

# 40 meter Recycling Program

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- Recycling: current optical Configuration & culmination of MK II facility development
  - ›› Design & implementation: J. Logan (to 9/98)
    - High coupled cavity (RC and F-P arms) gain ( $> 20$ ) with Schnupp asymmetry.
    - Full, LIGO like, core optics suspension: single wire loop; PM magnet actuation; 4 layer isolation stacks.
    - State of the art, low loss optics: superpolish; sputtered oxide coatings (principle difference from LIGO, 514 vs 1064 nm)
    - Single freq. frontal modulation servo scheme = LIGO (c 1996).
  - ›› Previous: “Recombination” (Michelson with F-P arms)
    - Demos LIGO displacement sensitivity. Finish: mid-97 with thesis
  - ›› Upgrade hardware for recycling ~mid 1997.
    - New ITM (F-P input “test mass”): improved optical figure & HTM rejection. Transmission increased by  $\sim 20$  (to 6000 ppm). Spring '97.
    - Addition of recycling mirror (installed 9-10/98)
    - New RF side-band  $\lambda$  (11 meters), and re-layout in vacuum optics for  $\lambda$  and RC.

SCANNED

LIGO-G980134-00-D

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- New PSL (still 514 nm)
- New (single wire loop) optics suspensions (RM, BS, EITM)
- WFS (Wave Front Sensing) auto-alignment (from MIT FMI 3/97)
- ››Recycled operation accomplishments
  - Recycling cavity (PRM) locked 11/97 (two servo loop bootstrap)
  - Full recycled interferometer lock 12/97. Quantitative agreement of PRM gains & alignment sensitivity with near degenerate cavity model.
  - Investigation of modal structure via RF sb resonances.
  - Full control of PRM alignment via WFS
  - Wide scale use of digital controls, filtering, and data acquisition.
  - Determination that interferometer is under-coupled, due to anomalously high arm loss, constant with measured gain =4.4
- ››Work in progress (through Winter 1999)
  - elucidate instability of full lock state to optimal alignment.
  - Understand servo dynamic range and gain margin limitations.
  - Invoke WFS for F-P arm DOFs: confirmed to be dominant perturbation on ifo power build up.

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# 40 meter Recycling Program

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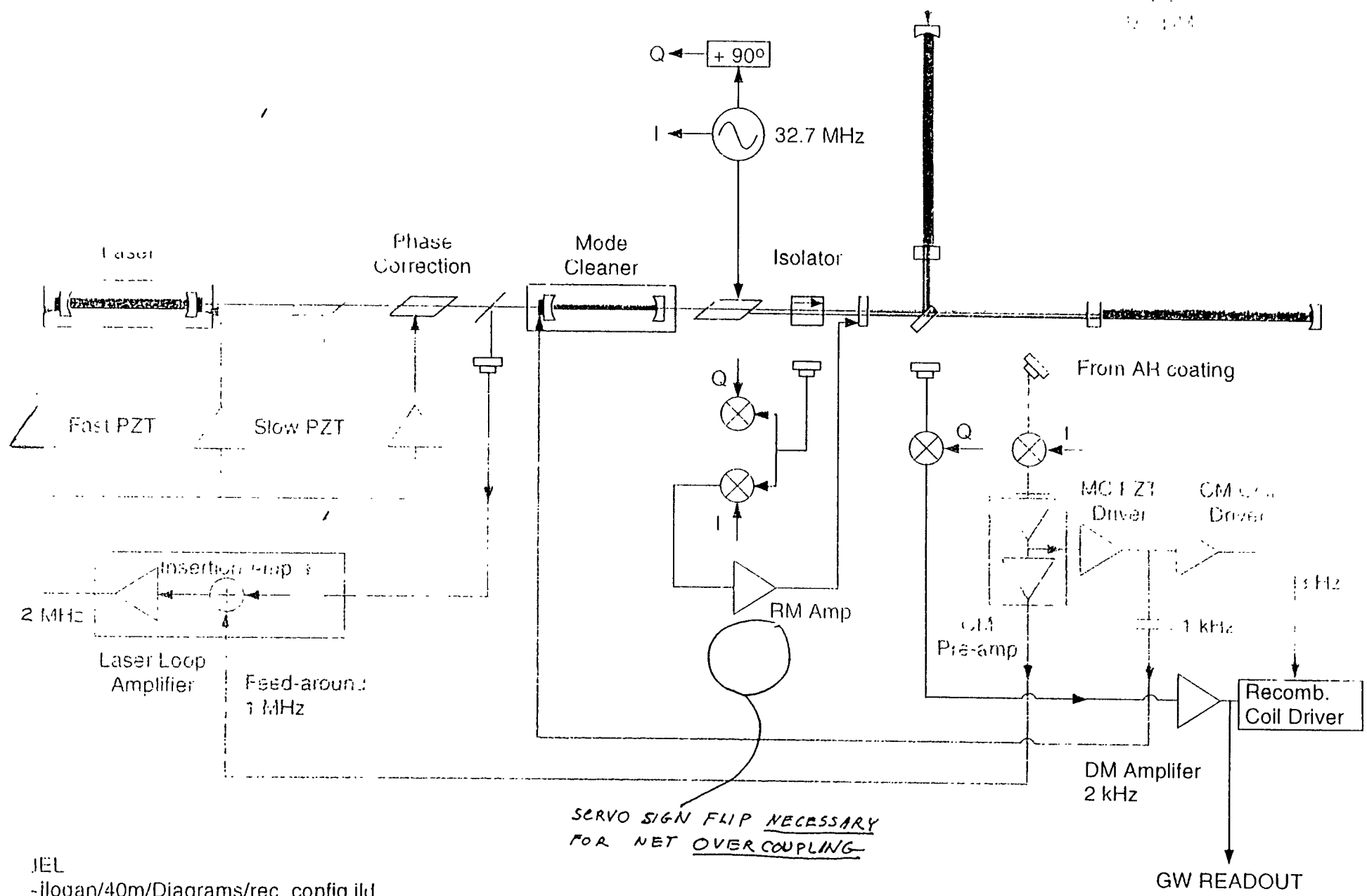
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  - Understand servo dynamic range and gain margin limitations.
  - Invoke WFS for F-P arm DOFs: confirmed to be dominant perturbation on ifo power build up.
  - Stage period of dedicated "data mode" full lock, writing tapes via LIGO model data acquisition system (U. Michigan team: Gustafson, Riles, Rollins)

# 40 meter Recycling Program

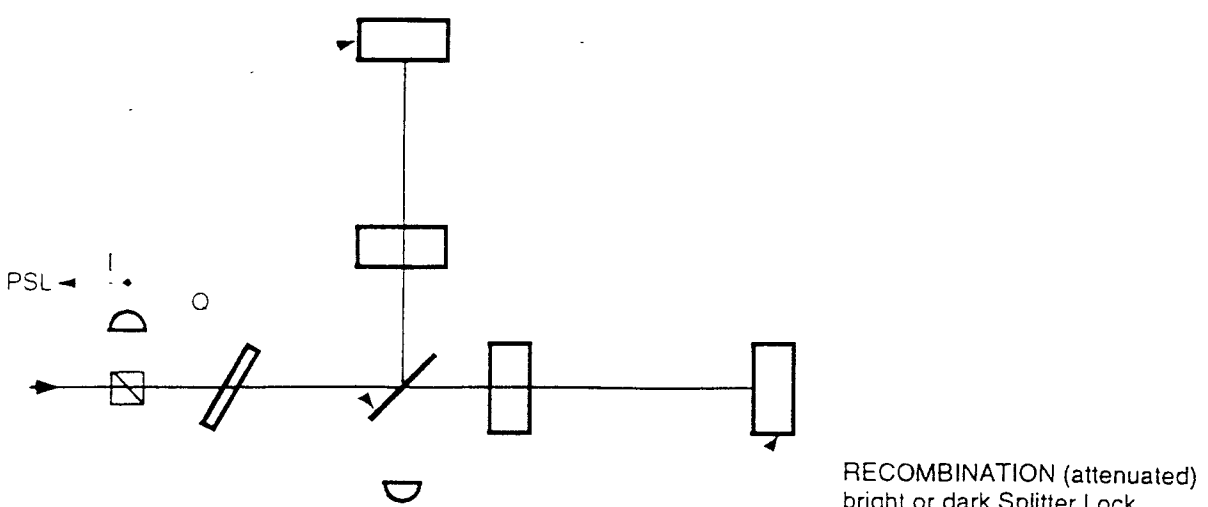
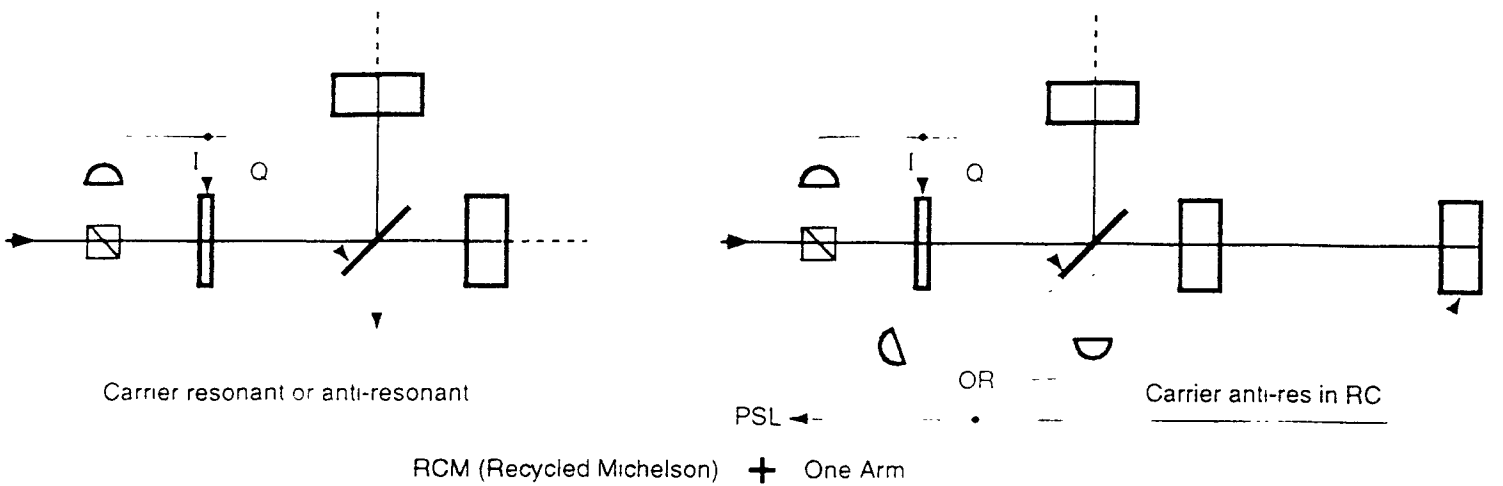
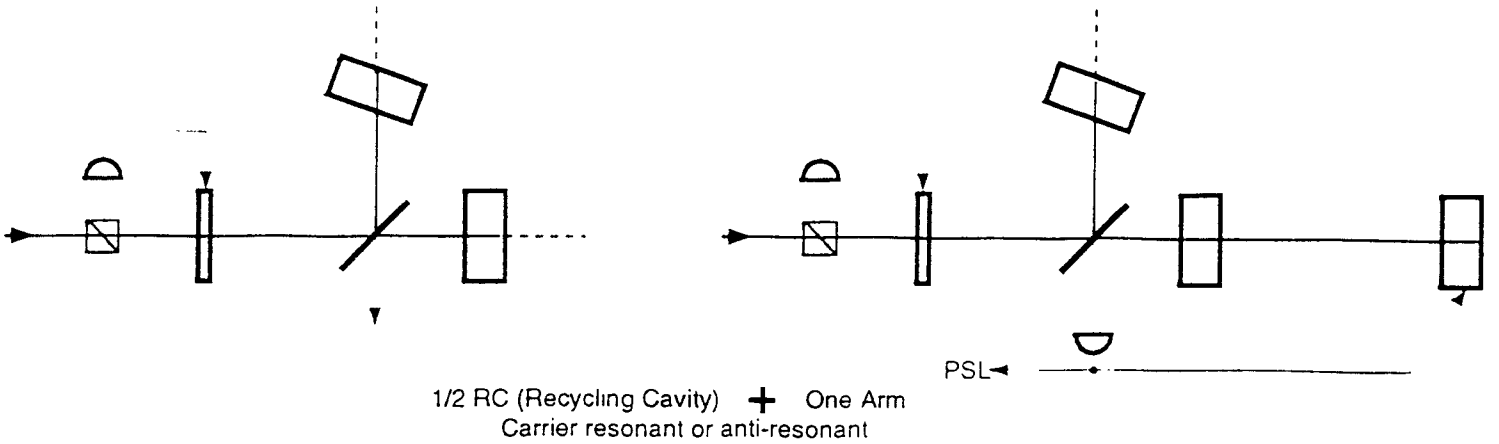
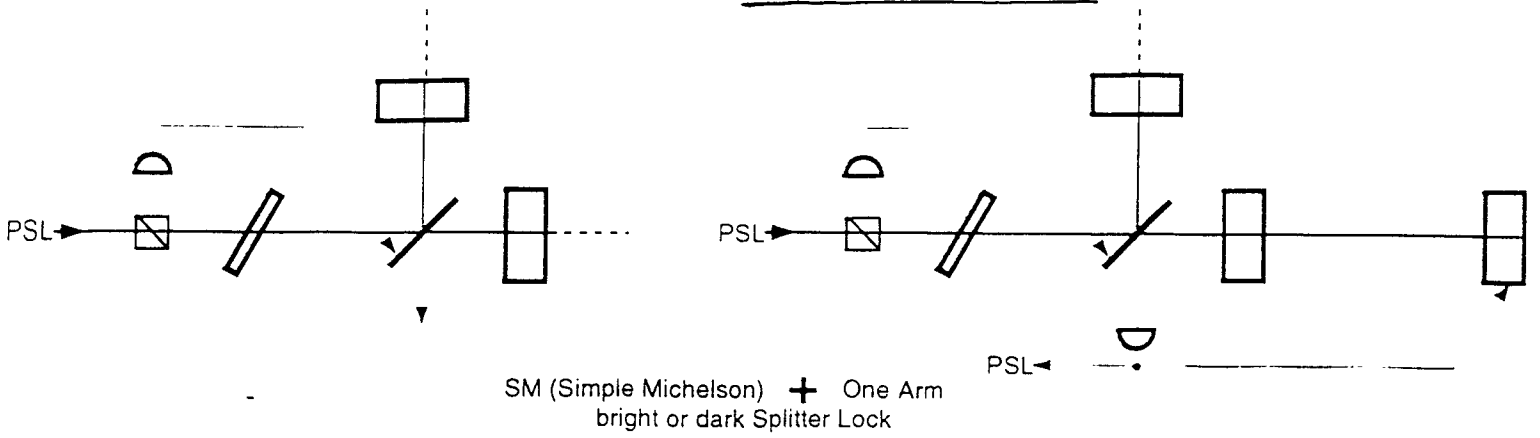
40 Meter interferometer Recycling status (11/98)

$\nu_{MOD}$	31-34 MHz	32.700 MHz ( $\lambda=9.16$ m)	
$L_{ARM}$	38.028 / 38.550	40 m	
$\nu_{MOD, RES.}$	31.5338 / 31.0855	—	
$L_{RC}$	2.3 m	2.29 m	
$T_{ARM}$	5900 / 6100 ppm	5950 / 5870 ppm	
$L_{LOSS, ARM}$	380 / 360 ppm	230 / 100 ppm	
ASYMMETRY	.540 m	.540 m	
$T_{RM}$	.87 m	.865 m	
$G_{RC}^{LR}$	~20	~21.5	
$G_{RC}^{SB}$	5.5	6.7	
$G_{FULL IFO}^{CR}$	4.4	9.2	
$g_{ARM}$	.3766 / .3627	1/3	

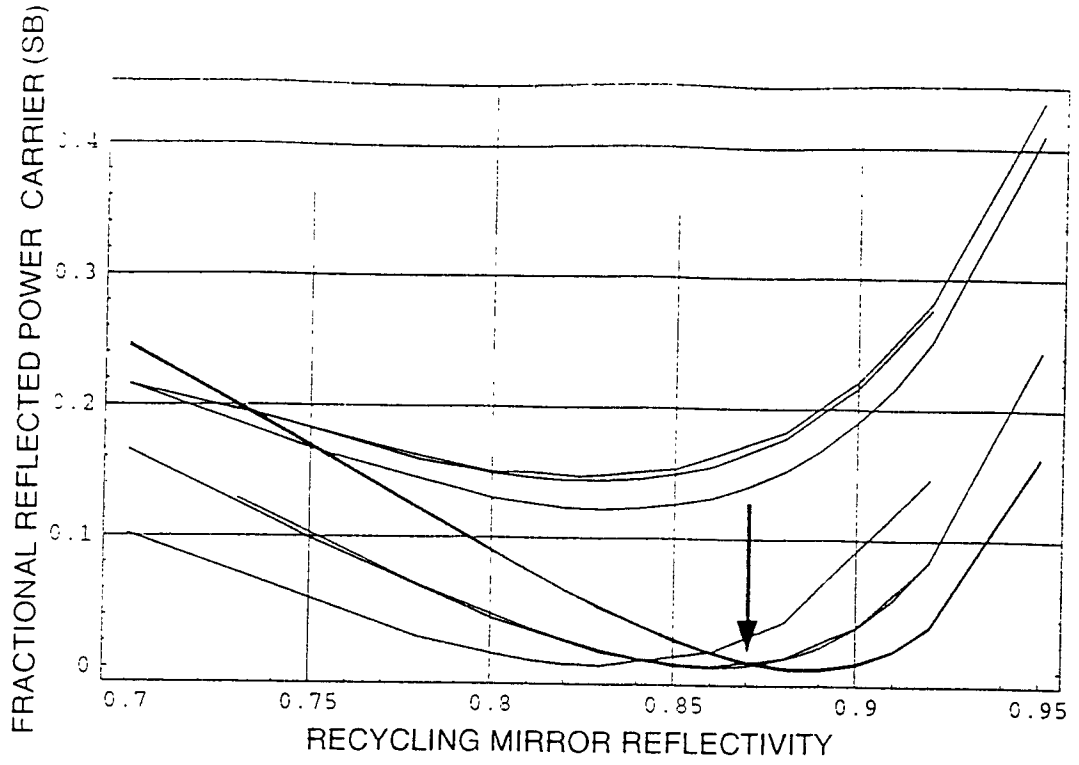
40 m POWER RECYCLING TOPOLOGY



# 40meter CONFIGURATIONS



# FFT Simulations of $40\text{ m}$ Recycling



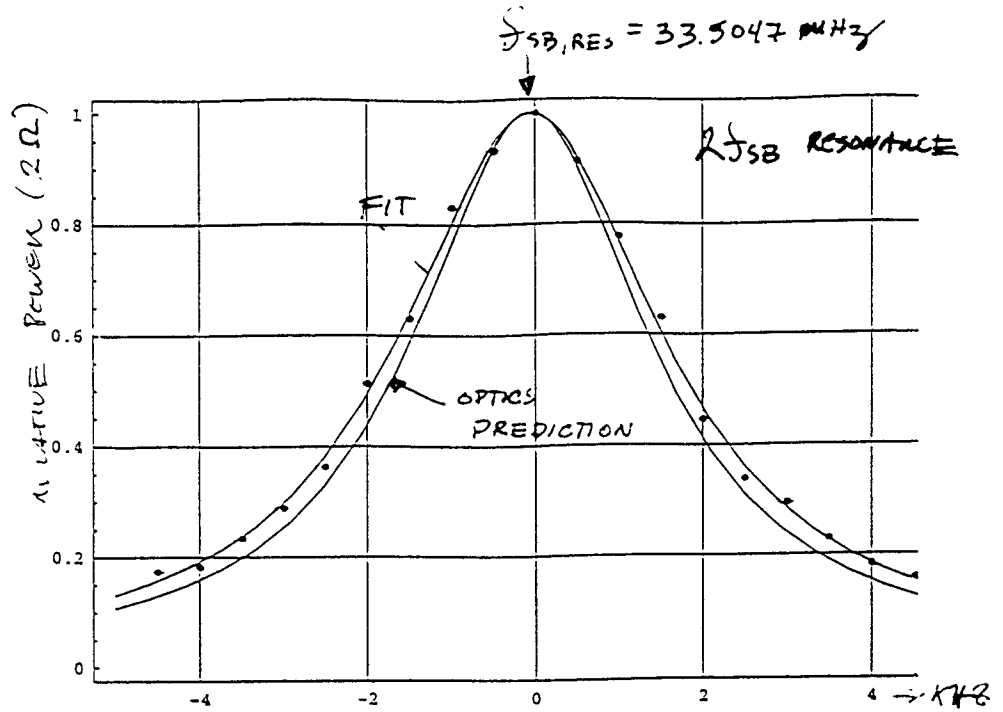




SIDE BAND TRANSMISSION THROUGH 40!!! TRANS

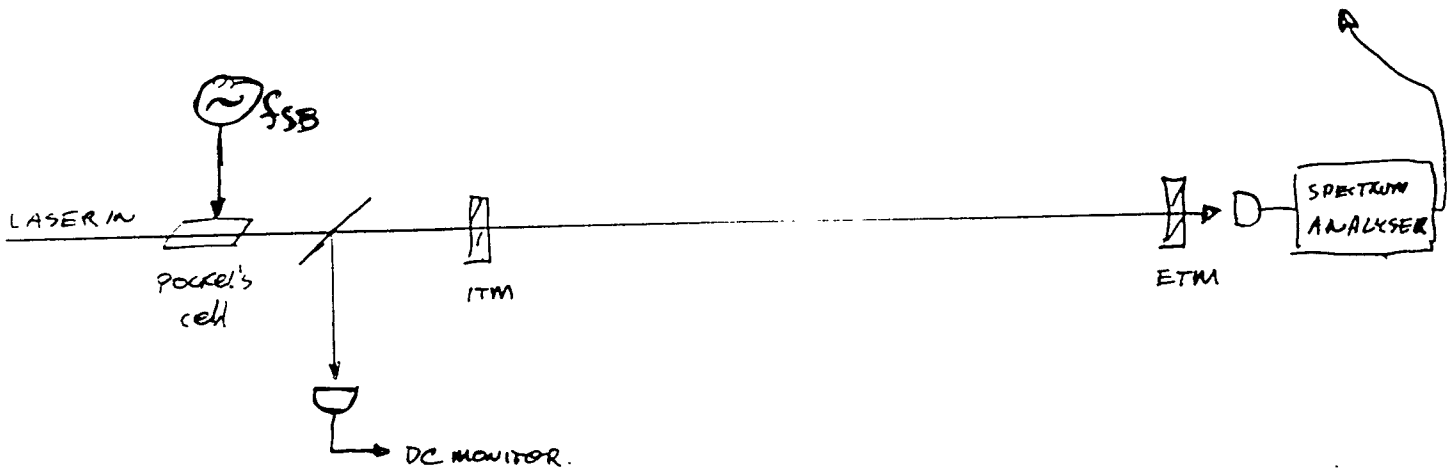
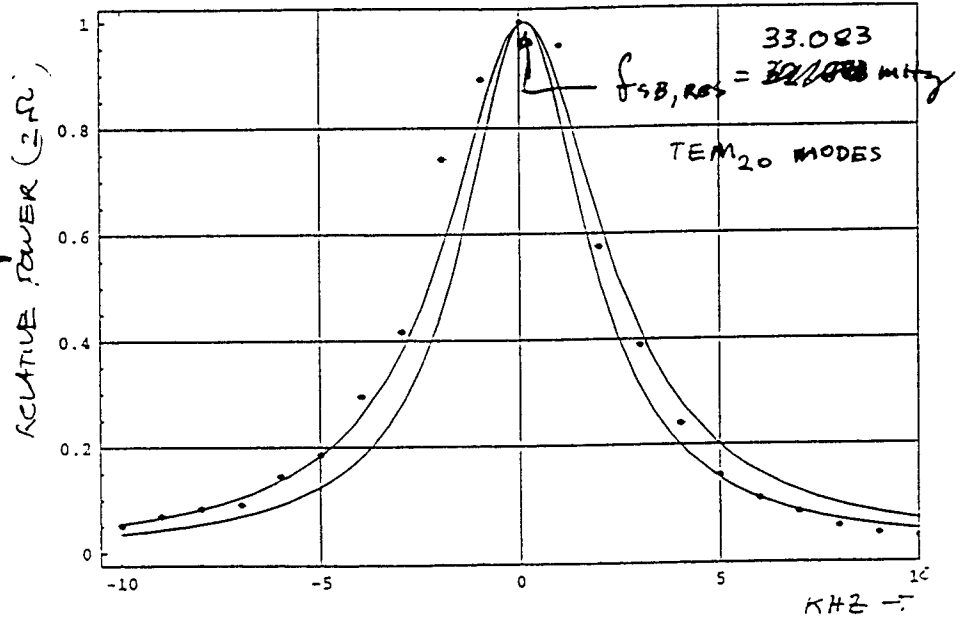
WIDTH GIVES  
CAVITY LOSS

$f_{RES}$  GIVES  
HIGH PRECISION CAVITY LENGTH

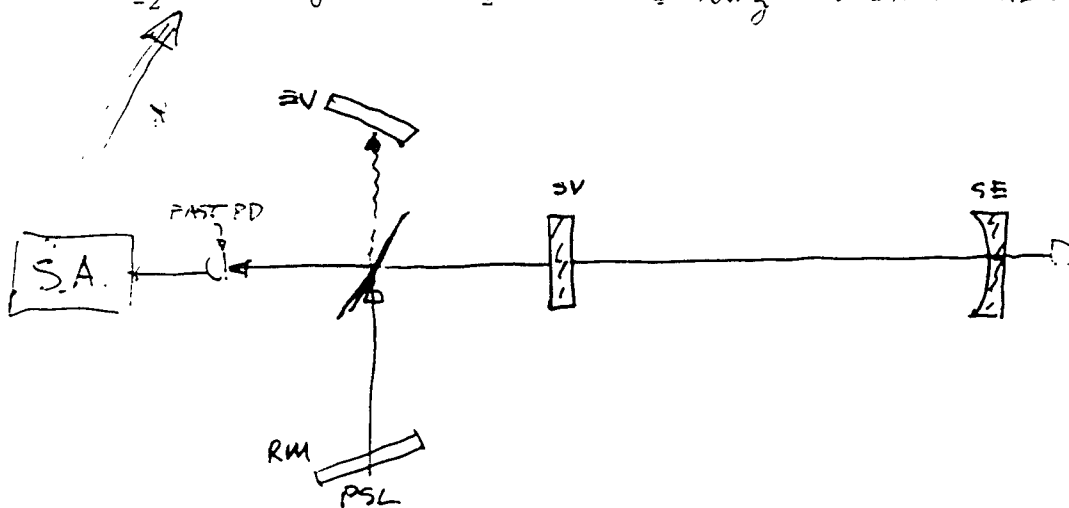
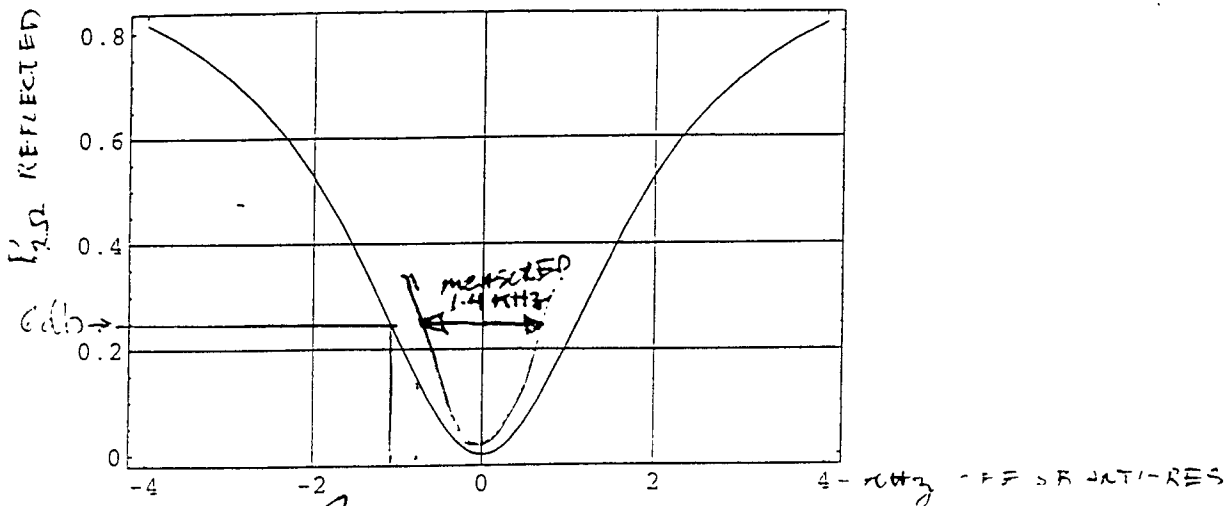


STRENGTH GIVES BEAM FOCUS  
MISMATCH INTO CAVITY

$f_{RES}$  GIVES CAVITY QUOCY



```
[37]:= Plot[.25 Abs[1 + Erfi[0.9114 + .00081 x, .0][[1]]]^2 /. x -> .997 /. f -> .999965,
(x, -4, 4), GridLines -> Automatic, Frame -> True]
```



THEORY: - PHASE MOD LIGHT:  $E_0 E^{(z_{\text{LASED}} + T \cos \Omega t)}$   $\sim E_0 (\bar{J}_0 + 2\bar{J}_1 i \cos \Omega t)$

-  $V_{\text{FPD}} \sim |E|^2 \sim \bar{J}_1^2 - \bar{J}_0 \bar{J}_2 \approx 0$

CARRIER (only) RESONANT:  $\bar{J}_0 \rightarrow -\bar{J}_0$

-  $V_{\text{FPD}} \sim |E|^2 \sim \bar{J}_1^2 - (-\bar{J}_0) \bar{J}_2 = 2\bar{J}_1^2 \propto P_{\text{SLR}}$

CARRIER & SB ANTI-RES:  $\bar{J}_0 \rightarrow -\bar{J}_0$   $\bar{J}_2 \rightarrow -\bar{J}_2$

-  $V_{\text{FPD}} \sim \bar{J}_1^2 - (-\bar{J}_0)(-\bar{J}_2) \approx 0$

TYPICAL FULL LOCKED FULL LOCKED FULL LOCKED PERFORMANCE

