



Composite mirror suspensions development status

Riccardo DeSalvo

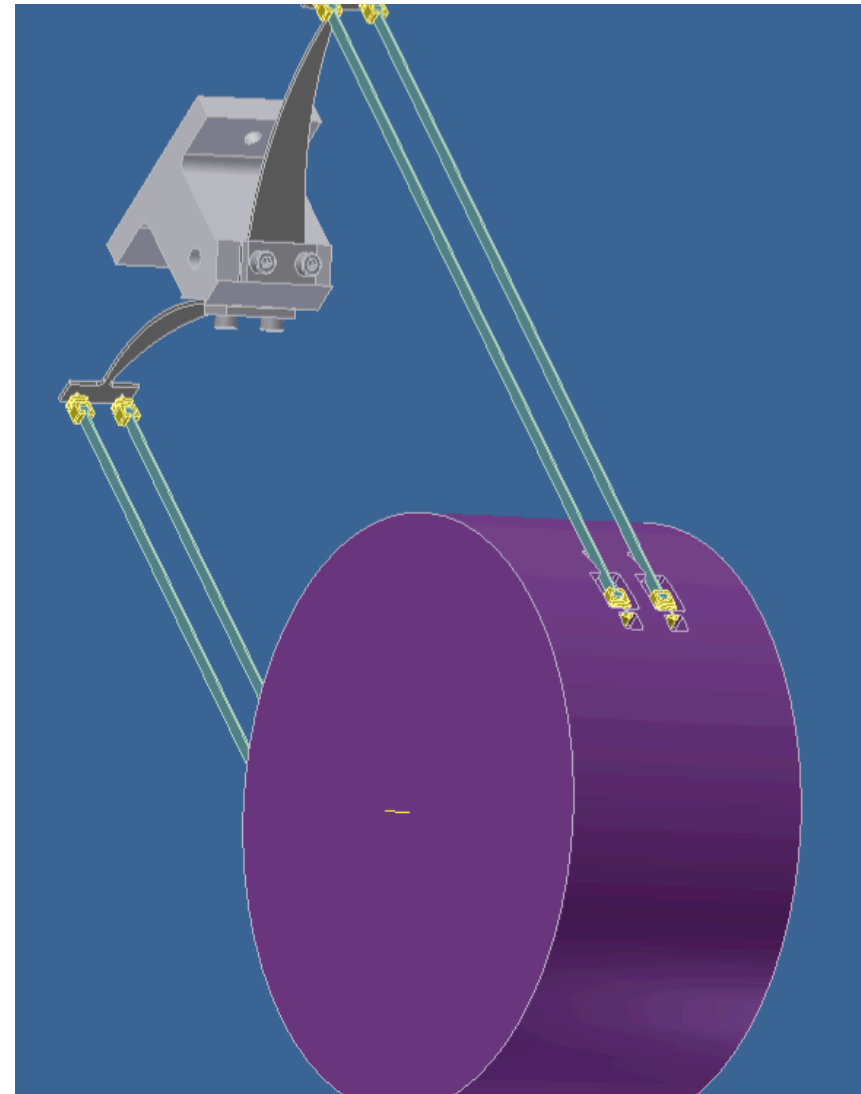
For the ELiTES R&D group WP1 & 2

JGW-G1201265

The idea

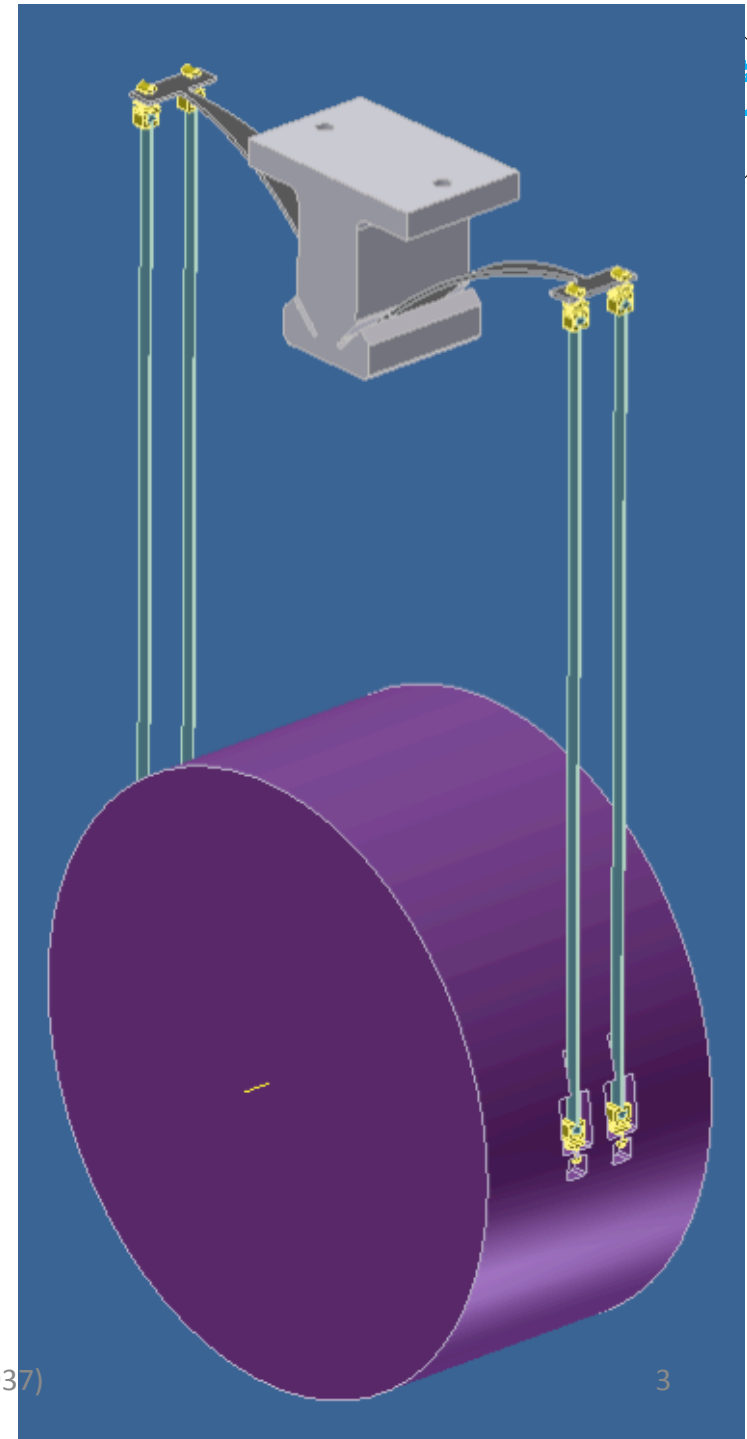


- A **fresh approach** to the design of **low thermal noise mirror suspensions** for KAGRA and ET



Key features:

- Composite structure
- Purely Compressive joints
- No shear noise
- No need for bonding
- Easy replacements
- Easily scalable to larger masses

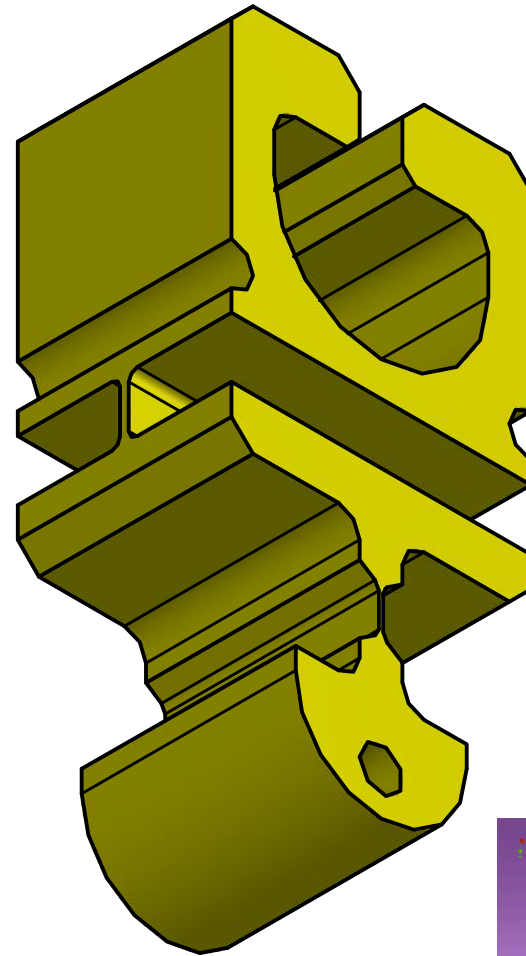


Flexure

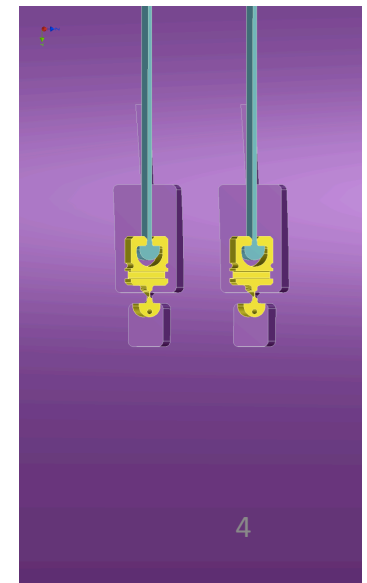
Key features:



- Silicon flexures
- Intrinsic Q-factor $>10^8$
- Thermo-elastic $>10^6$
- Diluted Q-factor $>10^9$
- Before cryo gain !



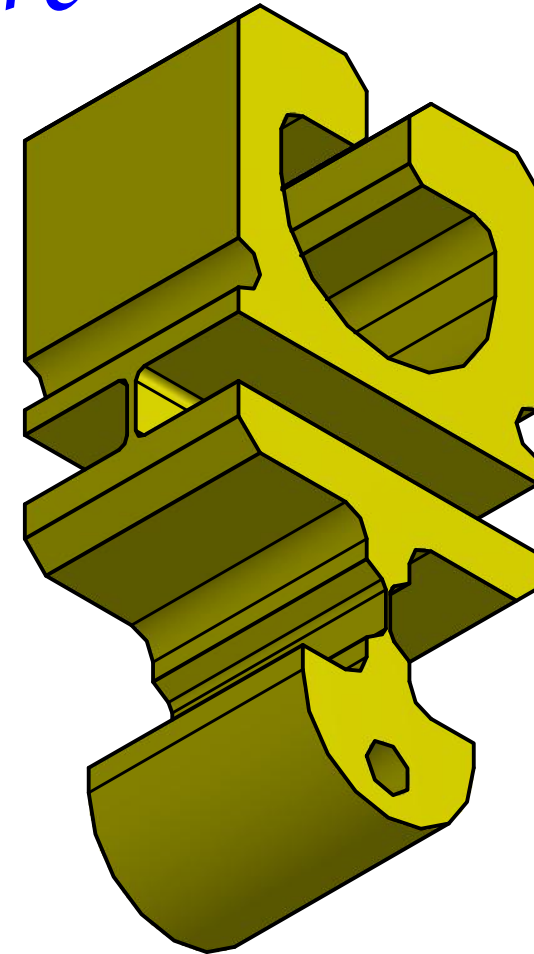
- Many Machining options available



Flexure structure



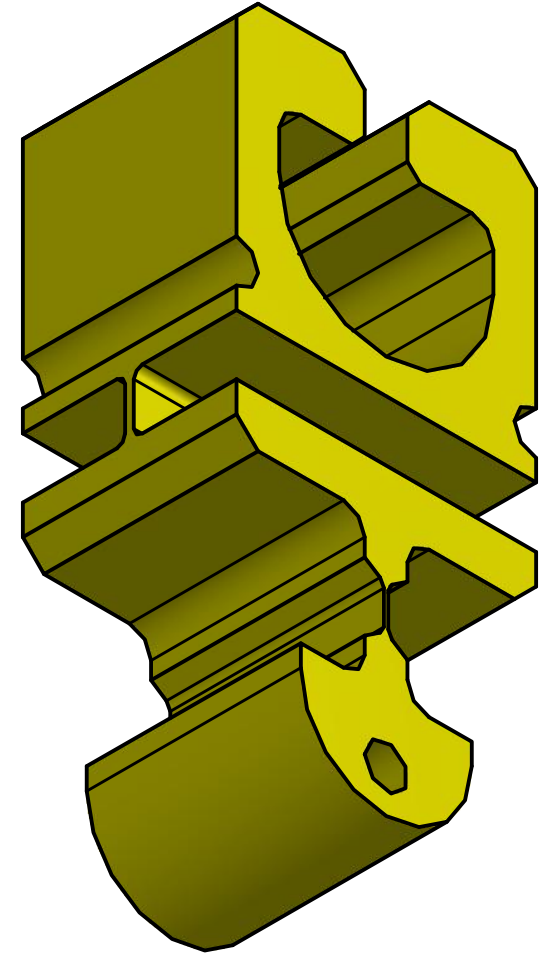
- Ultra-Sound Machined structure
- Etching of the flexure surface
- Sufficient 0.15 GPa b.p.
- Etching may increase the break point > 1GPa



Flexure structure

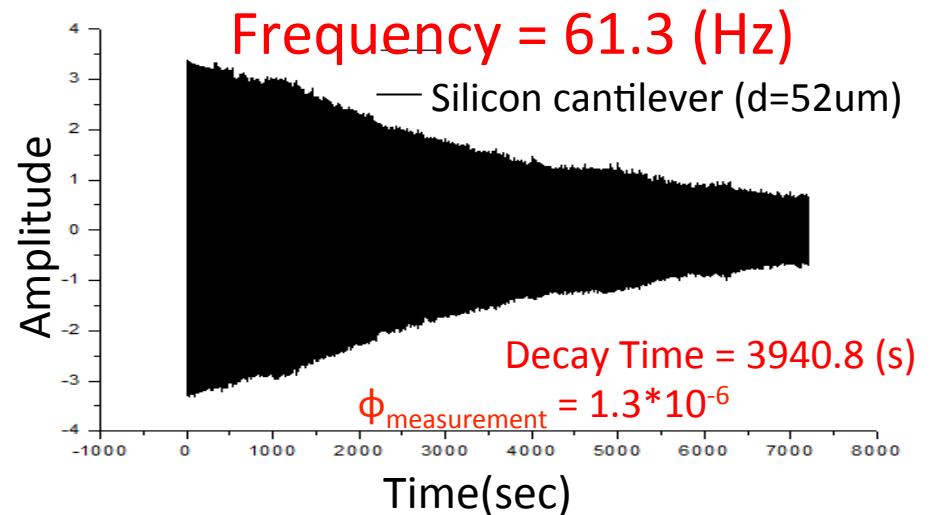
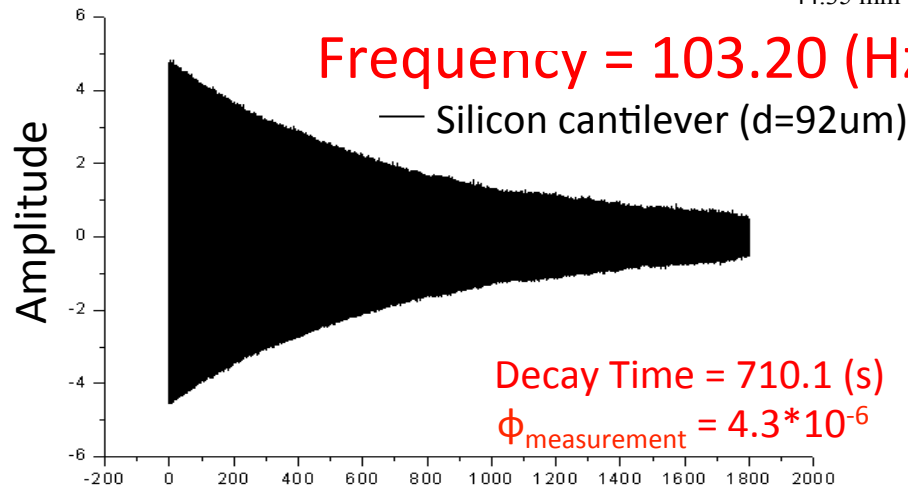
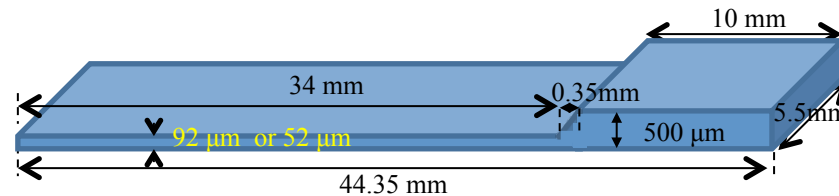
- Thin, short, etched flexure
- Small flexure aspect ratio

= > Large thermal conductance



Silicon cantilever with KOH wet etching

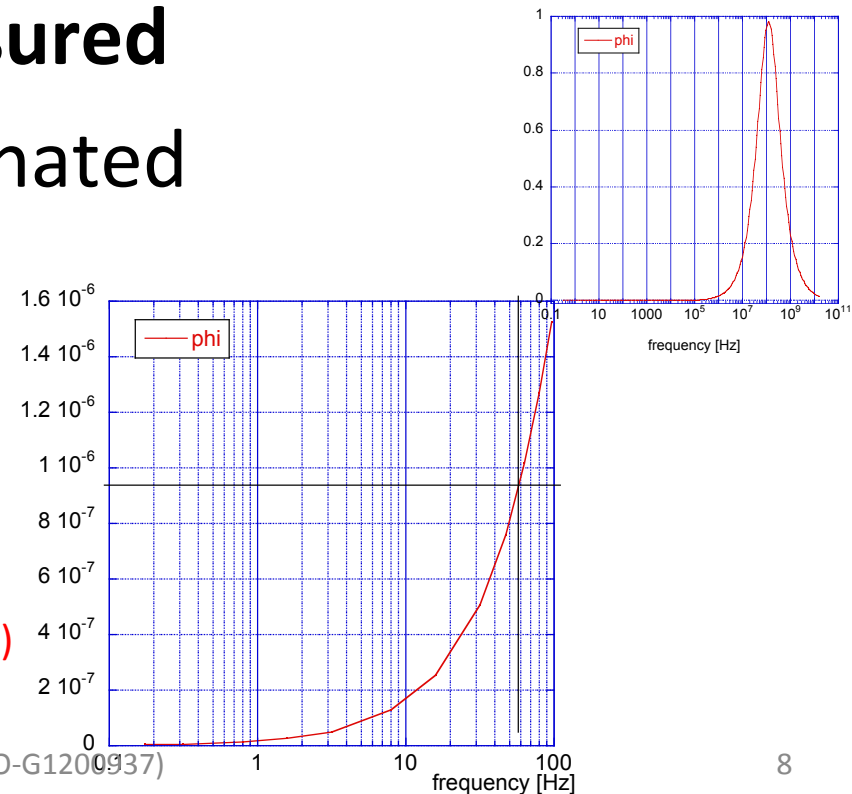
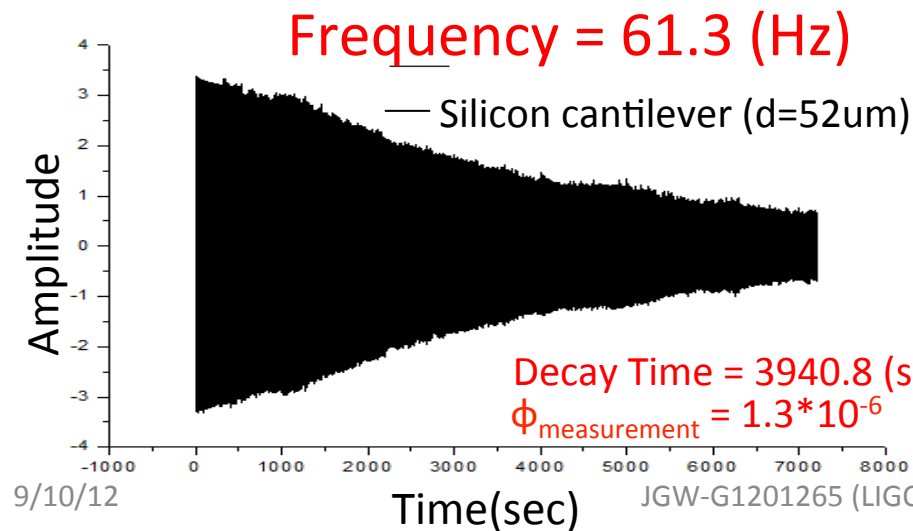
4" un-doped double-side polished (001) silicon wafer,
500um thickness etched down to 92 and 52 μm



0.3 10^{-6} loss measured from residual gas

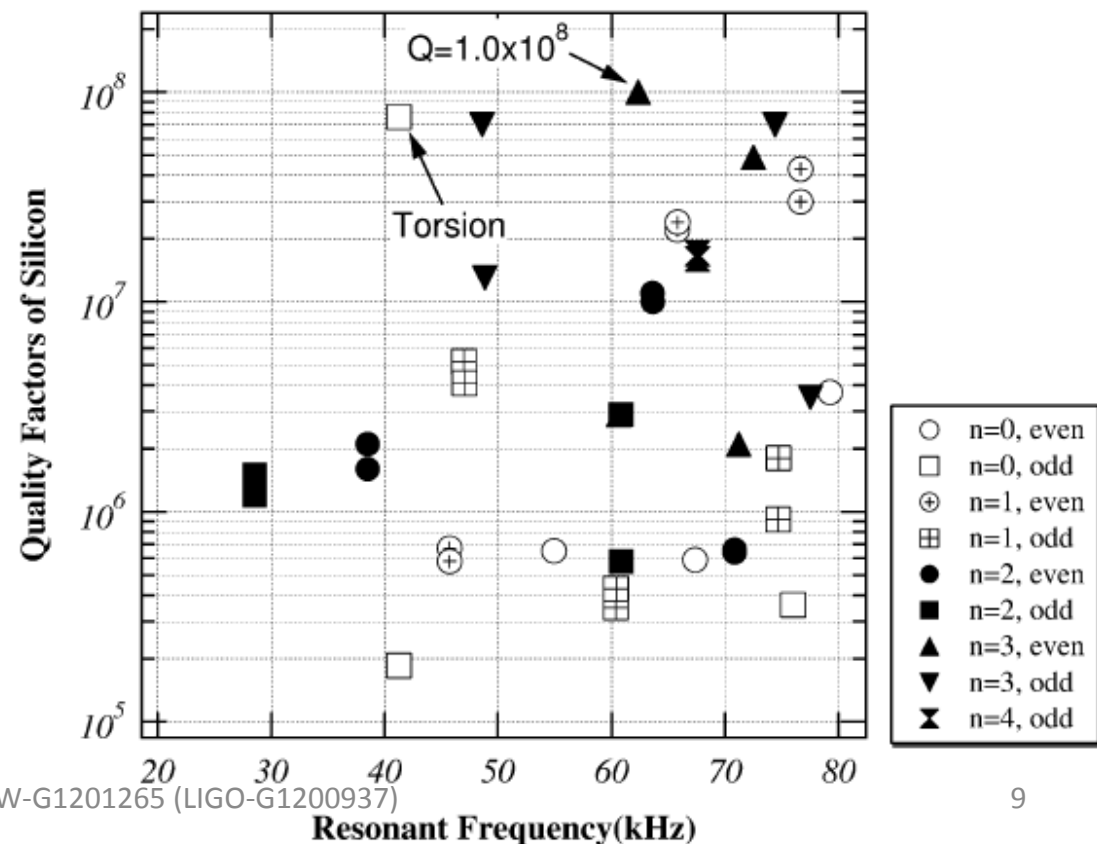
Thermo-elastic limit

- @ 60 Hz $0.945 \cdot 10^{-6}$ loss angle predicted (T.E.)
- $1.3 \cdot 10^{-6}$ measured (-) $0.3 \cdot 10^{-6}$ residual gas
- $1 \cdot 10^{-6}$ loss angle measured
- => Thermoelastic dominated



Kenji's Q-factor measurements

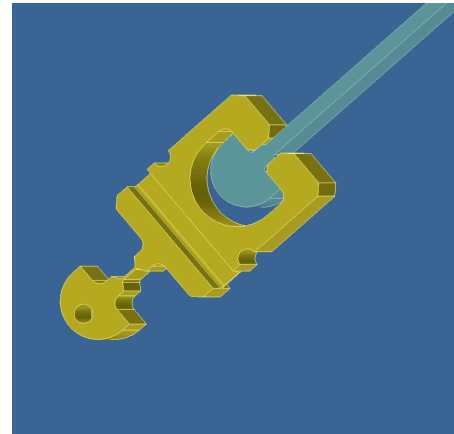
- Measurement on a mirror substrate
- 10^8 lower limit



Ribbons

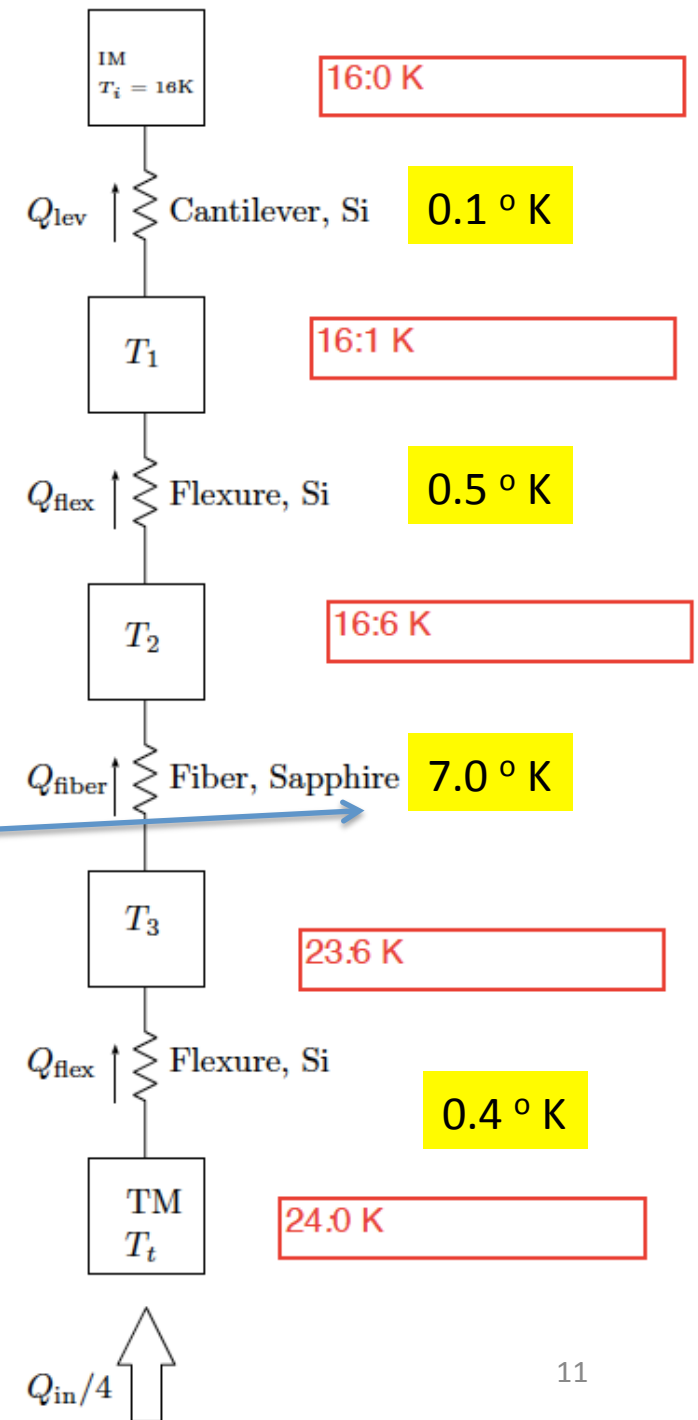
Key features:

- Compression joint attachment
- Machined-polished Sapphire ribbons
(from bulk, not grown)
- **High quality sapphire**
- High quality surface finish
(sub-phonon defect size)
- => **High thermal conductivity !**



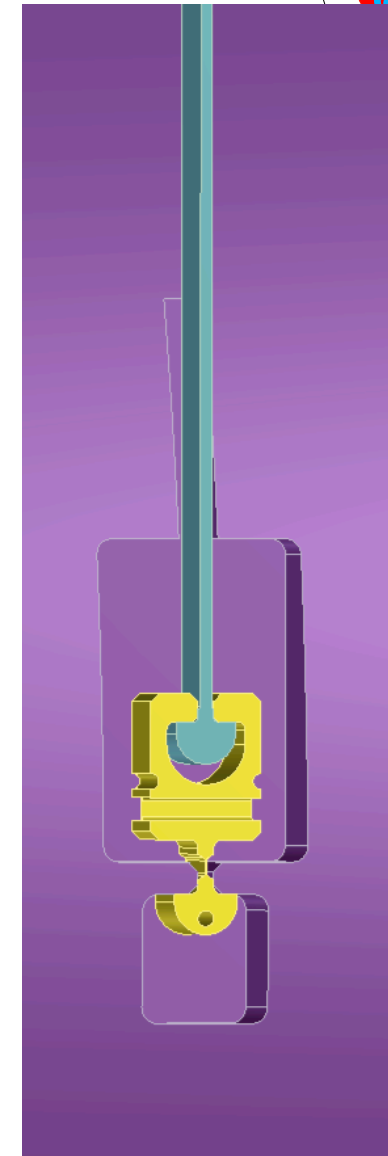
Conductance budget

- Preliminary conductance budget from Sakakibara with 1 W load
- Thin ribbon responsible for bulk of loss !!!
- Plenty of space for parametric optimization



Key features:

- Mini-alcoves (low volume machining)
- Machining before coating deposition
- Minimize substrate induced stress
- Recessed attachment, Low vulnerability
- No bonding shear noise
- No flats on mirror barrel
=> 100% of mirror front surface available

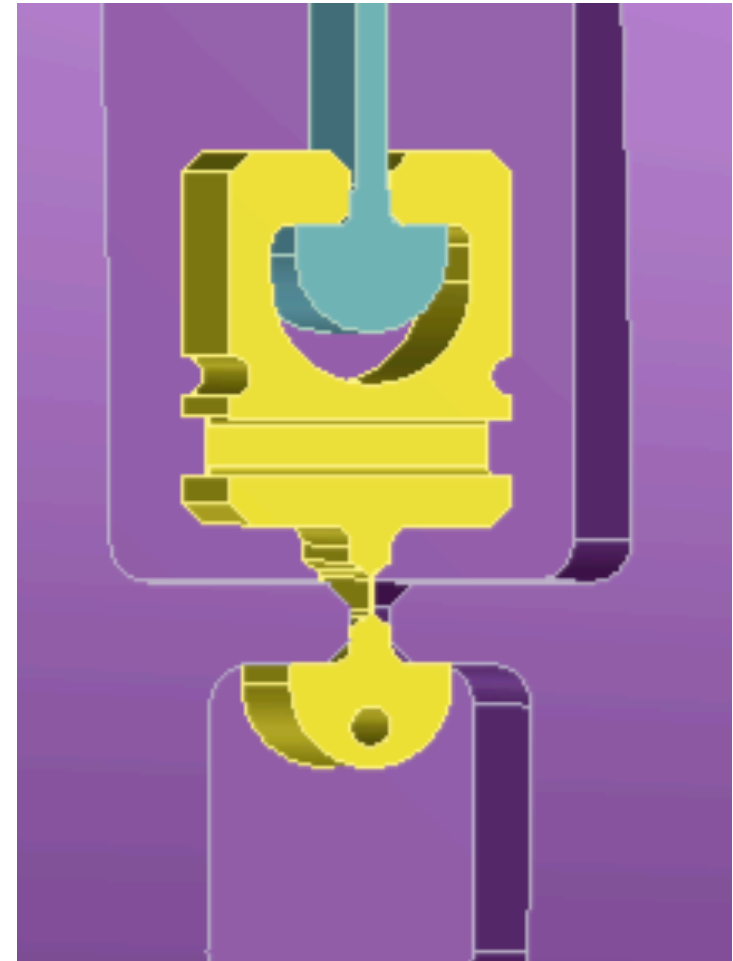


Connections

Key features:



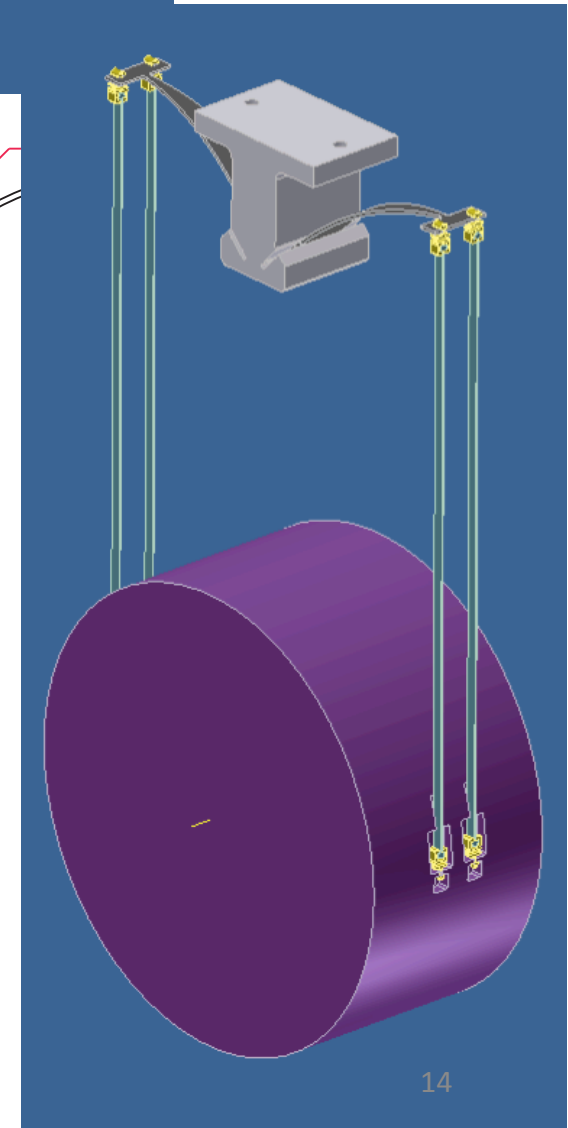
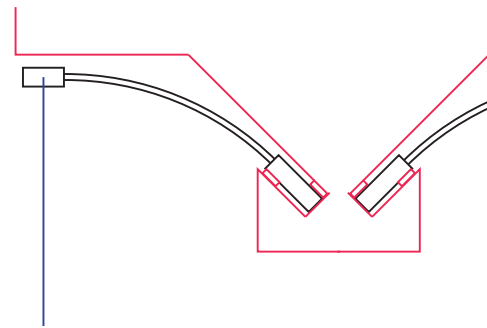
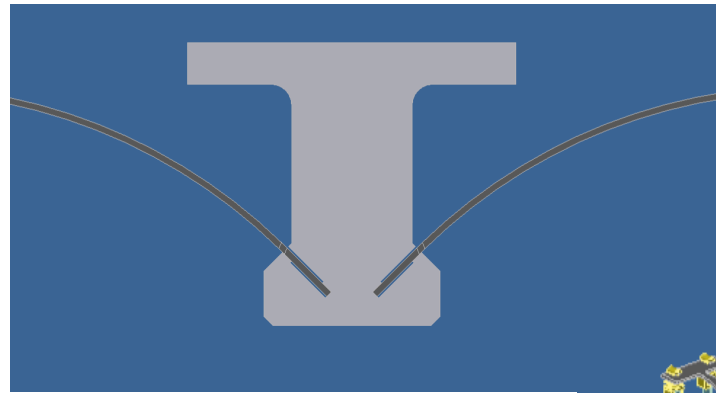
- Purely compressive joints
- Direct silicon-sapphire contact
- => No energy loss for bending
- **Problem:** Lateral slippage between hard surfaces
- Sub- μm Indium or Gallium gasket
- Elimination of stick and slip noise (credit: Vladimir Braginsky)
- Perfect heat conductivity
- Easy replaceability



The need for Springs

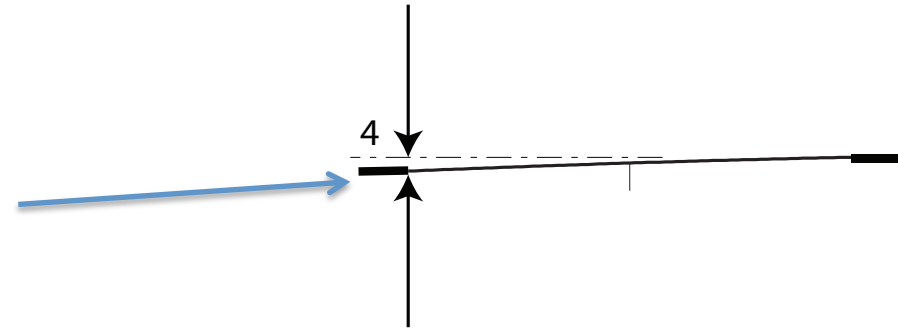


- Elimination of vertical suspension thermal noise (necessary due to KAGRA's tunnel tilt)
- Equalization of stress on wires
- Removal of bounce mode from sensitivity range

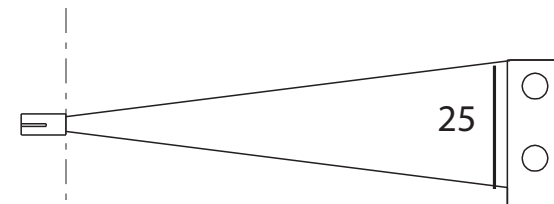


Cantilever blades vs. stress

- With 0.15 GPa only deflection is limited to 4 mm

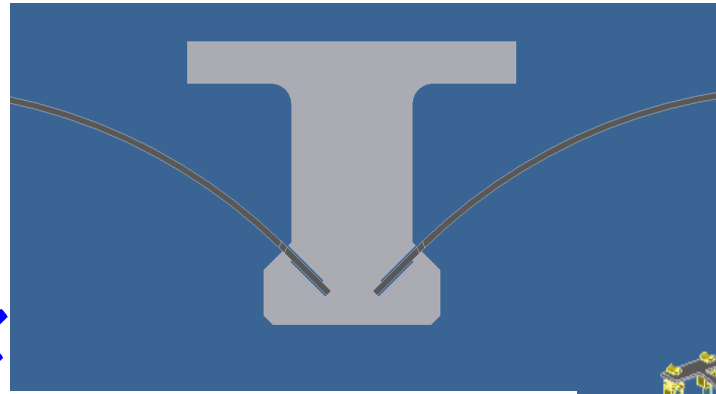


$$f = \frac{\sqrt{\frac{g}{h}}}{2\pi} \approx 8 \text{ Hz}$$

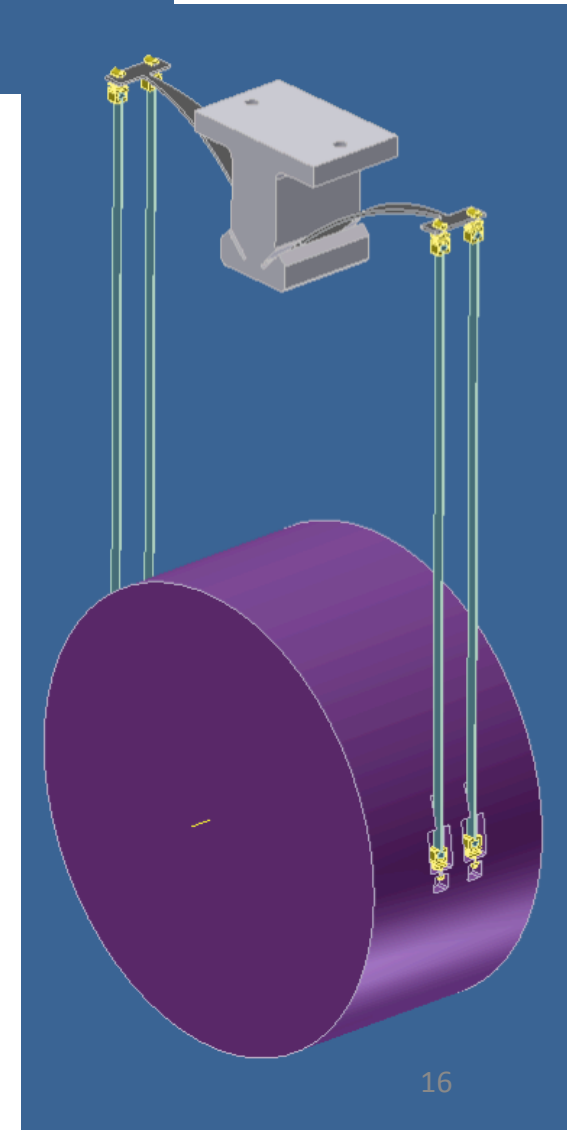


Springs

Key features:



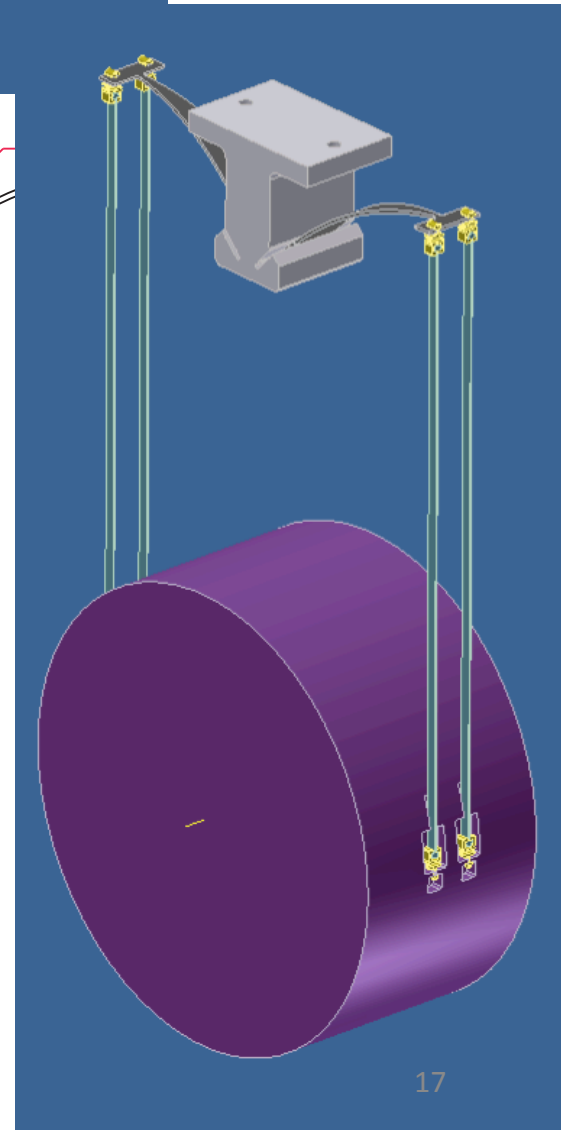
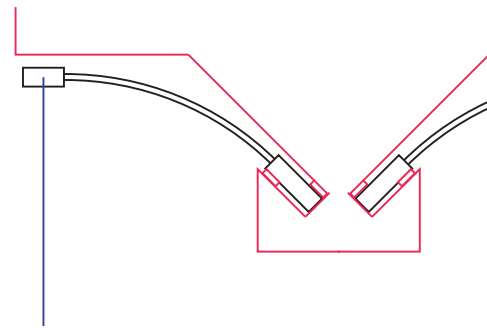
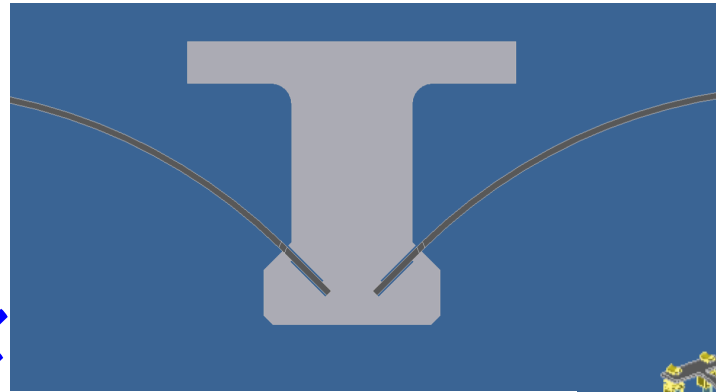
- Silicon springs
- 0.15 GPa break point
- Sufficient to equalize stress and shift bounce mode outside bucket
- Higher stress necessary to mitigate vertical thermal noise



Springs

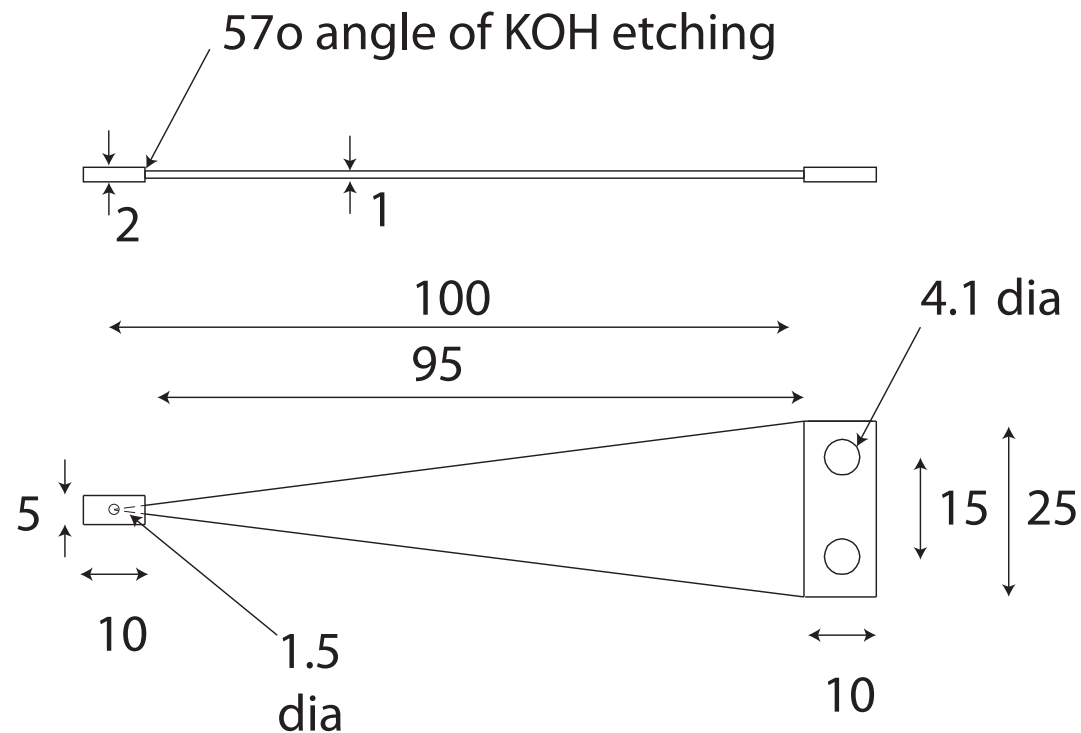
Key features:

- How much stress allowable?
- In etched MEMS 1.4 GPa OK
- Defects etched away
- Allowable surface stress may be > 1 GPa
- To be confirmed for this geometry



NIKHEF test

- Produce a number of samples



- Measure bending breaking point

Jena-Glasgow test



- Pull ribbons with different surface treatments to determine
-
- **longitudinal stress breaking point**

Why Gallium

- **Indium** proved extremely effective to eliminate friction noise in compression joints (Vladimir Braginsky)
 - How it works? it impedes slippage between hard surfaces
- Problems:
- **Melts at 160°C**
- Requires heating of mirror at **relatively high temperature** for assembly and disassembly

Indium vs. Gallium

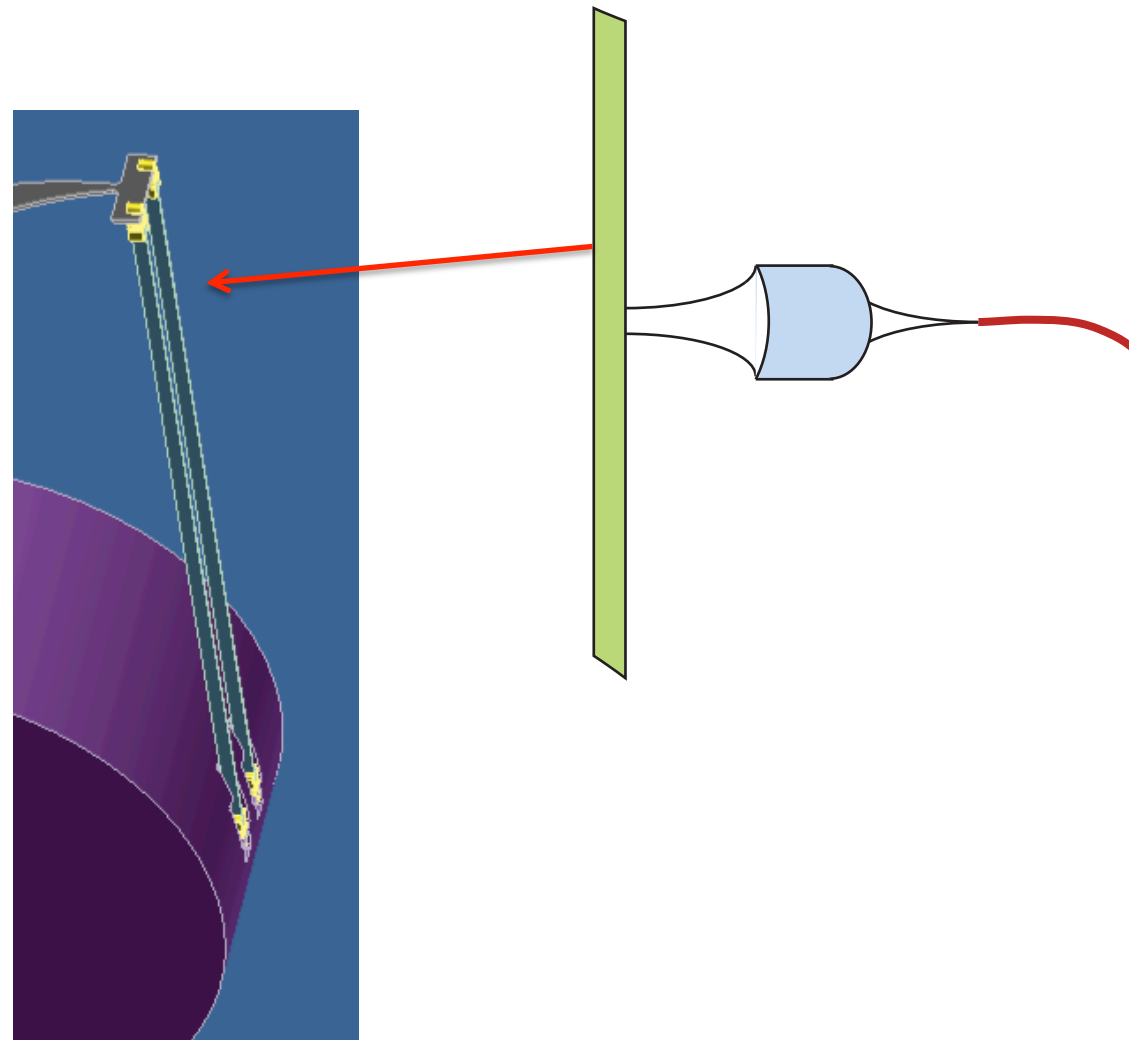
Property	Unit	Indium	Gallium	score
Solid density (near r.t.)	$\text{g}\cdot\text{cm}^{-3}$	7.31	5.91	
Liquid density @ m.p.	$\text{g}\cdot\text{cm}^{-3}$	7.02	6.095	
Expansion at melting		1.041	0.9696	G
Melting point	$^{\circ}\text{K}$	429.7485	302.9146	G
Melting point	$^{\circ}\text{C}$	156.60	29.77	G
Wetting silicates		Yes	Yes	X
Boiling point	K	2345	2477	G
Vapor pressure	Pa	1 @ 1196 $^{\circ}\text{K}$	1 @ 1310 $^{\circ}\text{K}$	G
Vapor pressure	Pa	10@1325 $^{\circ}\text{K}$	10@1448 $^{\circ}\text{K}$	G
Elec. resistivity (20 $^{\circ}\text{C}$)	$\text{n}\Omega\cdot\text{m}$	83.7	270	
Thermal conductivity	$\text{W}\cdot\text{m}^{-1}\cdot\text{K}^{-1}$	81.8	40.6	I
Therm. expansion (25 $^{\circ}\text{C}$)	$\mu\text{m}\cdot\text{m}^{-1}\cdot\text{K}^{-1}$	23.1	18.0	G
Young's modulus	GPa	11	9.8	X
Poisson ratio			0.47	
Brinell hardness	MPa	8.83	60	G
Atomic radius	pm	167	135	
Magnetic ordering		diamagnetic	diamagnetic	X

< 1

Violin mode mitigation

- Fiber-fed
Red-shifted
Fabry-Perot
- Can cool
violin modes and
bounce modes
to mK level

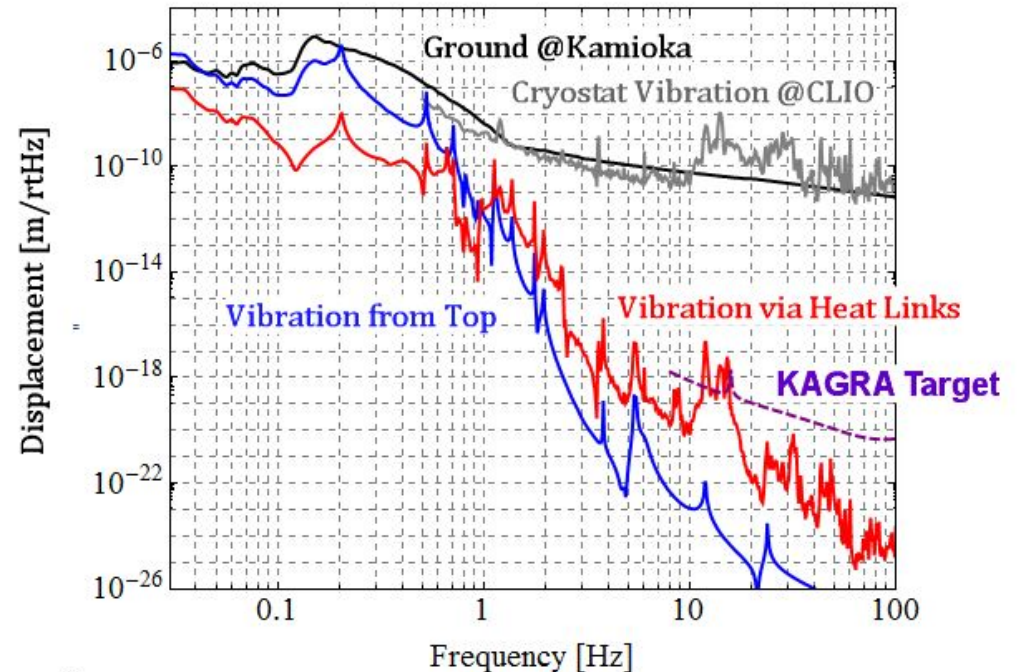
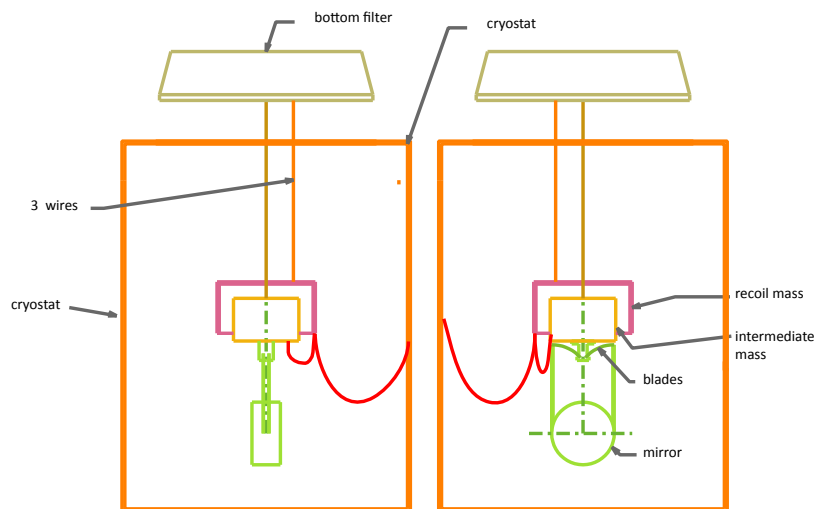
(Can we use the same idea for
Parametric instabilities ?)



Heat link limitations

- Mechanical noise re-injection with two step heat link isolation

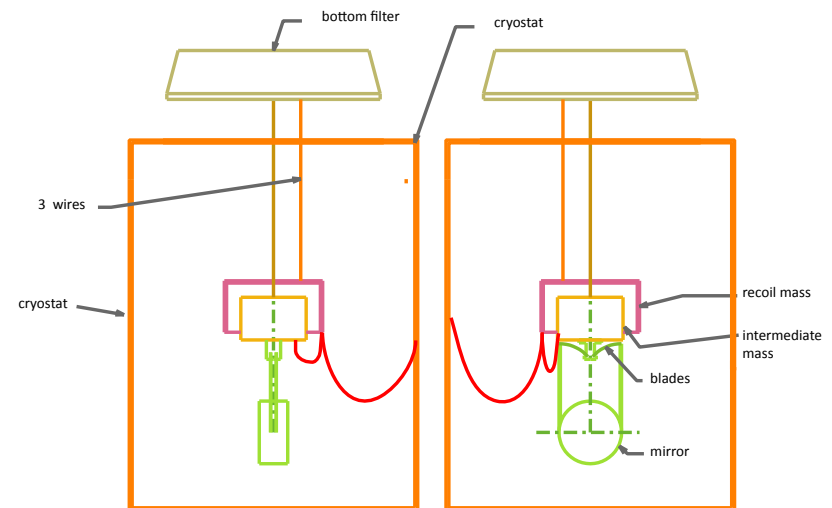
- **Insufficient !**



More Heat link limitations

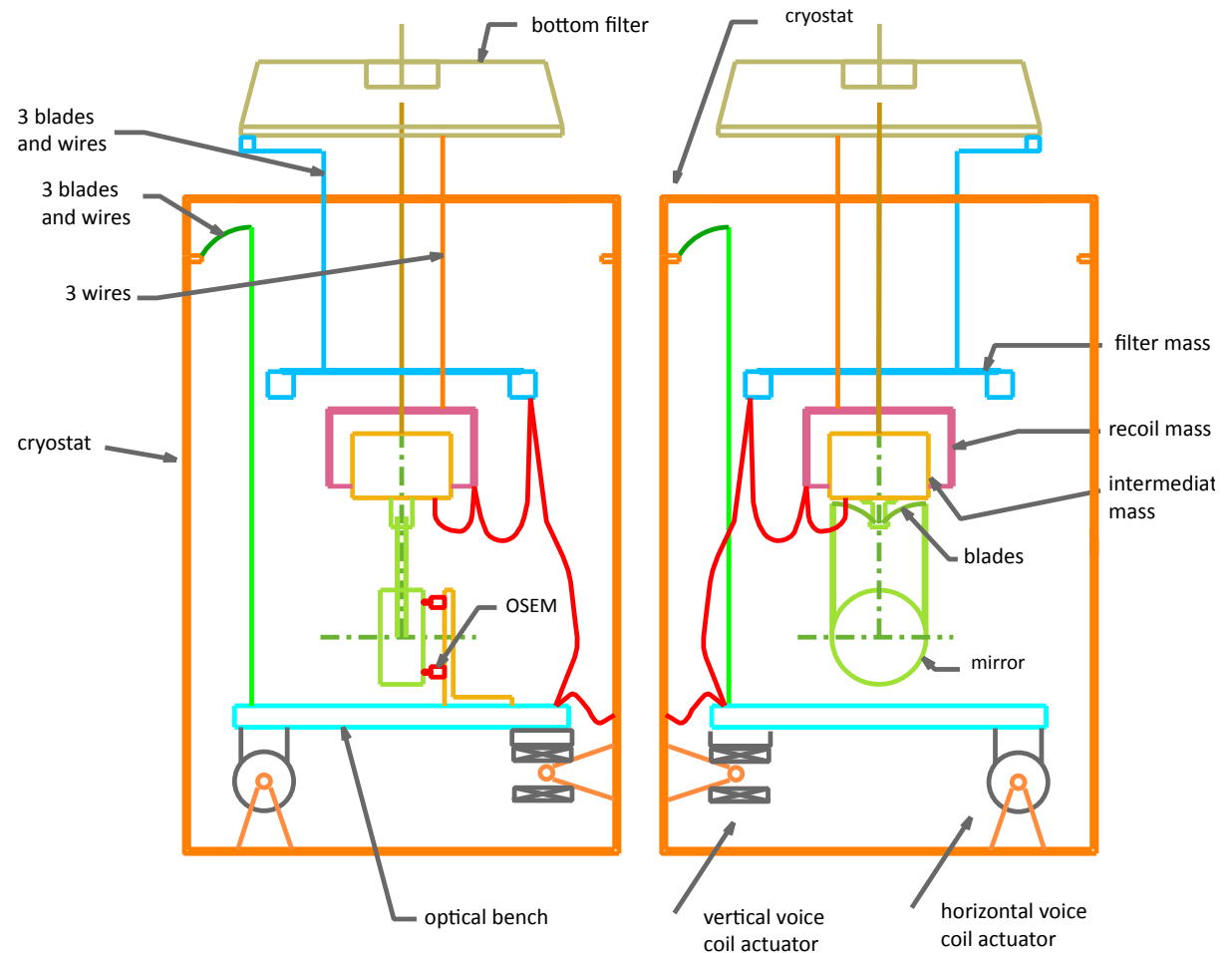


- The heat links are soft above 10 Hz
- At 100 mHz they are 10^4 x stiffer !!!
- Microseismic peak noise reinjected into mirror actuators is a serious controls problem !
- Need a solution !



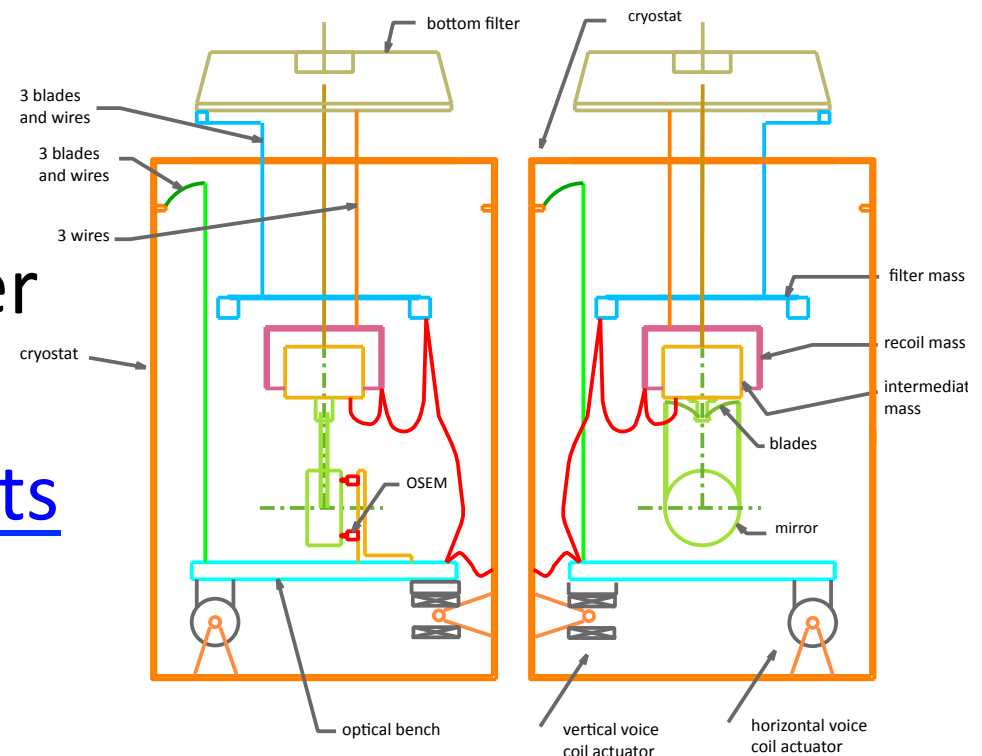
Geometry under study

- Suspended actuation platform
- Four step mechanical noise filtering
- Actuation platform slaved to mirror



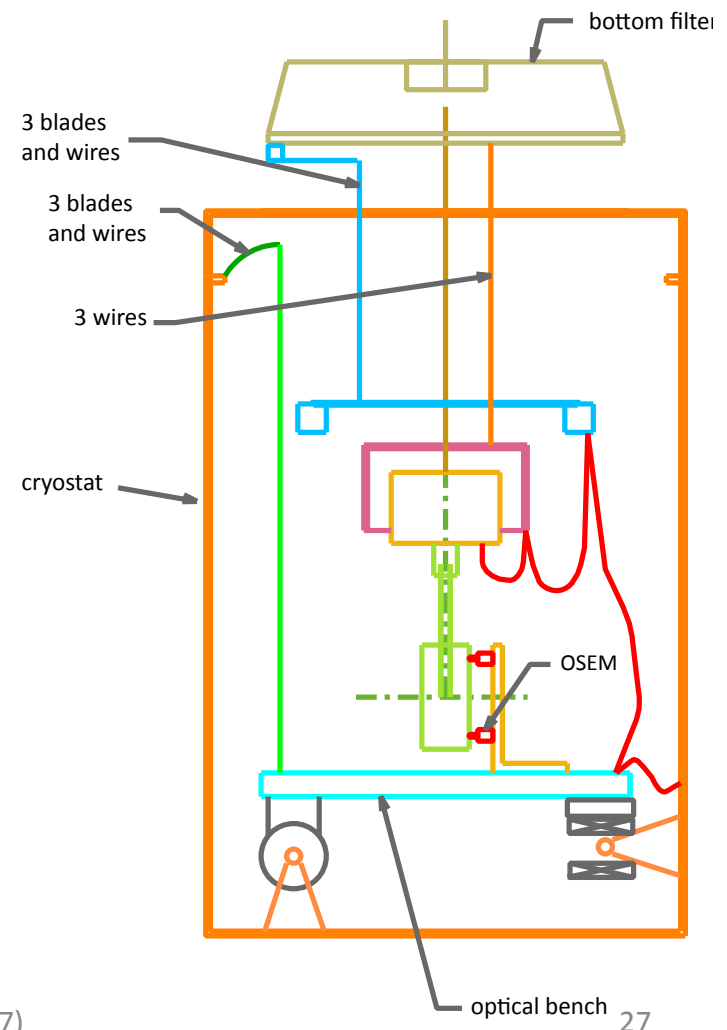
Filtering the heat pump noise

- The heat links are subjected to 4 filtering steps (2 extra)
- Both seismic and chiller noise are filtered way below the requirements in KAGRA's sensitivity band (> 10 Hz)



External lock acquisition controls

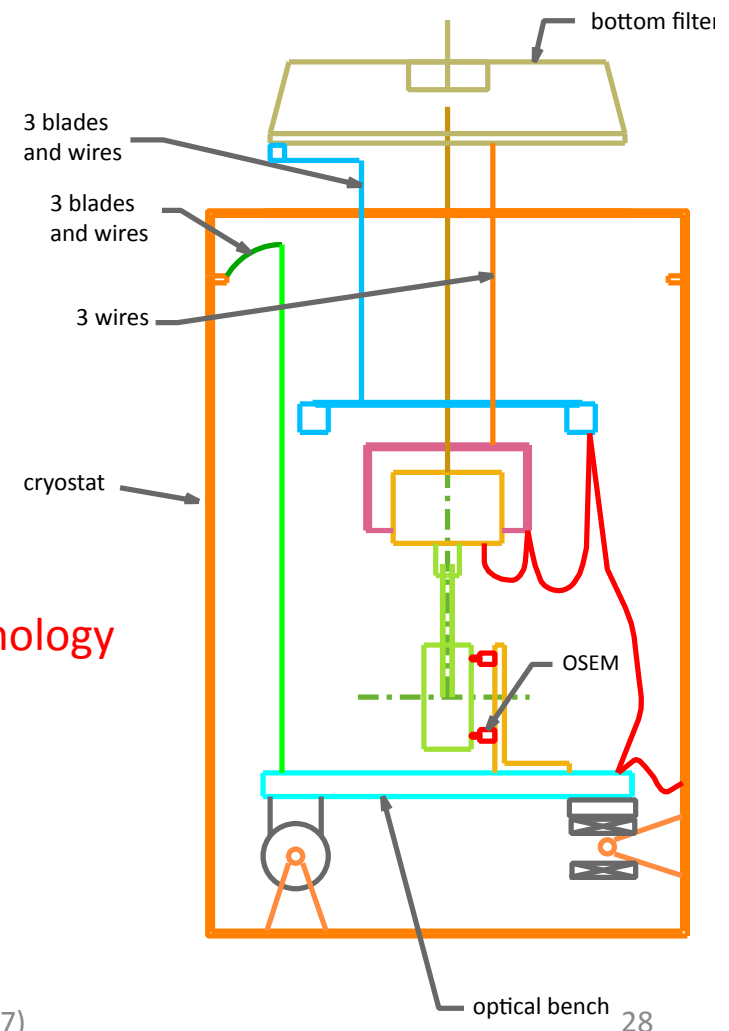
- Use Initial-LIGO-like controls for lock acquisition but from a suspended platform
- In this phase the optical bench actuators are used for viscous damping



In-lock controls

- Use Virgo-like marionetta controls during operation
- The mirror OSEM actuators are disconnected
- The OSEM sensors are used to slave the optical bench to the mirror
- The effects of microseismic noise on controls are neutralized

Borrowing AEI technology



Conclusions

- KAGRA was said to be : (with some reason)
Mission Impossible!
- Now it is just “difficult”, but feasible!
- KAGRA will be a great 2nd-1/2 generation GW Observatory
- It will also serve as the test-bed for all technology needed for the low frequency interferometer in the ET xylophone and for all 3rd generation observatories