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# Data Acquisition, Diagnostics & Controls (DAQ)

## Technical Status

NSF Review of Advanced LIGO Project

held April 25 – 27, 2011

at the LIGO Livingston Observatory

**Rolf Bork, CIT**



**Project cost for DAQ -  
\$4.4M**

# DAQ Functions

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- Provide a global timing and clock distribution system to synchronize all realtime control and data acquisition.
- Provide a common Control and Data System (CDS) infrastructure design and standards for use in all aLIGO subsystem controls.
  - » Real-time applications development tools and code library
    - Including “hard” real-time operating system, I/O drivers and inter-process communications.
  - » Computer and I/O standards
- Provide all software necessary to synchronously acquire and archive data.
- Provide all computing and networking hardware as necessary to collect data from the various subsystems, format the data and write the data to disk.
- Provide a standard set of diagnostic tools for use in all control subsystems, including ability to:
  - » Inject arbitrary waveforms into realtime control systems
  - » Set and acquire data from defined testpoints on demand
  - » Distribute both diagnostic data and acquired data channel to operator stations
  - » Provide data visualization and analysis tools in support of operations and commissioning.



# DAQ Functions (Continued)

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- Provide computers, I/O hardware and software for the acquisition of Physical Environment Monitoring (PEM) data.
  - » New interfaces for existing PEM sensors
- Computers and infrastructure software for the Diagnostic Monitoring Tools (DMT)
  - » Specific application software provided by LSC members
- Control room computers and associated networking, including a common set of operations support software.
- Provide off-line test and development systems for both sites



# DAQ System

## Data Acquisition Requirements

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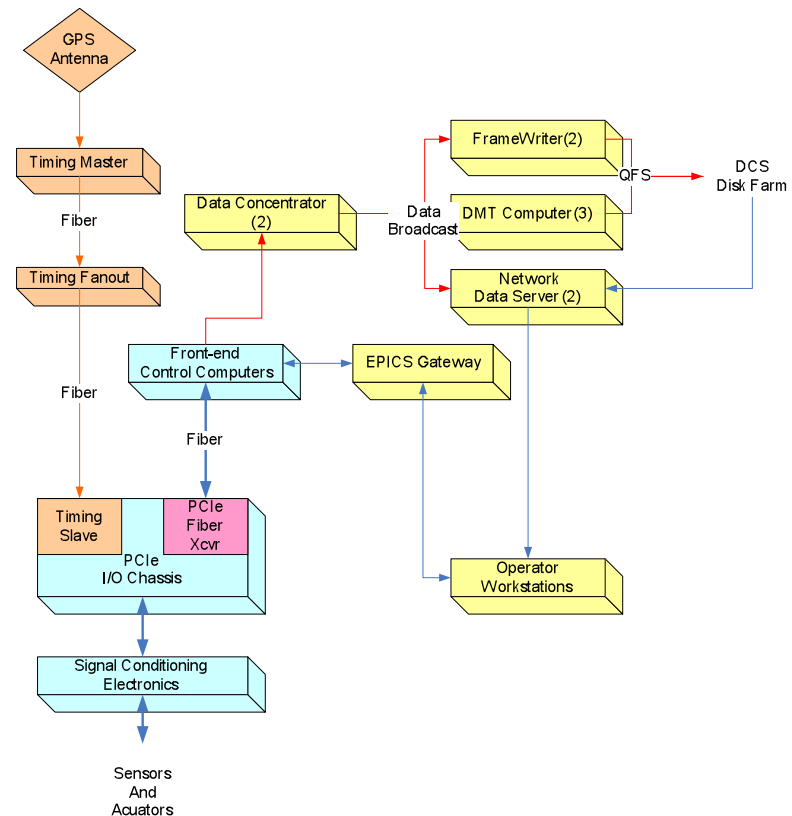
- Provide a hardware design and software infrastructure to support real-time servo control applications
  - » Deterministic to within a few  $\mu\text{sec}$ .
  - » High performance to support servo loop rates from 2048Hz to 65536Hz
  - » Built-in diagnostic and data acquisition features
- Acquire and record up to 15MBytes/sec continuously from each interferometer.
  - » 'Fast' data channels at rates from 256 to 32768 samples/sec (Up to 3000/IFO)
  - » 'Slow' data channels at up to 16 samples/sec, with up to 70K channels per interferometer
- Provide capabilities to acquire (but not record) an additional 15MB/sec of diagnostic data.
- Write data in LSC/VIRGO standard Frame format to disk system provided by Data and Computing System (DCS).
  - » Provide local disk to allow up to two weeks of data storage
- Provide an internal data distribution system to communicate diagnostic and acquired data to operator stations and Diagnostic Monitoring Tool (DMT) computers.





# DAQ System Design Overview

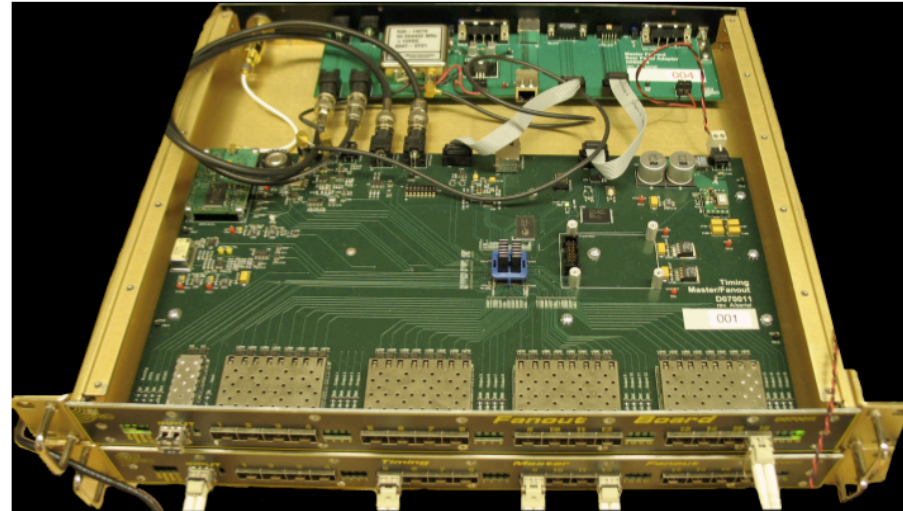
- Timing system provides clocks to PCI Express (PCIe) modules in I/O chassis.
- PCIe modules interface to control computer via PCIe fiber link.
- Control computer acquires data and transmits to DAQ data concentrator (DC) via network.
- DC assembles data from all controllers and broadcasts full data blocks every 1/16 second.
- FrameWriter computers format data and write to disk (32sec. data frame)
- Network Data Server (NDS) provides data on demand either live or from disk.





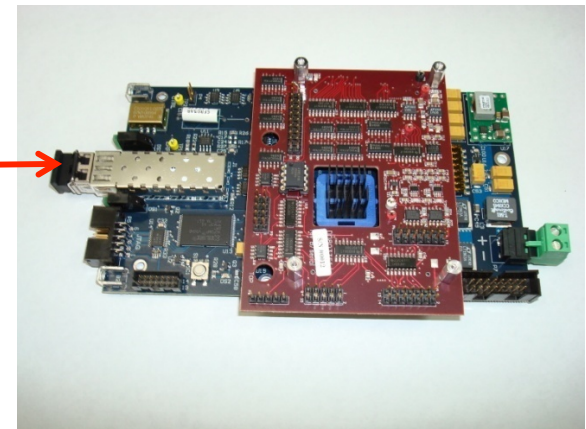
# Timing Distribution System (TDS)

- Contracted to Columbia Univ. for manufacture and test after a joint development effort. Design described in the journal *"Classical and Quantum Gravity"* under Imre Bartos et al., 2010 *Class. Quantum Grav. Vol. 27, No. 8, 084025*



**IRIG-B Timing Fanout**  
Provides accurate time information to computers.

LIGO-G1100458-v3



**Timing Slave provides accurate clocks**  
At 65536Hz to ADC/DAC modules.



# TDS IRIG-B Distribution Unit



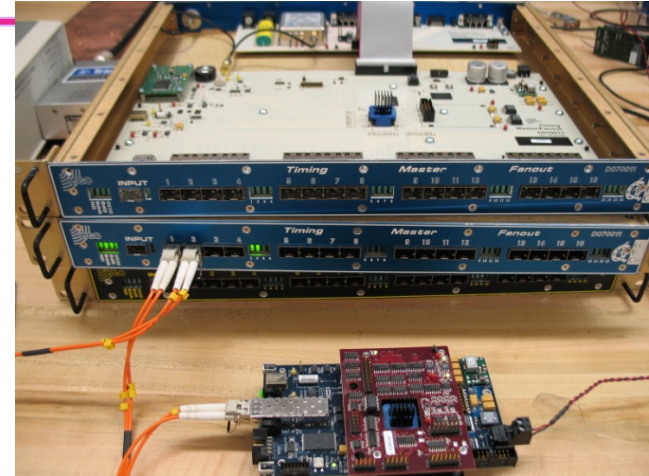
- IRIG-B system used to provide time information, in GPS seconds, to DAQ and control computers.
  - » Includes standard timing slave card to get time information from TDS.
  - » Outputs IRIG-B standard time code
    - DC Level Shift format
  - » Commercial IRIG-B Receiver modules in computers for accurately setting time in GPS seconds.
  - » Time accuracy to better +/- 1  $\mu$ sec.
  - » Second source of system time verification, along with duotone signal acquired from timing slave in I/O chassis.

GPS	986662955
Sync Source	TDS
CYC/USR	14 6 us
CPU Max	7 7 us
DT/IRIG	5 12 us

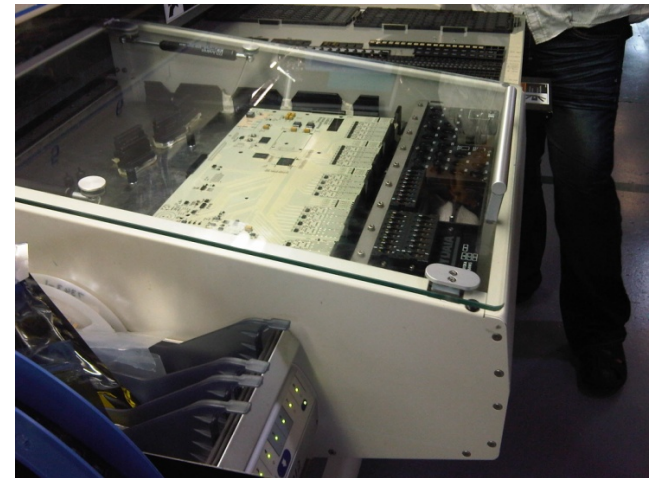


# Timing Distribution System Status

- 110 Timing Slaves, 60 DuoTones, 4 FanOuts and 2 Masters have been delivered to LIGO sites (CIT, LLO, LHO )
  - Timing slave units also used to synchronize RF distribution system.
- Slave-DuoTone assemblies are integrated into DAQ I/O
- All Master chassis are manufactured
- Production of remaining Fanouts is scheduled
- Comparator boards are manufactured, chassis builds started.
- All IRIG-B boards are manufactured, chassis builds ongoing.



Slave-DuoTone pair being tested at Columbia



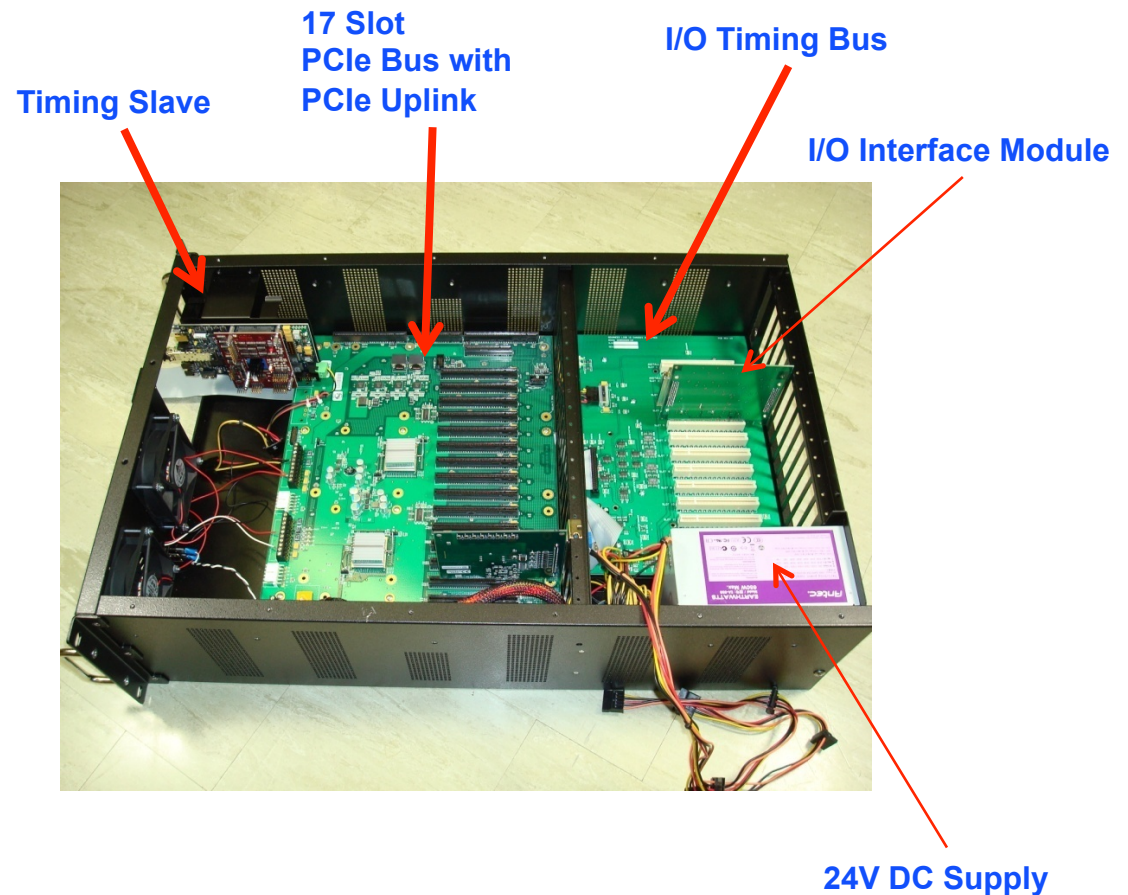
Master front boards under production





# CDS Standard PCI Express I/O Chassis

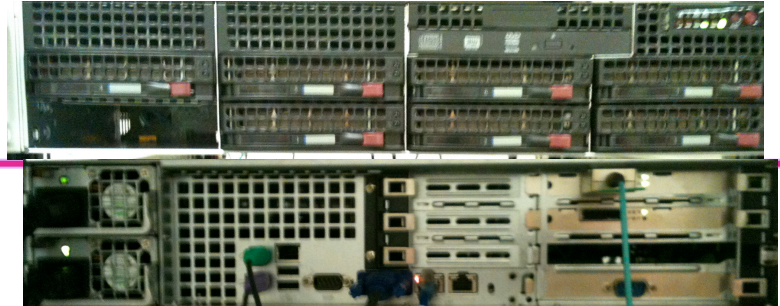
- Commercial PCIe expansion motherboards.
- Custom I/O timing and interface backplane.
- I/O interface modules provide timing and interface between PCIe module connectors and field cabling.
- Two fiber optic links.
  - To timing distribution system via timing slave module.
  - To computer, via fiber optic PCIe link.





# CDS Standard Computers

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- Supermicro X8DTU-F Motherboards
  - » Fulfills BIOS PCI-e card mapping and real-time stability requirements
- Single Xeon X5680 processor with six cores at 3.33GHz
- Up to 4 full height + 1 half-height PCIe slots
- Two GigE Ethernet ports
  - » Separate EPICS/DAQ networks
- No disk drives installed in computers used for real-time control
  - » Operated as diskless-node from central boot server
- Operating Systems
  - » Gentoo with Linux kernel 2.16.34, plus LIGO RT patch
  - » Ubuntu Linux for CDS servers and other non-real-time computers



# Networking



- Ethernet backbones for most applications
  - » GigE switches with fiber uplinks from end stations
  - » GigE switches with 10G uplink options for corner station
    - 10G uplink for DAQ and video connections
  - » 10G switches for DAQ Broadcasts
- Low latency networks for real-time data communications.
  - » Initial LIGO type reflected memory (for long runs to end stations)
  - » PCIe network, employing reflected memory software (corner station computers)



# PCI Express (PCIe) Real-time Control Network

- Low Latency (1.25usec)
- High speed (10Gbit/sec)
- Cable or Fiber connections
  - CX-4 cable to 3 meters
  - Multi-core fiber to 100 meters
- Stackable 10 port Switches
- Reflected Memory Mode
  - Data broadcast to same memory location on each computer on the network.







# Corner to End Station Real-time Control Network

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- Loop topology
- Low Latency (700nsec/node)
- High speed (2Gbit/sec)
- Fiber connections
  - Up to 10km
- Bypass Switch provided at each location
- Reflected Memory
  - Data broadcast to same memory location on each computer on the network.





# Networking – Progress

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- All Ethernet switches have been procured and delivered for all three interferometers.
  - » All network switches have been configured for L1 and H2.
  - » Network switch and cabling installation in progress.
    - Corner station and one end station complete at LLO.
    - H2 DAQ and MSR switches installed.
      - Waiting for new Electronics Equipment building for H2
- All real-time networking equipment procured and delivered.
  - » Systems installed and running at both sites.



# LIGO Physical Environment Monitoring Infrastructure

- For aLIGO, PEM system will provide control as well as DAQ
  - » On-line Adaptive Filtering and feed-forward control.
- One computer + 1 I/O chassis at each station and at corner station.
- Re-use existing PEM sensors
- Up to 128 channels of ADC + 8 channels of DAC
  - » I/O connections via AA/AI chassis with BNC connections.
- Progress
  - » Computers, I/O chassis and ADC/DAC modules have all been procured and delivered.
  - » 6 of the 12 AA Chassis have been built and tested.
  - » LLO End Station system under test ----->

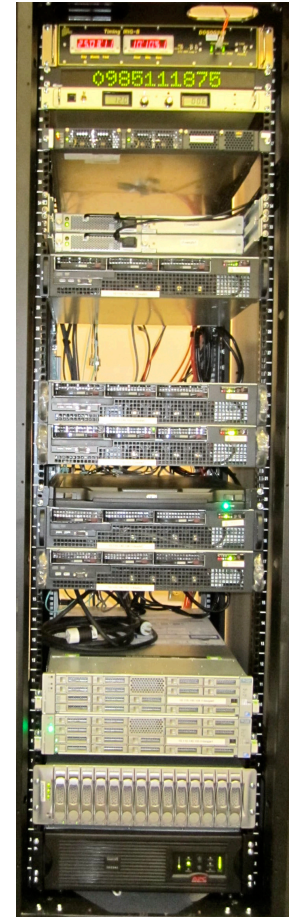




# DAQ

## Computing / Storage Equipment

- Data Concentrator (DC) (2)
  - » Collects data from all real-time control computers and broadcasts to 10GigE network.
  - » One unit on-line, second hot backup
- FrameWriter (2)
  - » Receive data from DC
  - » Format data into LVC standard Frame format
  - » Write data to disk
    - Local
    - Data Analysis group disk farm
- Network Data Server (NDS) (2)
  - » Provides real-time or stored data on request to various control room software tools
    - NDS clients also developed for Perl, Python and Matlab
- Two computers running Solaris operating system to connect disk systems via QFS.
- 24 TByte Local Disk





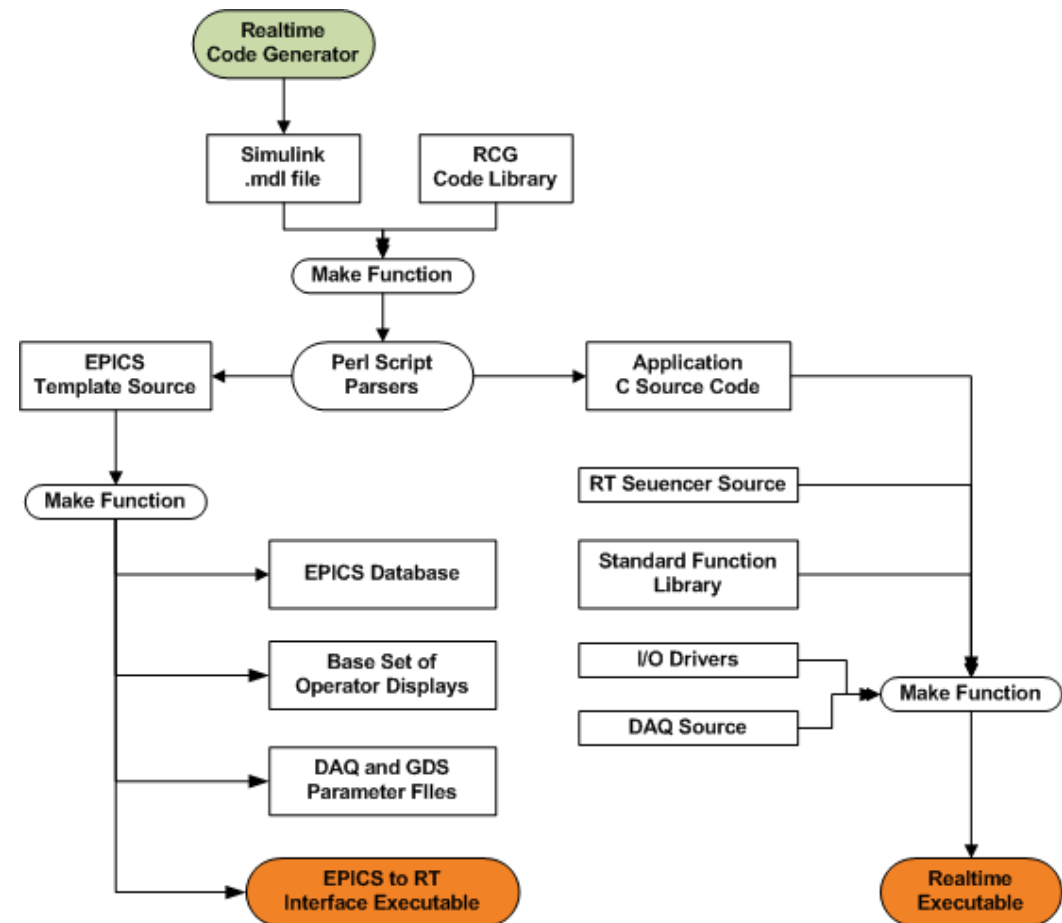
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- The figure displays two parts related to a multi-axis motion control system.
- Left Panel:** A detailed block diagram of the system architecture. It shows multiple input channels (e.g., \$X\_{in}\$, \$Y\_{in}\$, \$Z\_{in}\$, \$RZ\_{in}\$, \$Z\_{in}\$, \$RX\_{in}\$, \$RV\_{in}\$) feeding into various processing blocks like "EPIC2-CART", "ORIGIN", "BLEND", "ISO", "ISOBLOCK", "ADD", "CART2ACT", and "MASTER". The outputs are labeled as \$X\_{out}\$, \$Y\_{out}\$, \$Z\_{out}\$, \$RZ\_{out}\$, \$Z\_{out}\$, \$RX\_{out}\$, and \$RV\_{out}\$. There are also feedback paths from the outputs back to the inputs.
- Right Panel:** A screenshot of the IliasITMX/ST1/ISO software interface. It shows a simulation environment with a yellow background. On the left, there's a vertical list of axes (1 through 6). In the center, there's a grid of status indicators for each axis, showing "correct/in" and "good/out" states. On the right, there's a "MASTER" block. At the bottom, there's a note: "If the STATE\_OK is 1 then all the synchros are in the correct state".



# Software

## Real-time Application Build Process

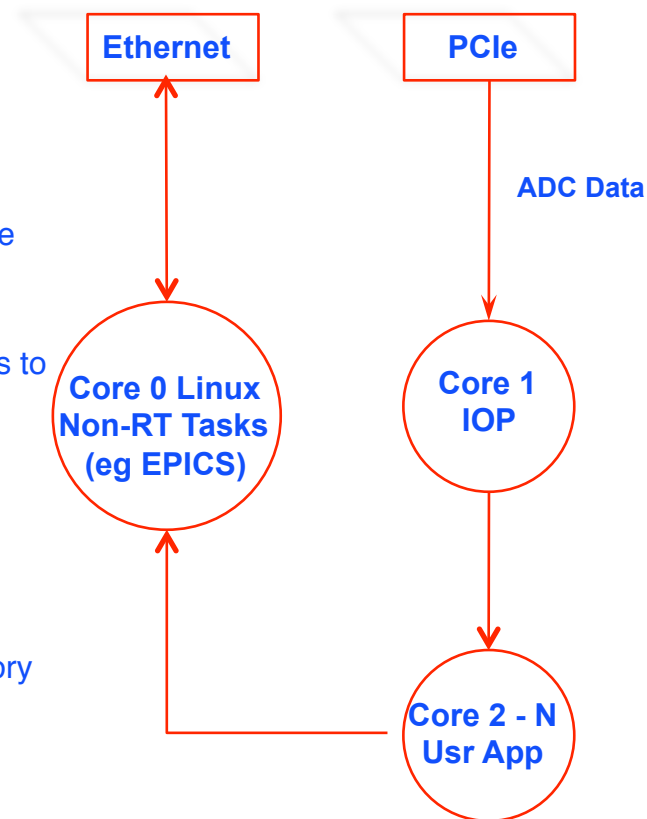
- Build and save RCG model.
- make 'modelName'
  - Perl scripts parse the model file to determine signal connections and code flow
  - Perl scripts generate EPICS and real-time source code.
  - Compiler is invoked to link common code libraries and produce real-time and EPICS executable software.
- make install
  - Moves executables to target directories for load onto real-time computers.
  - Channel descriptor files generated for use by DAQ and GDS
  - Basic set of operator displays generated.





# Real-time Core and Patch

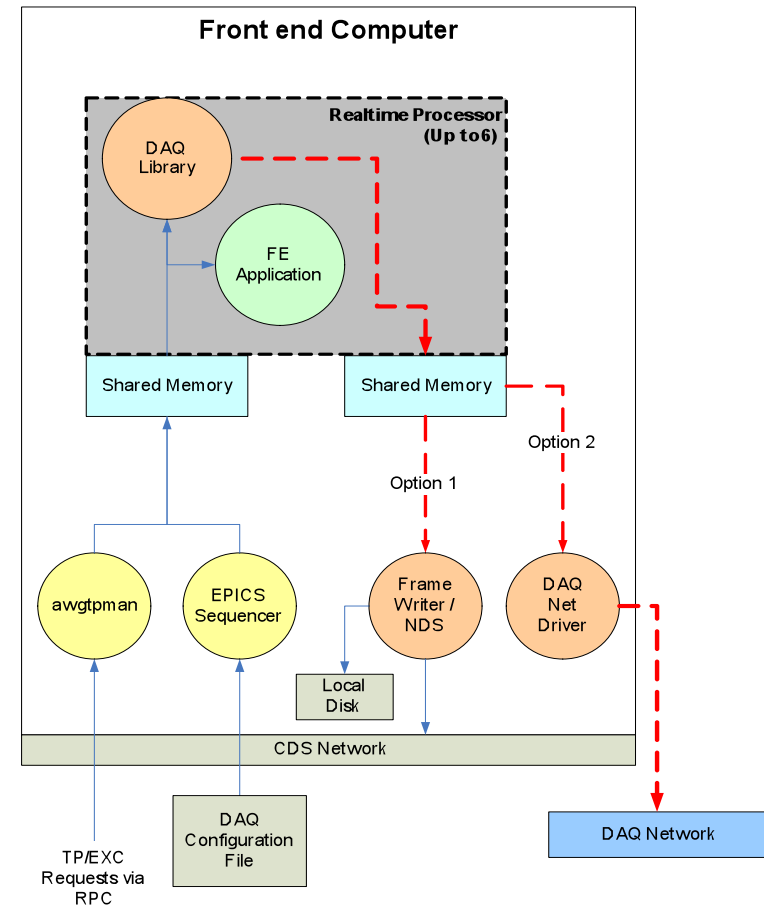
- aLIGO Real-Time (RT) code not “traditional”
  - » No pre-emptive operating system scheduler
  - » No interrupts, semaphores, priorities, ensuing context switching, etc.
- Each RT app locked to its own CPU core
  - » Using custom patch to Linux kernel “play dead” routine
    - Notifies Linux scheduler that CPU is going down and unavailable for interrupts/task assignment.
    - Inserts RT app code instead of Linux idle routine.
    - Removal of RT app brings the CPU “back to life” and reconnects to Linux as a useable resource.
  - » RT code runs in continuous loop
    - Triggered by arrival of ADC data in local memory (polling or MONITOR/MWAIT CPU instructions)
      - ADC modules set up to automatically transfer data to computer memory on clock trigger
    - Never switched out ie always resident on stack, in cache, memory
- For each RT computer, there is a special case model called an Input/Output Processor (IOP)
  - » Controls startup timing and synchronization.
  - » Maps and initializes all of the PCIe I/O interfaces
  - » Triggers and monitors user applications.
  - » Always running, allowing user apps to come and go, as necessary





# DAQ System Front-End Software Design

- A common DAQ library is compiled into each FE application.
- Acquires data at user defined rates and transmits data as 1/16sec data blocks:
  - » For archive, as described in a DAQ channel configuration file.
  - » Test point and excitation channel data on demand
    - As requested via the arbitrary waveform generator/ test point manager (awgtpman)
  - » Supports aggregate (DAQ+TP) data rate of 2MB/sec per FE processor
  - » CRC checksums and timestamps sent with all data blocks
- Supports various configurations
  - » (1) Data to FrameWriter/NDS software on same computer via shared memory
    - Allows a complete stand-alone system to support various subsystem test stands
  - » (2) Data to shared memory, with separate network software
    - Supports multiple FE applications on same computer
    - Relieves RT front end code from network error handling and other possible delays

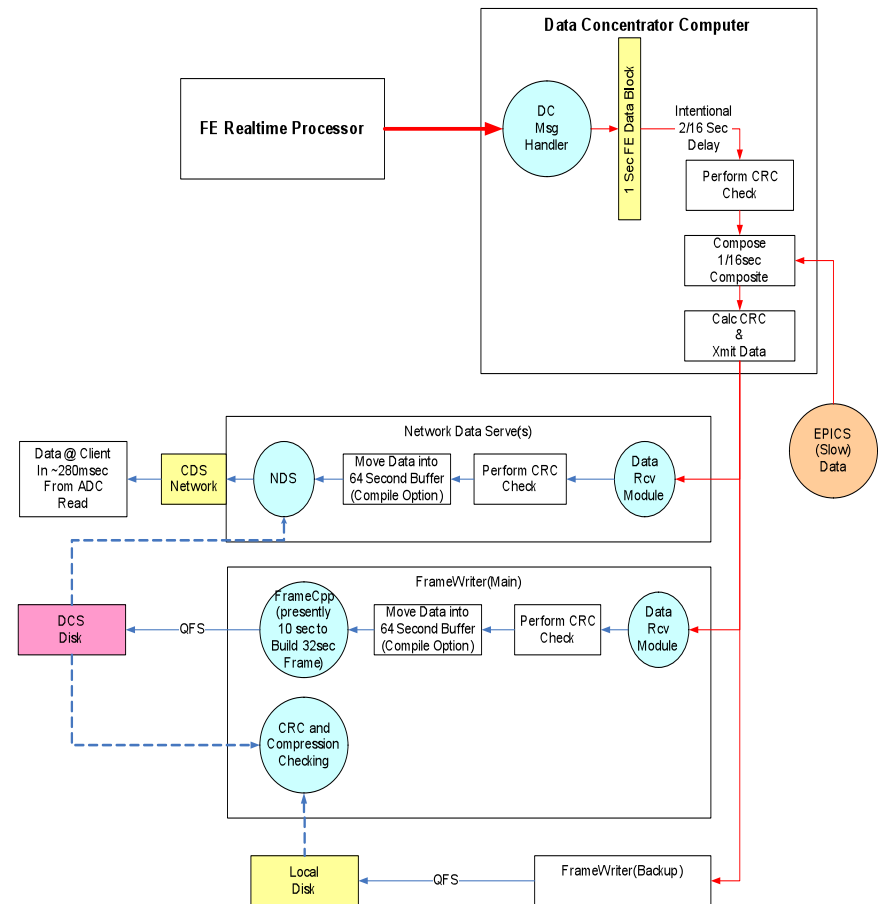






# DAQ System Backend Software Design

- Data Concentrator
  - » Collects 'fast' data from all FE computers via dedicated network
  - » Collects 'slow' (EPICS) data via CDS network
  - » Broadcasts combined data to upstream computers as 1/16 sec data blocks on to 10Gb Ethernet
- FrameWriter
  - » Format data into standard LIGO Frame using FrameCpp library, with data compression.
  - » Write data, via QFS, to DCS disk farm (32 second data file)
- Network Data Server (NDS)
  - » Provides live and archived data feeds, on request, to CDS operator stations





# Software Version Control

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- All software version control done using SVN
- Software developed by “core” group maintained in
  - » advLigoRTS – DAQ and Real-time Code Generator (RCG) tools and other code required to support real-time operation.
  - » Global Diagnostic System (GDS)
- Two control application developers SVN repositories
  - » Seismic group (legacy)
  - » CDS group supported SVN for all other user applications
- Documentation written which specifies CDS production system directory structure and proper linkage of various SVN branches.
- Working with subsystem application developers to form commonly structured SVN areas to ease link to production.



# CDS SVN Repository

A screenshot of a web browser window displaying the "WebSVN - Subversion Repositories" interface. The browser's address bar shows the URL "https://redoubt.ligo-wa.caltech.edu/websvn/". The page has a light blue background and a navigation bar at the top with links like "LAX Airport Tracker", "WebSVN", "LIGO", "PCard", "Apple", "Yahoo!", "Google Maps", "YouTube", "Wikipedia", "News (222)", and "Popular". The main content area is divided into two columns. The left column, titled "LIGO CDS SUBVERSION", contains links for "To Check Out A Repo" (with a command: `svn co https://redoubt.ligo-wa.caltech.edu/svn/<repo-name> --username your.name`), "User Accounts", "Read/Write Access", "User Guide", "Link to CDS wiki svn user guide", "What To Do If Broken", and email addresses "barker@ligo-wa.caltech.edu" and "jhanks@ligo-wa.caltech.edu". The right column, titled "SUBVERSION REPOSITORIES", lists various repositories: advLigoRTS, archive, cds, cds\_user\_apps, controls, daq, dave, docs, GC, gds, iLigoRTS, orig\_gds, pcal, projects, sus, sysadmin, target, and temp. At the bottom right, it says "powered by: WebSVN 2.2.1".



# Software Reviews

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- Driven by the high cost of commercial real-time OS, developed our own patch to GPL Linux to provide the real-time features that we require.
  - » Reviewed as part of meeting at AEI, Hannover, Germany last July
  - » AEI brought in two Linux consortium members, with expertise in real-time, as consultants for this review.
- Lab internal review held last November for DAQ software and real-time application development tools.
- Informal Reviews
  - » A number of meetings with AEI Hannover staff, who use our software on a number of projects, including updates to GEO subsystem controls and DAQ.
  - » Recently held two user/control application developers workshops, one day of which was devoted to going through the core software components part by part.



# Software Testing

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- In process of developing automated testing. In preparation:
  - » Added a number of new diagnostics to system.
  - » New scripting language interfaces to EPICS and NDS
    - Perl and Python
- Caltech 40m lab interferometer controls upgraded to use aLIGO hardware/software. Part of the lab's mission is control/DAQ software test on an operating interferometer.
- Automated I/O chassis test system at Caltech used to verify I/O in new releases.
- Software also deployed in support of a number of seismic and suspension subsystem test stands.
  - » Users often operate/configure systems in ways not considered by software test developers.



# Recommendations from NSF April 2010 Review

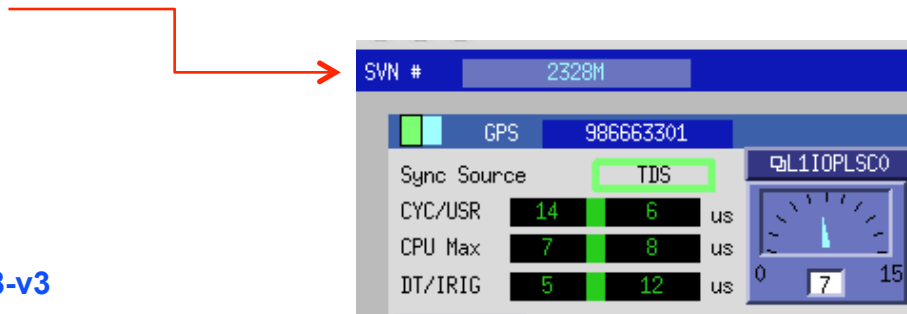
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- Actively working to incorporate the recommendations, as listed in following bullets and next page. Many have been incorporated, but more work still to be done.
- Separate builds for development and production code
  - » Action: Implemented SVN “tagged release” system for core software
- Development builds on regular, fast turnaround basis
  - » Action: Already being done
- All builds exercise all component test suites (In process of incorporating)
  - » Action: In process of documenting and automating test procedures.



# Recommendations from NSF April 2010 Review

- Code install and operation on interferometers
  - » Only fixed production release code to be used on interferometer
  - » Clear structure for managing software module versions.
  - » Builds fixed and reproducible
  - » Only code from SVN
  - » **Actions Taken:**
    - Additional SVN structure set up for user developed control applications
    - Standard production code directory structure implemented and documented
    - Control application developer training and SVN assistance
    - Documentation of exactly which real-time control code will run on which processor
- Archival of software build metadata
  - » **Action:** In process of producing auto-generated EPICS database channels for code SVN tags, which are then saved as part of the Frame data.





# Software Documentation

- Base set of documentation in place.
  - » Part of November 2010 review
- Software test procedure documents still need to be added.
- Document updates a continuous process.

**CDS Software Documentation**  
(QA: Uncertified)

**Abstract:**  
List of CDS software documentation for 2010 CDS software review.

**Files in Document:**  
None

**Topics:**

- [Meeting](#)
- [Data Acquisition System](#)

**Authors:**

- [Rolf Bork](#)

**Related Documents:**

- LIGO-T0900603: [aLIGO CDS Real-time Control Software Requirements](#)
- LIGO-T0900607: [AdvLigo CDS Realtime Sequencer Software](#)
- LIGO-T0900638: [CDS Real-time Data Acquisition Software](#)
- LIGO-T0900612: [AdvLigo CDS Design Overview](#)
- LIGO-T1000560: [CDS Software Development Plan FY11](#)
- LIGO-T1000561: [aLIGO CDS Software Test Plan](#)
- LIGO-T1000587: [aLIGO CDS Inter-Process Communication Software Design](#)
- LIGO-T0900636: [Frame Builder and Network Data Server](#)
- LIGO-T1000588: [aLIGO CDS Computer and Networking Rack Layouts](#)
- LIGO-T080135: [AdvLigo CDS Realtime Code Generator \(RCG\) Application Developer's Guide](#)
- LIGO-T0900531: [CDS Subversion Users Guide \(wiki document\)](#)
- LIGO-T1000248: [aLIGO CDS File System Directories](#)
- LIGO-T1000379: [CDS Environment Configuration Scripts](#)
- LIGO-T1000496: [aLIGO CDS Software Bug Reporting User Guide](#)
- LIGO-T0900606: [CDS Standard IIR Filter Module Software](#)





# DAQ System Project organization

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- Three software engineers at Caltech
  - » DAQ and realtime infrastructure software development
- Three additional software staff at sites
  - » Global Diagnostic Tools
  - » Additional control room tools
  - » System Administration
- Columbia University
  - » Manufacture and test of timing system
  - » Developed associated timing diagnostics software



# DAQ System Flow of Activities

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- Software Development
  - » Focus on “short list” of additional features/bug fixes for RCG put forward during user group meetings.
    - Updated Software Development Plan
  - » DAQ specific software development complete.
    - Implement and verify DAQ test procedures and scripts.
    - Preliminary performance tests have been run to 48MB/sec + 45K EPICS channels.
  - » Test and verify production release procedures.
  - » Complete/update documentation.
  - » Complete/verify implementation of NSF 2010 review recommendations
- Equipment Procurement
  - » Specify/Procure system servers and operator station computers.
- Installation
  - » LLO system in place.
  - » Install/test H2 system as building becomes available (May).
    - System already built and ready to move in place.
  - » H1 system after Squeezing Experiment complete



# Challenges, risks, and mitigations

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- Technical
  - » Scaling from relatively small test systems to a large, integrated AdvLigo System
    - Large scale testing continues
      - L1 system, with complete set of real-time computers in place.
      - Caltech 40m lab, on operational interferometer.
    - Large number (>100K) of slow (EPICS) data channels of particular concern and focus of testing.
      - May require separate data frames for fast and slow data.
      - May require slow data be moved to DAQ as a separate transmission on fast DAQ network if EPICS channel access mechanism becomes overloaded.
- Cost
  - » Increased cost of Commercial Real-time Linux OS
    - Mitigated by development of patch to GPL Linux.



# DAQ System Summary

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- Timing system component delivery and installation continues.
  - » Equipment necessary to support early commissioning activities are in place.
- LLO DAQ system and networking infrastructure installed and operational.
- LHO H2 DAQ and networking system operational and ready to move into place as space becomes available (late May).
- Two off-line DAQ / control application development/test systems operational, one at each site.
- Stand-alone systems installed and in constant use at sites, and elsewhere, to support testing of suspension and seismic isolation systems.
- Distributed systems installed and operational at CIT 40m lab, MIT LASTI, and at AEI/GEO in Germany.