Results from TOBAs

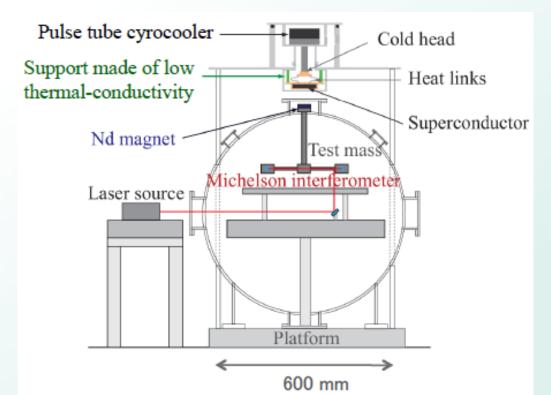
Cross correlation analysis to search for a Stochastic Gravitational Wave Background

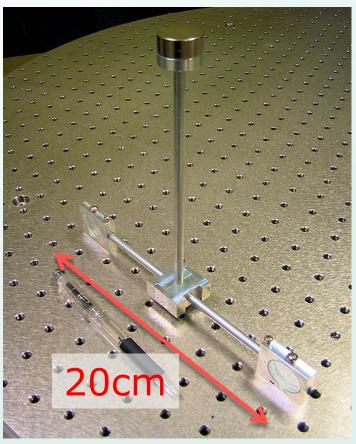
University of Tokyo Ayaka Shoda

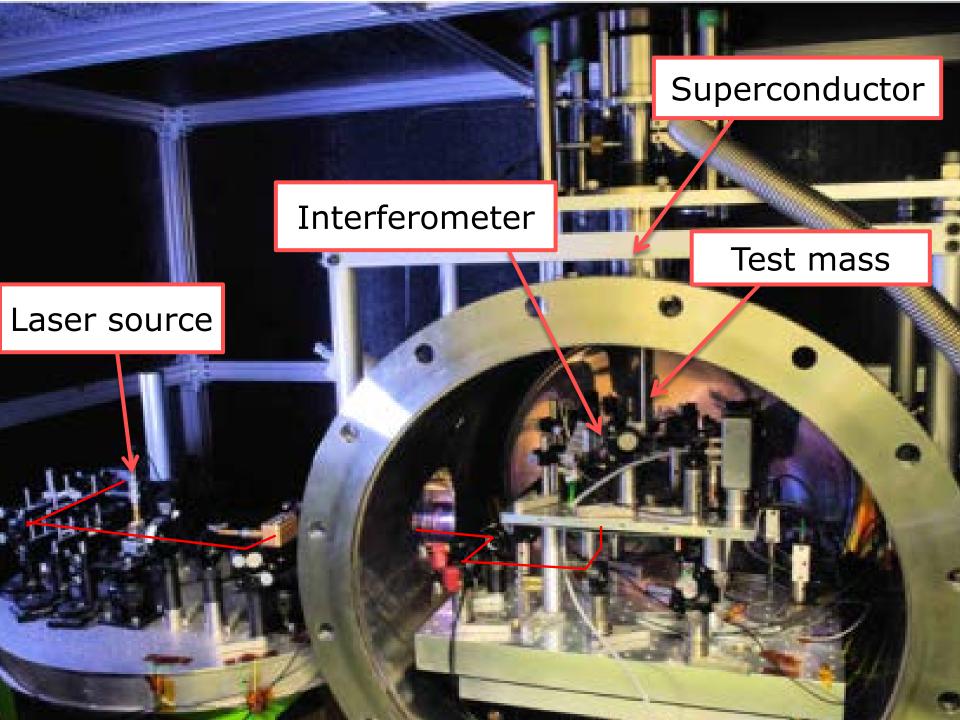
M. Ando, K. Okada, K. Ishidoshiro, W. Kokuyama, Y. Aso, K. Tsubono

Prototype TOBA

- > 20-cm small torsion bar
- Suspended by the flux pinning effect of the superconductor
- > Rotation monitor:
 - laser Michelson interferometer
- > Actuator: coil-magnet actuator

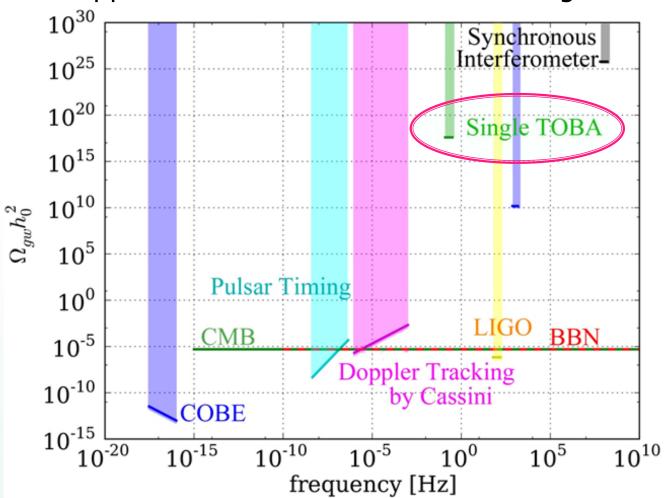






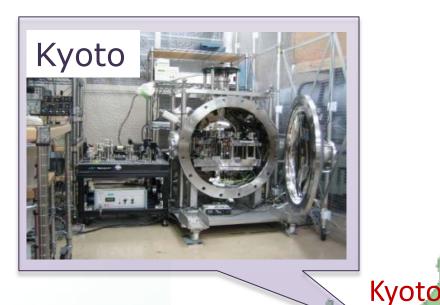
Previous Result





For the detection of a stochastic gravitational-wave background, simultaneous observation is necessary.

Simultaneous Observation



Tokyo

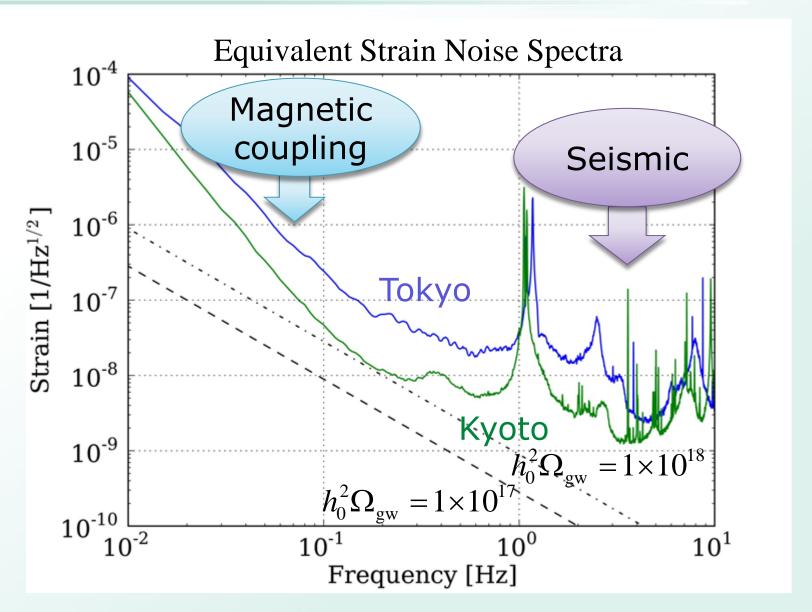


~370km

DATE: 21:30 – 7:30, Oct. 29, 2011

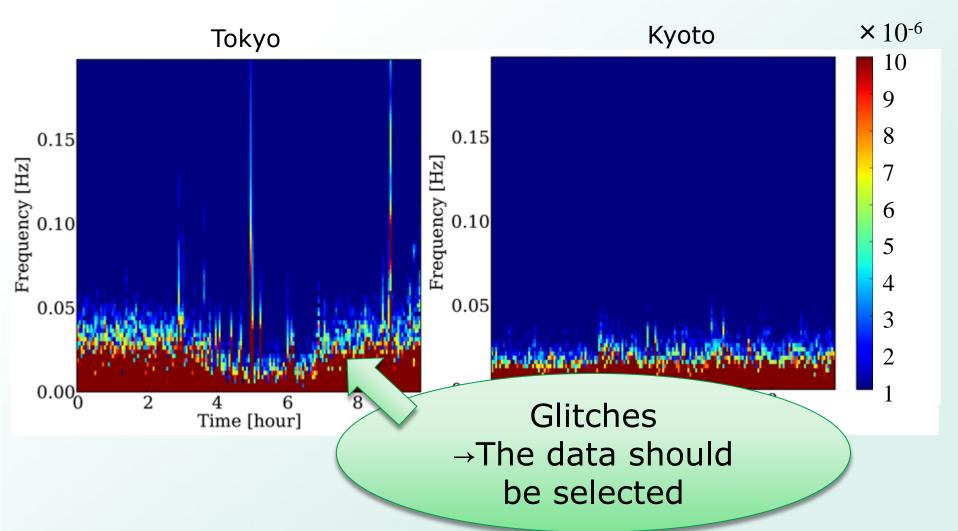
Sampling frequency: 500 Hz, the direction of the test mass: north-south

Data Quality



Data Quality

Spectrogram



Cross Correlation Analysis

Concept

difficult to predict the waveform of a stochastic GW background

Search the coherent signal on the data of the two detectors.

Correlation Value=
$$\int_{f_{\min}}^{f_{\max}} df \, \tilde{s}_1^*(f) \tilde{Q}(f) \tilde{s}_2(f)$$

 $\widetilde{S}_i(f)$: The signal of *i*-th detector

 $\widetilde{Q}(f)$: The optimal filter (Weighting function)

Cross Correlation Analysis

Data selection



 Delete 10% of the segments whose noise level is worst

Calculate the cross correlation value

 Choose the analyzed frequency band as 0.035 - 0.84 Hz

Detection test

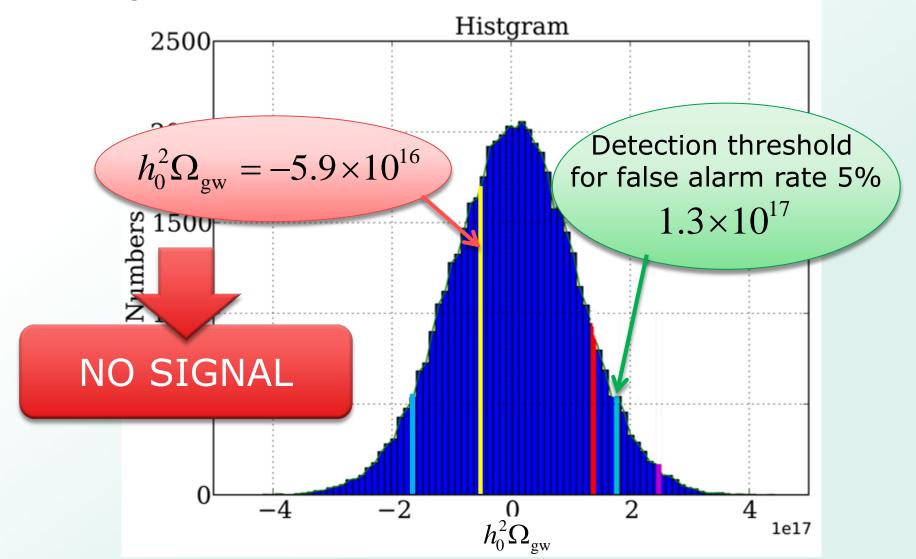
If not detected

Set the upper limit

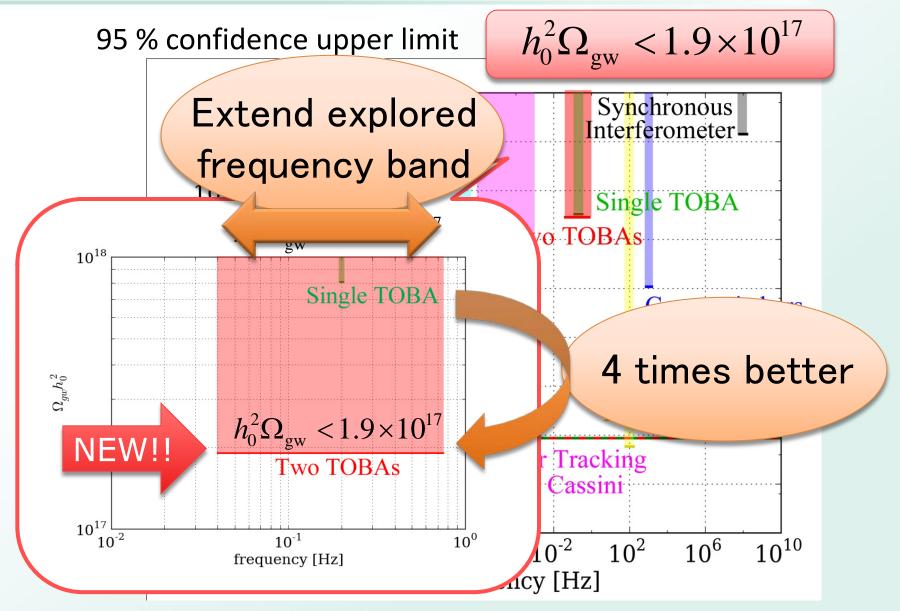
 Inject mock signals into the real data and calculate the detection efficiency

Result





Result -upper limit

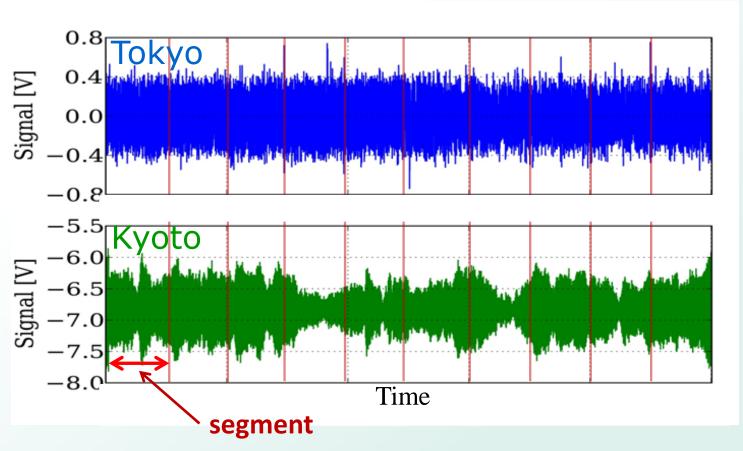


Summary

- Established the pipeline of the cross correlation analysis with TOBAs
- The stochastic GW background signal is not detected.
- Update the upper limit on a stochastic GW background at $0.035\sim0.840~{\rm Hz}$: $h_0^2\Omega_{\rm gw}<1.9\times10^{17}$

Backup slides

Data Selection



- Divide time series data into several segments
- Remove the segments in which RMS is big
- Calculate cross correlation with the survived segments

Cross Correlation Value

$$Y \approx \int_{f_{\min}}^{f_{\max}} df \, s_1^*(f) s_2(f) Q(f)$$

Optimal Filter: a filter which maximizes the signal-to-noise ratio

$$Q(f) = N \frac{\gamma(f)}{f^3 P_1(f) P_2(f)}$$

 $P_i(f)$: PSD of i-th detector

Overlap reduction function

: a function which represents the difference of response to the GWs between two detectors



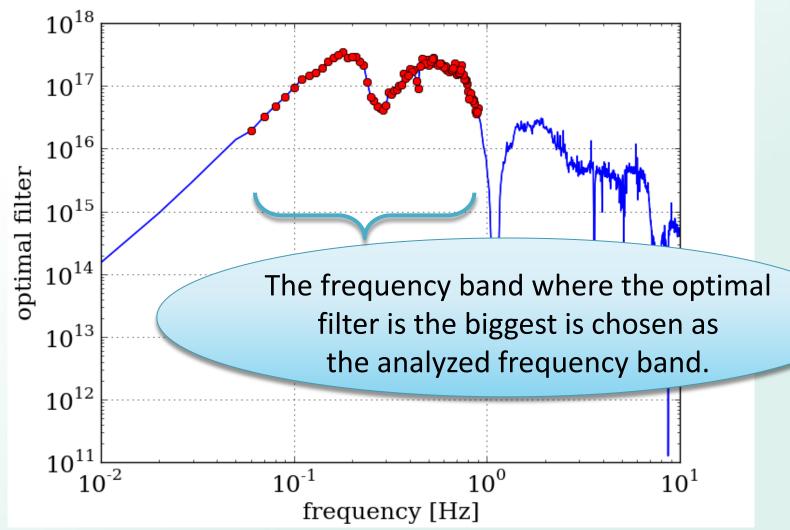
In the case of TOBAs, same as the interferometer's one

In this case, $\gamma(f) \approx 1$

Optimal filter

Optimal filter =

big when the sensitivity to a stochastic GW background is good



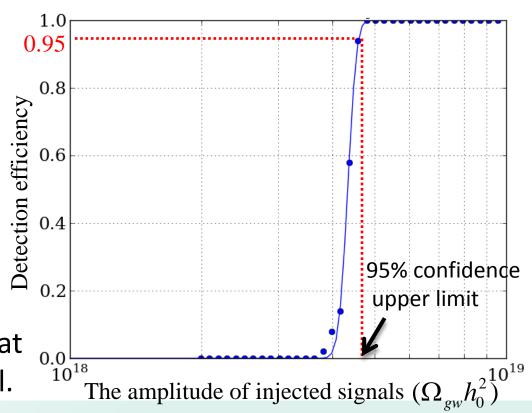
Upper Limit

How big a stochastic GW background can we detect if it would come to this data set?

1. Make a mock signal of a stochastic GW background

- 2. Inject the signal into the observational data
- Perform same analysis as explained above

Repeat 1-3 to compute the rate at which we detect the mock signal.





Parameter Tuning

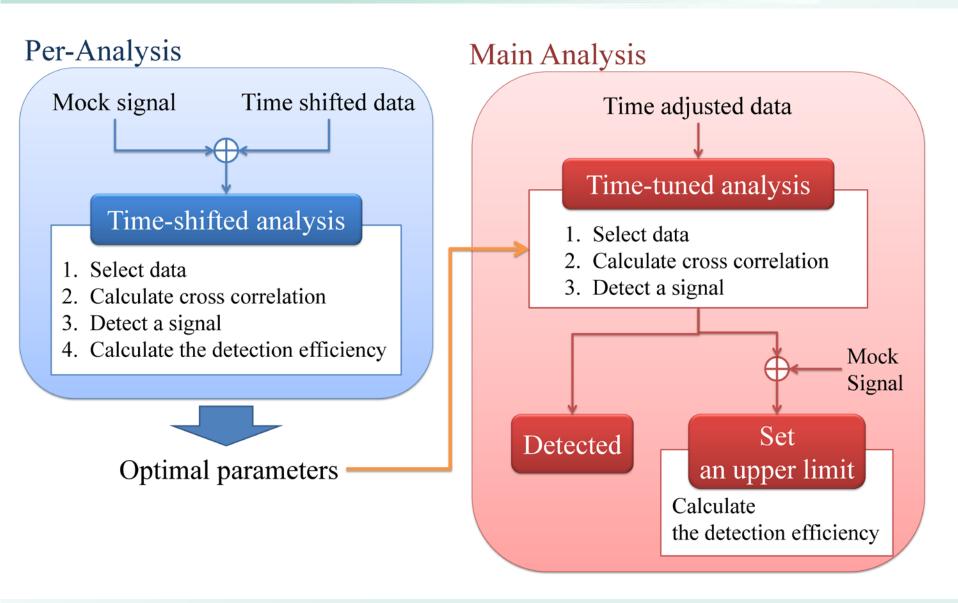
There are some parameters whose optimal values are depend on the data quality

- \triangleright The length of the segments \rightarrow 200 sec
- ➤ The amount of the segments removed by data selection
 →10 %
- The bandwidth of the analyzed frequency band $\rightarrow 0.8 \text{ Hz}$

Determined by the time shifted data.

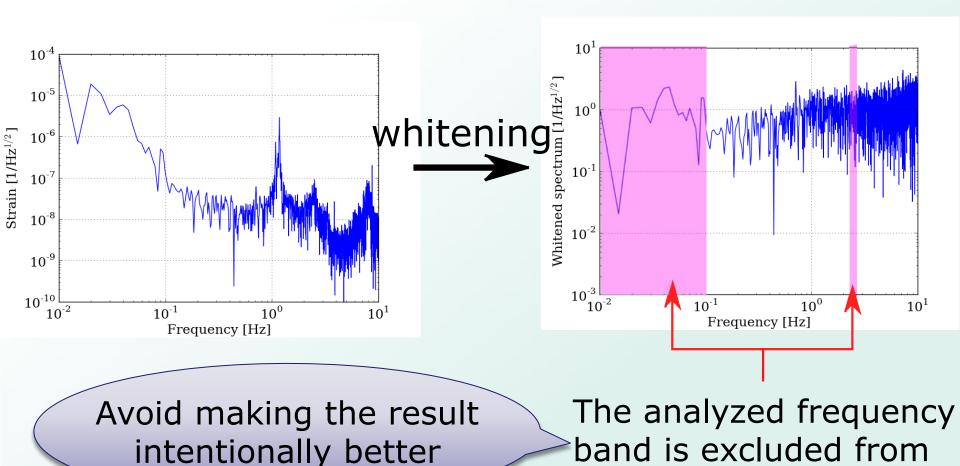
The values which make the upper limit calculated with time shifted data best is used.

Summary of Analysis



Data selection

The indicator of the noise level = Whitened RMS



RMS calculation

Cross correlation anlysis

$$s(t) = h(t) + n(t)$$

$$signal \quad GW \quad noise$$

$$signal \quad = \int_{-T/2}^{T/2} s_1(t) s_2(t) Q(t) dt$$

$$= \int_{-T/2}^{T/2} \left(h_1(t) + n_1(t)\right) \left(h_2(t) + n_2(t)\right) Q(t) dt$$

$$= \int_{-T/2}^{T/2} h_1(t) h_2(t) Q(t) dt$$
Noise is reduced
$$= \int_{-T/2}^{T/2} h_1(t) h_2(t) Q(t) dt$$

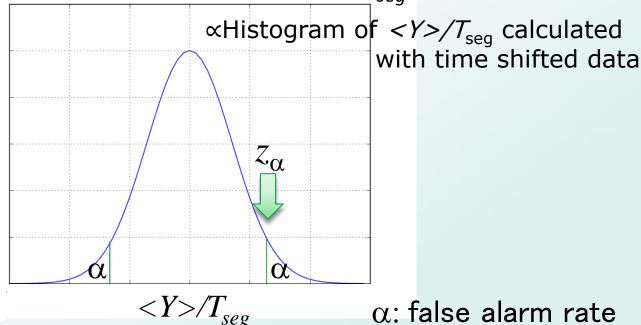
Fourier transformation

Cross correlation value
$$= \int_{f_{\min}}^{f_{\max}} df \, \tilde{s}_1^*(f) \tilde{Q}(f) \tilde{s}_2(f)$$

Detection Criteria

By the Neuman-Peason criterion,

Probability distribution of $\langle Y \rangle / T_{seg}$



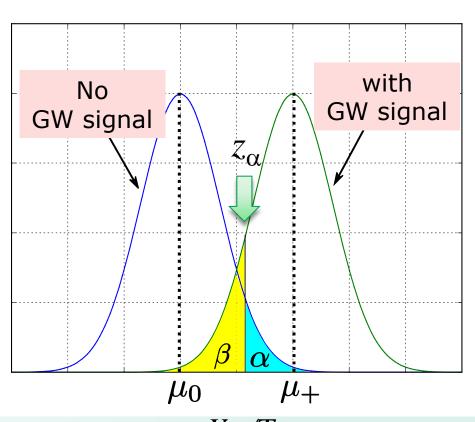
Note: we do not know the sign of the two signal.

$$\langle Y
angle / T_{seg} \geq |z_{lpha}|$$
 Signal is present $\langle Y
angle / T_{seg} < |z_{lpha}|$ Signal is absent

Signal detection

How to decide \mathcal{Z}_{α} :

- •Calculate $\langle Y \rangle / T_{\rm seg}$ with diversely time shifted data •Histogram of calculated $\langle Y \rangle / T_{\rm seg}$ when the signal is absent.



 α : false alarm rate

β: false dismissal ra

Future plan

