

Data Acquisition, Diagnostics & Controls (DAQ)

Technical Status

Annual NSF Review of Advanced LIGO Project

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DAQ Functions

- Provide a global timing and clock distribution system to synchronize all realtime control and data acquisition.
- Provide a common Control and Data System (CDS) infrastructure design and standards for use in all aLIGO subsystem controls.
 - » Real-time applications development tools and code library
 - Including "hard" real-time operating system, I/O drivers and inter-process communications.
 - » Computer and I/O standards
- Provide all software necessary to synchronously acquire and archive data.
- Provide all computing and networking hardware as necessary to collect data from the various subsystems, format the data and write the data to disk.
- Provide a standard set of diagnostic tools for use in all control subsystems, including ability to:
 - » Inject arbitrary waveforms into realtime control systems
 - » Set and acquire data from defined testpoints on demand
 - » Distribute both diagnostic data and acquired data channel to operator stations
 - » Provide data visualization and analysis tools in support of operations and commissioning.



DAQ Functions (Continued)

- Provide computers, I/O hardware and software for the acquisition of Physical Environment Monitoring (PEM) data.
 - » New interfaces for existing PEM sensors
- Computers and infrastructure software for the Diagnostic Monitoring Tools (DMT)
 - » Specific application software provided by LSC members
- Control room computers and associated networking, including a common set of operations support software.
- Provide off-line test and development systems for both sites



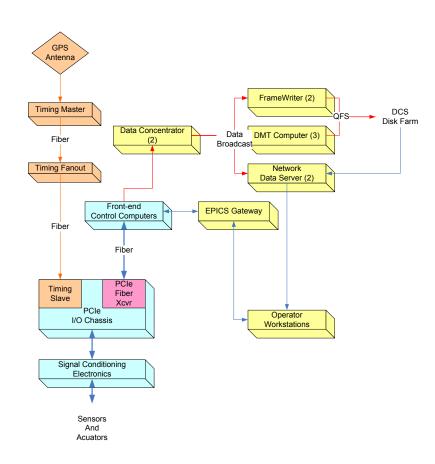
DAQ System Data Acquisition Requirements

- Provide a hardware design and software infrastructure to support real-time servo control applications
 - » Deterministic to within a few usec.
 - » High performance to support servo loop rates from 2048Hz to 65536Hz
 - » Built-in diagnostic and data acquisition features
- Acquire and record up to 15MBytes/sec continuously from each interferometer.
 - "Fast' data channels at rates from 256 to 32768 samples/sec (Up to 3000/IFO)
 - "Slow" data channels at up to 16 samples/sec, with up to 70K channels per interferometer
- Provide capabilities to acquire (but not record) an additional 15MB/sec of diagnostic data.
- Write data in LSC/VIRGO standard Frame format to disk system provided by Data and Computing System (DCS).
 - » Provide local disk to allow up to two weeks of data storage
- Provide an internal data distribution system to communicate diagnostic and acquired data to operator stations and Diagnostic Monitoring Tool (DMT) computers.



DAQ System Design Overview

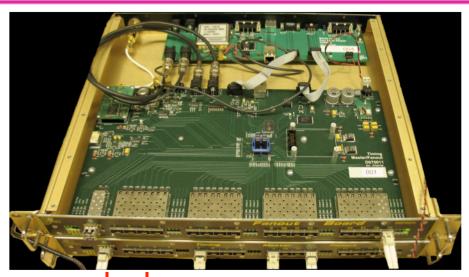
- Timing system provides clocks to PCI Express (PCIe) modules in I/O chassis.
- PCIe modules interface to control computer via PCIe fiber link.
- Control computer acquires data and transmits to DAQ data concentrator (DC) via network.
- DC assembles data from all controllers and broadcasts full data blocks every 1/16 second.
- FrameWriter computers format data and write to disk (32sec. data frame)
- Network Data Server (NDS)
 provides data on demand either live
 or from disk.





Timing Distribution System (TDS)

 Contracted to Columbia Univ. for manufacture and test after a joint development effort. Design described in the journal "Classical and Quantum Gravity" under Imre Bartos et al., 2010 Class. Quantum Grav. Vol. 27, No. 8, 084025





IRIG-B Timing Fanout Provides accurate time information to computers.



Timing Slave provides accurate clocks At 65536Hz to ADC/DAC modules.



TDS IRIG-B Distribution Unit



Sunc Source

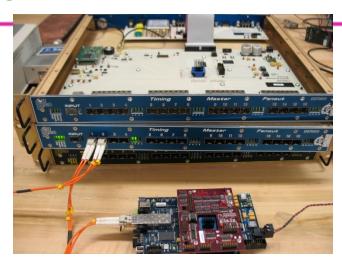
DT/IRIG

- IRIG-B system used to provide time information, in GPS seconds, to DAQ and control computers.
 - » Includes standard timing slave card to get time information from TDS.
 - » Outputs IRIG-B standard time code
 - DC Level Shift format
 - » Commercial IRIG-B Receiver modules in computers for accurately setting time in GPS seconds.
 - » Time accuracy to better +/- 1 μsec.
 - » Second source of system time verification, along with duotone signal acquired from timing slave in I/O chassis.



Timing Distribution System Status

- Major components for all IFO have been delivered
 - L1/H2 systems installed.
 - H1 installation in progress.
- Remaining deliveries should be complete by June, 2012:
 - Timing comparators in test.
 - 4 additional IRIG-B fanout units in production.



Slave-DuoTone pair being tested at Columbia

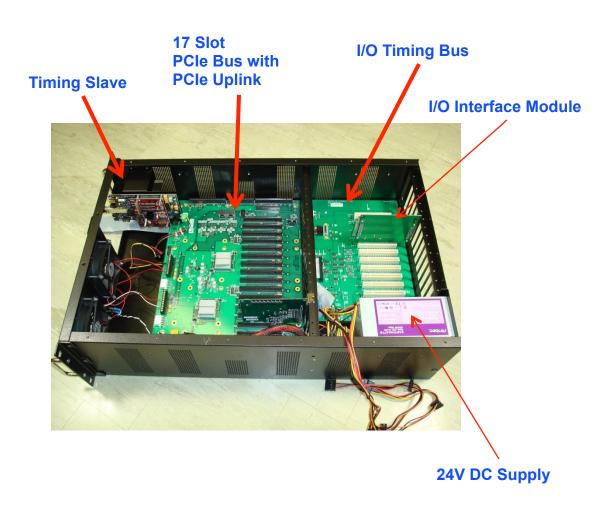


Master front boards under production



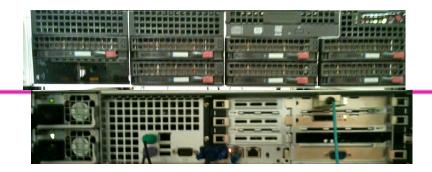
CDS Standard PCI Express I/O Chassis

- Commercial PCle expansion motherboards.
- Custom I/O timing and interface backplane.
- I/O interface modules provide timing and interface between PCIe module connectors and field cabling.
- Two fiber optic links.
 - To timing distribution system via timing slave module.
 - To computer, via fiber optic PCle link.



LIGO

CDS Standard Computers



- Supermicro X8DTU-F Motherboards
 - » Fulfills BIOS PCI-e card mapping and real-time stability requirements
- Single Xeon X5680 processor with six cores at 3.33GHz
- Up to 4 full height + 1 half-height PCle slots
- Two GigE Ethernet ports
 - » Separate EPICS/DAQ networks
- No disk drives installed in computers used for real-time control
 - » Operated as diskless-node from central boot server
- Operating Systems
 - » Gentoo with Linux kernel 2.16.34, plus LIGO RT patch
 - » Ubuntu Linux for CDS servers and other non-real-time computers

LIGO

Networking



- Ethernet backbones for most applications
 - » GigE switches with fiber uplinks from end stations
 - » GigE switches with 10G uplink options for corner station
 - 10G uplink for DAQ and video connections
 - » 10G switches for DAQ Broadcasts
- Low latency networks for real-time data communications.
 - » Initial LIGO type reflected memory (for long runs to end stations)
 - » PCIe network, employing reflected memory software (corner station computers)



PCI Express (PCIe) Real-time Control Network

- Low Latency (1.25usec)
- High speed (10Gbit/sec)
- Cable or Fiber connections
 - CX-4 cable to 3 meters
 - Multi-core fiber to 100 meters
- Stackable 10 port Switches
- Reflected Memory Mode
 - Data broadcast to same memory location on each computer on the network.





Corner to End Station Real-time Control Network

- Loop topology
- Low Latency (700nsec/node)
- High speed (2Gbit/sec)
- Fiber connections
 - Up to 10km
- Bypass Switch provided at each location
- Reflected Memory
 - Data broadcast to same memory location on each computer on the network.





Networking – Progress

- All Ethernet switches have been procured and delivered for all three interferometers.
 - » All network switches have been configured for L1 and H2.
 - » H1 switches are being installed/configured.
- All real-time networking equipment procured and delivered.
 - » Systems installed and running at both sites.

LIGO Physical Environment Monitoring Infrastructure

- For aLIGO, PEM system will provide control as well as DAQ
 - » On-line Adaptive Filtering and feed-forward control.
- One computer + 1 I/O chassis at each station and at corner station.
- Re-use existing PEM sensors
- Up to 128 channels of ADC + 8 channels of DAC
 - » I/O connections via AA/AI chassis with BNC connections.
- Progress
 - » Computers, I/O chassis and ADC/DAC modules have all been procured and delivered.
 - » 9 of the 12 AA Chassis have been built and tested.



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G1200370



DAQ Computing / Storage Equipment

(All Delivered and Installed)

- Data Concentrator (DC) (2)
 - » Collects data from all real-time control computers and broadcasts to 10GigE network.
 - » One unit on-line, second hot backup
- FrameWriter (2)
 - » Receive data from DC
 - » Format data into LVC standard Frame format
 - » Write data to disk
 - Local
 - Data Analysis group disk farm
- Network Data Server (NDS) (2)
 - » Provides real-time or stored data on request to various control room software tools
 - NDS clients also developed for Perl, Python and Matlab
- Two computers running Solaris operating system to connect disk systems via QFS.
- 24 TByte Local Disk





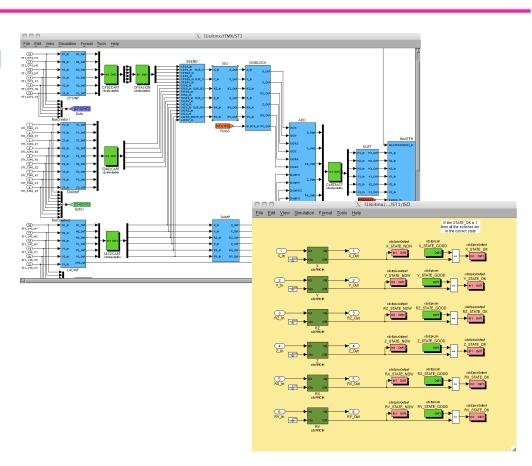
Control Room and Global Diagnostic Systems

- iMac computers w/additional monitor chosen as the standard configuration for operator stations.
 - » Ubuntu Linux Operating System
- Two, dual CPU computers, similar to real-time control computers, in place for Global Diagnostic Monitoring Tool (DMT) applications.
 - » 24TByte disk drive provided for storage of DMT information.
- All equipment is in-house and undergoing installation/test.



Software Real-time Application Support

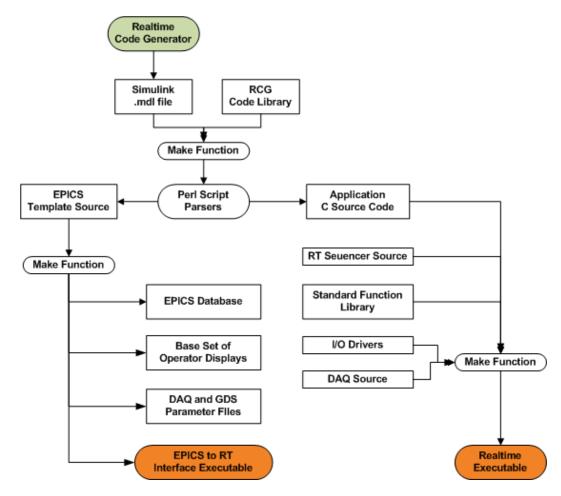
- Continued refinement of graphical tool for real-time code generation ("RCG").
- Allows control application development and documentation without having to know a programming language.
- Allows programming staff to concentrate on development and test of common code modules.





Software Real-time Application Build Process

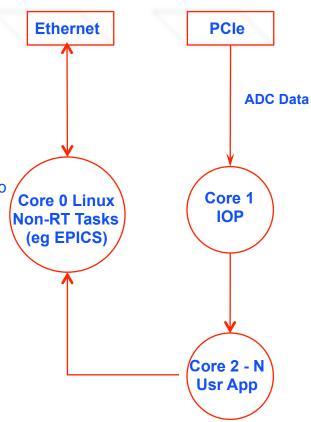
- Build and save RCG model.
- make 'modelName'
 - Perl scripts parse the model file to determine signal connections and code flow
 - Perl scripts generate EPICS and real-time source code.
 - Compiler is invoked to link common code libraries and produce real-time and EPICS executable software.
- make install
 - Moves executables to target directories for load onto realtime computers.
 - Channel descriptor files generated for use by DAQ and GDS
 - Basic set of operator displays generated.



LIGO

Real-time Core and Patch

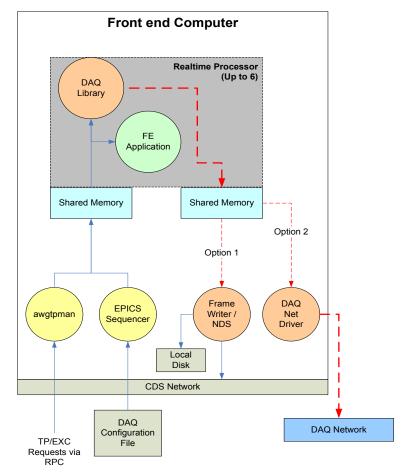
- aLIGO Real-Time (RT) code not "traditional"
 - » No pre-emptive operating system scheduler
 - » No interrupts, semaphores, priorities, ensuing context switching, etc.
- Each RT app locked to its own CPU core
 - » Using custom patch to Linux kernel "play dead" routine
 - Notifies Linux scheduler that CPU is going down and unavailable for interrupts/task assignment.
 - Inserts RT app code instead of Linux idle routine.
 - Removal of RT app brings the CPU "back to life" and reconnects to Linux as a useable resource.
 - » RT code runs in continuous loop
 - Triggered by arrival of ADC data in local memory (polling or MONITOR/MWAIT CPU instructions)
 - ADC modules set up to automatically transfer data to computer memory on clock trigger
 - Never switched out ie always resident on stack, in cache, memory
- For each RT computer, there is a special case model called an Input/Output Processor (IOP)
 - » Controls startup timing and synchronization.
 - » Maps and initializes all of the PCIe I/O interfaces
 - » Triggers and monitors user applications.
 - » Always running, allowing user apps to come and go, as necessary





DAQ System Front-End Software Design

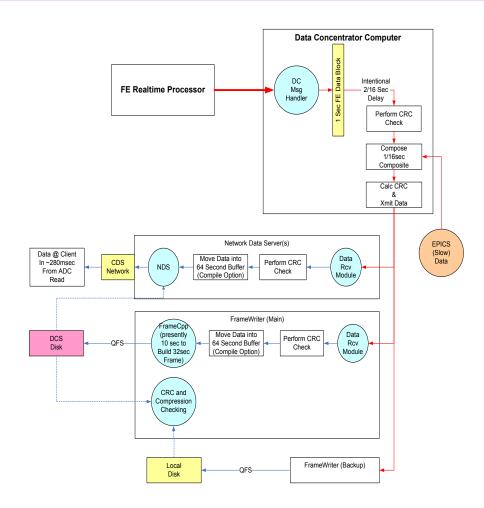
- A common DAQ library is compiled into each FE application.
- Acquires data at user defined rates and transmits data as 1/16sec data blocks:
 - » For archive, as described in a DAQ channel configuration file.
 - » Test point and excitation channel data on demand
 - As requested via the arbitrary waveform generator/ test point manager (awgtpman)
 - » Supports aggregate (DAQ+TP) data rate of 2MB/sec per FE processor
 - » CRC checksums and timestamps sent with all data blocks
- Supports various configurations
 - » (1) Data to FrameWriter/NDS software on same computer via shared memory
 - Allows a complete stand-alone system to support various subsystem test stands
 - » (2) Data to shared memory, with separate network software
 - Supports multiple FE applications on same computer
 - Relieves RT front end code from network error handling and other possible delays





DAQ System Backend Software Design

- Data Concentrator
 - » Collects 'fast' data from all FE computers via dedicated network
 - » Collects 'slow' (EPICS) data via CDS network
 - » Broadcasts combined data to upstream computers as 1/16 sec data blocks on to 10Gb Ethernet
- FrameWriter
 - » Format data into standard LIGO Frame using FrameCpp library, with data compression.
 - » Write data, via QFS, to DCS disk farm (32 second data file)
- Network Data Server (NDS)
 - » Provides live and archived data feeds, on request, to CDS operator stations





Software Status

- "Final" code version tested and released.
 - » Any new code change requests / bug fixes are to be part of commissioning and operations activities.
- "Line by Line" code review in progress by team not involved in the code development.
 - » Additional outside review planned.
- In process of completing/updating documentation necessary to meet system acceptance requirements.



NSF Review 2011 Concerns

Concern:

» Cyber-security, particularly as it pertains to remote access to LIGO control/DAQ systems.

Action Taken:

- » Continuing to work with LIGO cyber-security staff on issues / solutions.
 - Presently have a two tier authentication system in place, with access provided to a limited set of staff.
 - In process of implementing and testing "one time use" password system.
 - Working to develop a method for the site operator to provide final approval for remote logins.



DAQ System Summary

- Software Development
 - » Complete soon, pending final reviews.
- Equipment Procurement
 - » Complete
- Installation
 - » L1/H2 systems complete and operational.
 - » H1 system installed; cabling and network setup in progress. Anticipate system will be operational by end of April 2012.