

R&D Overview

David Shoemaker

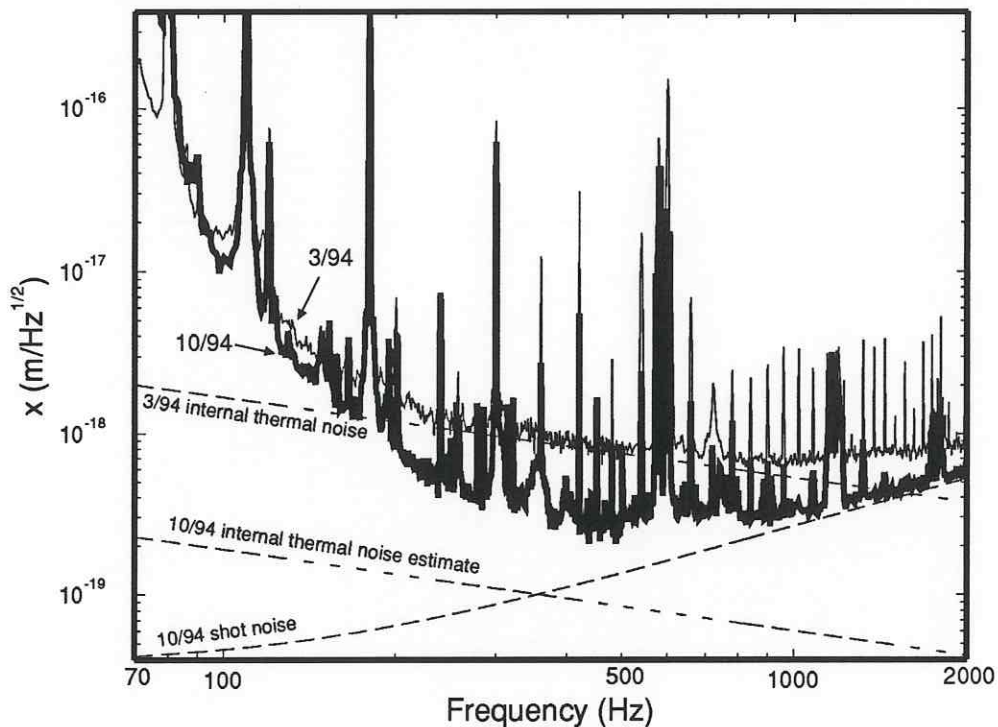
NSF LIGO Review 22 May 95

- Overall Goal of R&D: Support detector technology
 - > close coordination with Detector
 - > tasks and schedules planned to deliver information when needed
- Highlights of R&D Program since September review
 - > more detailed reports tomorrow, 23 May
- Cost and Schedule overview

40m Interferometer Research

THERMAL NOISE STUDIES (Thesis for Aaron Gillespie)

- thermal noise of substrate, pendulum significant for LIGO
 - › no direct experimental observations to verify models
 - › opportunity to observe in 40m by changing test masses
- thermal noise in compound test masses carefully calculated
 - › measurements on 40m in good agreement
- new monolithic masses studied separately
 - › coupling of control/sensing magnets/fins, suspension wires...
- installed in 40m
- new (improved!) spectrum consistent with thermal noise model



40m Interferometer Research (con't)

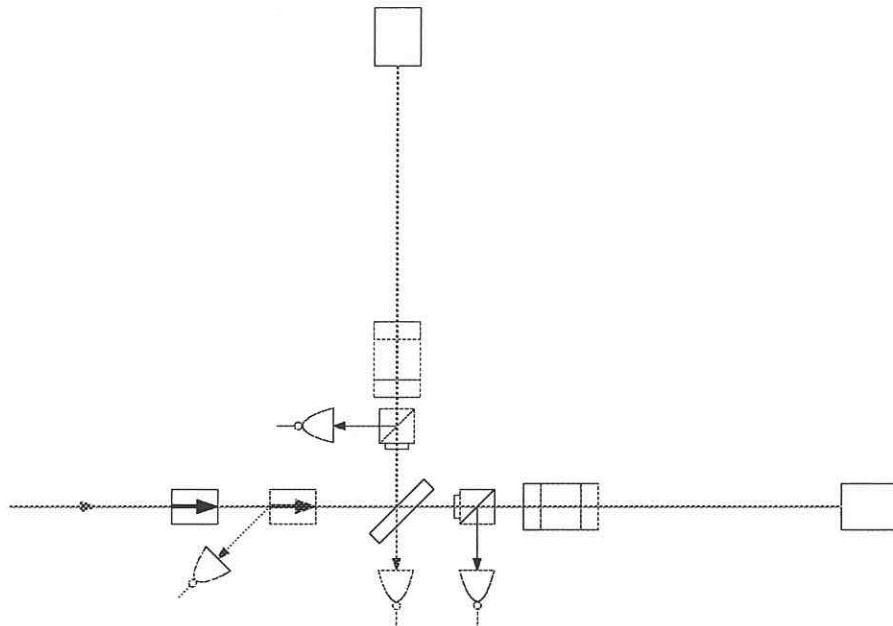
WRAP-UP OF '94 CONFIGURATION CHARACTERIZATION

- long data streams (28 hours)
 - › most interferometer data to date in form of spectrum
 - › time series more important for real data analysis
 - › non-gaussian statistics
 - › operational issues
 - › analysis for coalescing binaries
- pre-'95 configuration 'done'

40m Interferometer Research (con't)

RECOMBINATION RECONFIGURATION

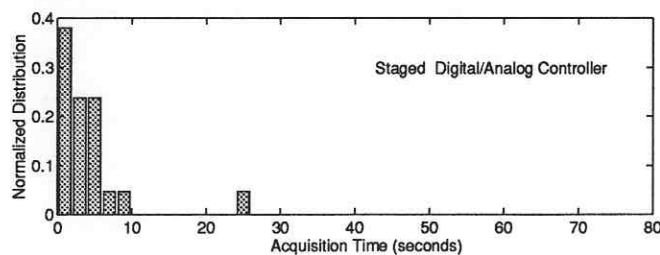
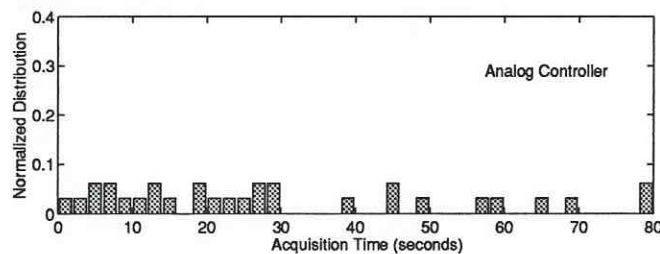
- modeling of LIGO configuration well advanced
- very eager to have experimental verification
 - > tests of acquisition and linear control modeling and procedures
 - > improved common-mode noise rejection for displacement studies
- status
 - > arms asymmetrized for modulation technique
 - > arm beams brought to interference on beamsplitter
 - > major changes made, debugging/realigning
 - > first interference and locking tests underway



40m Interferometer Research (con't)

GUIDED-LOCK ACQUISITION

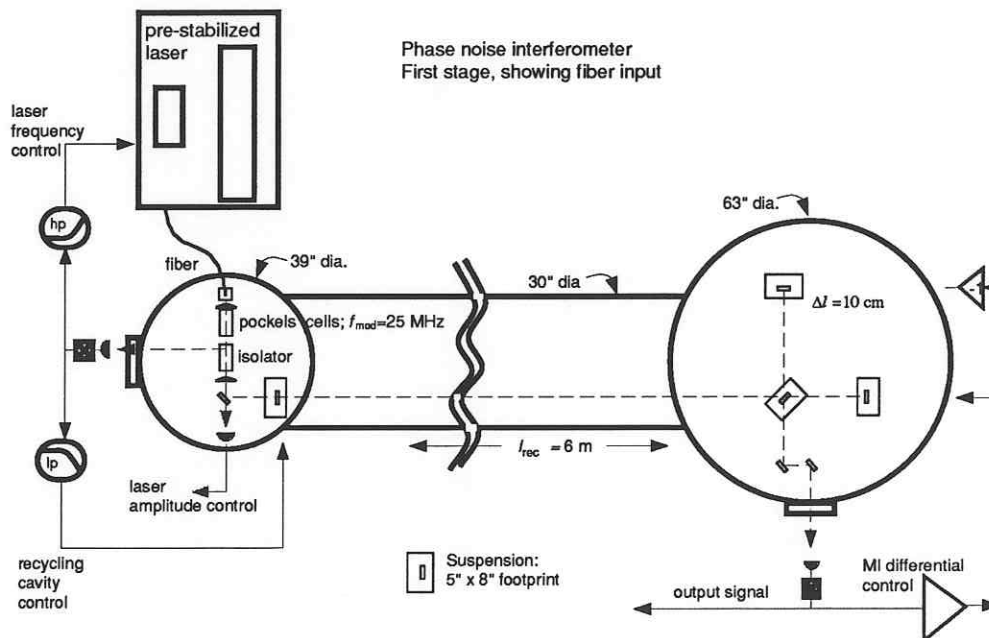
- traditional brute-force method for acquiring 'lock' of cavity
 - › system moves very quickly through resonance - non-adiabatic
 - › very wide-bandwidth, high-force servo control
 - › short effective duty-cycle
- better idea: reduce test-mass velocity
 - › analyze signal output in time domain of unlocked system
 - › calculate relative velocity of test masses
 - › apply force X duration to 'brake' masses
 - › THEN acquire lock
- success
 - › considerably reduced locking time
 - › valuable information for locking strategies
 - › good technical experience for hardware/software



Phase Noise Research

OBJECTIVES

- displacement sensitivity under study in 40m
- LIGO requires also high phase sensitivity (10^{-10} rad/ $\sqrt{\text{Hz}}$)
 - > present 40m uses ~ 130 mW
 - > Garching interferometer functioned with 1 W
 - > LIGO requires roughly 75 W
- PNI will demonstrate this sensitivity, at this power
 - > confirms shot-noise formula
 - > solve many technical problems along the path
 - > non-recycled Michelson initial configuration; recycling mid-95



Phase Noise Research (con't)

INTERFEROMETER CONSTRUCTION

- seismic isolation stacks
- vacuum system modifications
- mirror suspensions and control systems
- laser frequency stabilization
- soft-wall clean rooms

STATUS

- first interference observed!
- characterization in air of sensing/control
- close to pumpdown, first low-noise measurements

Phase Noise Research (con't)

CHARACTERIZATION OF ACTIVE ISOLATION SYSTEM

- 'beta' test of commercial system
 - › active servo system, measures ground noise, feedback
 - › six degrees of freedom
 - › at MIT, suppresses local non-stationary noise (trucks, subways...)
 - › for LIGO, can reduce controller dynamic range, up-conversion
- system functional
 - › required collaborative work between Barry, Inc. and LIGO staff
 - › significant reduction in noise: factor 100 in vertical, 2-30 Hz
 - › still short of prediction in horizontal, but
 - › makes qualitative difference in seismic environment

Some other significant R&D efforts

TABLE-TOP CONFIGURATION STUDIES

- definition of initial LIGO (Thesis for J. Giaime)
- wavefront sensing research
 - > first complete test of proposed length control system
 - > development of design process for LIGO
 - > detailed test of alignment sensor/control system

NUMERICAL OPTICS MODELING

- predictions of signal/noise for real mirror maps
 - > leads to specifications for LIGO mirror figure
- working toward studies of advanced configurations
 - > good graduate student thesis

SUSPENDED MODE CLEANER

- major review on 21 April
 - > culmination of design, construction, characterization
- preparation for moving to 40m lab well underway

TEST MASS 'Q' MEASUREMENTS

- characterization of internal, suspension thermal noise
- initial measurements just starting
 - > scaling of Q appears to be understood

Organization, Schedule and Cost

ORGANIZATION, TRACKING

- Stan Whitcomb (leader), David Shoemaker (deputy)
 - › both look across project R&D
 - › deal with local opportunities, problems locally
- goals, means, milestones negotiated in yearly SOWs
- monthly reports from major tasks
- take earned value for milestones achieved

STATUS

- most projects on schedule, some several-week delays
- delays mostly 'R&D' causes
 - › discoveries requiring new procedures/meriting further research
 - › longer debugging/analysis times
- no present/anticipated delays with impact on LIGO schedule

COST

- standard report includes history of R&D
 - › big offset from previous years cost/performance
 - › fractional variances small
- more detailed study shows good budget/performance

Start: 01Apr95
 Finish: 01Apr95
 Time Now: 01Apr95
 Project: Untitled #1
 Run: 18May95
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Milestone
 BaselineMS



Research & Development



Open Plan Professional by Welcom Software

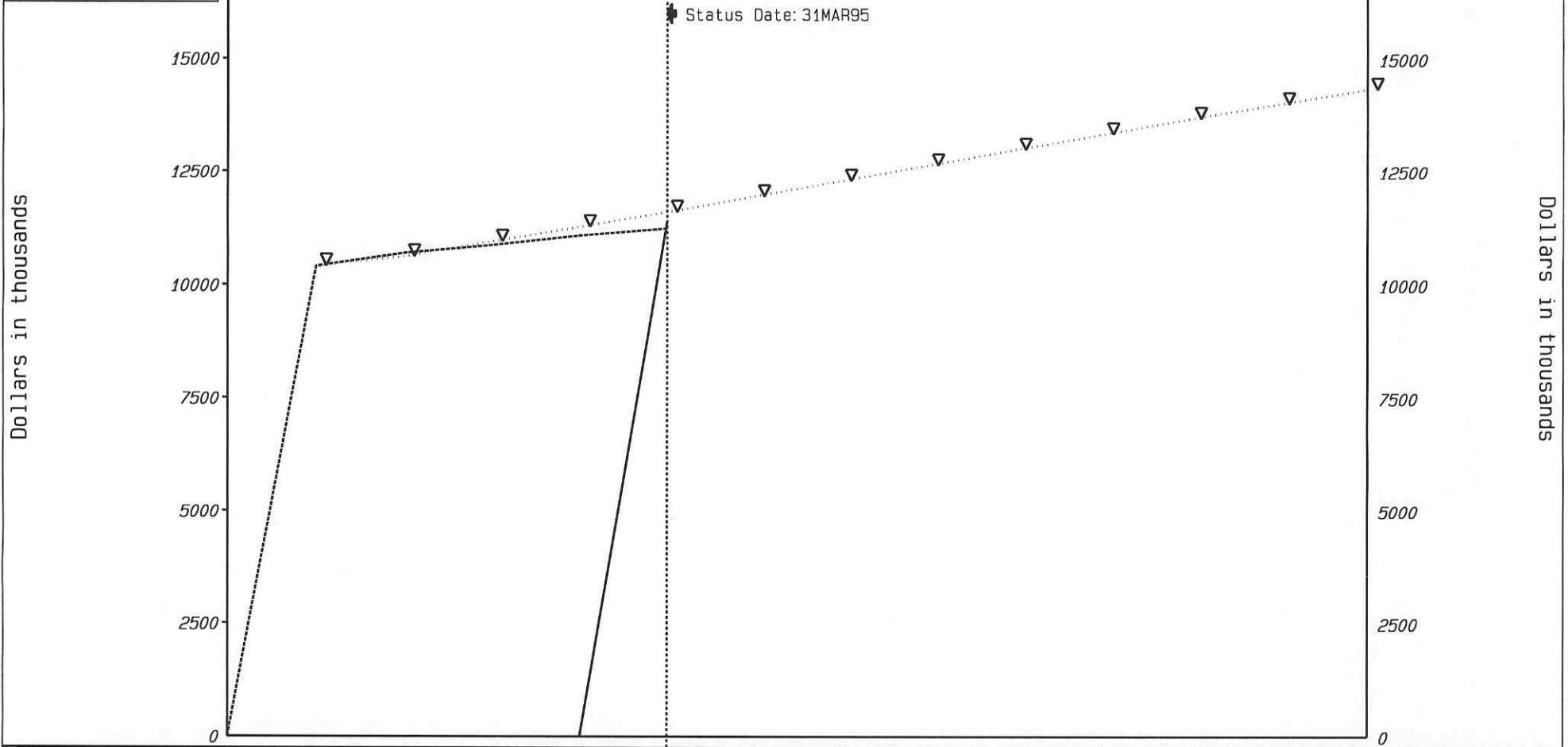
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			Ja	Ap	Jul	Oc	Ja	Ap	Jul	Oc	Ja	Ap	Jul	Oc	Ja	Ap	Jul	Oc	Ja	Ap	Jul	Oc	Ja	Ap	Jul	Oc	Ja	Ap	Jul	Oc	Ja	Ap	Jul	Oc	
13220905	PFQ T/M FIXT INITIAL FIT-CHCK (UNBAKD)	1.3.2.2.7													▲22Dec94 ★22Dec94																				
13220910	PFQ BAKED TEST MASS FIXTURE READY	1.3.2.2.7													▲20Jan95 ★20Jan95																				
13220915	PFQ VACUUM TEST COMPLETE	1.3.2.2.7													▲10Feb95 ★10Feb95																				
13220920	PFQ E/S DRIVE BOARD/CABLNG ELEC TST COMP	1.3.2.2.7													▲09Nov94 ★09Nov94																				
13220930	PFQ FIRST Qs-SIMPLE SINGLE LOOP SUSP	1.3.2.2.7													▲05May95 ★05May95																				
13220935	PFQ CHARACTERIZATION MEASUREMENTS COMP	1.3.2.2.7													▲13Jun95 ★13Jun95																				
13220940	PFQ MEASUREMENT RESULTS ANALYZED	1.3.2.2.7													▲26Jun95 ★26Jun95																				

LIGO PROJECT
1.3 Research & Development
Budget vs Performance vs Actual

LEGEND

Bud▽.....▽.....▽.....▽
Per	—————
Act	—————
ETC	—————

Schedule Performance Index= 98 Cost Performance Index= 102



	FY94	DEC94	JAN95	FEB95	MAR95	APR95	MAY95	JUN95	JUL95	AUG95	SEP95	OCT95	NOV95	SCALE
Budget	10,407	10,609	10,935	11,258	11,586	11,935	12,285	12,636	12,992	13,337	13,681	14,007	14,326	K\$
Performance	0	0	0	0	11,397									K\$
Actual/Forecast	10,407	10,683	10,854	11,069	11,225									K\$
Schedule Variance	-10,407	-10,609	-10,935	-11,258	- 189									K\$
Cost Variance	-10,407	-10,683	-10,854	-11,069	172									K\$

Schedule Variance = Perf-Budg Cost Variance = Perf-Actual Schedule Performance Index= Perf/Budg Cost Performance Index= Perf/Actual