



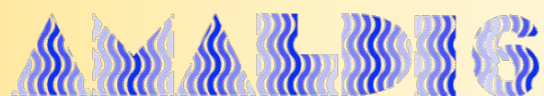
**LIGO**



# The Advanced LIGO detector

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Louisiana State University,  
for the **LIGO Scientific Collaboration**

40+ institutions, hundreds of people  $\Rightarrow$  it is difficult to give credit where due ...



24 June, 2005 LIGO-G050315-00-D

# Clippings from the NSF FY '06 budget request to the US Congress

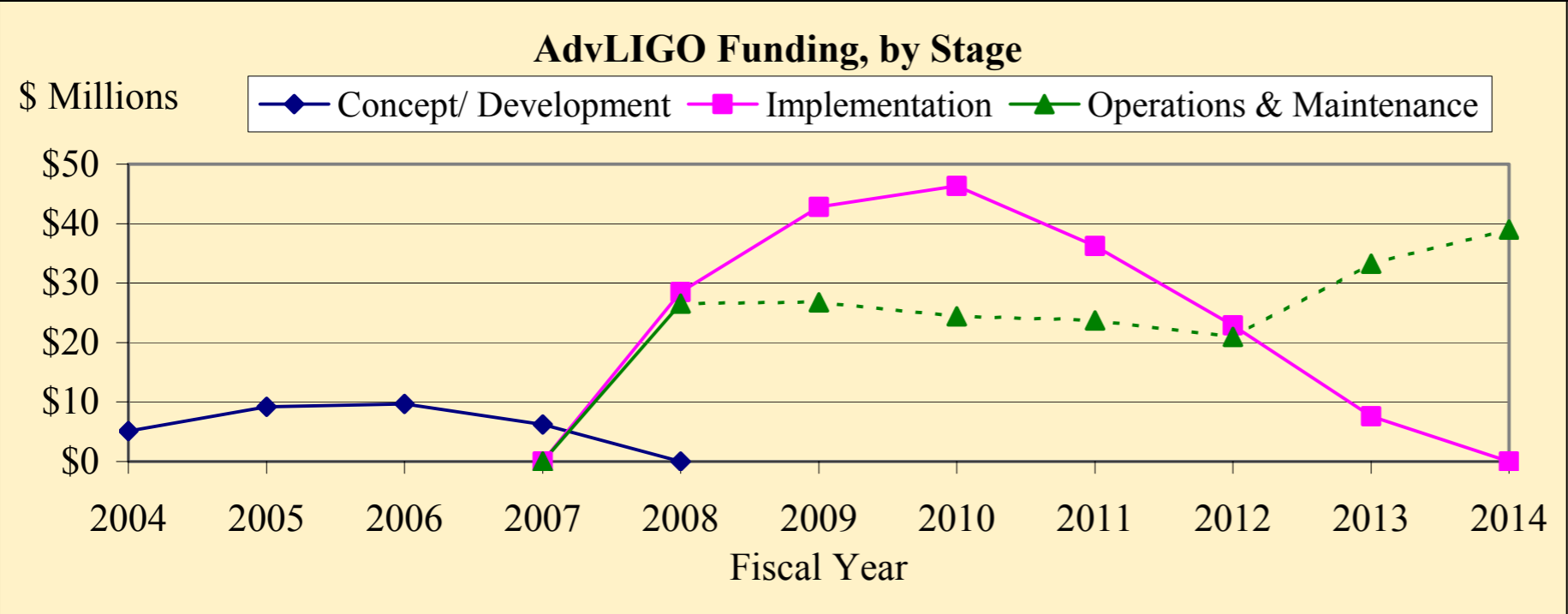
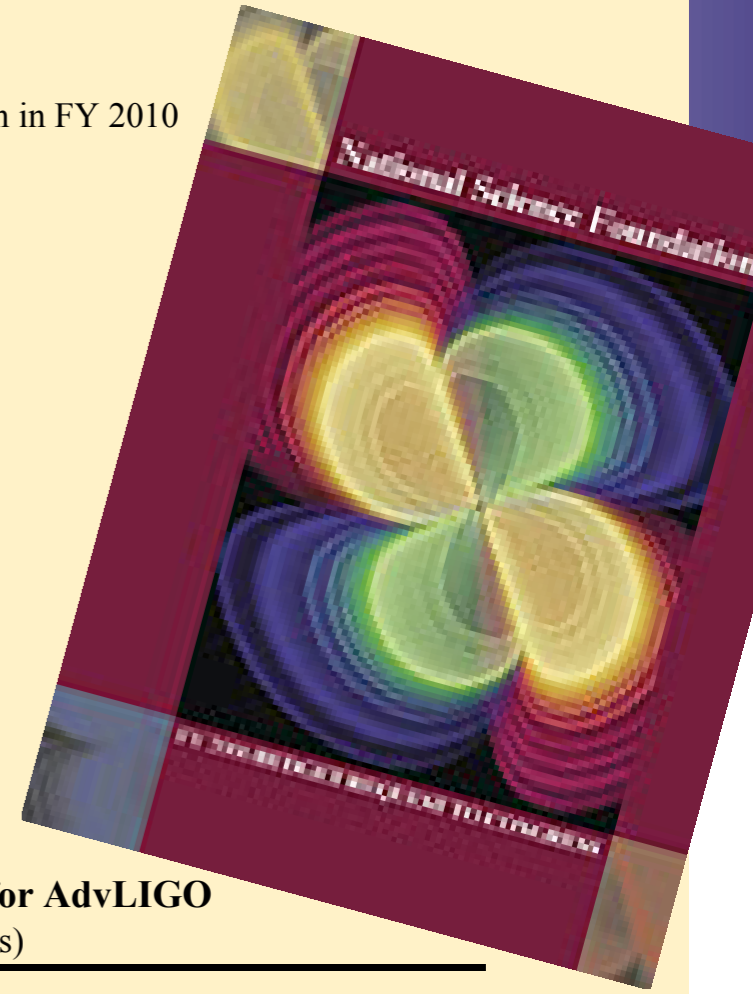
**FY08: funding begins**

**FY10: Livingston installation starts**

**FY12: Commissioning begins**

Major milestones for Advanced LIGO include:

- FY 2006-2007 Milestones:  
Finalize concept design and development of instrumentation
- FY 2008 Milestones  
Place orders for long lead time items such as test mass optics; continue design of remaining instrumentation
- FY 2009 Milestones:  
Acquisition of all components needed to begin installation in FY 2010  
Prepare for installation
- FY 2010 Milestones:  
Installation begins at Livingston
- FY 2011 Milestones:  
Installation begins at Hanford
- FY 2012 Milestones:  
Commissioning begins at Livingston  
Commissioning begins at Hanford
- FY 2013 Milestones:



**Needs for AdvLIGO**  
(in millions)

	FY 2012	FY 2013	Total
	\$22.90	\$7.60	\$184.35

onfile

# Partner contributions

- GEO/Germany

- ▶ Presidential board of the Max Planck Society has endorsed Albert Einstein Institute (AEI) plans for Adv LIGO material contribution, the **Laser** etc.

- GEO/U.K.

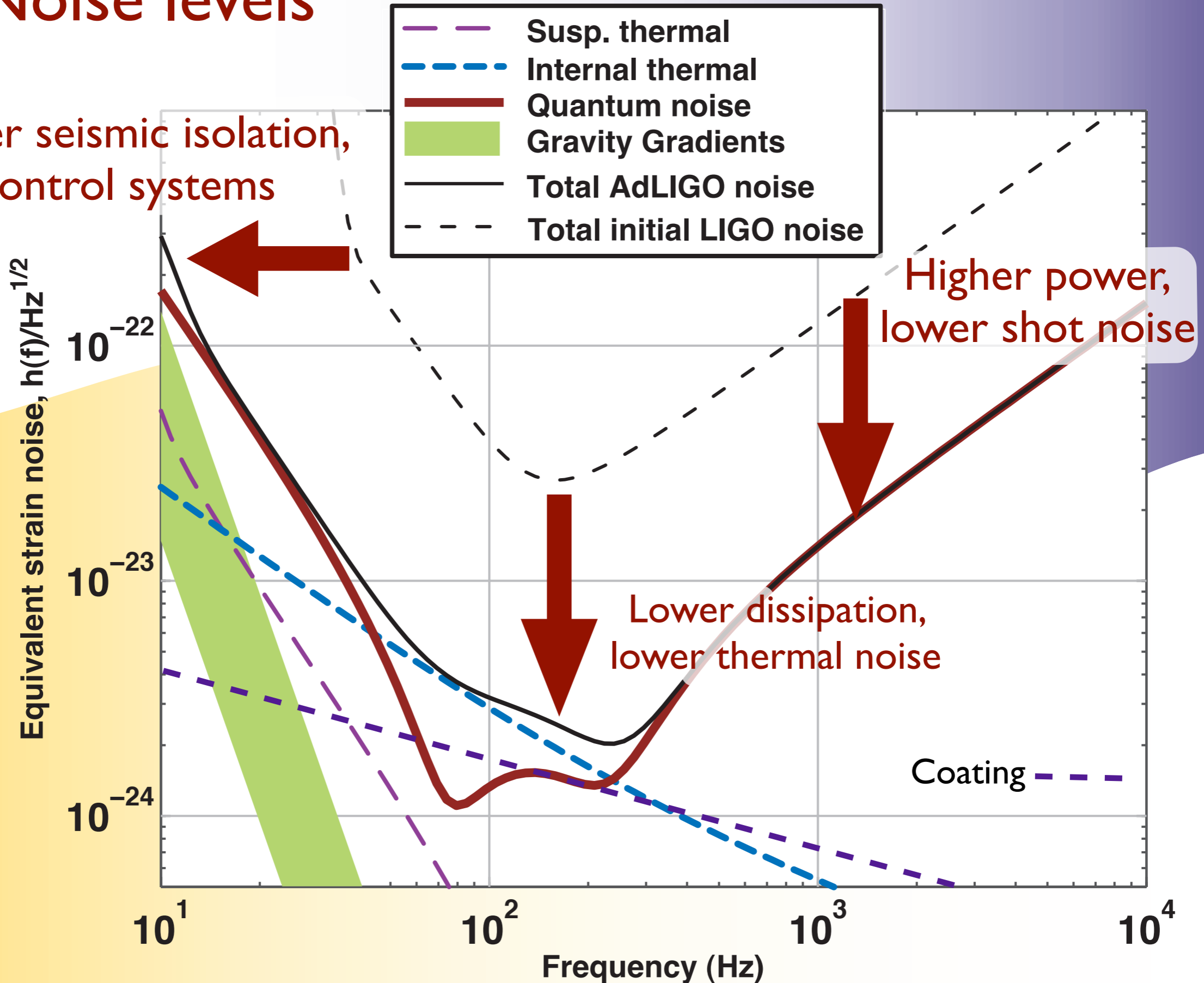
- ▶ U.K. PPARC approved (2003) approximately £ 8.8 M for
  - **Suspension** systems based on GEO technology
  - displacement sensors
  - one interferometer's test mass substrates.

- ACIGA

- ▶ applied to ARC for funding to carry out (e.g.) parametric instability tests at Gingin, and development/production of output mode cleaner

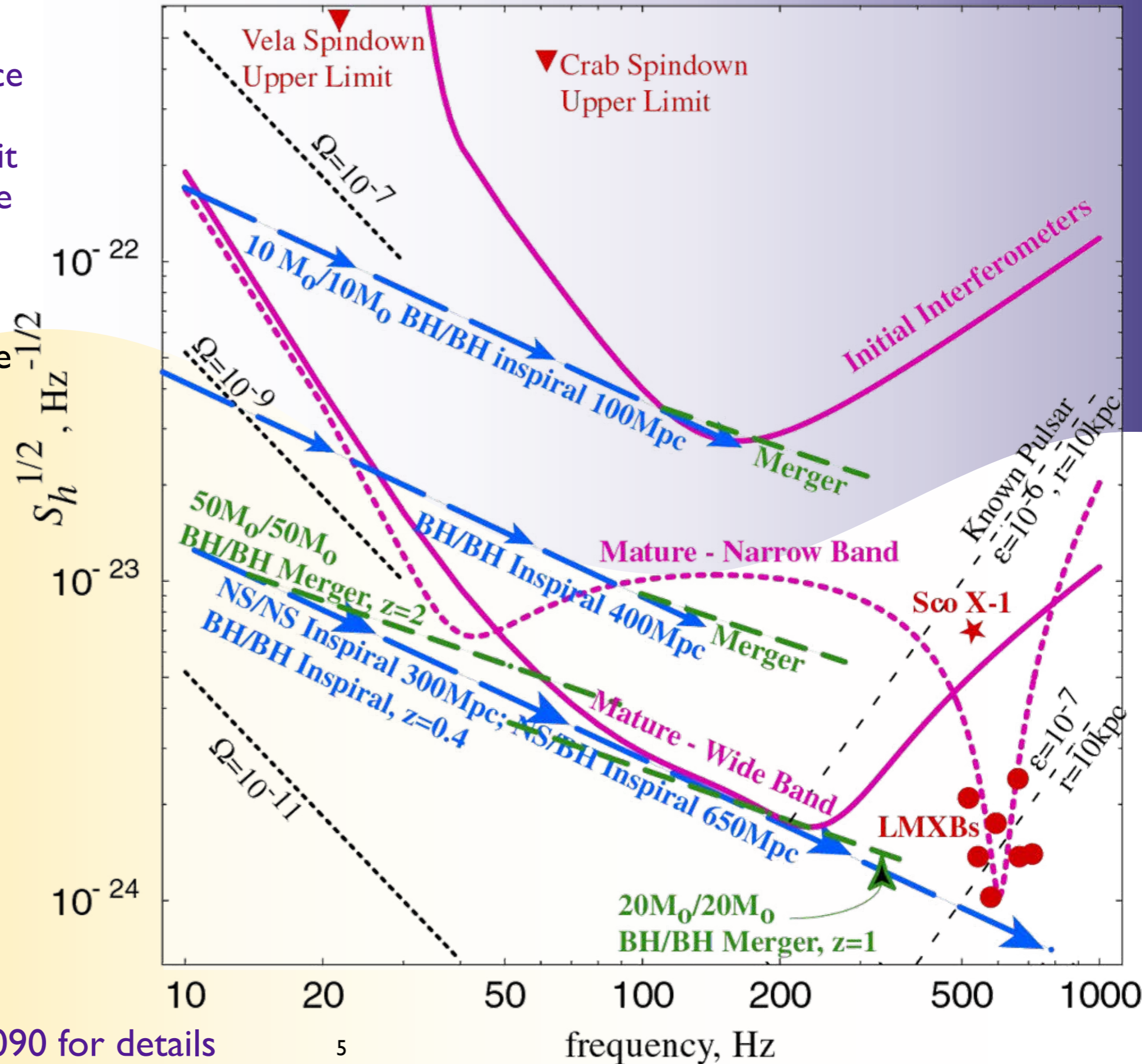
# Noise levels

Better seismic isolation,  
control systems



# Sources for Advanced LIGO (Thorne)

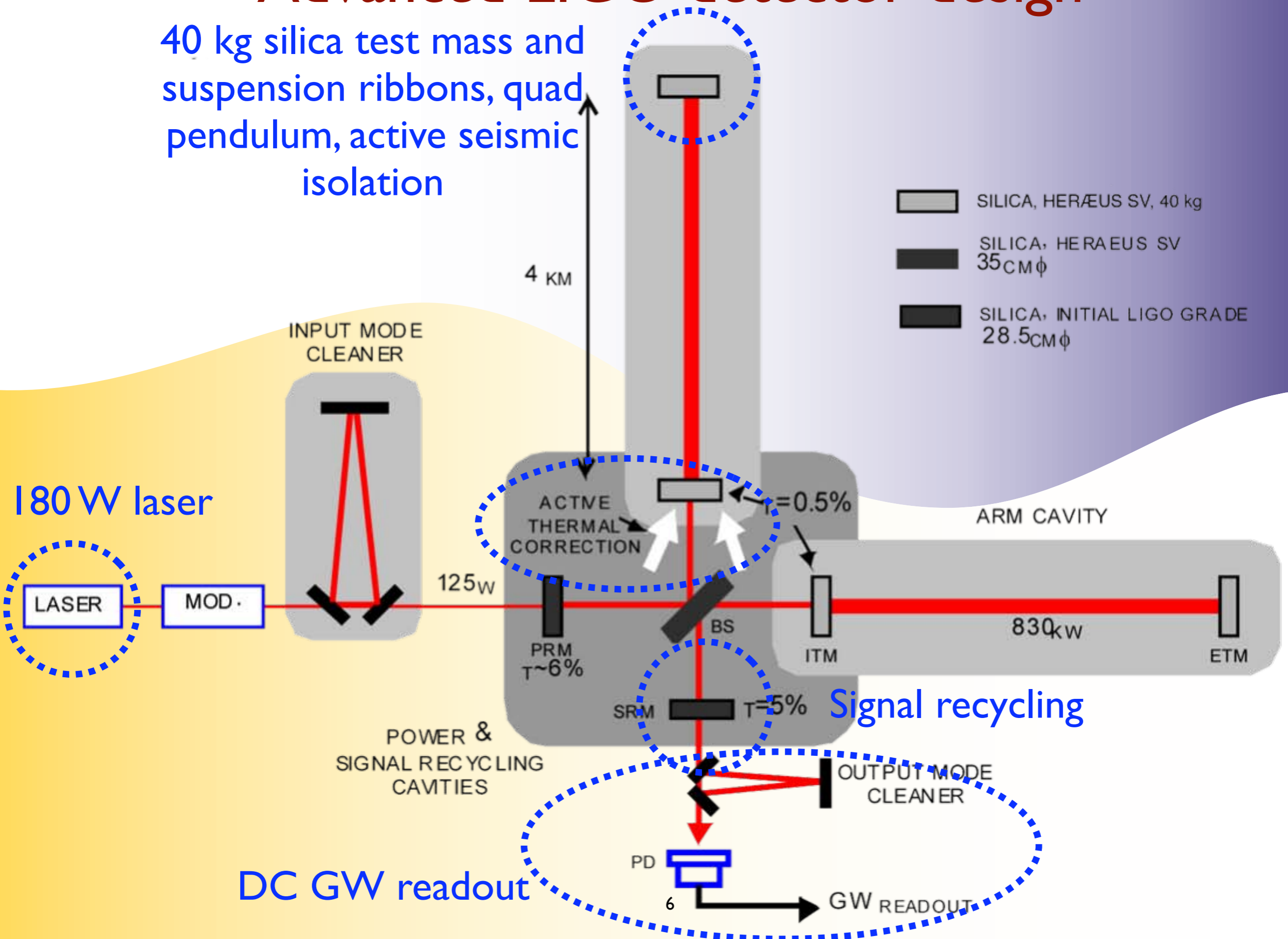
- “Kip” diagram: when source line coincides with that of interferometer sensitivity, it is detectable with  $10^{-6}$  false alarm rate for reasonable observation time...
- Neutron Star & Black Hole Binaries
  - ▶ inspiral
  - ▶ merger
- Spinning NS's
  - ▶ LMXBs
  - ▶ known pulsars
  - ▶ previously unknown?
- NS Birth (SN)
  - ▶ tumbling
  - ▶ convection
- Stochastic background
  - ▶ big bang
  - ▶ early universe



Please see [gr-qc/0204090](https://arxiv.org/abs/gr-qc/0204090) for details

# Advanced LIGO detector design

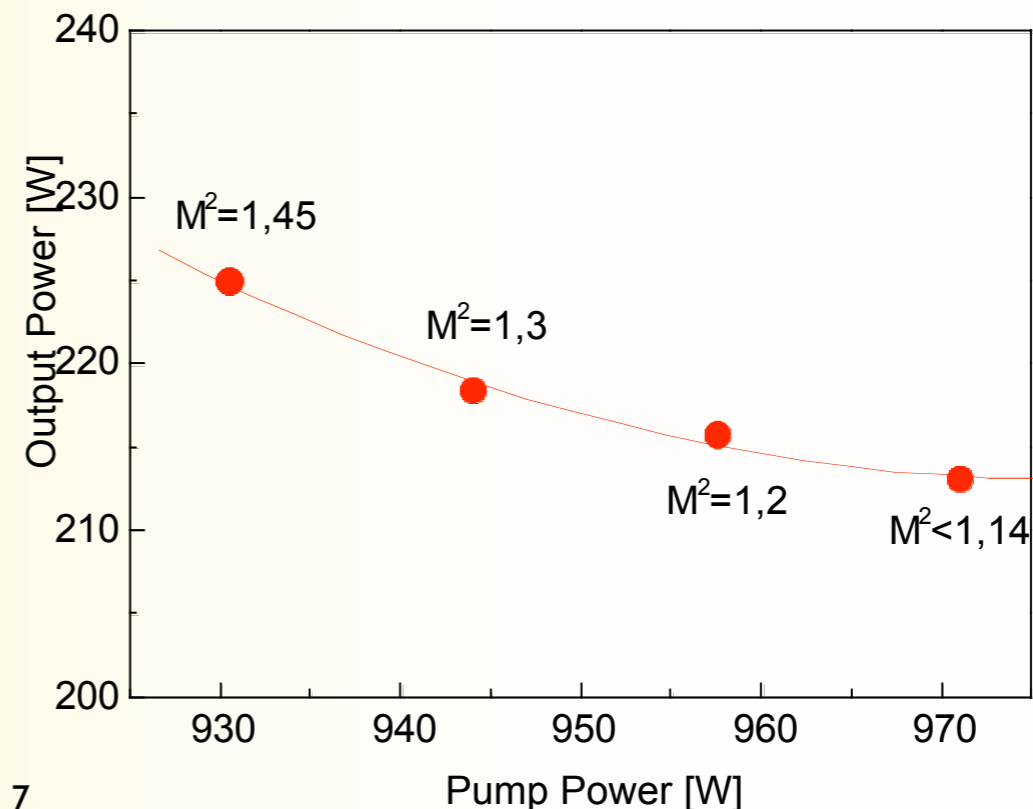
40 kg silica test mass and suspension ribbons, quad pendulum, active seismic isolation



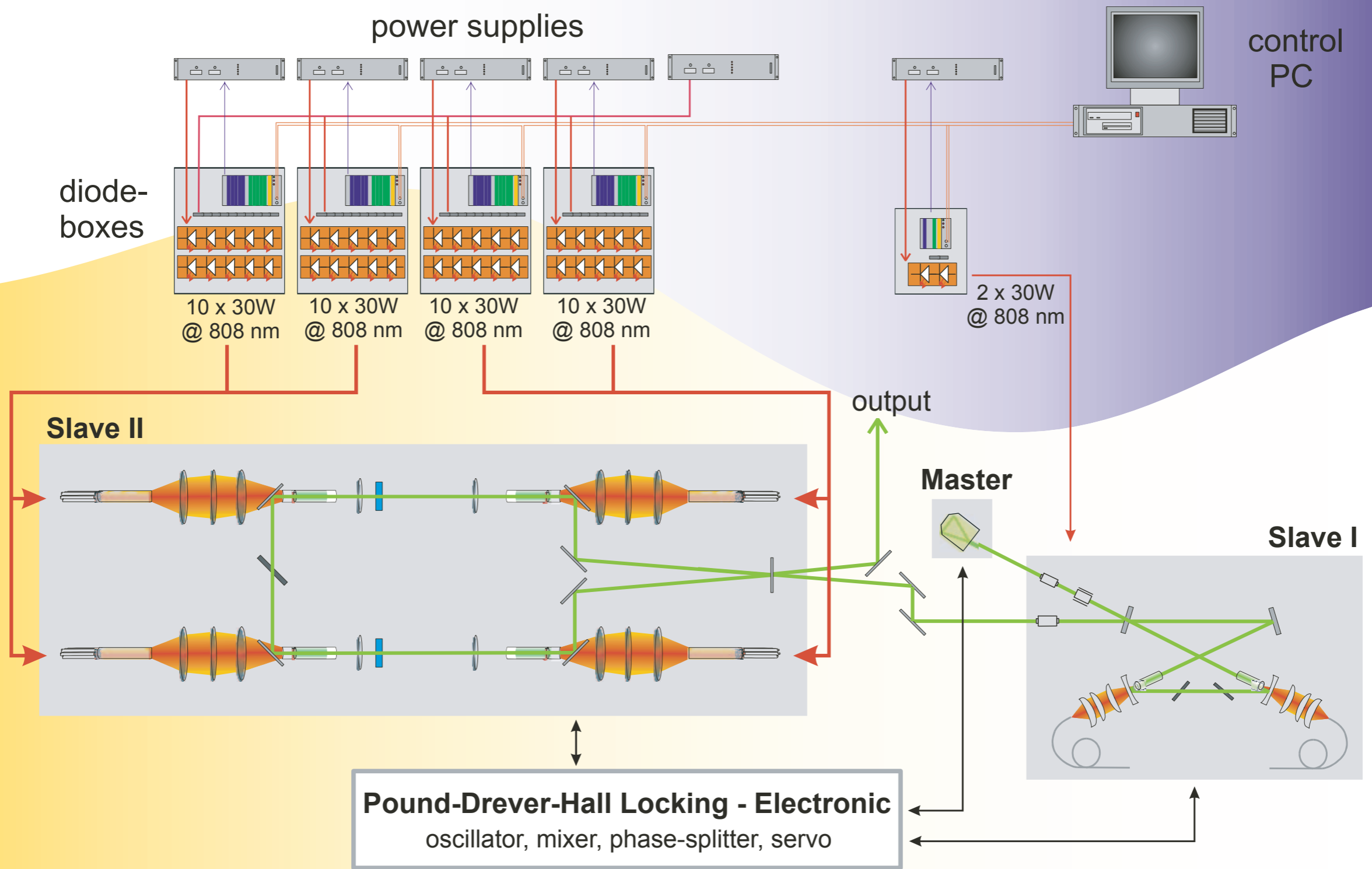
# High power laser

- Front end similar to what is in service at GEO 600, monolithic ring oscillator, diode pumped, followed by injection-locked oscillator.
- New, high-power second injection-locked oscillator, 200 W
  - ▶ Conduction-cooled, end-pumped rods
  - ▶ Thermal compensation via symmetry in ring
- Active control of pump diode and laser rod temperatures.
- Design and production at Laser Zentrum Hannover. Please listen for Benno Willke's talk this afternoon.

Parameter	Specification
1. type of laser	Nd:YAG
2. wavelength	1064 nm
3. power in a circular TEM <sub>00</sub> mode	>200 W
4. power in all other modes	< 20 W
5. polarization extinction ratio	100:1 in the vertical plane
6. relative power fluctuations	$< 10^{-3} / \sqrt{\text{Hz}}$ between 0.1 Hz and 10 Hz $< 10^{-5} / \sqrt{\text{Hz}}$ between 10 Hz and 10 kHz $< 2 \times 10^{-9} / \sqrt{\text{Hz}}$ for $f > 9$ MHz (3dB above shot noise of 50mA photocurrent)
7. frequency fluctuations	$< 1 \times 10^4 \text{ Hz} / \sqrt{\text{Hz}} \times [1 \text{ Hz} / f]$ between 1 Hz and 10 kHz (same as NPRO free running)



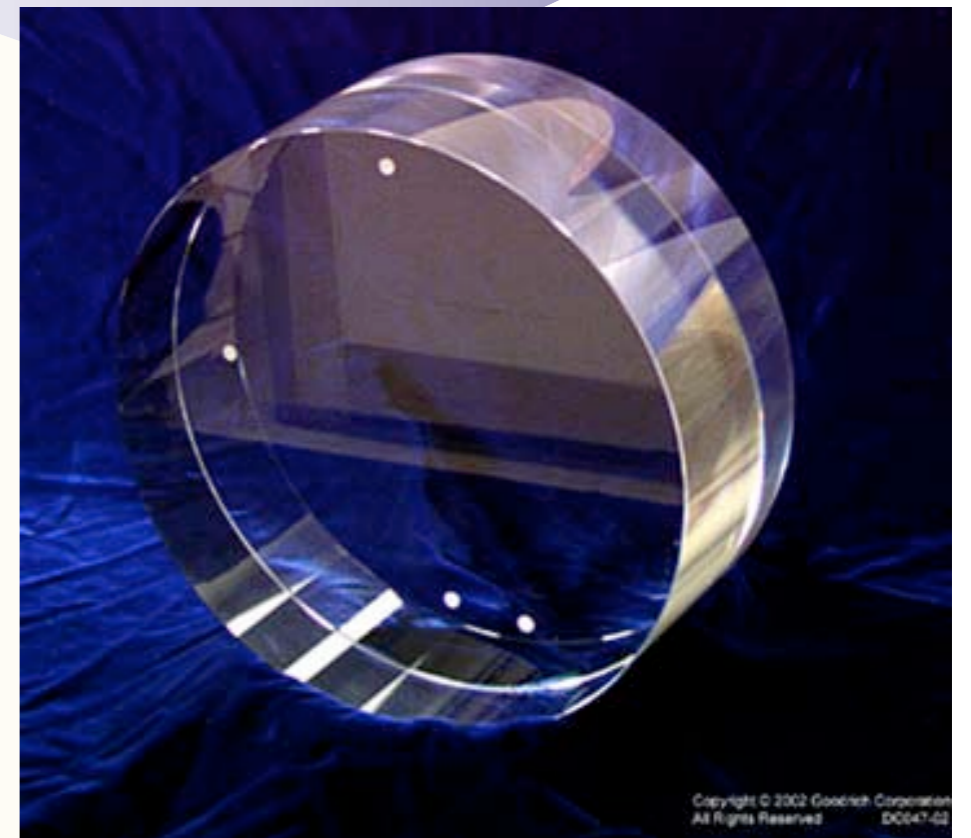
# Adv LIGO high-power Laser





# Test mass material selection: **Silica**

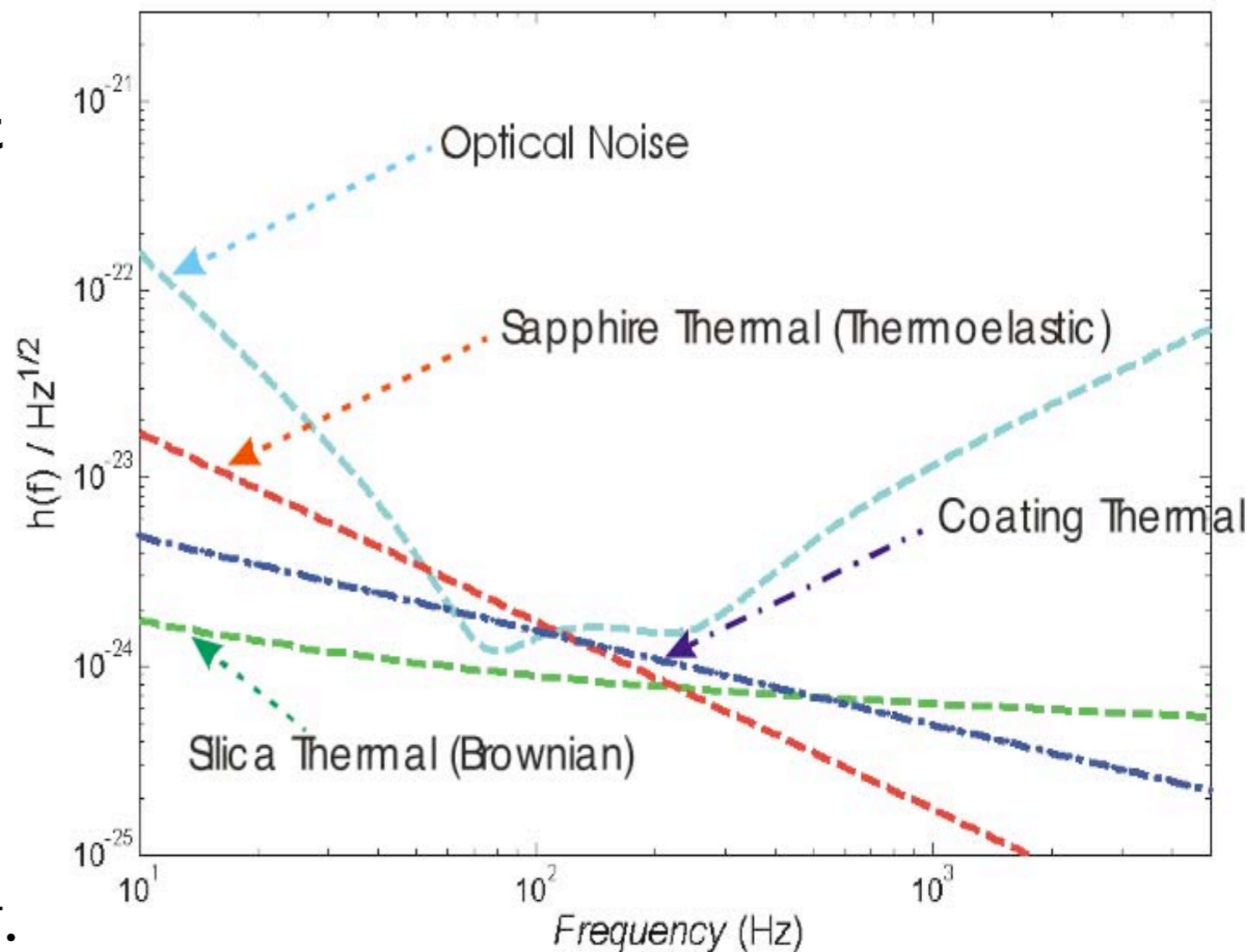
- The decision between sapphire and Silica was very close.
  - ▶ Each substrate is believed to meet Adv LIGO's requirements.
- **Sapphire:**
  - ▶ *risks:* single vendor for required size/properties, possible high or inhomogeneous optical loss.
  - ▶ *potential:* lower high-frequency thermal noise, *if* coating loss low enough, allowing deeper RSE.
- **Silica:**
  - ▶ *risks:* thermal noise (mechanical loss) likely dominated by coating. (noise from bulk loss thought to be lower)
  - ▶ *potential:* lower low-frequency thermal noise, which could open low-f end with squeezing or low laser power, and if we tackle the gravity gradients.



	<b>Silica</b>	<b>Sapphire</b>
NS/NS inspiral range	191 Mpc	191 Mpc
BH/BH inspiral range	1050 Mpc	920 Mpc
Stochastic $\Omega$ limit	$2.6 \times 10^{-9}$	$4.8 \times 10^{-9}$

# Coating dissipation

- With Silica substrate choice, kT noise from mirror coatings will likely be our noise floor over part of the band.
- Coatings are being fabricated at LMA/Virgo and CSIRO to study methods to reduce mechanical loss.
- Results from LMA for titania doped tantila show reduction in loss angle from LIGO-I coatings by factor of two, to  $\varphi \approx 1.3 \times 10^{-4}$ .
- Please see Geppo Cagnoli's poster.



# Input Optics R&D (U. of FI. / LLO)

- Modulation

- ▶ RTP-based electro-optic modulators tested for RFAM
  - ▣ currently looking at added phase noise
  - ▣ were using New Focus/UF hybrids; looking at all UF version for economy
- ▶ Mach Zehnder modulation
  - ▣ noise analysis substantially complete for requirements on stability
  - ▣ prototype built and locked, currently undergoing characterization

- Mode Cleaner

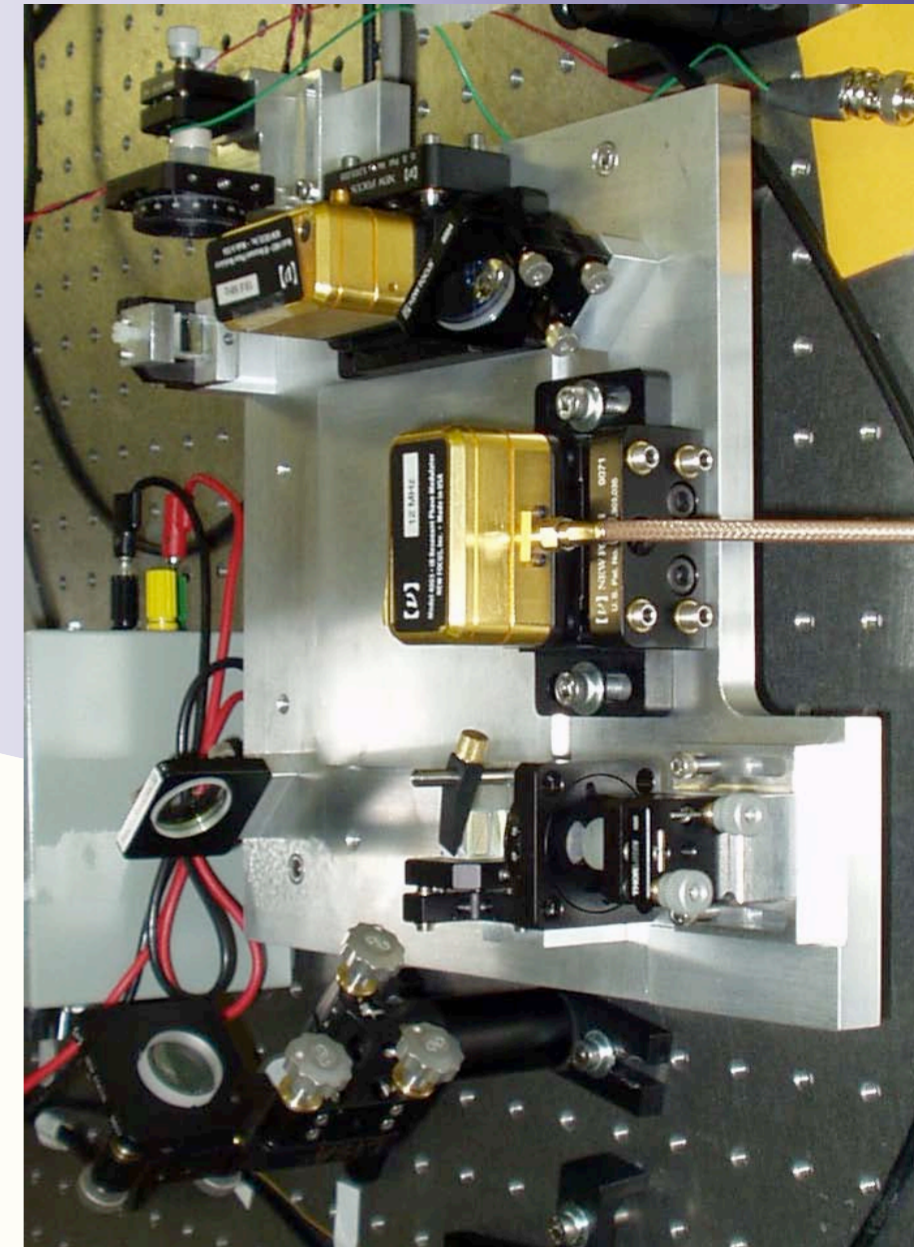
- ▶ optics design substantially complete
- ▶ thermal modeling shows some degradation at reflected power mode at 180 W input
- ▶ looking at alternative injection schemes

- Faraday Isolator

- ▶ prototype AdvLIGO Faraday isolator tested up to 100 W
- ▶ Need better thermal lens compensation, but performance adequate.

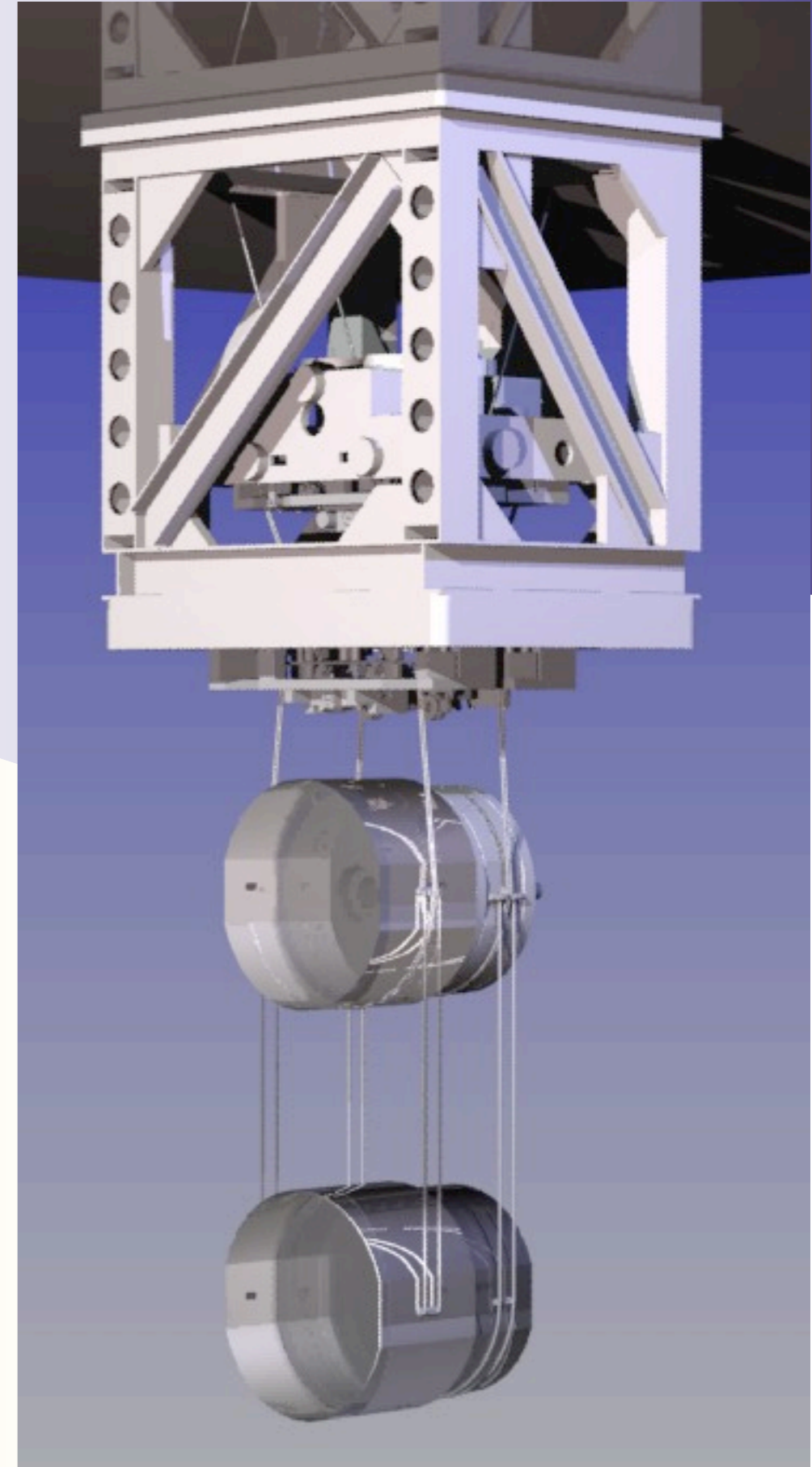
- Mode Matching Telescope

- ▶ finished first generation table-top adaptive mode matching experiments
- ▶ currently implementing table-top CO<sub>2</sub> laser based adaptive telescope



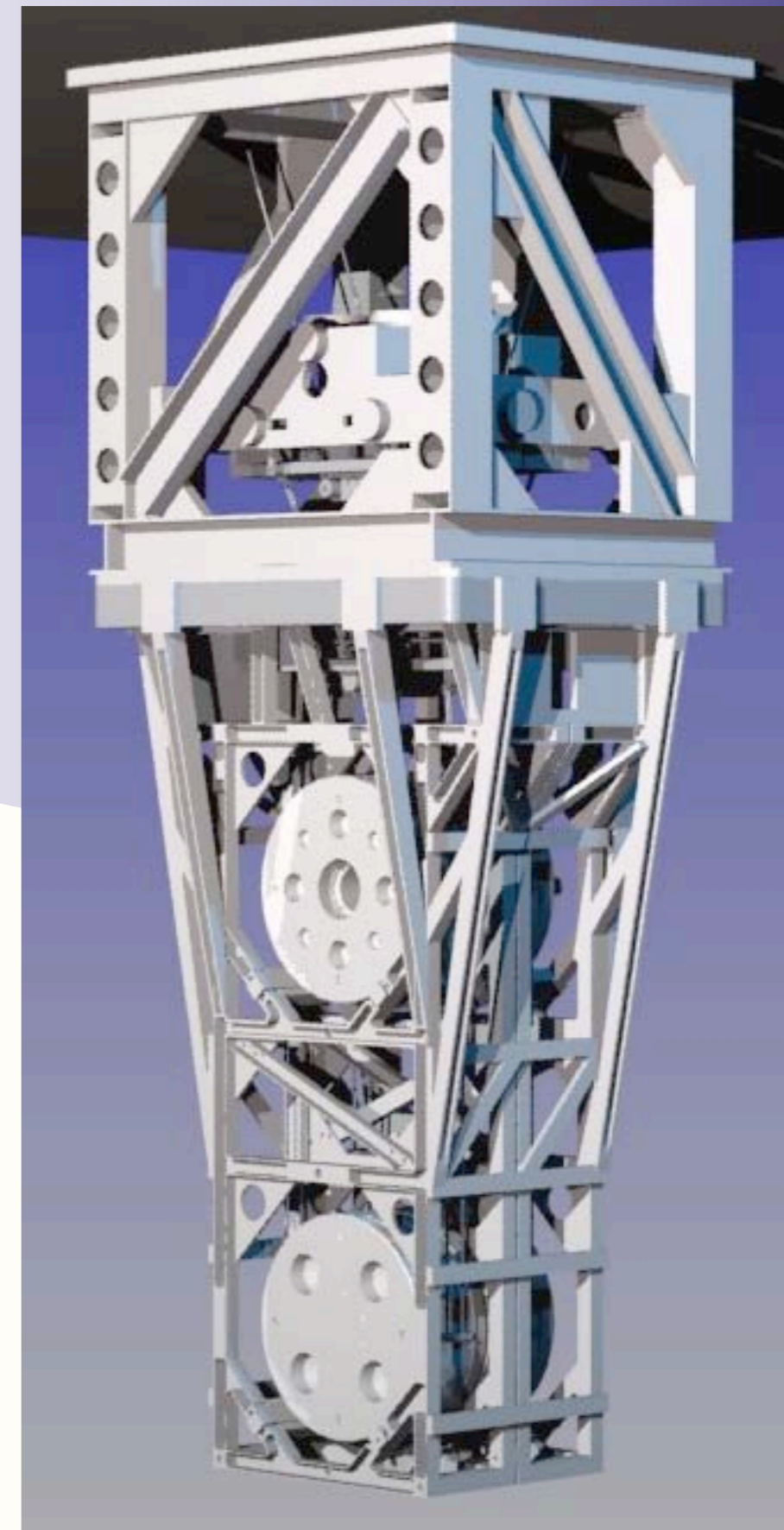
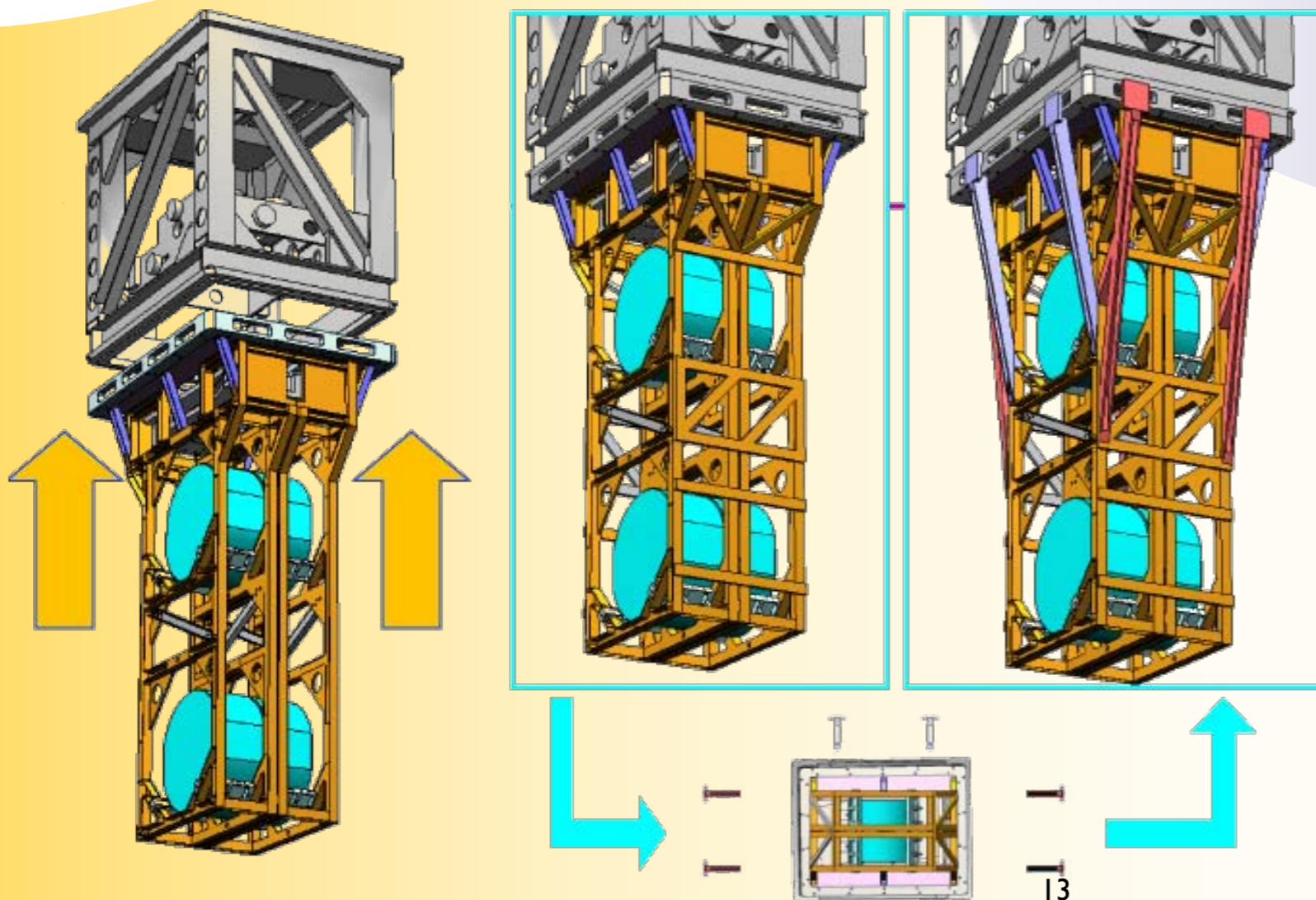
# Test mass suspension design

- 40 kg synthetic fused silica mirror suspended on silica ribbons
  - ▶ Silica 'ears' silicate-bonded to test and penultimate masses;
  - ▶ ribbons laser-welded to ears.
  - ▶ Upper stages connected using steel wires.
- four-stage pendulum with 3 stages of cantilever blade springs for vertical isolation
- Rigid-body modes at and below the 10 Hz end of the Adv LIGO detection band, damped at the top mass and by use of a reaction pendulum.
- Some violin-string modes damped using fiber coating.
- Target noise from suspension:  $10^{-19}$  m/ $\sqrt{\text{Hz}}$  at 10 Hz
- Please see Norna Robertson's poster



# Test mass suspension R&D

- Suspension cage design is a challenge
  - ▶ goal is that the elastic mode frequencies that are  $> 100$  Hz. Present state is getting close, making use of careful light-weighting.
- Design allows '3+1' assembly and installation
  - ▶ lower stages can be installed and serviced separately



# Fibers/ribbons & attachment

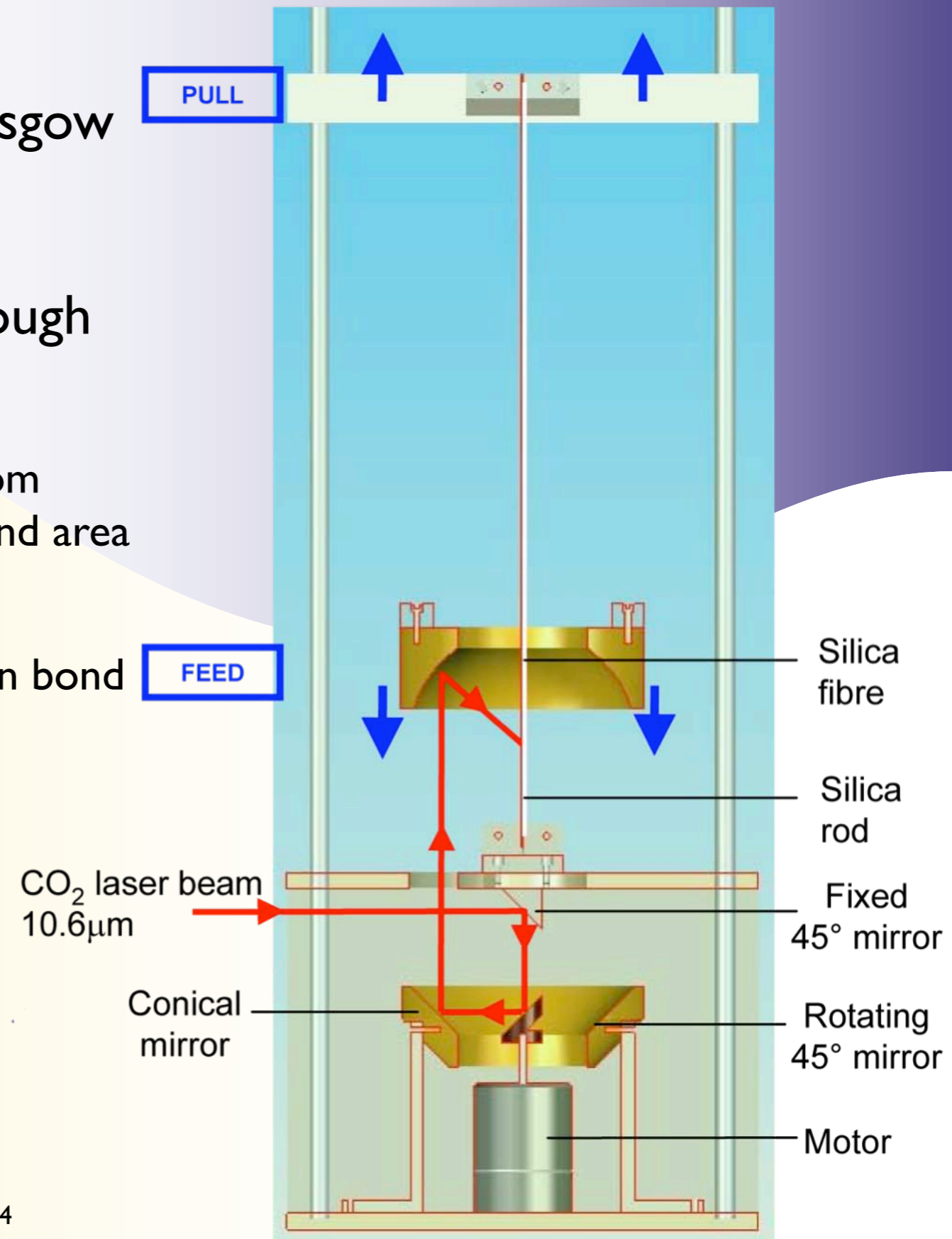
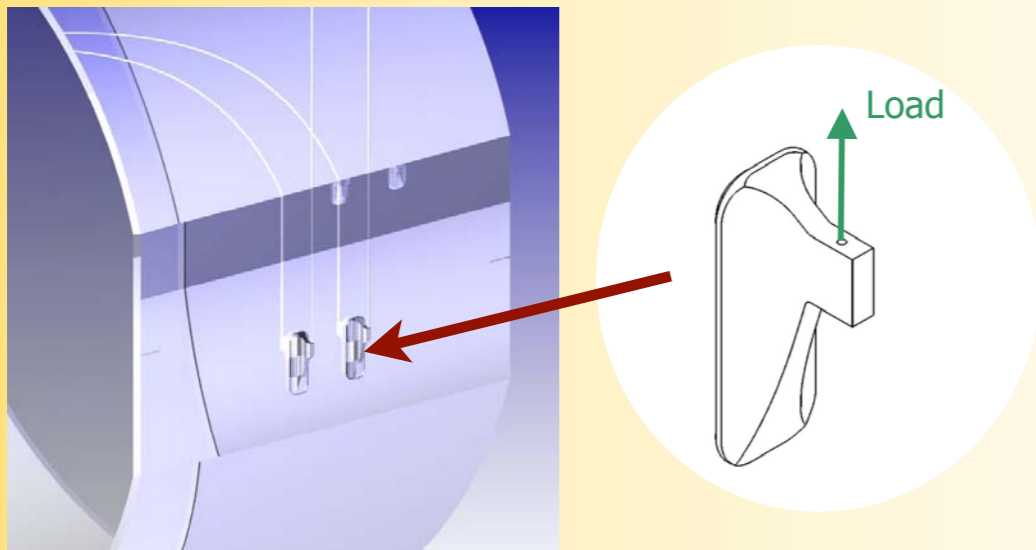
- Fiber/ribbon forming automation, Glasgow

- ▶ CO<sub>2</sub> laser heat and CNC feed

- Fiber/ribbon connection to optic through ear will be using silicate-bonded ear.

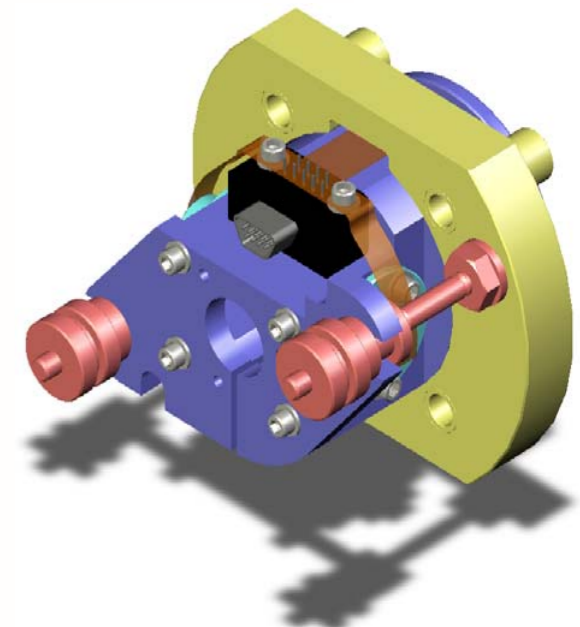
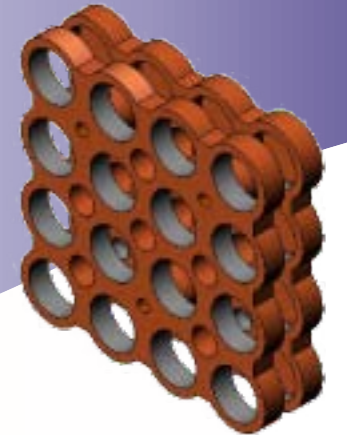
- ▶  $8 \times 10^{-21} \text{ m}/\sqrt{\text{Hz}}$  at 100 Hz 'contribution' from suspension thermal noise allows 7.1 cm<sup>2</sup> bond area per test mass.

- ▶ This represents a factor of 6 safety margin in bond strength.



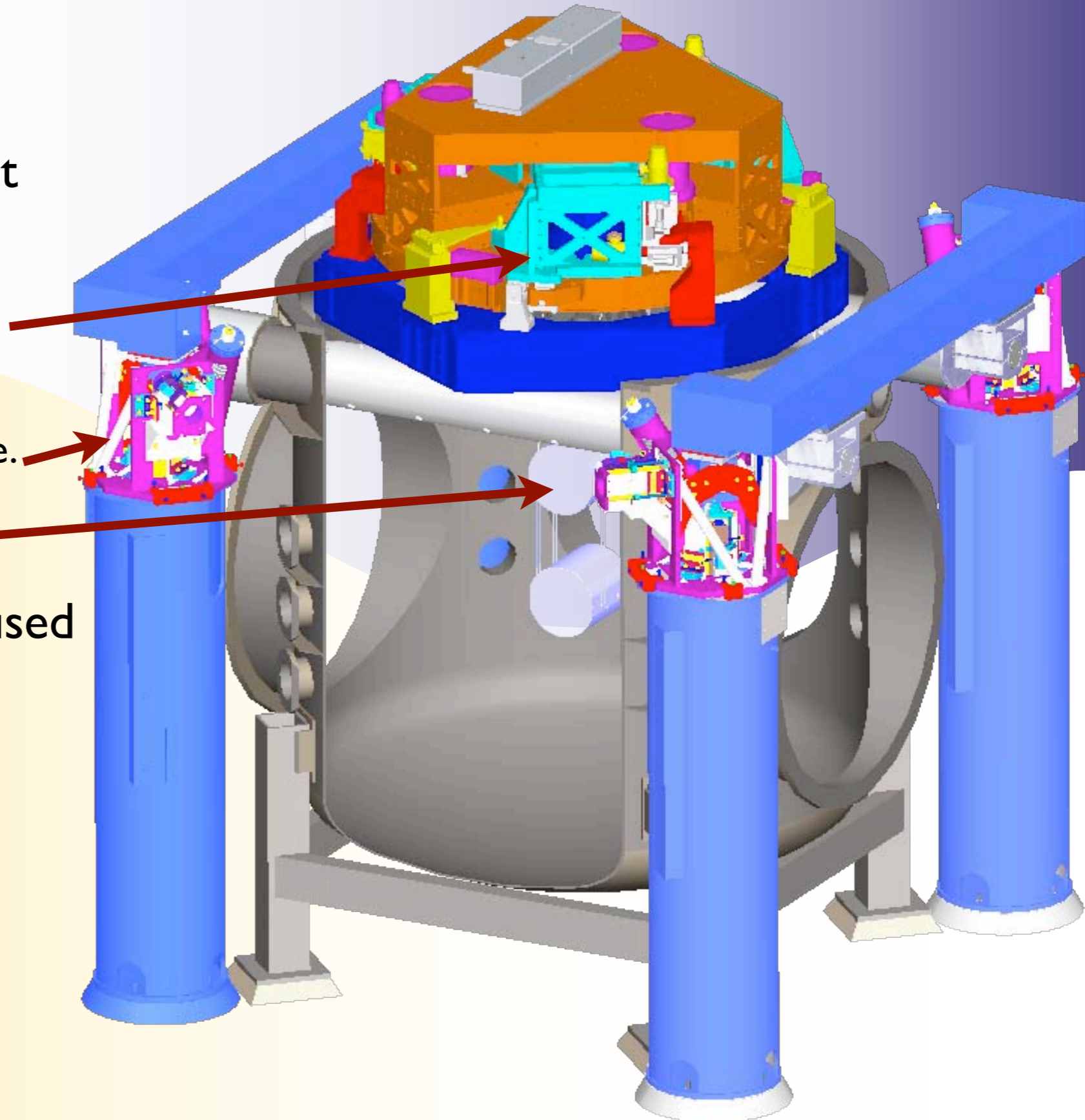
# Suspension testing

- ‘Controls’ prototype:
  - ▶ correct geometry, masses and moments.
  - ▶ Metal mock-up optics
  - ▶ correct damping, sensing, actuation
  - ▶ to be installed at MIT’s ‘LASTI’ facility late summer ‘05.
- ‘Noise’ prototype:
  - ▶ concurrent design and manufacture by U.K. group
  - ▶ the real thing, to be tested at LASTI after seismic isolation in place.
- Triple-pendulum input optics controls prototype:
  - ▶ successfully tested at LASTI, used to refine dynamic models and control techniques.
- Damping and actuation:
  - ▶ Eddy current dampers fabricated and tested
  - ▶ Electrostatic actuation grid fabricated on penultimate mass
  - ▶ New displacement sensor/ actuator (‘osem’) design.

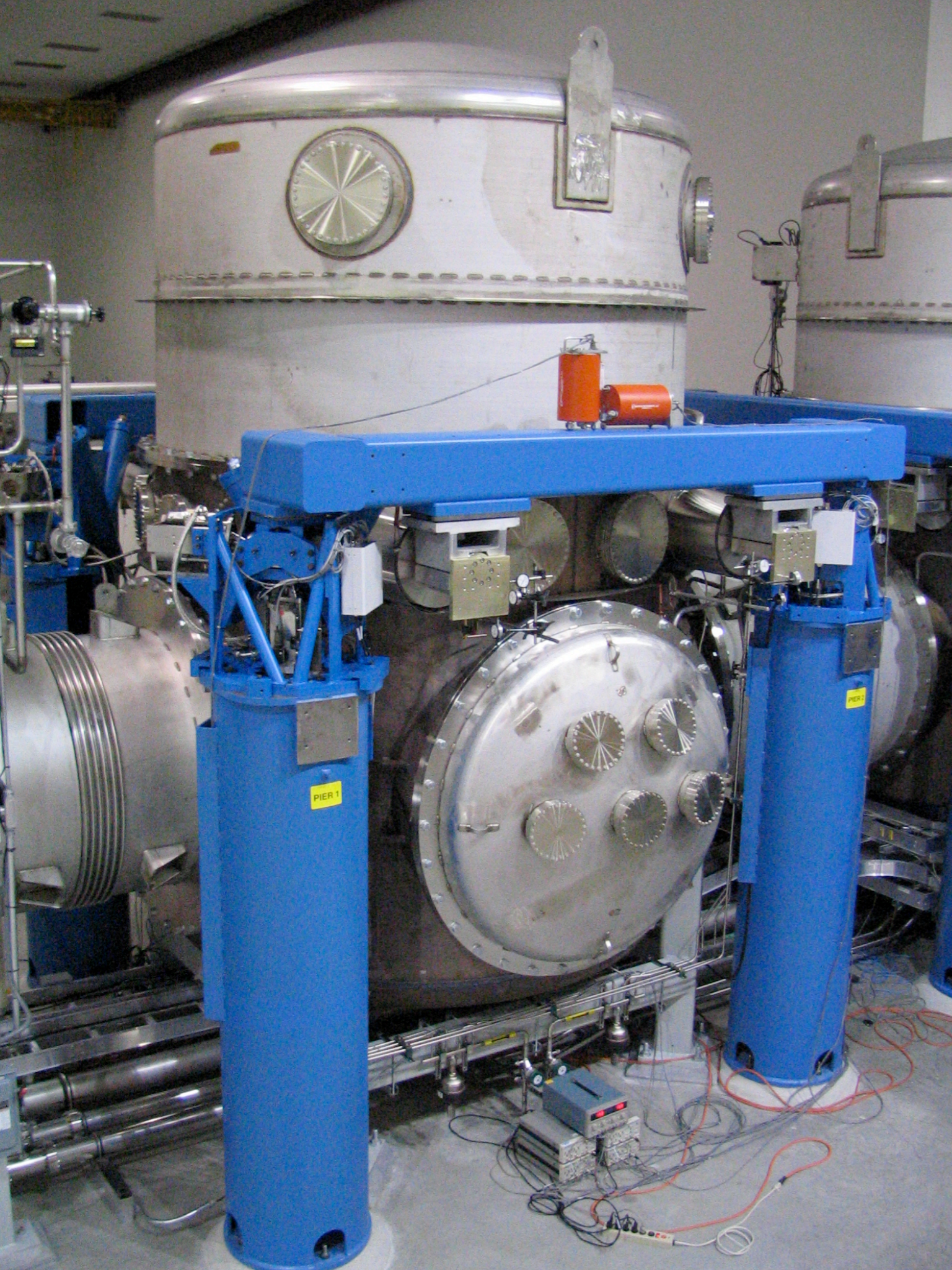


# Seismic Isolation

- Seismic isolation of the test mass occurs in:
  - ▶ A two-stage in-vacuum active platform
  - ▶ An external pre-isolation stage.
  - ▶ A quadruple pendulum
- R&D of seismic group focused on two-stage platform.



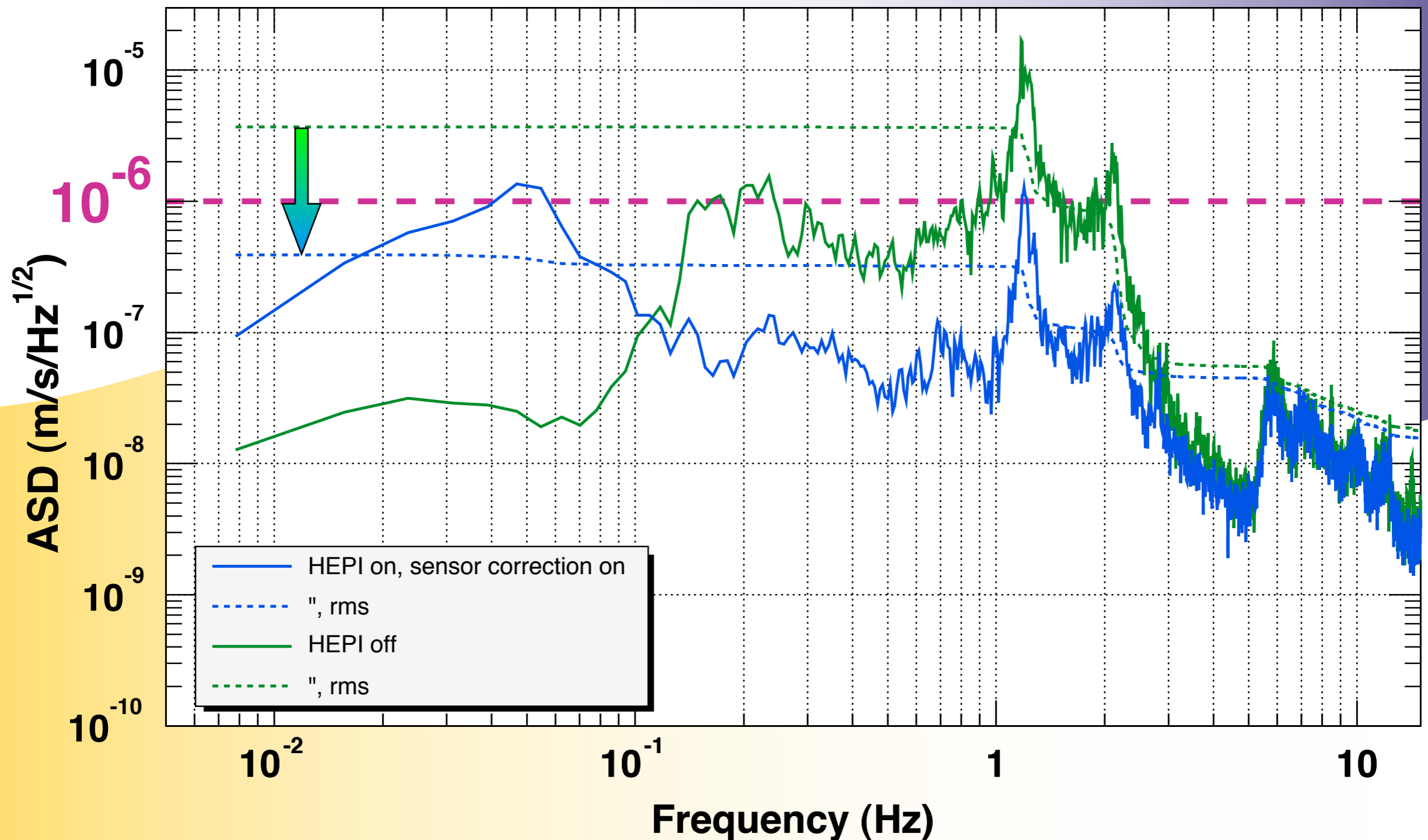




# Hydraulic External Pre-isolation

- The payload is supported by large coil springs, and actuated by quiet, high force hydraulic bridges.
- Vibration reduction is obtained by actively following inertial sensor signals from payload-mounted seismometers (L-4C) and by canceling floor vibrations measured by a broadband seismometer (Streckeisen STS-2).
- This is a 6 DOF system, though only x, y and z are quieted below 0.5 Hz.
- Already installed and commissioned at LIGO Livingston to overcome excess double-frequency microseism and local human-generated noise in the 0.1–2 Hz band.

# X-arm length disturbance, noisy afternoon



- Noisy afternoon of Aug 10, 2004 had a BLRMS ground velocity 1–3 Hz monitor value between the 90th and 95th percentiles.
- The remaining RMS equivalent velocity is  $< 4 \times 10^{-7}$  m/s, integrated down to 0.01 Hz.

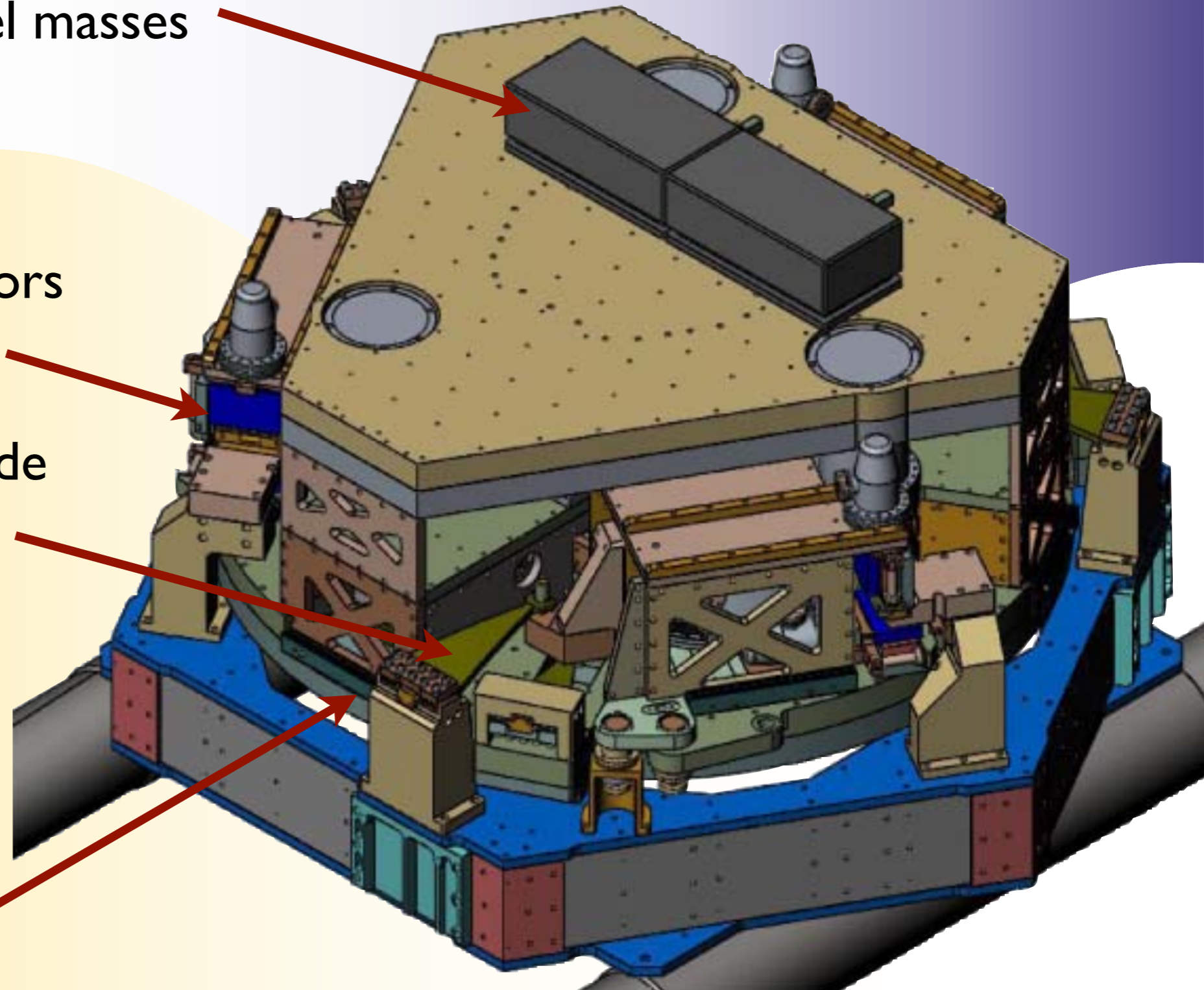
# In-vacuum active platform

relocatable  
keel masses

collocated sensors  
& actuators

stages supported by blade  
springs and vertical  
flexure rods

wide, matrix-drilled  
optics table for payload

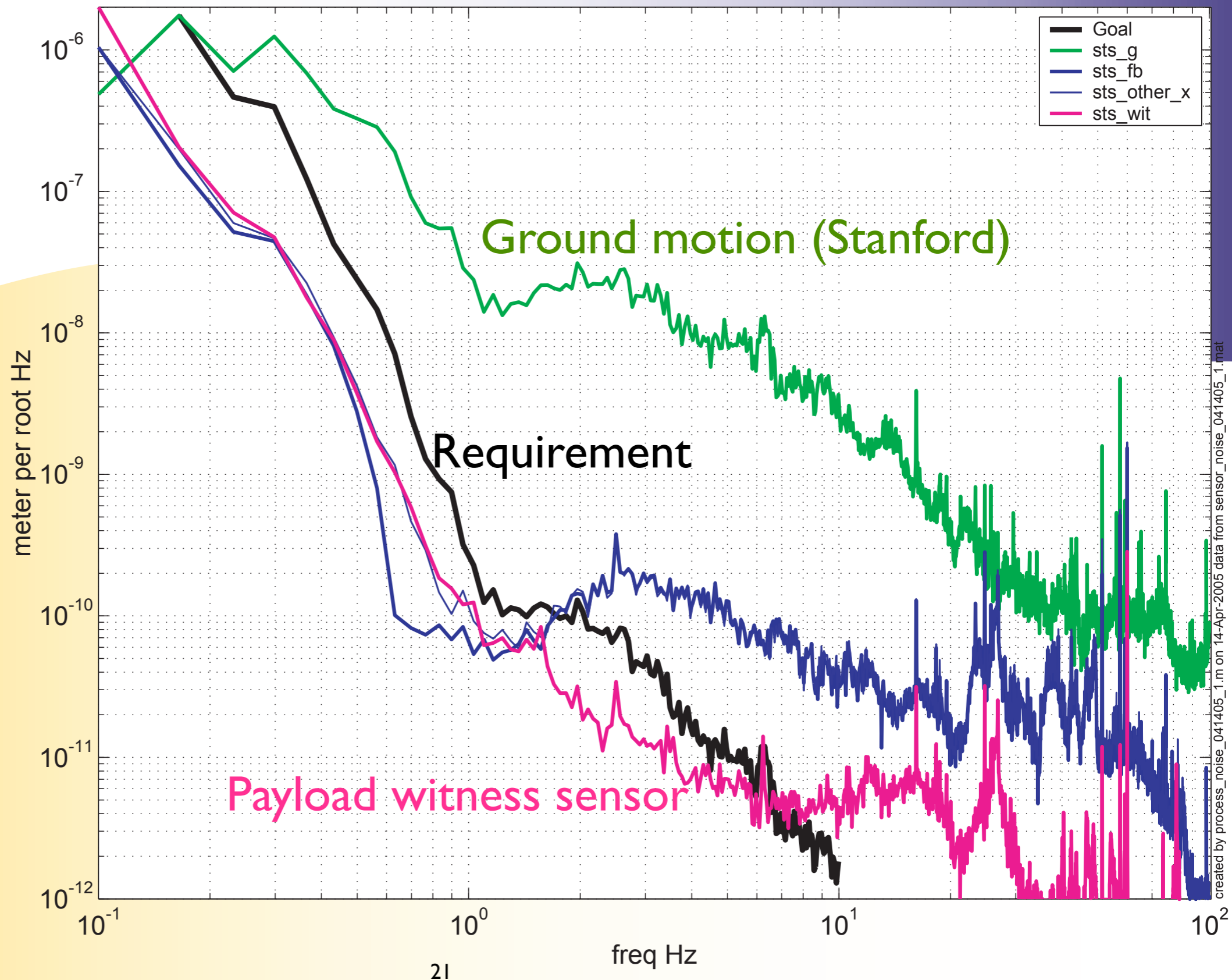


# Active platform design

- Technology demonstrator designed and installed in Stanford vacuum system (ETF).
  - ▶ mechanical system designed for approximately LIGO size platform, with approx half-size payload capacity.
  - ▶ most sensors and actuators as final design.
- True prototype design has been prepared for fabrication and installation in LASTI (at MIT) for full scale, UHV, tests with suspension systems.
  - ▶ finite-element modeling of structural and rigid-body modes. we require modal frequencies to be  $> 150$  Hz to accommodate  $\approx 50$  Hz servo unity-gain point.
  - ▶ modeling of  $6 \times 6$  DOF stiffness at low frequencies. For example, we require horizontal-tilt cross coupling  $< 1/500$  m.
  - ▶ new design for rigid and strong stops, to exactly position stages and restrict motion during earthquakes.
  - ▶ can accommodate  $\approx 1$  ton payload. Servo and mechanical design need to tolerate mechanically reactive massive payload.

# Technology demonstrator results

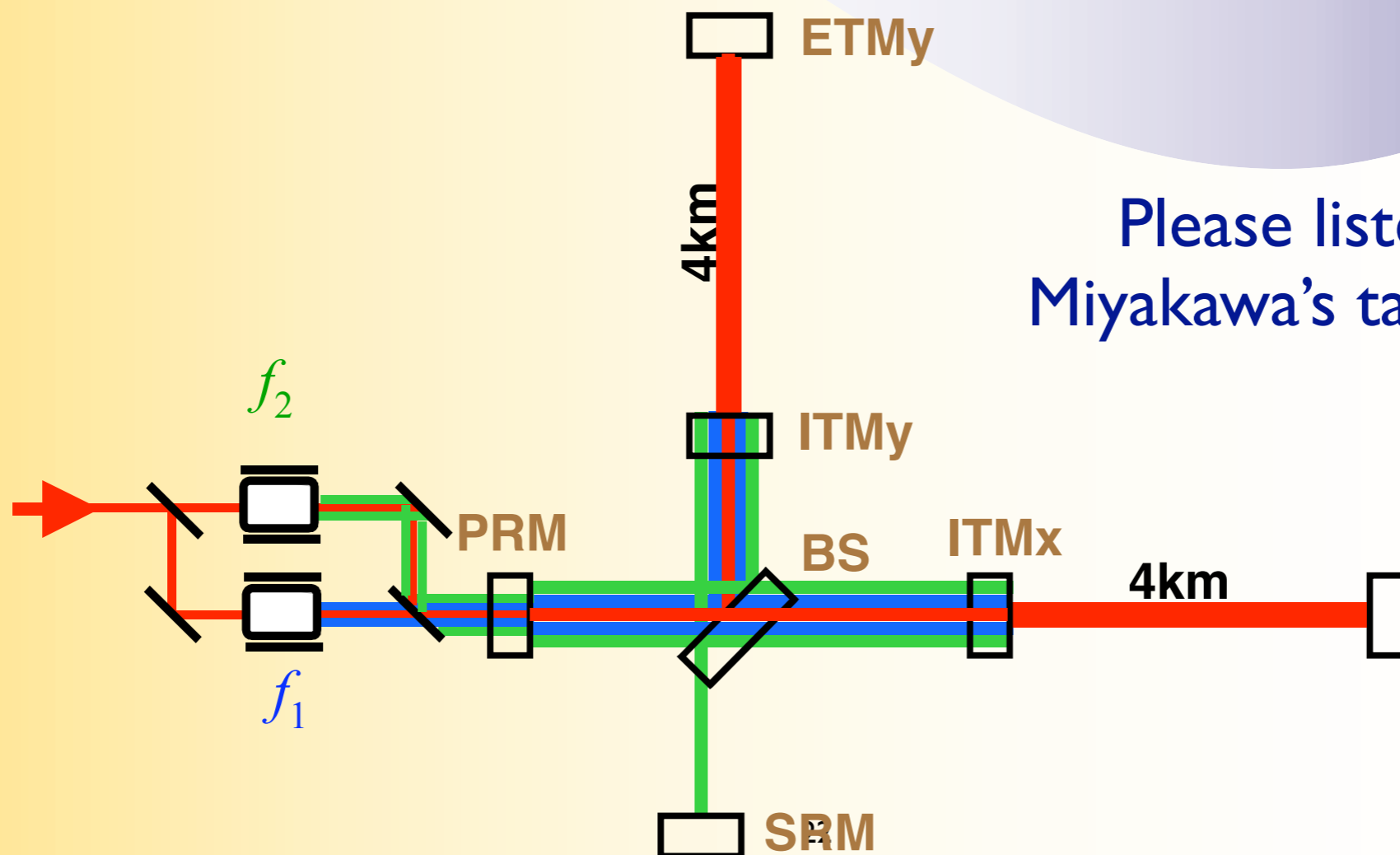
Horizontal FIR blending performance X



- Requirements: factor of 100 at 1 Hz and factor of 1000 at 10 Hz.
- We are modifying the LASTI prototype mech. design to increase vertical passive isolation at 10 Hz, based on these tests.

# Length sensing and control

- Baseline scheme is a narrowband-signal-recycled, and power recycled, Fabry-Perot Michelson.
  - ▶ Detuned resonant sideband extraction, with noise minimum tuned to make 'the bucket' deeper.
- Frontal RF modulation and synchronous demod used for all length (and angle) DOF's, except differential arm.
- DC detection is the baseline design for the GW DOF.



Please listen for Osamu Miyakawa's talk this afternoon

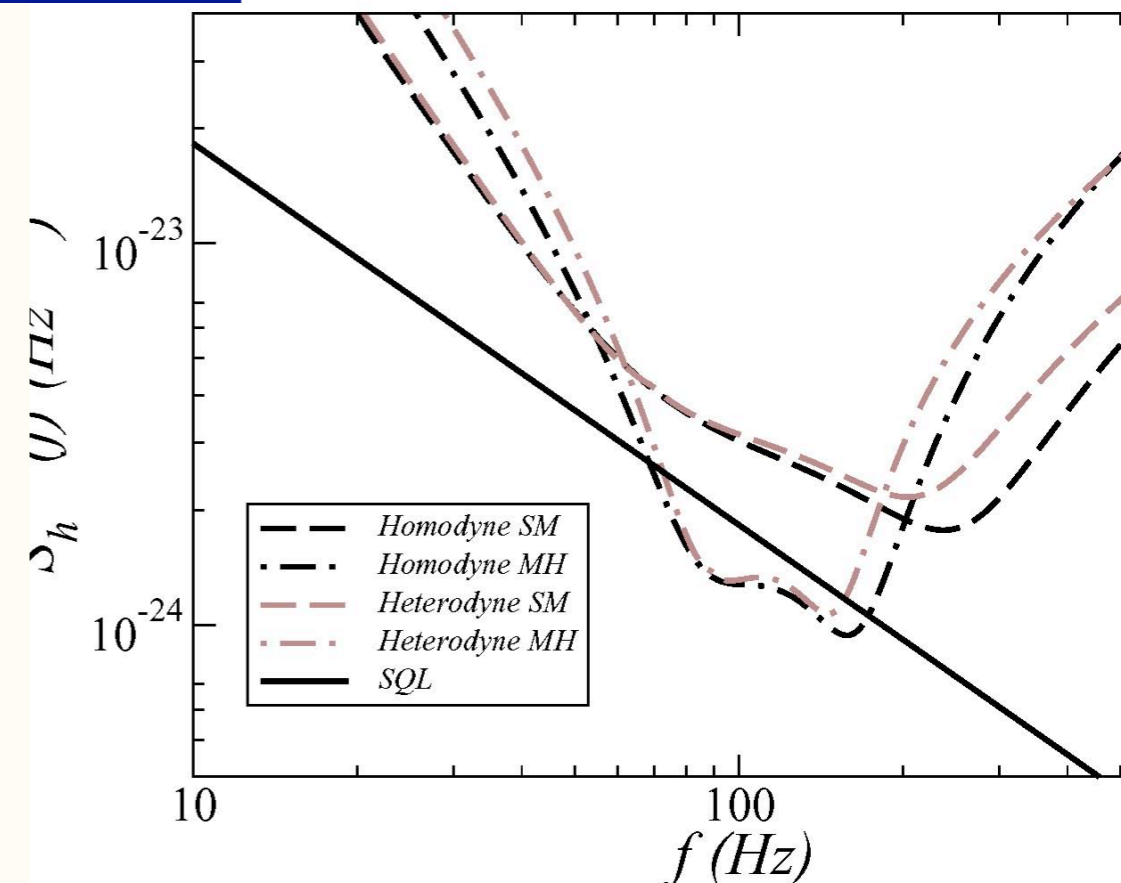
# DC readout

- The ‘traditional’ RF detection method is to apply frontal RF phase modulation on the light, such that the sidebands are not resonant in the long FP arms.
  - ▶ The PM sidebands serve as an optical phase reference at the photodiode, converting the phase difference signal to an RF intensity.
  - ▶ RF detection requires that the output photodiodes have both high efficiency and high bandwidth. This usually means small size.
  - ▶ As we use detuned RSE, there will be an imbalance in the antisymmetric port PM sidebands.
- Using homodyne, or DC readout, we arrange to operate such that there is some carrier always incident on the photodiode.
  - ▶ The constant carrier light serves as the phase reference, and the phase difference signal is converted to an intensity signal at the baseband.
  - ▶ The phase reference light comes either from an arm loss imbalance or intentional servo offset from the dark fringe.
  - ▶ DC readout requires an output mode cleaner to prevent fake signals due to (e.g.) intensity noise in recycling cavity light higher-order modes.
  - ▶ Large-area, low-bandwidth photodiode is allowed.

# DC readout

Noise Source	RF readout	DC readout
Laser frequency noise	~10x more sensitive	Less sensitive since carrier is filtered
Laser amplitude noise	Sensitivity identical for frequencies below ~100 Hz; both driven by technical radiation pressure	
	10–100x more sensitive above 100Hz	Carrier is filtered
Laser pointing noise	Sensitivity essentially the same	
Oscillator phase noise	-140 dBc/rtHz at 100 Hz	NA

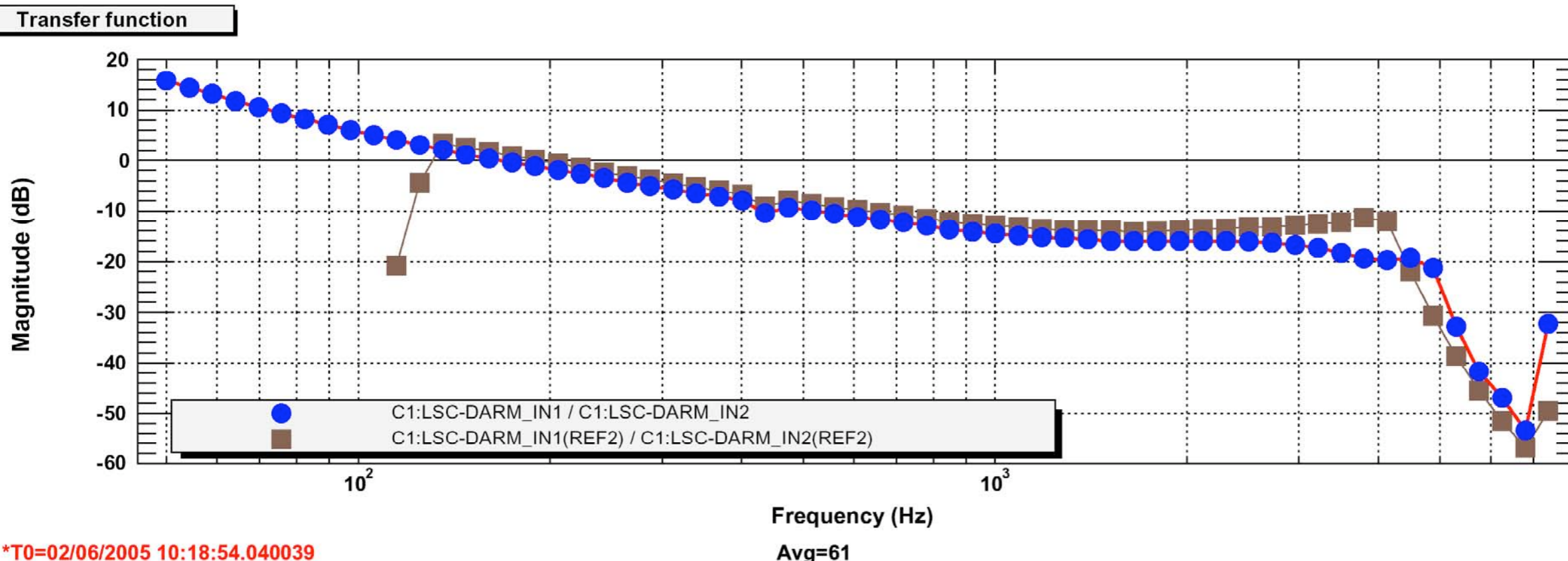
- Buonanno & Chen model, parameters optimized for NS/NS binaries
- SNR for DC higher than RF by  $\approx 5\%$ .





# 40 m facility: Resonant sideband extraction

- Experiment underway at 40 m facility (Caltech) to develop and test a length sensing and control scheme for *detuned* resonant sideband extraction, using two frontal modulation frequencies. DRSE has been demonstrated, with a few loose ends (Please listen for Osamu Miyakawa's talk this afternoon.)



# And more ...

- End-to-end detector model being re-built for Adv LIGO
- Thermal noise interferometer facility tests.
- Data pathways and analysis computing resources to be augmented.
- Installation planning for complex, fragile, heavy and large components.
- Continued R&D on substrate and coating technology.
- R&D on flat-top beams.
- R&D on squeezed light methods. [Please see Nergis Mavalvala's poster.](#)
- etc.