
LIGO II:
MIT/Caltech Advanced
R&D Program

Gary Sanders

LSC Formation Meeting

Baton Rouge

August 14-15, 1997

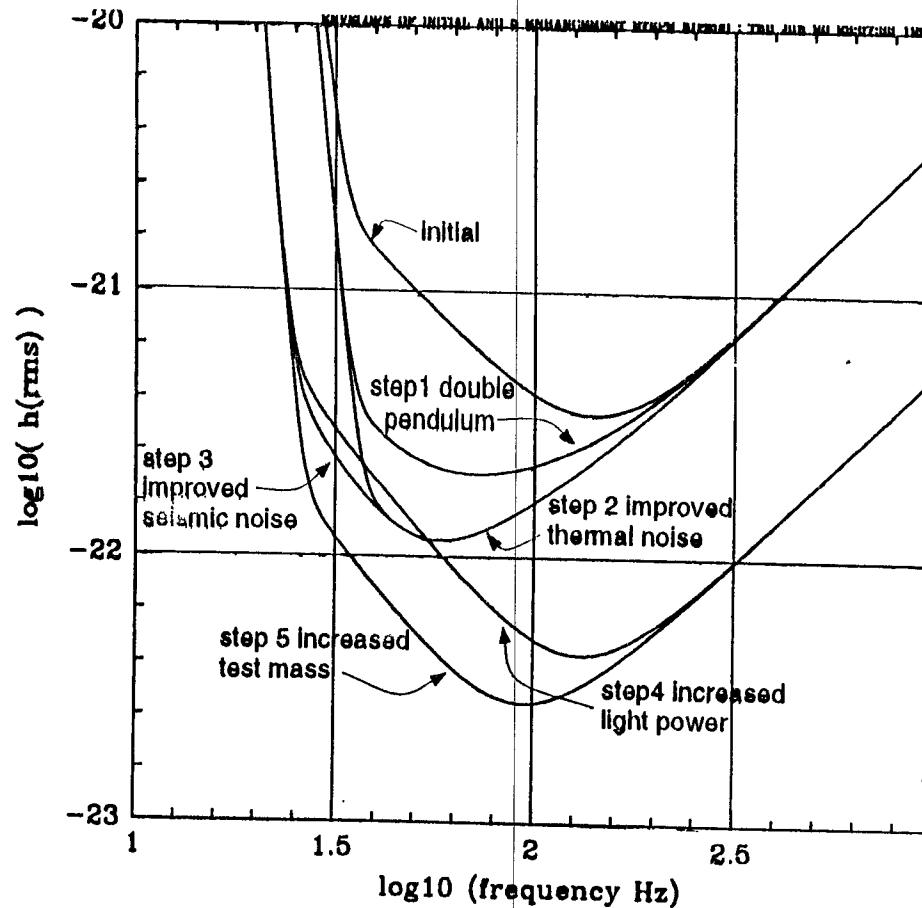


Evolution

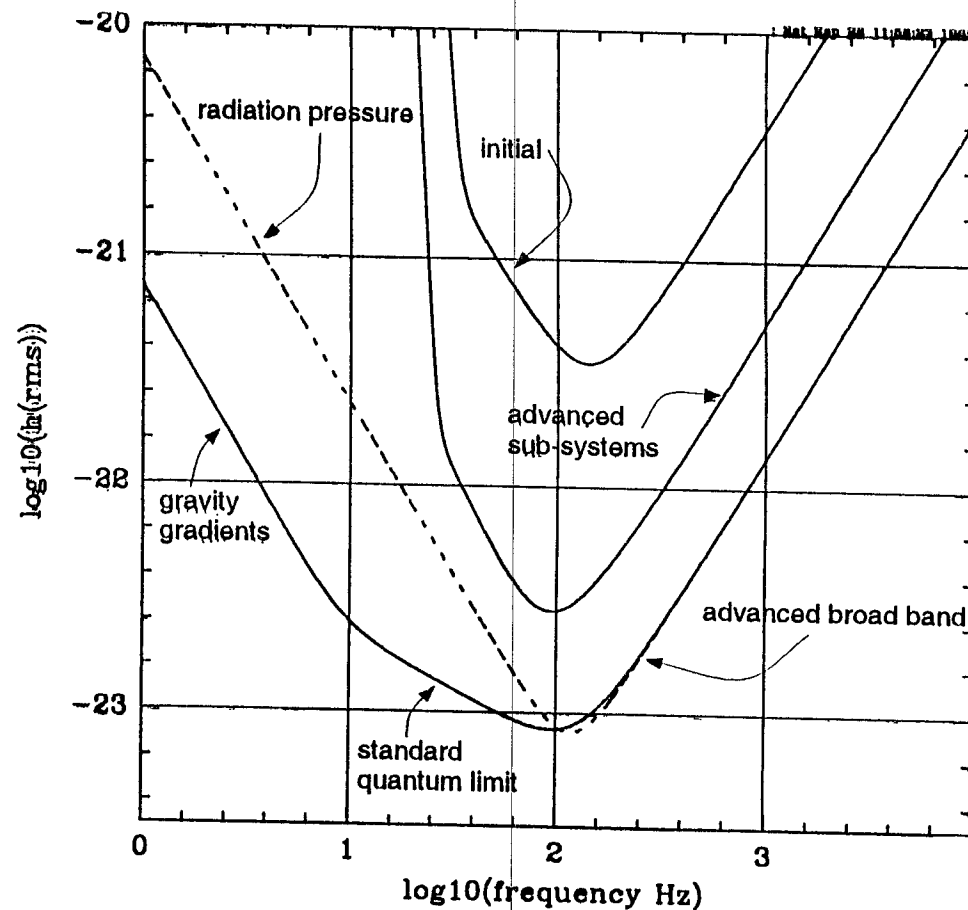
- LIGO Project - 1994
 - LIGO Research Community - 1995
 - Collaborative Advanced R&D proposals - 1996
 - collaboration and Collaboration
 - LIGO I and LIGO II - 1997
 - LIGO Laboratory - 1997
 - LIGO Scientific Collaboration - 1997
-
- Caltech/MIT LIGO Advanced R&D program will focus on delivering technology basis for LIGO II detector system
 - ››replacing the “Advanced Subsystems” and “Advanced Detectors” framework of last year



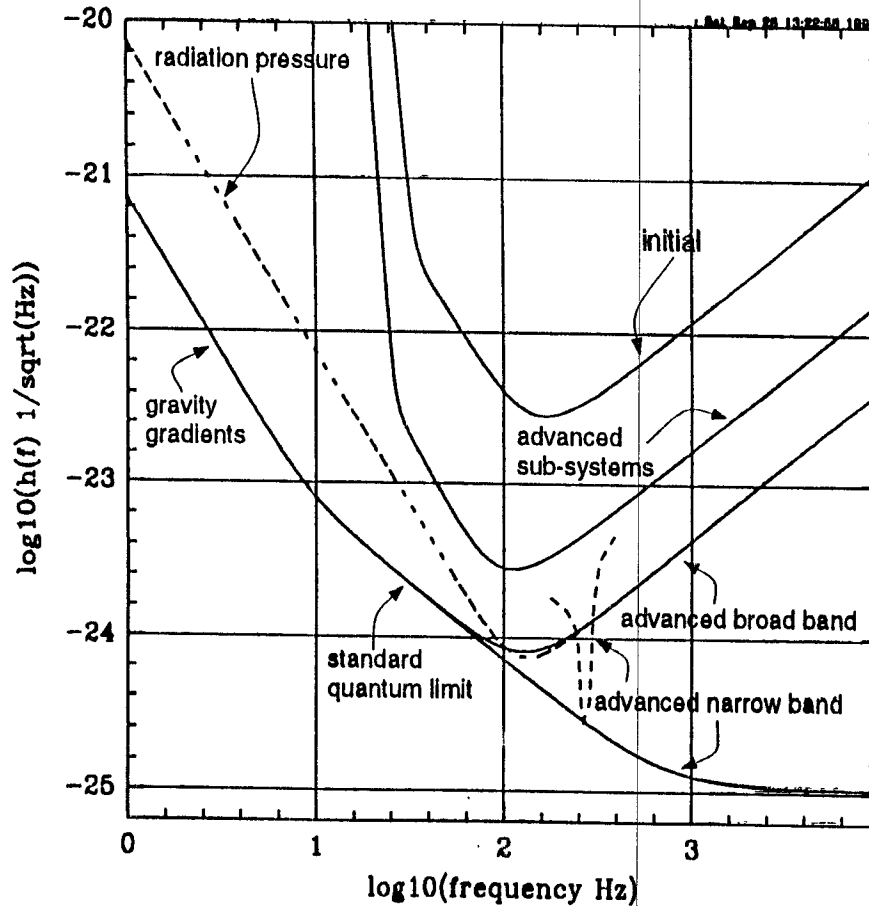
Steps in the Advanced Subsystems Research



h_{rms} Noise Envelopes for Initial LIGO and Advanced Subsystems/Detectors



Amplitude Spectral Strain Noise Expressed as an Equivalent $h(f)$



Development of Higher Power Lasers

- Motivation and Goal

- ›› Higher laser power is an important path toward improved phase sensitivity, leading to better GW sensitivity in shot noise limited regime (above ~150 Hz)

- ›› Build one or more 100 W Nd:YAG lasers and test their stability and suitability for LIGO control

- ›› Model and understand their characteristics, including frequency noise, intensity noise, pointing stability, and beam quality

- Background and Previous Research

- ›› 10 W Nd:YAG laser currently under development

- Collaborative development with Lightwave Electronics
 - MOPA configuration, side-pumped rod geometry
 - Could serve as first stage for 100 W laser

- ›› Superiority of zig-zag slab geometries established for higher powers (greater than 10's of Watts)

- ›› Models under development for MOPA and stable-unstable resonator optical configurations



Development of Higher Power Lasers (continued)

- Collaborators and Responsibilities

- ›› LIGO

- Interferometer modelling to develop requirements
 - Participate in testing with Galileo and ACIGA
 - Possible work with Lightwave

- ›› Galileo (Stanford)

- Fabricate and test high power MOPA

- ›› ACIGA (Adelaide)

- Continued development of stable-unstable resonator design

- ›› GEO

- ?



Development of Higher Power Lasers (continued)

- Work Plan and Schedule

- ›› Evaluate performance of 10 W LIGO laser -- 3/98 (LIGO, Galileo)
- ›› Develop laser requirements for LIGO-II interferometer -- 7/98 (all)
- ›› Build 40 W stable-unstable resonator laser -- 12/98 (ACIGA)
- ›› Characterize 40 W stable-unstable resonator laser -- 5/99 (ACIGA, LIGO)
- ›› Upgrade to 100 W stable-unstable resonator laser -- 12/00 (ACIGA)
- ›› Characterize 100 W stable-unstable resonator laser -- 5/01 (ACIGA, LIGO)
- ›› Build 40 W MOPA laser -- 12/98 (GALILEO)
- ›› Characterize 40 W MOPA laser -- 5/99 (GALILEO, LIGO)
- ›› Build 100 W MOPA laser -- 6/00 (GALILEO)
- ›› Characterize 100 W MOPA laser -- 12/00 (GALILEO, LIGO)
- ›› Decision on LIGO-II high power laser configuration -- 9/01 (all)



Optics For Higher Power

- **MOTIVATION**

- ›› Reduce Shot noise by decreasing cavity loss due to surface structure, surface and bulk absorption, and degradation.

- **BACKGROUND AND PREVIOUS RESEARCH**

- ›› LIGO Pathfinder has generated momentum in industry for production of high quality optics. This momentum can be maintained with the following development programs while valuable resources are still available.

- **WORK PLAN**

- ›› Surface Loss

- Coating Uniformity development. Investigation of alternate Coating Materials.

- Polishing development. Improvement in Figure as well as supersmoothing.

- Metrology development to support Coating and Polishing improvements.

Optics For Higher Power

Work Plan, continued

>>Bulk Absorption

- Material Development. Industry is considering production of Low absorption glass
- Investigate active compensation for thermal lensing

>>Degradation Loss

- Investigate Surface and Bulk damage mechanisms in high CW fields
- Investigate contamination processes, prevention and cleaning

• COLLABORATORS, RESPONSIBILITIES AND SCHEDULE

>>LIGO/Industry: Coating, Polishing, Metrology

- Small scale development in parallel with LIGO Fabrication, Large Scale applications beginning early in 1999.

>>LIGO/Eastern Michigan/Industry: Low loss material

- Test and development 1998, 1999. Full scale test 2000

Optics For Higher Power

Collaborators, Responsibilities... continued

>>LIGO: Investigate active compensation, damage mechanisms and contamination processes.

—3 year program beginning in 2000

Adaptive Core Optics

- Problem: LIGO I sees thermal effects at 10 W laser power.¹
> 100 W required for “Advanced” shot noise sensitivity.
- Several thermal effects foreseen:
 - cavity mode distortion --> poor coupling
 - differential cavity mode mismatch --> contrast defect
 - recycling cavity sideband loss for power-recycled Schnupp scheme
- Several strategies proposed:
 - Insensitive configuration (RSE), readout (all-resonant SB, no resonant SB)
 - lower bulk- and surface-loss, CTE, dN/dT and higher κ_{th} optics
 - Adaptive Core Optics

1. Recycling mirror curvature specifications must counteract calculated ITM thermal lens to avoid significant performance penalty.

Research Program Components

- Modeling
 - Couple quasi-static thermal FEA with FFT-based and/or modal expansion-based optical mode propagation (a portion of Adv. Configs. research topic)
- Sensing research
 - Modified Shack-Hartmann sensors
 - “Super Wavefront Sensor” (SWFS)
 - > “bull’s eye” RF detectors and rectilinear PD arrays
 - > strobed video detect/demod methods
 - Dithering & synchronous image processing
- Actuation research
 - scanned auxiliary (‘heater’) laser (e.g., CO₂; highly general, “brute force”)
 - radiative coupling control (e.g., filaments & low- ϵ shields; “finesse”)

Sapphire for Advanced LIGO

- Motivation: Superior bulk material properties.

- ›› Thermal noise: $dz_{\text{rms,thermal}} \sim (\rho v_{\text{sound}} Q)^{-1/2} \sim .06x \text{ Silica}$

- $\rho = \text{density} \sim 1.9 x \text{ fused silica}$

- $v_{\text{sound}} \sim 1.8 x \text{ fused silica}$

- $Q_{\text{mechanical}} \text{ demonstrated} > 50 x \text{ typical fused silica}$

- ›› Thermal lens: dominant (trans.) distortion $\propto \beta/\kappa \sim .05x \text{ Silica}$

- $\beta = d(\text{refractive index})/dT \sim 2 x \text{ fused silica}$

- $\kappa = \text{thermal conductivity} \sim 45 x \text{ fused silica}$

- ›› TM mass: quantum limit $\sim \text{Mass}_{\text{TM}}^{-1/2}$

- ›› Mechanical design flexibility potential: modulus $\gamma \sim 5x \text{ Silica}$

- Monolithic suspensions, attaching directly to TM

- Reduced suspension induced optical distortion.

- Goal: LIGO I sized sapphire without retreat from Silica features:

- ›› Large area precision superpolish.

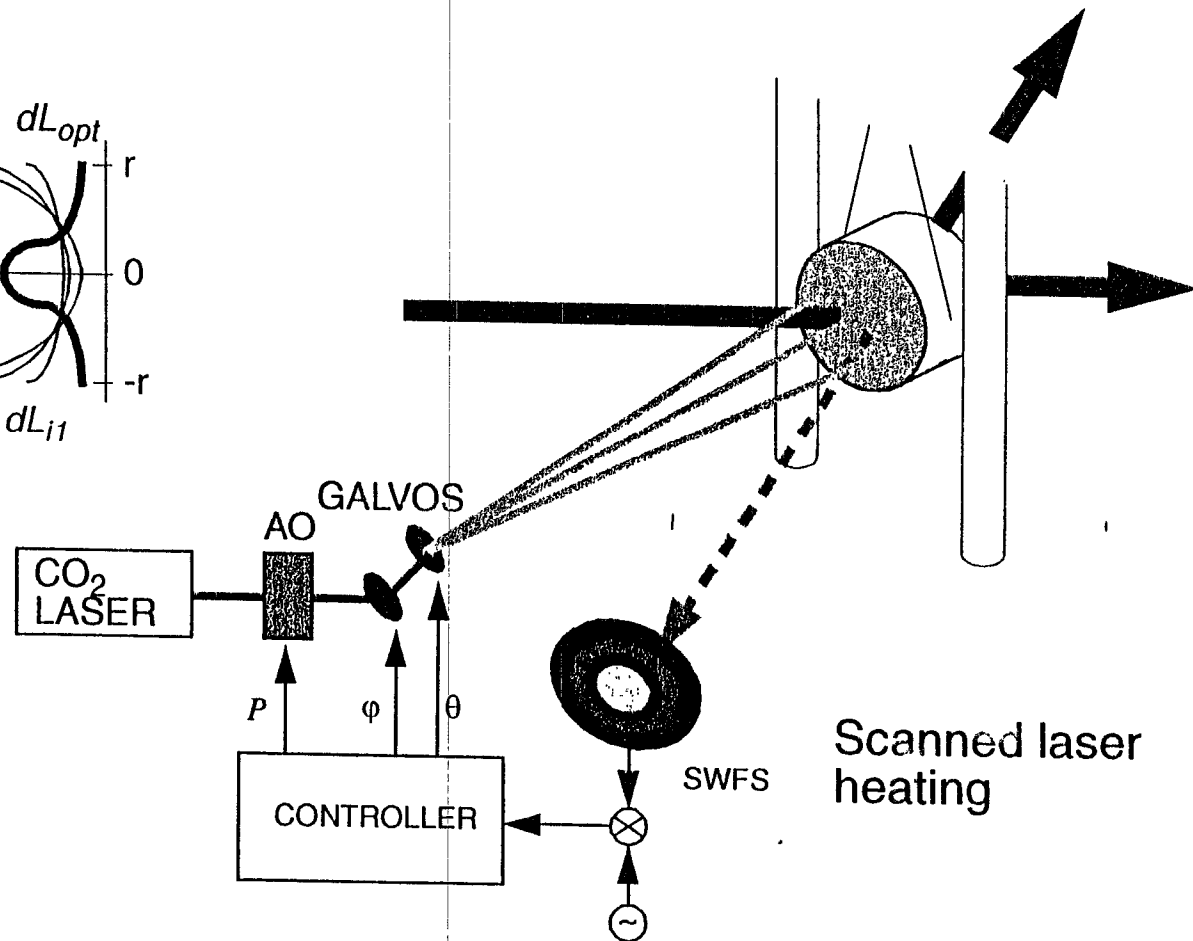
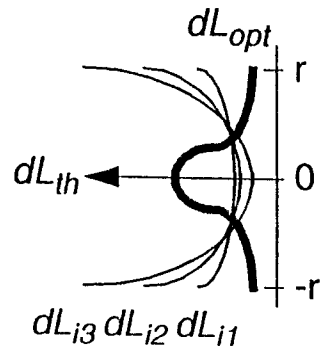
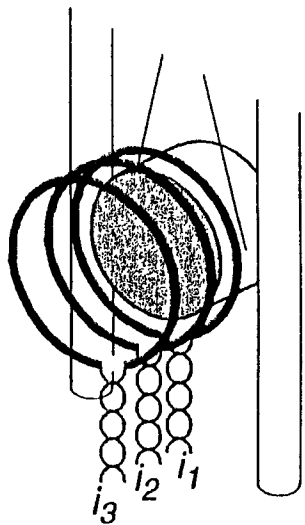
- ›› High, large volume, optical uniformity ($\Delta n_{\text{effective}} < 5 \times 10^{-7}$)

- ›› Low volume absorptivity @ $1.06 \mu\text{m}$ ($< 5 \text{ ppm/cm}$)



Actuation concepts (prelim.)

Radiative load tailoring



Sapphire for Advanced LIGO

- Prospect: individual samples ($< \phi$ 8cm) have already demonstrated these goals.
- Present status: contract (Crystal Systems) and MOU (SIOM, Shanghai) to produce ~half size blanks (along azimuthally uniform “c” axis)
 - ›› Use Pathfinder related metrology to evaluate vs fused silica
 - ›› reproducible high bulk uniformity (difficult for “c” axis growth) and low absorption of particular concern.
- Further necessary R&D
 - ›› Pathfinder like program to identify polish process (comparable to LIGO I, fused silica).
 - ›› Similar coating development program (coef. thermal expansion $> 10x$ silica presents new challenge for large area multi-layer coatings).
 - ›› Problem of TM attachments: engineer new approach.
 - “Dressed” Q test bed



Advanced Control Techniques (Adv. R&D Proposal)

- Motivation

- ›› Detection Mode Control System design for LIGO assumes that optical parameters don't drift---but they do (changes due to misalignment, mirror degradation, etc.)
- ›› Resulting performance and robustness of interferometer is sub-optimal

- Proposal

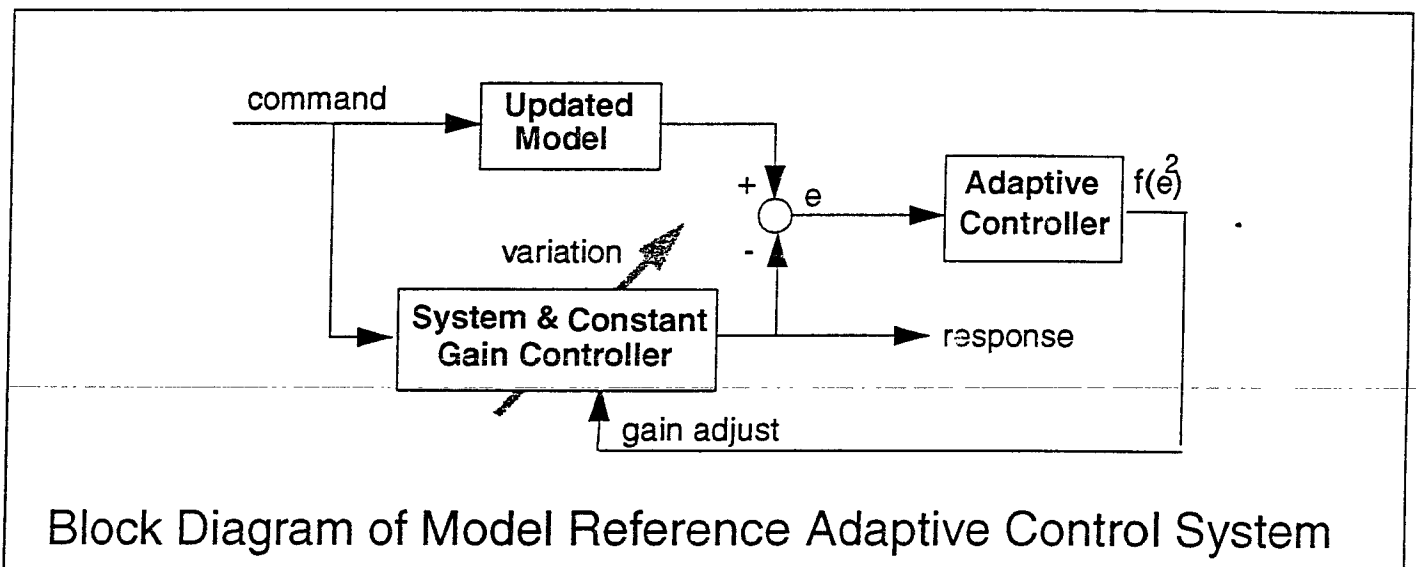
- ›› Use Adaptive Control and System Identification to keep interferometer locked indefinitely with optimal performance
 - Adapt Parameters in Detection Mode Length Control System to improve performance and robustness
 - Identify physics of why interferometers unlock (little fundamental understanding of unlocking mechanisms)
 - Design adaptive controller to desensitize interferometer to unlocking mechanisms



Advanced Control Techniques (contd. 2)

- Background and Previous Research

- ›› Large body of literature on Adaptive Control and System ID (Astrom and Whittenmark, Widrow and Stearns, etc.)



- Research Plan

- ›› Caltech 40 m prototype as testbed
 - System ID studies to identify drifting optical plant matrix
 - Adaptive control design testbed for Detection Mode controller
 - Study mechanisms that throw interferometer out of lock and propose ways to eliminate problem

LIGO Lab 'Stochastic Forces' Research

David Shoemaker

Research that targets physical motions of the test masses

- thermal noise
- seismic noise
- 'excess' noise - e.g., stress release
- control forces and hierarchies to allow interferometer 'locking' and operation

Principal focus: LIGO II, ~2003

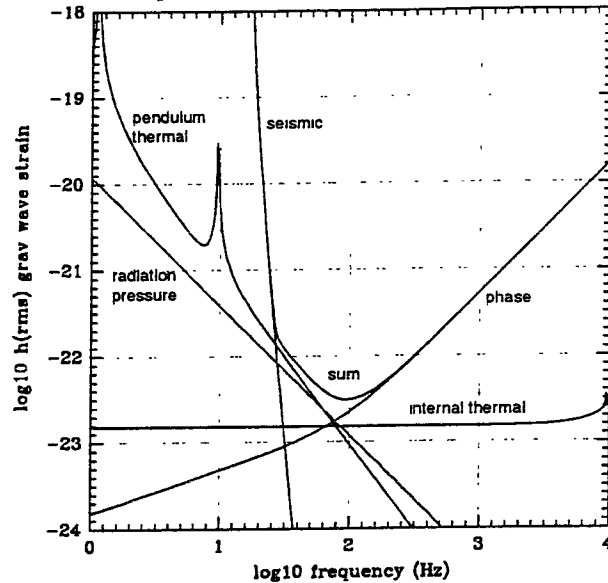
- double pendulum suspension for test mass
 - > possible changes in test mass material (sapphire??)
 - > certainly changes in fibers (probably fused quartz)
- associated changes in rest of system
 - > some damping/taming of LIGO I passive isolation
 - > active isolation, probably external to vacuum
 - > control hierarchy to get signals away from test masses

Collaboration an important aspect of this work

- GEO, Stanford, JILA, Syracuse, PSU, LSU, Moscow
- our plan designed to be complementary
- capitalize on LIGO experience and infrastructure

Structure of LIGO Lab effort

1) Approach problem from a 'systems' view



- establish the performance requirements (baseline: 'Advanced Subsystems')
- determine the site environment, constraints from existing systems
- learn what is good in present LIGO suspension designs
- learn from collaborators what conceptual designs work

2) Modeling

- combine environmental info, LIGO I suspension characterization, concepts
- refine concepts; special effort to reduce/eliminate test mass actuation
- generate design questions to be answered by experiments

3) Control and configuration prototyping:

- build up low-performance partial suspension prototypes, in-air or bell jars
- tests for actuation, dynamics, practical questions (alignment)

Prototype studies of thermal/excess noise

Trial designs need noise testing at design sensitivity

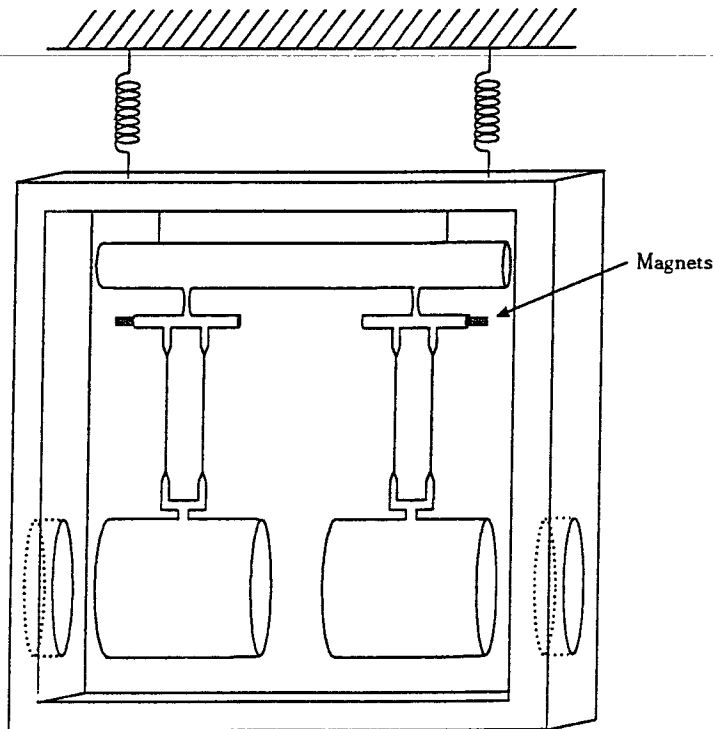
- creaking, actuator noise/coupling, and thermal noise

Special purpose interferometer

- targets displacement noises
- designed to suppress sensitivity to environment
- no attempt to reach phase or strain sensitivities; not a michelson

Configuration

- short (mm) test cavity, longer referece cavity to hold down frequency noise
- built inside single vacuum chamber, on common seismic isolation 'stack'
- will test partial suspension systems in iterative development phase



Testing of Suspension Systems

Systems are a key issue in suspension design

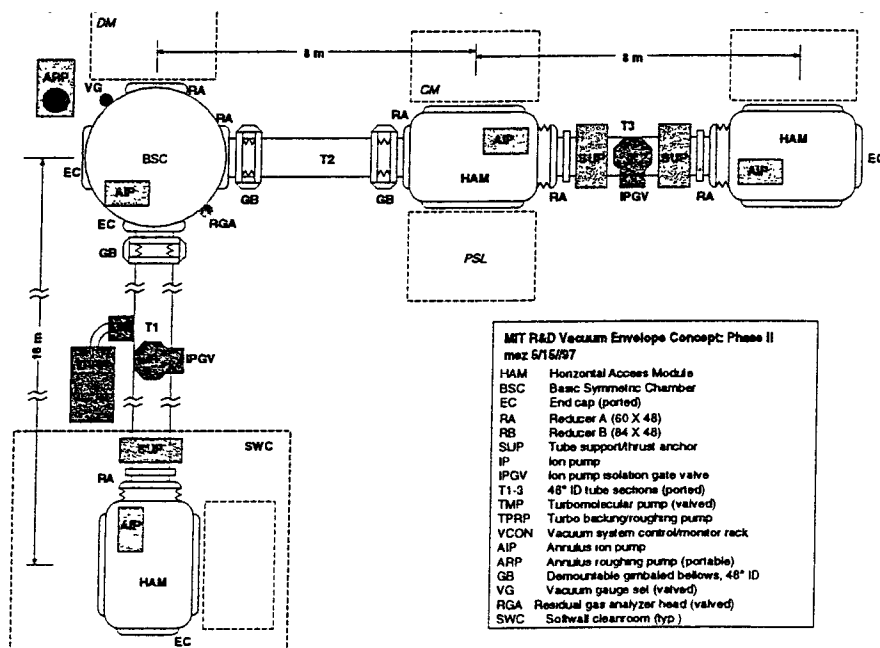
- some tests must include the dynamics of the entire isolation system
- scaling laws helpful, but actual placement of resonances, coupling critical
- need a test facility which includes all LIGO components from ground up

Full-scale tests of prototypes

- single suspensions for actuator, control tests
- pairs of suspensions for transfer functions, pointing
- complete interferometers for end-to-end tests, including noise performance

Pre-installation testing

- as a 'last stop' before LIGO
- minimize down time at the sites; practice installation and debugging



Milestones

Significant milestones in design process

- establishing requirements, interfaces, design constraints (~now)
- determining the state of the art, lessons from initial LIGO
- conceptual design (1998)
- construction and test of lab prototypes of aspects of design (1999)
- initial complete prototype testing (2000)
- test of final design (2001)
- qualification of suspensions to be installed (2002)

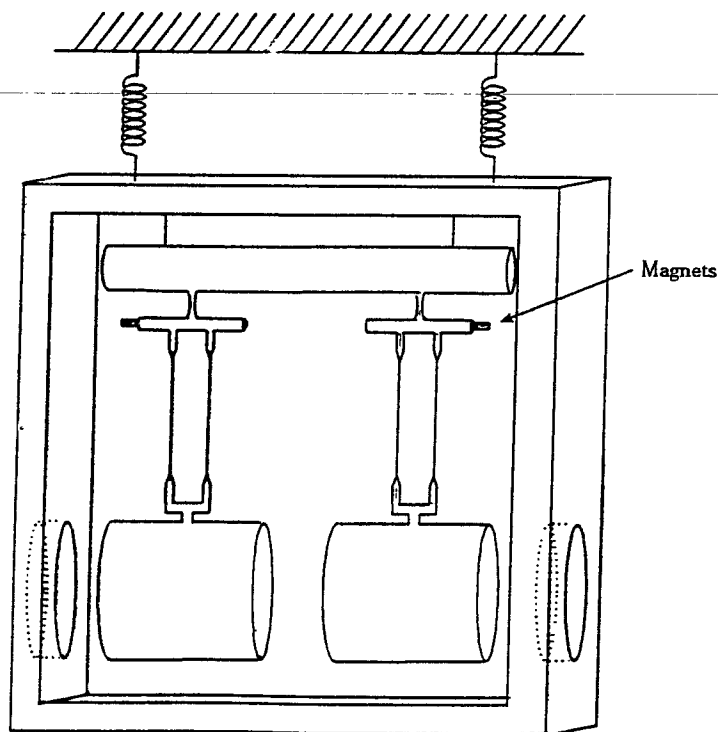
The Thermal Noise Interferometer

- Caltech - Ken Libbrecht, Eric Black
- The TNI Concept:
 - ›› A Suspended Interferometer for Direct Measurement of Displacement Noise
 - instrument optimized for displacement noise measurements
 - direct determination of overall displacement noise performance
- The Need for Direct Displacement Noise Measurements:
 - Far-Off-Resonance Thermal Noise Hasn't Been Adequately Measured
 - The Possibility of a Non-Uniform Material Loss Function (e.g. from coatings) adds Uncertainty to Thermal Noise Calculations. Measuring Q is not sufficient for calculation of thermal noise.
 - Can Directly Measure Excess Noise (e.g. from material creep)
 - Examination of Potential Technical Noise Sources: actuator noise, mass charging, etc.
 - Test and Characterize Advanced LIGO Masses before Installation



TNI Test Masses -- Mark I

- >> short cavity lengths --> reduced laser stability requirements
- >> high finesse --> low shot noise (along with small cavity storage time)
- >> convex/concave cavity geometry --> large beam spot size
- >> welded silica double suspension --> low thermal noise
- >> single bar suspension --> common-mode rejection of seismic noise



Signal Recycling and Resonant Sideband Extraction I

- Motivation

- ›› Narrow band operation - better sensitivity with reduced bandwidth

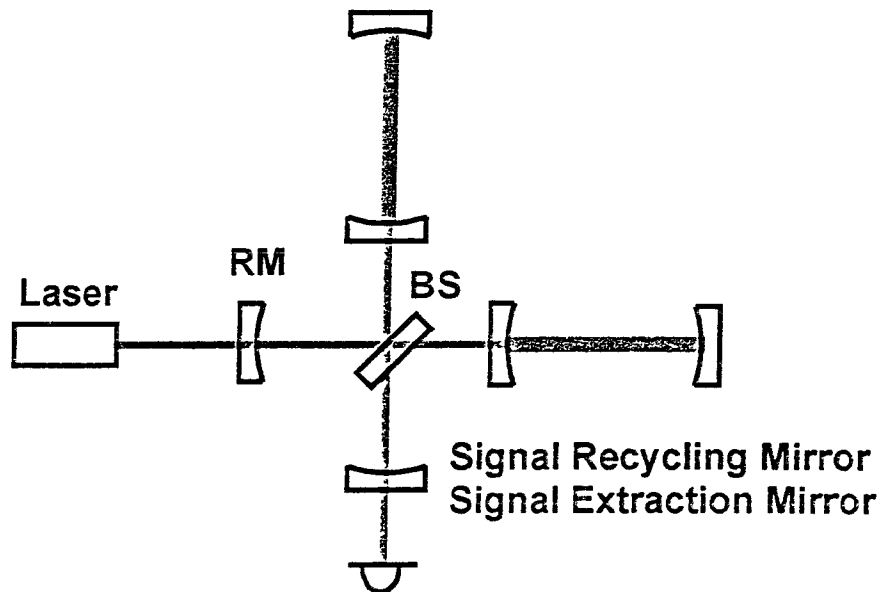
- Background

- ›› **Signal Recycling** (Invented by B. Meers)

- Signal recycled by signal recycling mirror

- ›› **Resonant Sideband Extraction** (Invented by J. Mizuno)

- Signal extracted by signal extraction mirror



Signal Recycling and Resonant Sideband Extraction II

- Previous Research

- » Experiment done by non-ideal configuration for LIGO

- No arm cavities for SR, No recycling mirror for RSE
- External modulation

- Work Plan

