188: [Models of the Advanced LIGO Suspensions in MATLAB](https://dcc.ligo.org/LIGO-T080188)

## Version history

7/7/2014: -v1. Initial version based on triple version, T040072.

# Parameters

The following parameters are the minimum set necessary to define a case of the Mathematica TwoWireSimpleBlades and FourWireSimpleBlades models used for the aLIGO HAUX, HTTS and OFIS, or the equivalent Matlab model (ssmake1MBf.m). The choice of the two-wire and four-wire matrix elements in the matlab is determined by whether the parameters dx1 and dx2 (for the wire front-back separations) are both defined. As near as practical, all of the parameters have the same names in both models. The parameters for blade and wire stiffness are defined per side in the Matlab but per blade in the Mathematica, and to prevent (total) confusion have been given different names. The Mathematica model has a large number of additional parameters for the damping of the elastic elements which are beyond the scope of this document. The Matlab model also handles certain additional Mathematica models that were generated for R&D purposes such as TwoWireSimple, etc, but the extra parameters which trigger this are beyond the scope of this document.

## Parameters common to Mathematica and Matlab

|  |  |  |
| --- | --- | --- |
| Parameter | Unit | Description |
| g | m/s^2 | local gravity |
| m0 | kg | mass of optic/bench |
| I0x, I0y, I0z | kg.m^2 | diagonal components of optic/bench MOI |
| I0xy, I0yz, I0zx | kg.m^2 | off-diagonal components of optic/bench MOI |
| dtop, dpitch | m | vertical offsets of wire attachments from COM (positive outward, towards wire) - see diagrams |
| dyaw1, dyaw2 | m | two-sided lateral (y-direction) wire attachment point separations at top and bottom, - see diagrams |
| dx1, dx2 (OFIS only) | m | two-sided front-back (x-direction) wire attachment point separations at top and bottom. If these are defined, matrix elements for a four-wire suspension are used. |
| l0 | m | stretched lengths of wires |
| Y0 | Pa | Young's moduli of wires |
| r0 | m | radii of wires |
| b0x, b0y,b0x | N/(m/s) | linear velocity damping coefficients (optional) |
| b0yaw, b0pitch, b0roll | N.m/(rad/s) | angular velocity damping coefficients (optional) |

## Parameters unique to Matlab

|  |  |  |
| --- | --- | --- |
| Parameter | Unit | Description |
| kc0 | N/m | blade vertical stiffnesses ***per side***, equivalent to kbz |
| stage2 | - | switch governing the interpretion of the d’s: state2=1 => d’s are physical, apply flexure correction; stage2=0 => d’s are effective, flexure correction already included, don’t reapply. |
| bd | N/(m/s), N.m/(rad/s) | a small amount of damping which is added to all DOFs to avoid unrealistically peaky TFs; defaults to 0.001. |

## Parameters unique to Mathematica

|  |  |  |
| --- | --- | --- |
| Parameter | Unit | Description |
| kbz | N/m | blade vertical stiffnesses ***per blade***, equivalent to kc0 Matlab |
| kw0 | N/m | wire vertical stiffness, per wire; case definer needs to calculate these manually whereas they are calculated automatically in the Matlab |

# Diagrams

In the final PDF of this document, OmniGraffle diagrams of the dimensional parameters will be appended.