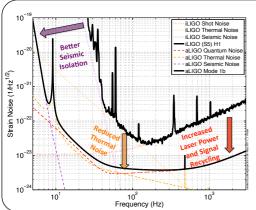


## **Advanced LIGO:** The Rubber Hits the Road!





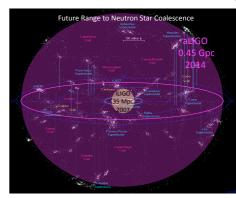
Jeffrey S. Kissel<sup>1</sup>, for the LSC <sup>1</sup>jkissel@ligo.mit.edu, Massachusetts Institute of Technology

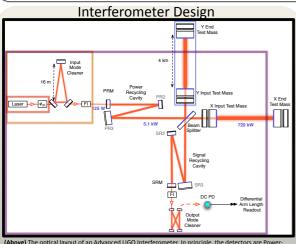


Between 2005 and 2010, the LIGO gravitational wave detectorrs collected two and a half years of data at the strain sensitivity predicted by their original design. In October of 2010, the three detectors were decommissioned and are now offline undergoing a major upgrade; the first interferometer to see "first light" in 2013, and all three by the end of 2014. The advanced detectors, collectively dubbed Advanced LIGO, will implement improvements on many opto-mechanical fronts in order to achieve the designed strain sensitivity; a factor of 10 improvement in the most sensitive frequency band and above, and by many orders of magnitude in the lower third of the detectors bandwidth. When the designed sensitivity is achieved, the astrophysical range out to which each detector would see and optimally oriented, binary neutron star system will increase from 35 Mpc to 0.45 Gpc, increasing the expected obervation rate from 0.02 to 40 per year.

(Left) A comparison of the measured strain sensitivity of the Initial LIGO detectors, compared against the design sensitivity of the Advanced LIGO detectors.

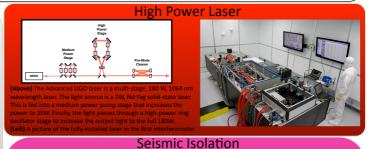
(Right) An illustration comparing the approximate volume of the local universe covered by the initial and advanced LIGO

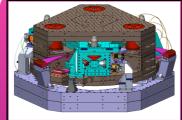




and Signal- Recycled Michelson Interferometers with Fabry-Perot Cavities for arms. The differentia change in length of the 4 km arms is the degree of freedom most sensitive to gravitational waves. (Below) A comparison the design parameters of the initial LIGO detectors with the Advanced Detectors, explaining how each change improves the design.

Property	Initial LIGO	Advanced LIGO	Improves
Num. 4 km Interferometers	2 (with 1 2km)	3	Network Sensitivity
Tunable Frequency Response?	No	Yes	Adaptabilty to Exected Sources
Test Mass Size	10 kg, Ø25x10cm	40 kg, Ø34x20cm	Susceptibility to Force Noises
Isolation Stages	6 (one active)	7 (three active)	Seismic Isolation
Laser Power	up to 10 W	up to 180W	Shot Noise
Stored Arm Cavity Power	~10 kW	~750 kW	Sensitivity
ETM Beam Spot Size (1/e² Radius)	4.5 cm	6.2 cm	Coating Thermal Noise
Differential Arm Readout Scheme	Heterodyne	Homodyne	Shot Noise

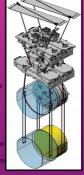






orders of magnitude at 10 Hz. To achieve

(Top) The two-stage, passive and active seismic isolation platform. Each stage is





## Schedule and Progress Full Oct, 20th 2010 <u>Interferometer</u> Full Interferometer Interferometer 2010 2011 2012 2013 2014

After spending the winter of 2010 decomissioning two of the three LIGO interferometers, installation has begun in early 2011. In order to mitigate risks and to commission critical subsystems as early as possible, the construction will follow two different paths. The detector in Livingston, LA will be the "path finder" -- its construction will follow a natural, from-the-laser-out installation and commissiong flow. The second detector in Hanford, WA will start by construct a full single arm cavity first, which will provide the first test a integrated test-mass seismic isolation systems over the long, 4 km baseline. Finally, the third interferometer in Hanford, WA will progress as the first, using the experience gained from building the first two

Fritschel, et al (2009) "Advanced LIGO Systems Design." LIGO T010075 B. P. Abbott et al (2009) Rep. Prog. Phys. **72** 076901 R Abbott et al (2002) Class. Quantum Grav. **19** 1591 N A Robertson et al (2002) Class. Quantum Grav. **19** 4043 B Willke et al (2008) Class. Quantum Grav. 25 114040