Notes on DRMI locking at LLO

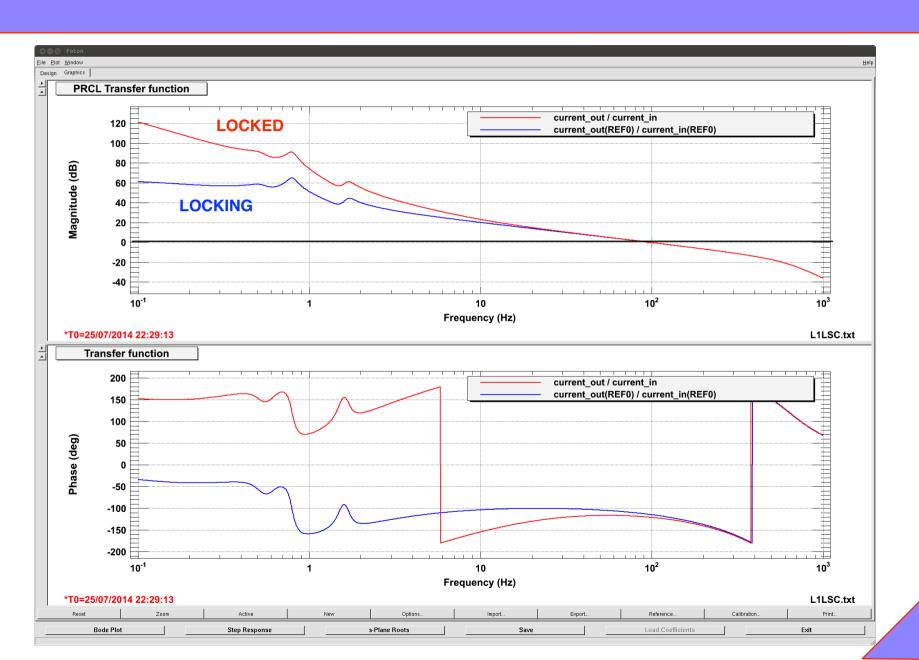
K.Izumi 2014.July.20

LSC settings Overview

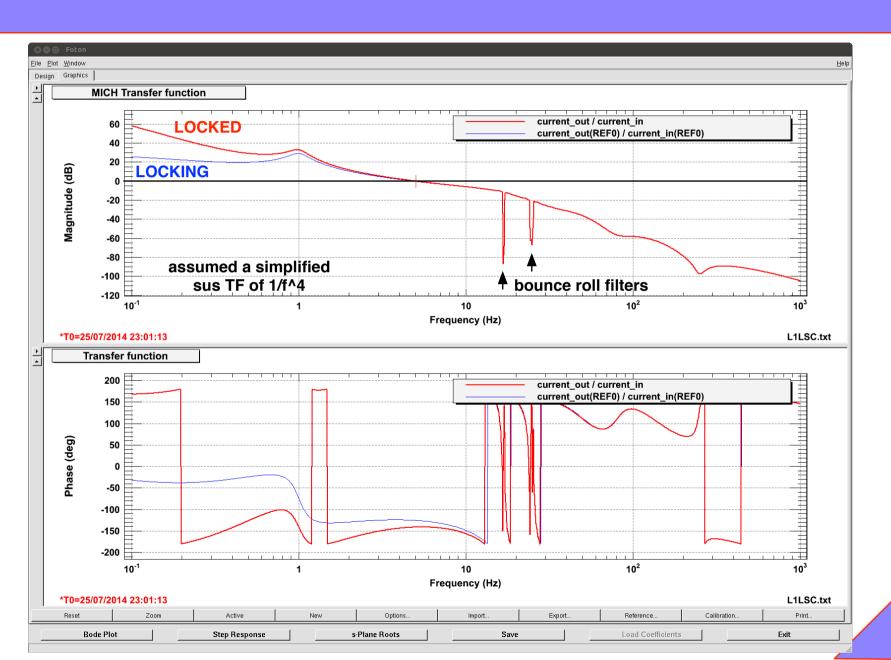
- Guardian-based (a part of the full lock sequence)
- No separate DRMI guardian (AM is working on)
- Several realtime triggers
- Non-diagonalized output matrix (AE is working on)

- REFL9I -> PRCL (UGF = 100Hz)
- REFL45Q -> MICH (UGF = 5Hz)
- REFL45I + REFL9I -> SRCL (UGF = 50Hz)

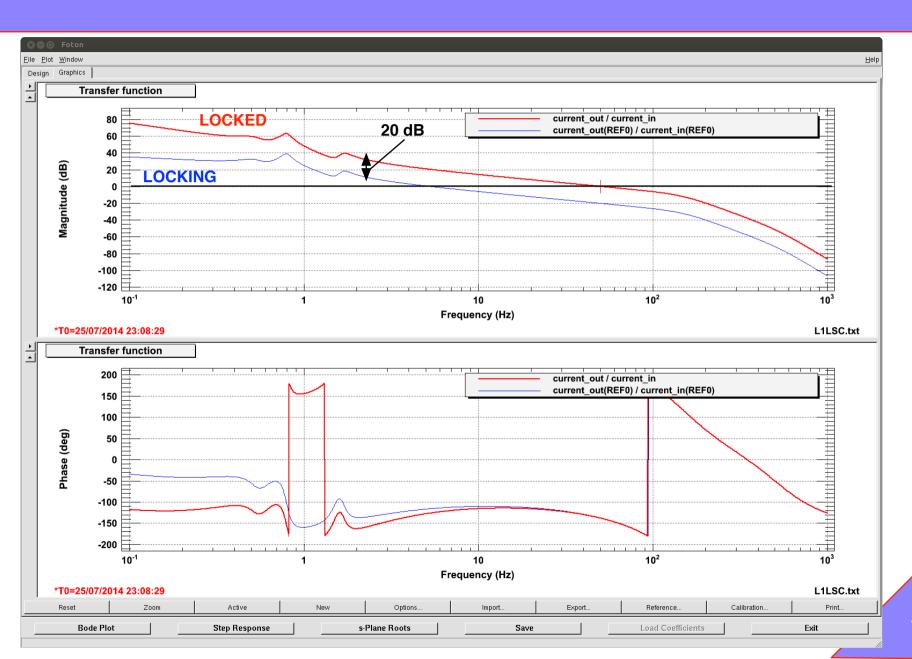
PRCL open loop



MICH open loop

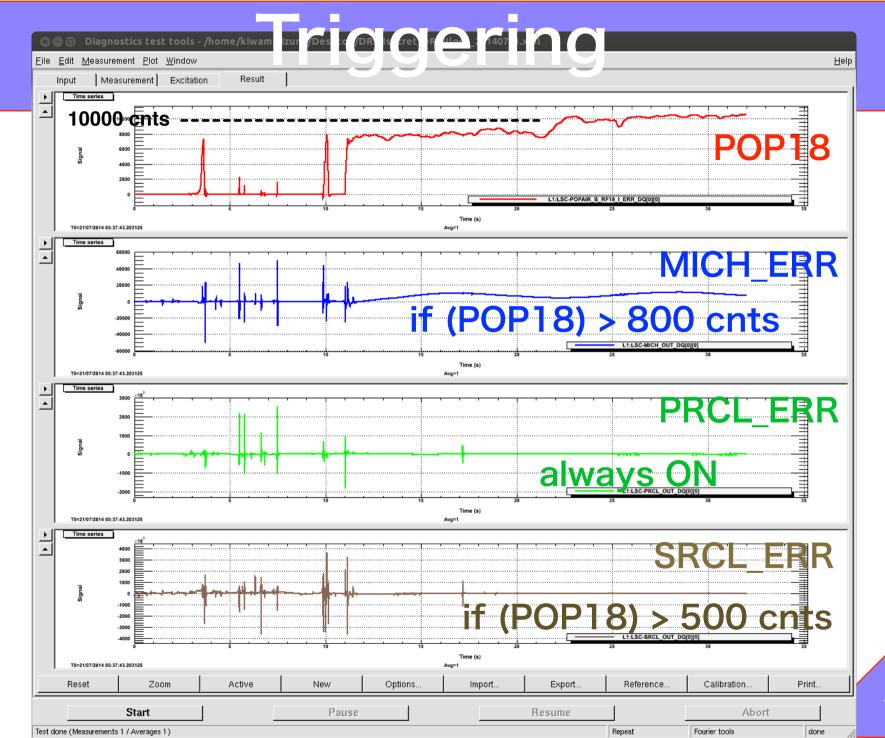


SRCL open loop



OUTPUT matrix





Length actuation on SUS

- Guardian-based triggering for the hierarchical longitudinal control
- PRM M2 stage turns on when DRMI is locked
- **SRM M2** stage turns on when DRMI is locked
- L2P(Y) and P(Y)2L filters are not used although once they have tried.
- crossover frequencies ?

ASC overview

- Crucial for locking and long term lock
- Initial alignment is critical for locking
- Misalignment easily elongates the locking down time from 10 sec to several minutes.
- WFS are used for in-lock control
- Multiple-steps for initial alignment

ASC Loops

- 4 auxiliary DC WFS centering, actuating on RM1/RM2/OM1/OM2
- BS oplev is tuend off when ASC is engaged

* in locking sequence

REFL9 -> PRM + PR2

AS36 -> BS

REFL45 -> SRM

* in full lock

REFL9 -> PRM + PR2

AS36 -> BS

AS36 -> SRM

control bandwidth ~ below 1 Hz

Initial Alignment

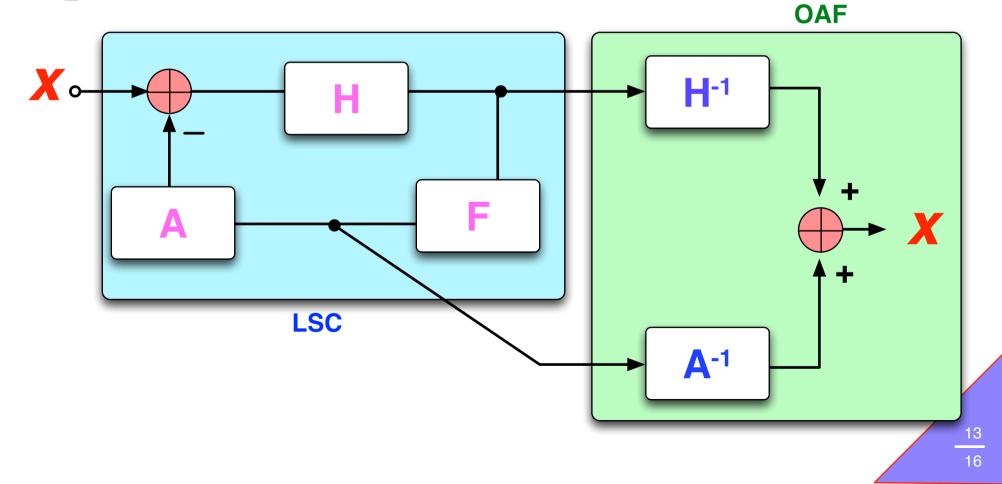
- Initial alignment is broken into three steps
- **REFL and AS WFSs are used**
- (0) Assume that PR2/IM4 input pointing to X
- arm and ITMs' angle are already good
- (1) Lock PRX to determine PRM angle
- (REFL WFS)
- (2) Lock MICH to determine BS angle
- (AS_WFS, currently not functional)
- (3) Lock SRY to determine SRM angle
- (REFL_WFS)
- This usually gives a smooth DRMI lock (~10sec)

Seismic

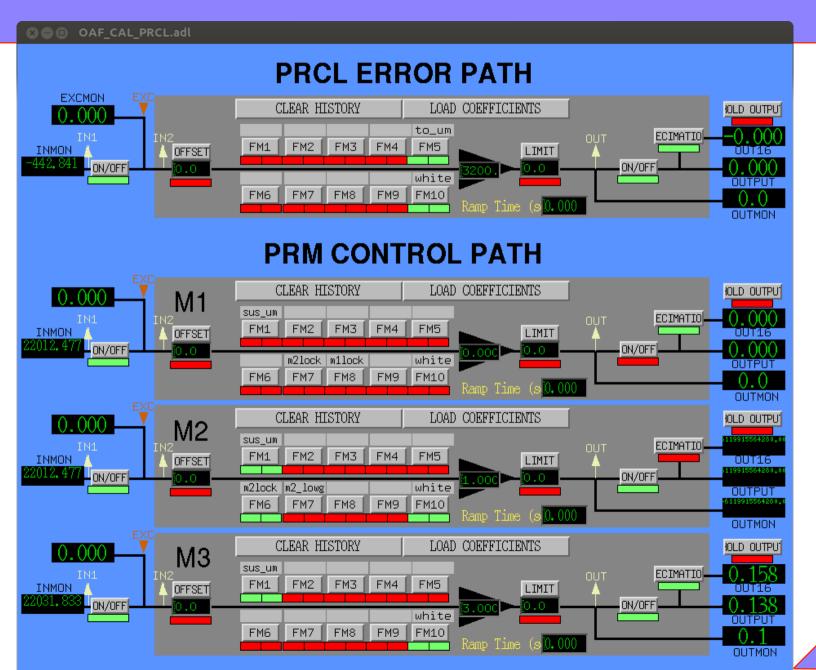
TBD

Calibration

- Online calibration to obtain open-loop equivalent noise (i.e. unsuppressed) in displacement
- **■** Model runs in L1OAF



Calibration screen



Misc.

- **■** Some noise budget code in SVN...
- Modulation depths?
- Power on 3f BBPD ?

Some considerations

- Decoupling of MICH actuator? a combination of PR2, SR2 and BS seems easier than using PRM, PR2, SRM, SR2 and BS. What do we want?
- How do we measure the SRC length?
- PR3, SR2 and SR3 angles were left untouched.
- Don't we want to control them in the initial alignment?
- Is the chosen ASC loops optimum? Is there a better solution?