

The Search for a Stochastic Gravitational Wave Background

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LIGO - G050228-00-Z



Characterization of a Stochastic Gravitational Wave Background

- Assuming SGWB is isotropic, stationary, and Gaussian the strength is fully specified by the energy density in GWs
- Ω_{gw}(f) in terms of the strain power spectrum, S_{gw}(f):

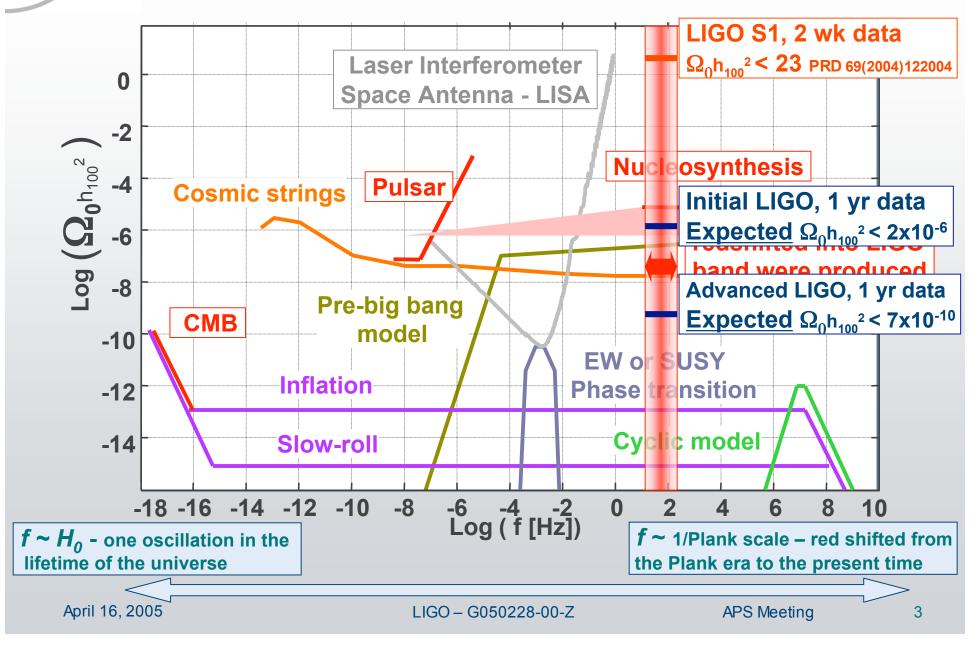
$$\boldsymbol{\Omega}_{gw}(f) = \frac{1}{\rho_{critical}} \frac{d\rho_{gw}}{d(\ln f)}$$

$$S_{\rm gw}(f) = \frac{3H_0^2}{10\pi^2} f^{-3}\Omega_{\rm gw}(f)$$

• Strain amplitude scale:

$$h(f) = S_{\rm gw}^{1/2}(f) = 5.6 \times 10^{-22} \ h_{100} \sqrt{\Omega_0} \left(\frac{100 \text{Hz}}{f}\right)^{3/2} \text{Hz}^{1/2}$$

LIGO Predictions and Experimental Limits





Data Analysis Strategy

- Assume that detector noise *n_i(t)* dominates the output, $P_i(f)$ - noise power spectrum
- Cross-correlate outputs from two interferometers $S_{i}(t) = h_{i}(t) + n_{i}(t)$
- Operator $\tilde{Q}(f)$ weights the • cross-correlation to maximize the signal-to-noise ratio of the $\Omega_{aw}(f)$ measurement
- **Overlap reduction function** $\gamma(f)$ accounts for separation and angle between two detectors

$$\begin{aligned} Y &= \iint dt_1 dt_2 \ s_1(t_1) Q(t_1 - t_2) s_2(t_2) \\ \overline{Y} &= \frac{T}{2} \int df \ \gamma(f) S_{gw}(f) \tilde{Q}(f) \\ \sigma_Y^2 &\approx \frac{T}{4} \int df \ P_1(f) \left| \tilde{Q}(f) \right|^2 P_2(f) \end{aligned}$$

 $\widetilde{Q}(f) \propto \frac{\gamma(f)S_{gw}(f)}{P_1(f)P_2(f)}$ Signal Noise

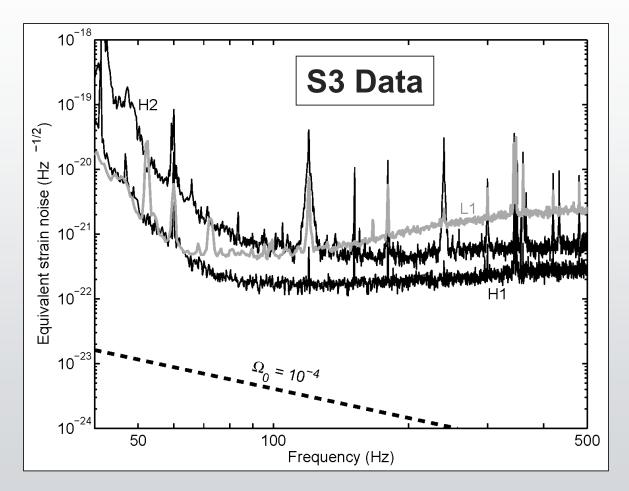
Allen, Romano, PRD59 (1999)

$$S_{gw}(f) \propto 1/f^3$$
 for $\Omega_{gw}(f) = \Omega_0 = const$



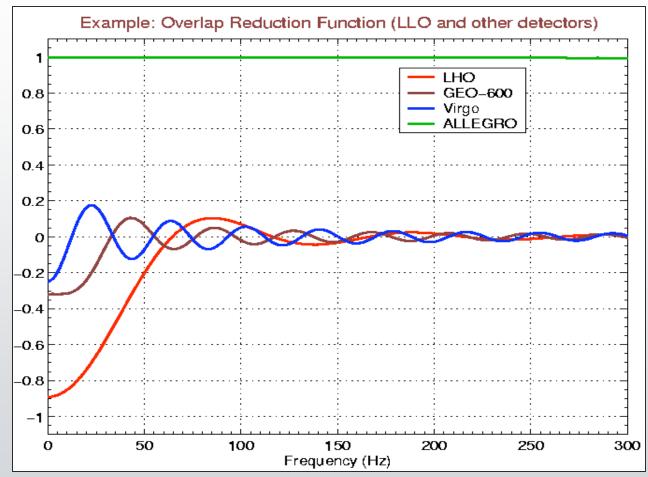
Strain Noise Spectral Densities

 S2 and S3 runs have comparable observation time (387 and 350 hours respectively) but S3 sensitivity is an order of magnitude better than S2.

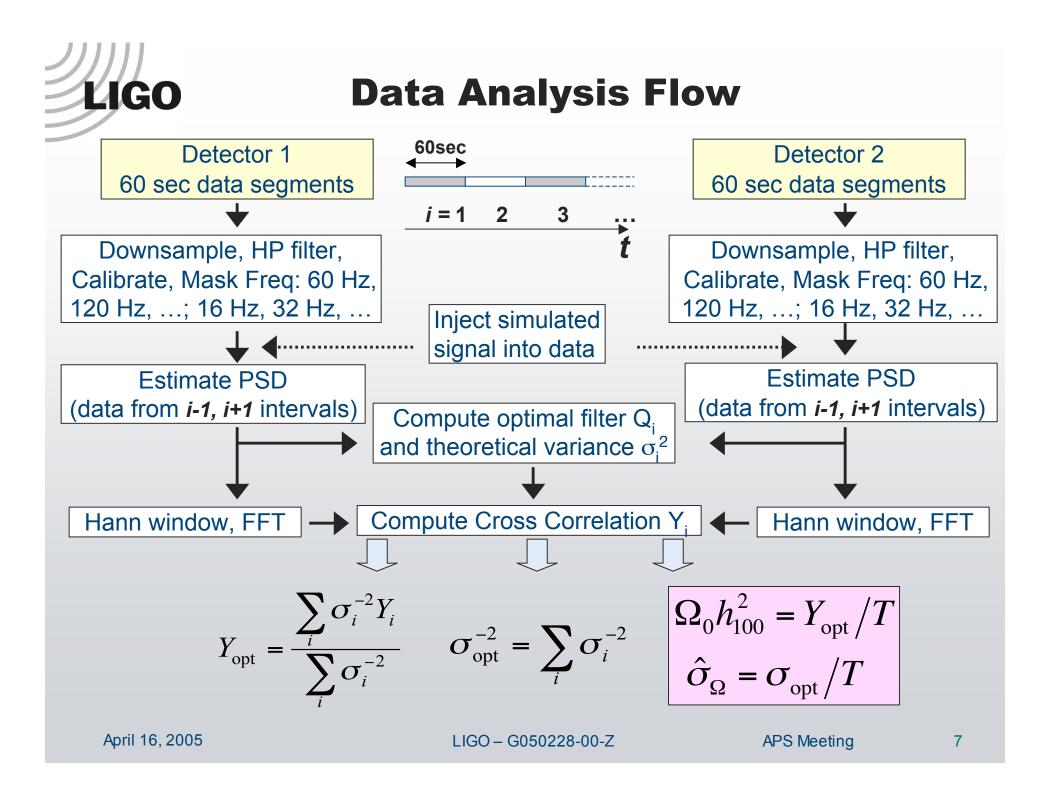




Overlap Reduction Functions Between L1 and Other Detectors

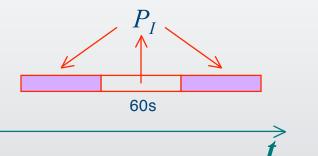


Flanagan, PRD48, 2389 (1993)

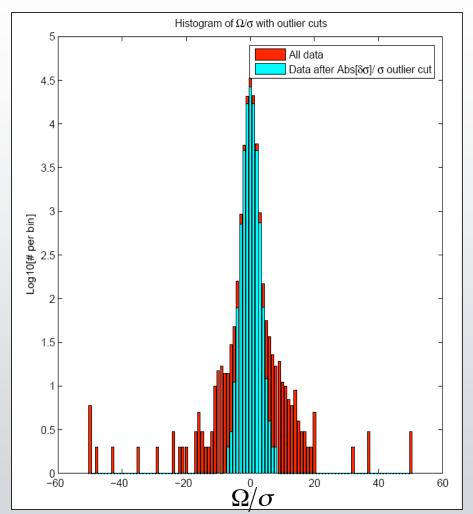


LIGO Dealing with Non-stationary Noise

- Sigma-integrand is proportional to 1/(P1*P2)
- P1, P2 estimated using data outside of 60s interval being analyzed, to avoid bias in crosscorrelation

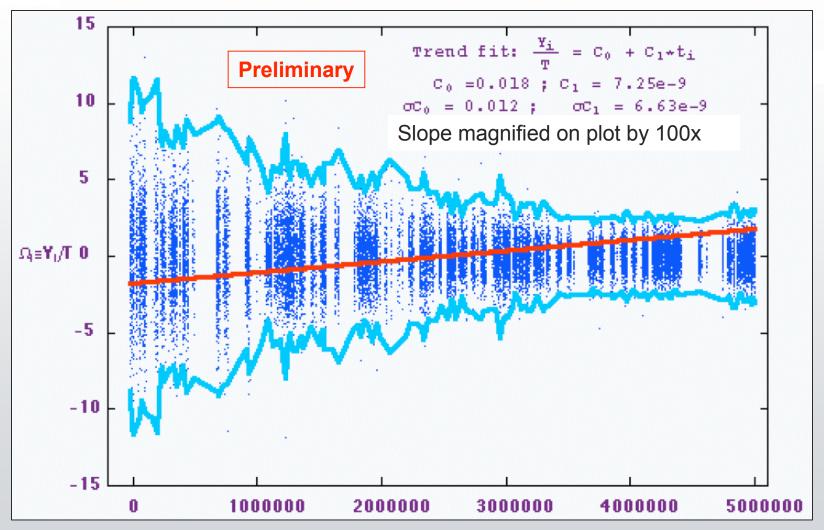


- Problems with PSD estimators when the noise is non-stationary over this time period
- Compare this PSD to that computed with data in the interval; reject interval if they don't agree within 20%





S2 Results: H1-L1 CC statistic trend



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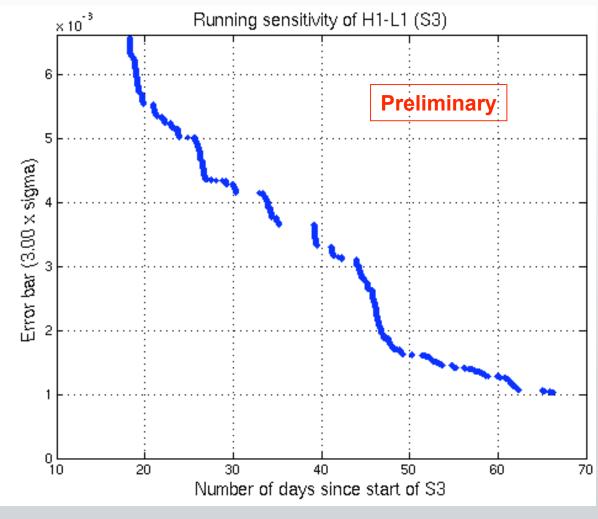
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S3 Sesitivity: H1-L1

Error-estimate $(+3\sigma)$ plotted for the H1-L1 pair as a function of run time.

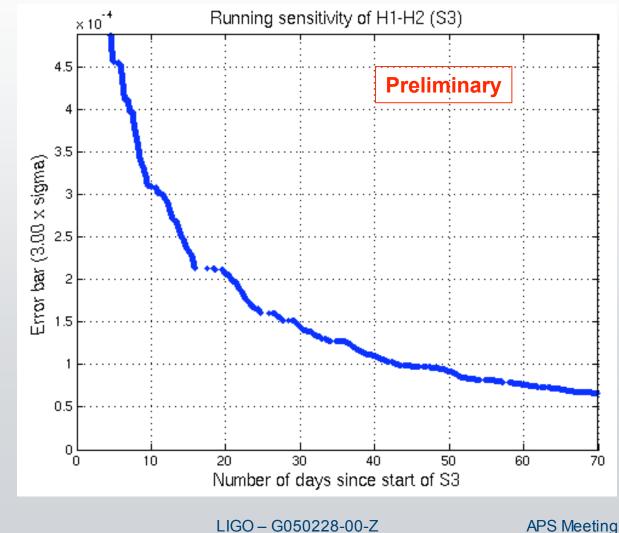


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S3 Sensitivity: H1-H2

Error-estimate $(+3\sigma)$ plotted for the H1-H2 pair as a function of run time.



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LIGO Results on $\Omega_0 h_{100}^2$

| LIGO run | H1-L1, H2-L1 | H1-H2 | Frequency Range | Observation Time |
|----------------------------|-------------------------------------|--|--|--|
| S1 PRD 69(2004) | < 23 +/- 4.6 (H2-L1) | Cross-correlated instrumental noise found | 40-314 Hz | 64 hours (08/23/02 – 09/09/02) |
| S2 <u>Preliminary</u> | < 0.018 +0.007- 0.003 (H1-L1) | Cross-correlated instrumental noise found | 50-300 Hz | 387 hours (02/14/03 – 04/14/03) |
| S3 In progress | | Trying to account for instrumental noise in bounding Ω_{gw} | 50-250 Hz (H1-L1) 70-220 Hz (H1-H2) | 350 hrs (H1-L1) 550 hrs (H1-H2) (10/31/03 – 01/09/04) |
| S4 Starting Analysis | | | | 447 hrs (H1-L1) 510 hrs (H1-H2) (02/22/05 – 03/24/05) |



Summary

- The current best IFO-IFO upper-limit is from S1: $\Omega_0 h^2 < 23 + / -4.6$
 - S2 result: 0.018 (+0.007- 0.003) PRELIMINARY
 - The S3 data analysis is in progress.
- H1-H2 is the most sensitive pair, but it also suffers from crosscorrelated instrumental noise.
- Also working on:
 - Set limits for $\Omega_{gw}(f) \sim \Omega_n(f/f_0)^n$
 - Targeted searches
- Expected sensitivities with one year of data from LLO-LHO:
 - Initial LIGO $\Omega_0 h^2 < 2x10^{-6}$
 - Advanced LIGO $\Omega_0 h^2 < 7x10^{-10}$