

Modeling the Input Optics with e2e

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[Objectives]

- Report status of e2e modeling
- Results
 - Calibrated floor motion
 - Better Mode Cleaner
 - Mode Matching Telescope in Detector.box
- Comments/Suggestions

Contents

- Estimate the table top motion for a given ground motion.
- Make a Small Optic Suspension (SOS) box with local damping, and find optimal gain settings to damp the optic when estimated table top motion is given.
- Create a Mode Cleaner (MC) box, and implement the length control for the mode cleaner cavity.
- Put all the optics (MCs, SM, and MMTs) in order, and create the Input Optic (IO) box.
- Use the IO box in Simligo, and run the simulation for the entire detector.

[Input Optics]

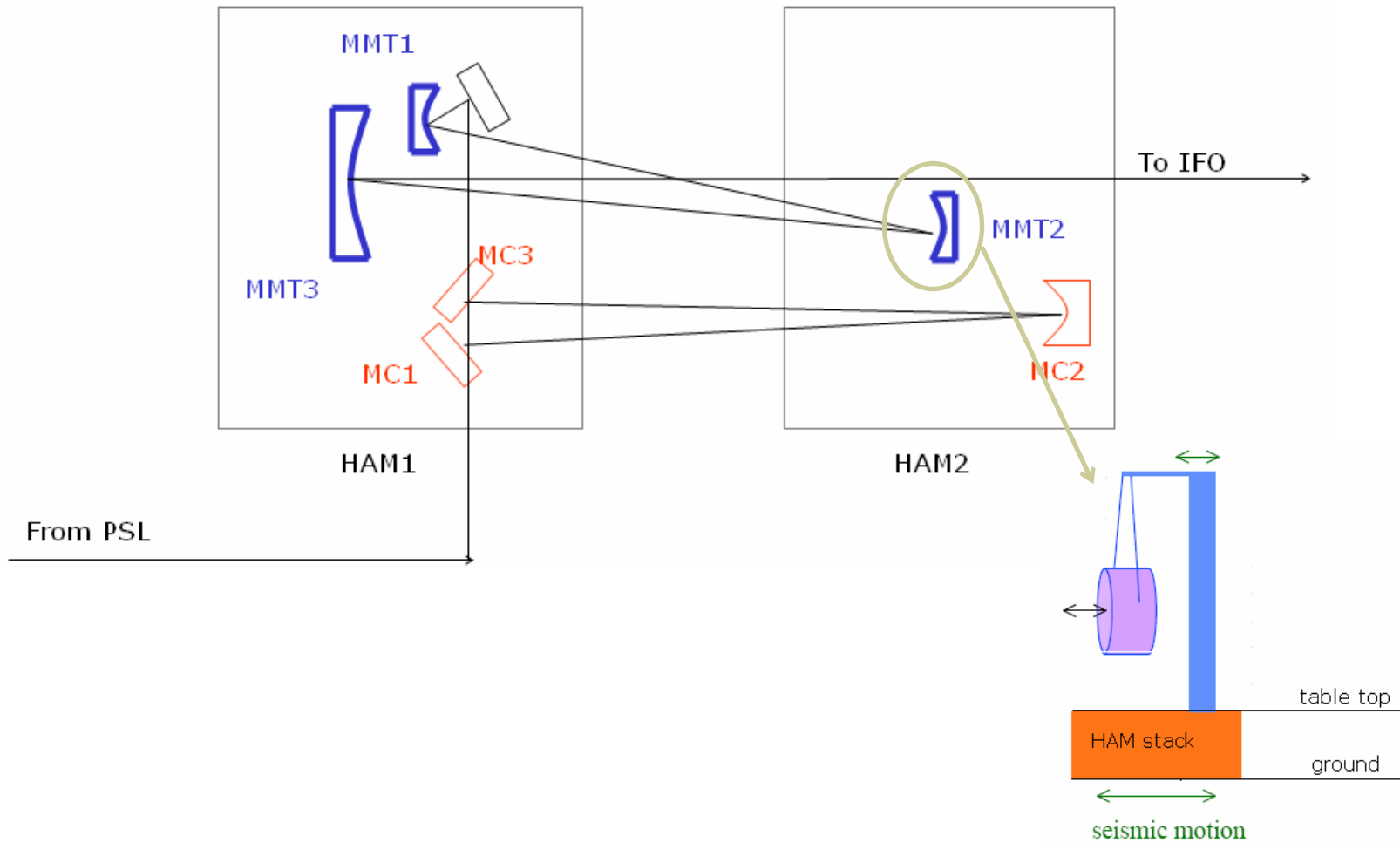
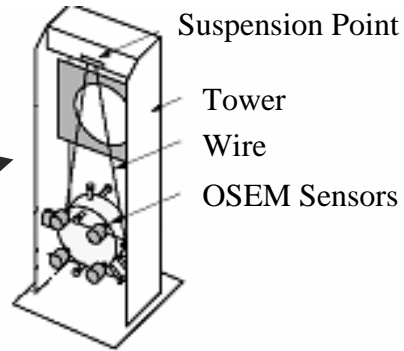
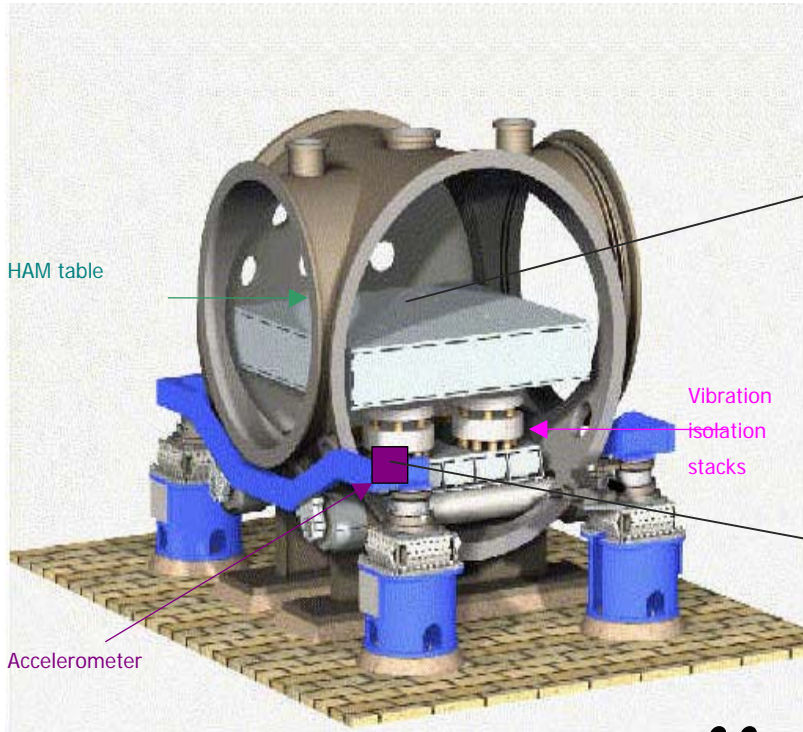
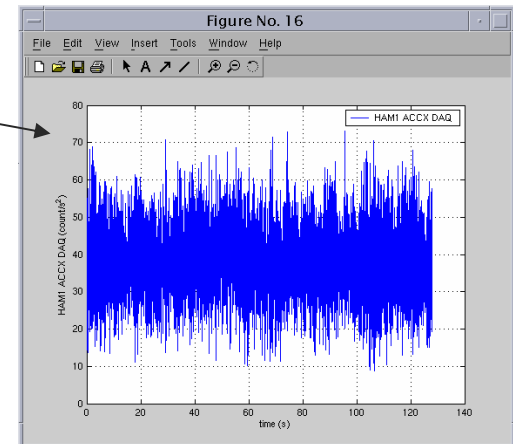


Table Motion

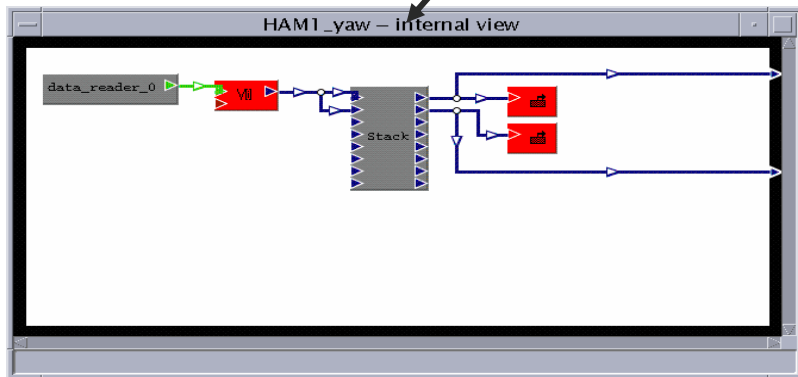
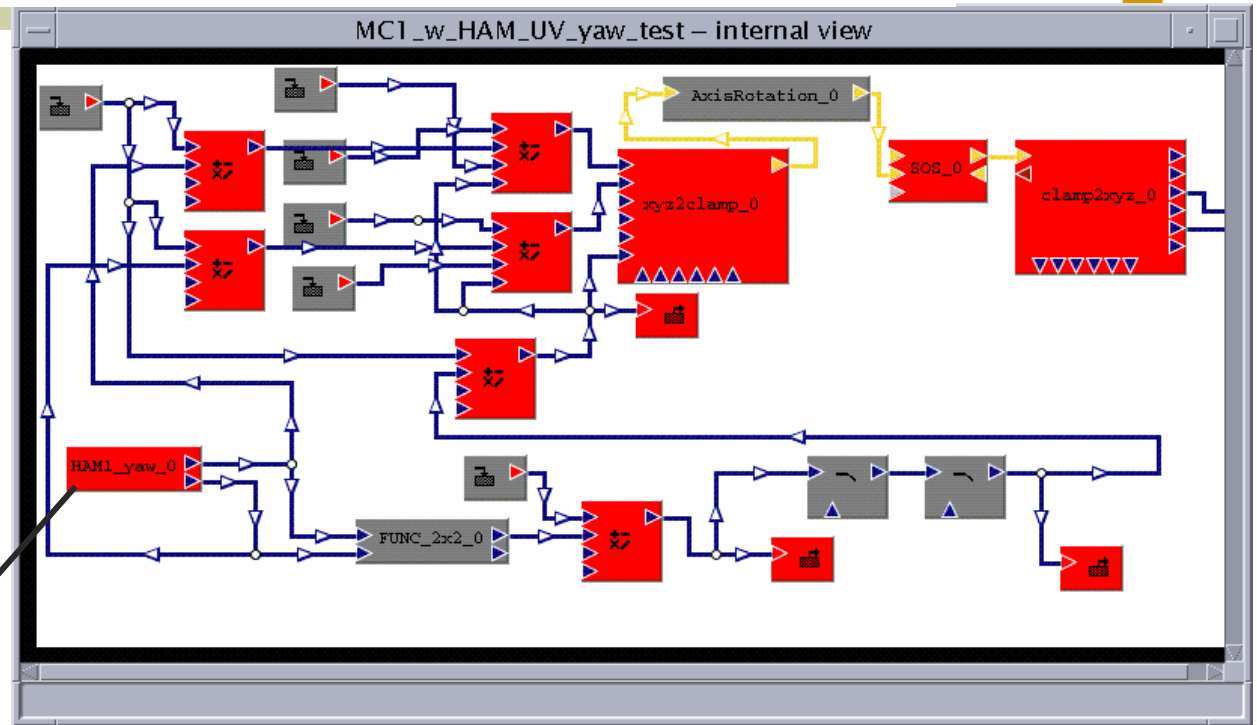


$$x(t) = \iint ACCX dt dt$$



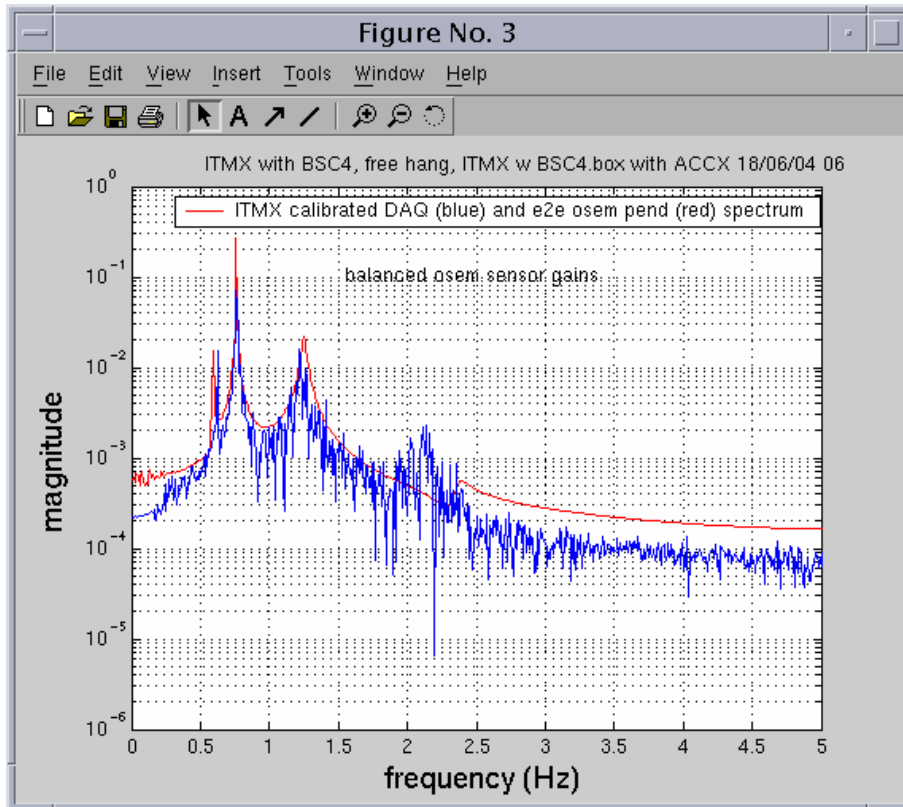
Calibrating the Table Motion

MC1 box

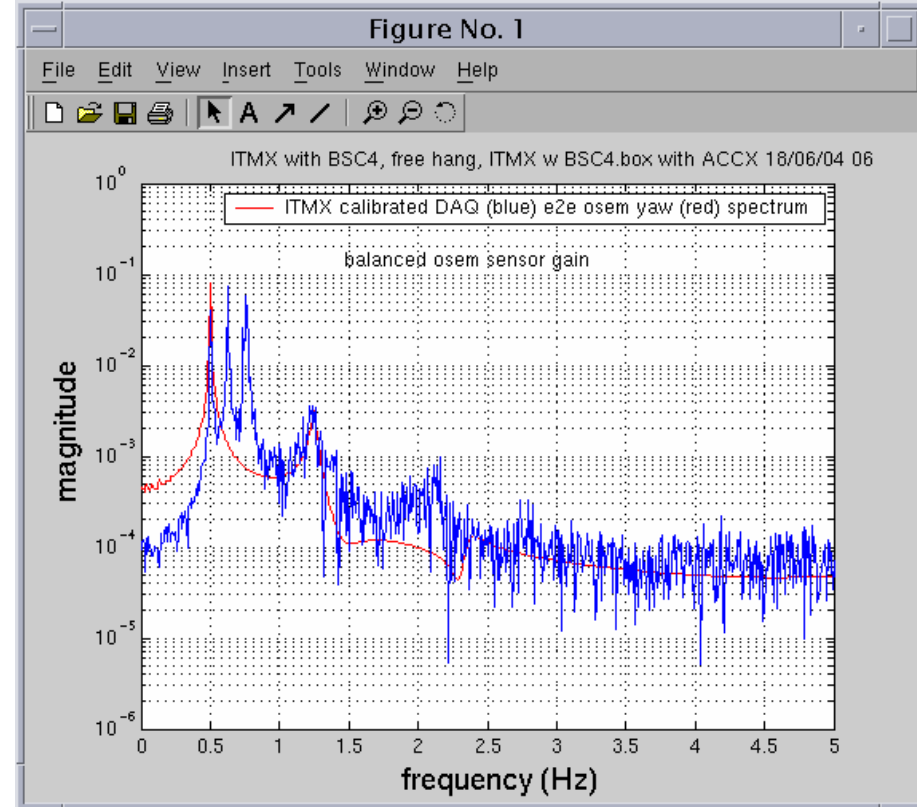


HAM box

ITMX pend/yaw with balanced OSEMs



Pendular



Yaw

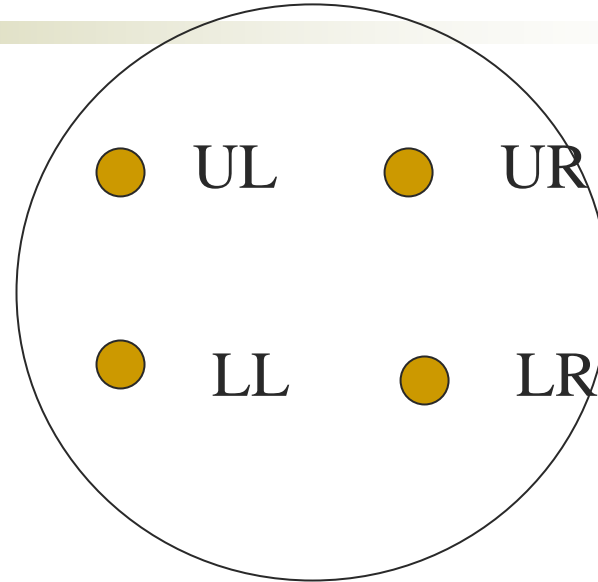
OSEM sensor imbalance

$$UR = (P + Y + T) g_1$$

$$UL = (P - Y + T) g_2$$

$$LL = (P - Y - T) g_3$$

$$LR = (P + Y - T) g_4$$



$$\text{OSEM } P = UR + UL + LL + LR$$

$$= (P + Y + T)g_1 + (P - Y + T)g_2 + (P - Y - T)g_3 + (P + Y - T)g_4$$

$$= (g_1 + g_2 + g_3 + g_4)P + \underbrace{(g_1 - g_2 - g_3 + g_4)}_{\downarrow} Y + \underbrace{(g_1 + g_2 - g_3 - g_4)}_{\downarrow} T$$

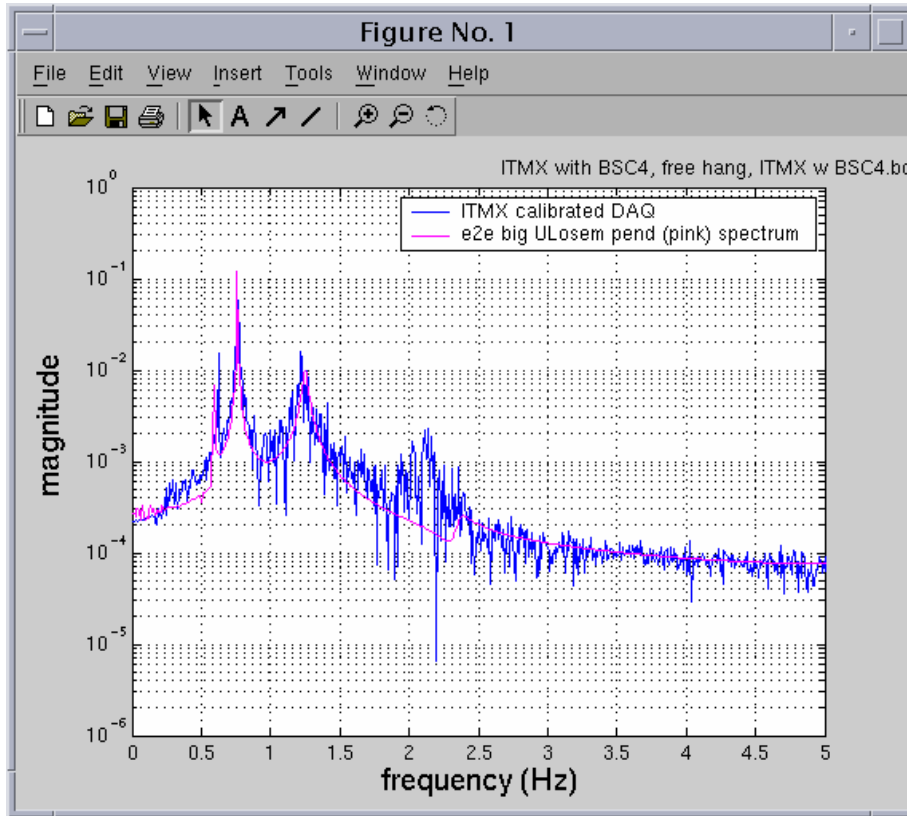
$$= 0, \text{ if } g_1 = g_2 = g_3 = g_4$$

If $g_1 = 1.05$, $g_2 = g_3 = g_4 = 0.95$

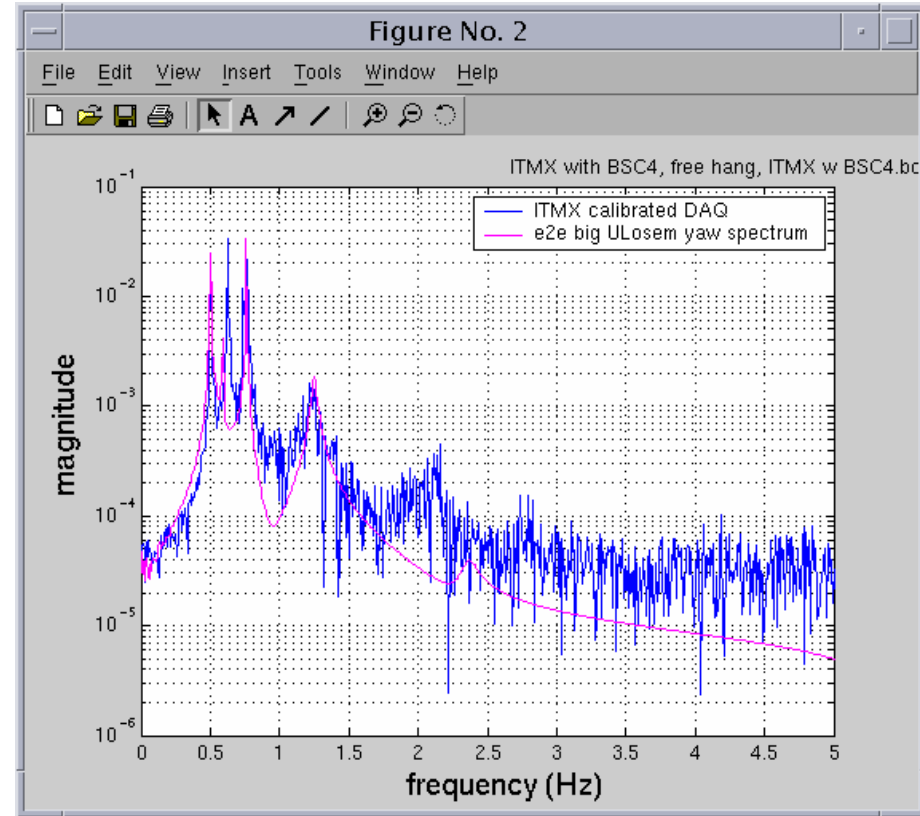
$$\text{OSEM } Y = UR - UL - LL + LR$$

$$= 0.1P + 3.9Y + 0.1T$$

ITMX pend/yaw with pend/yaw ratio = 0.023

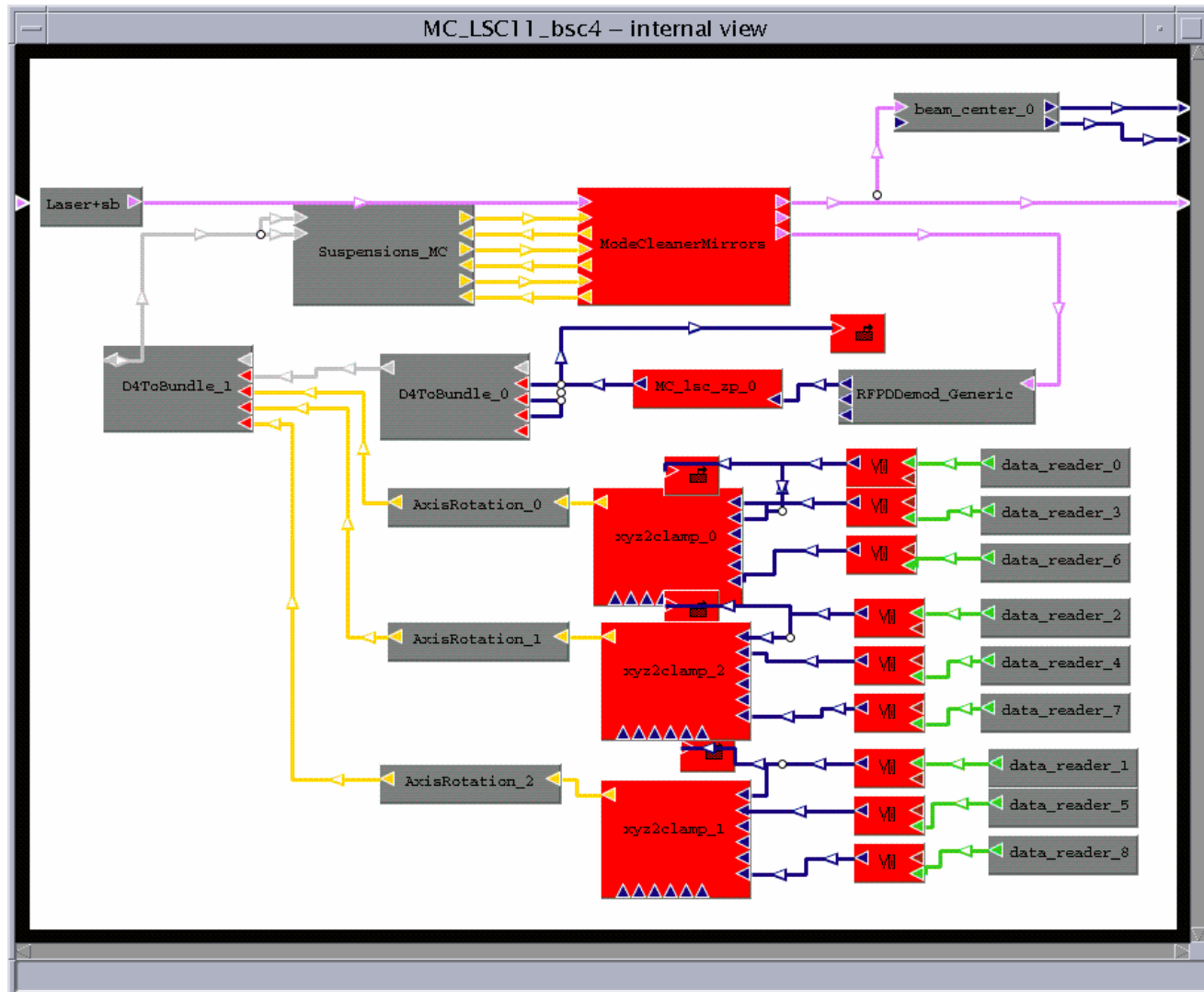


Pendular

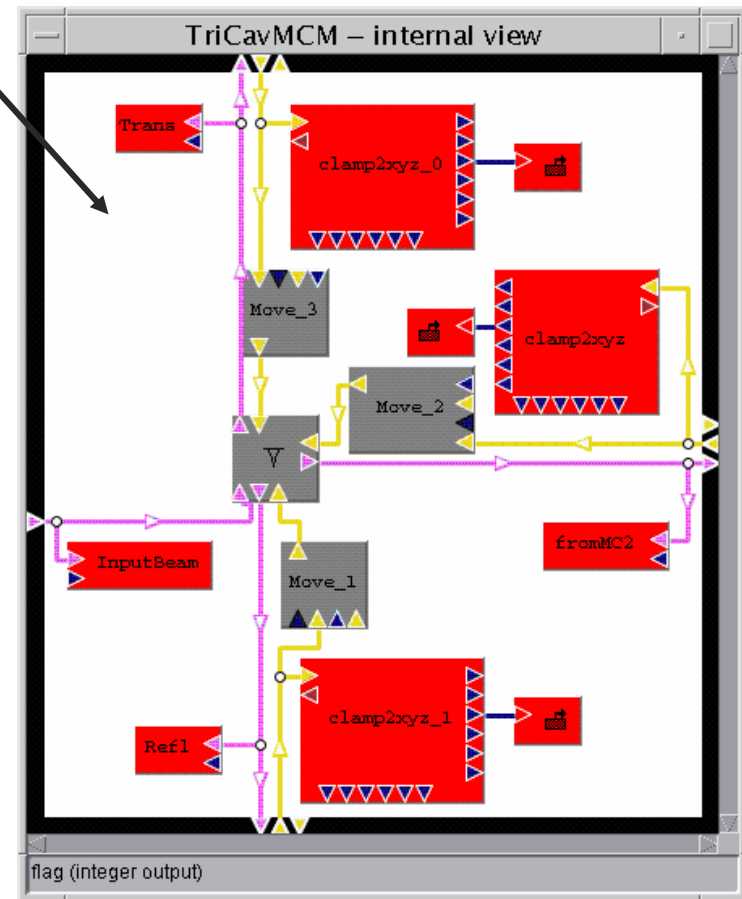
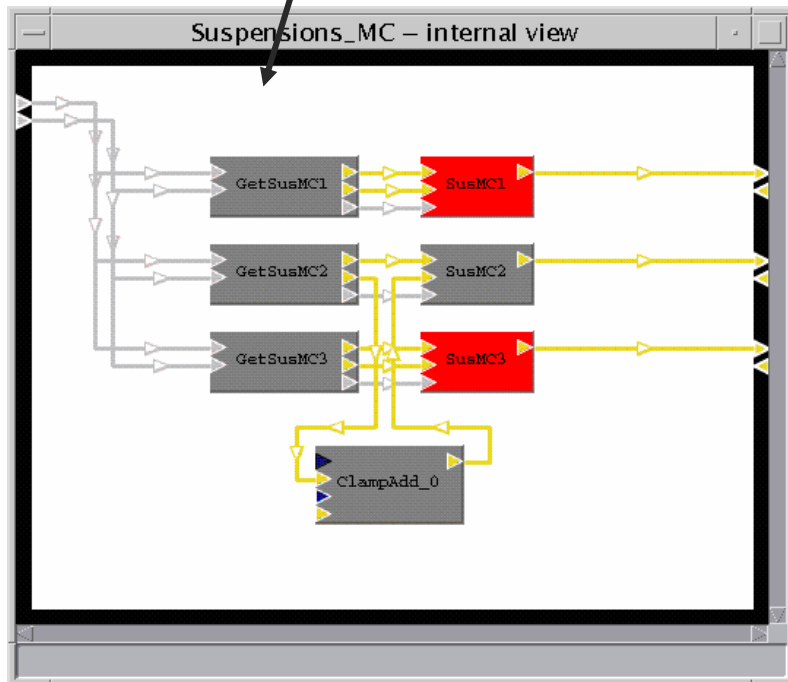
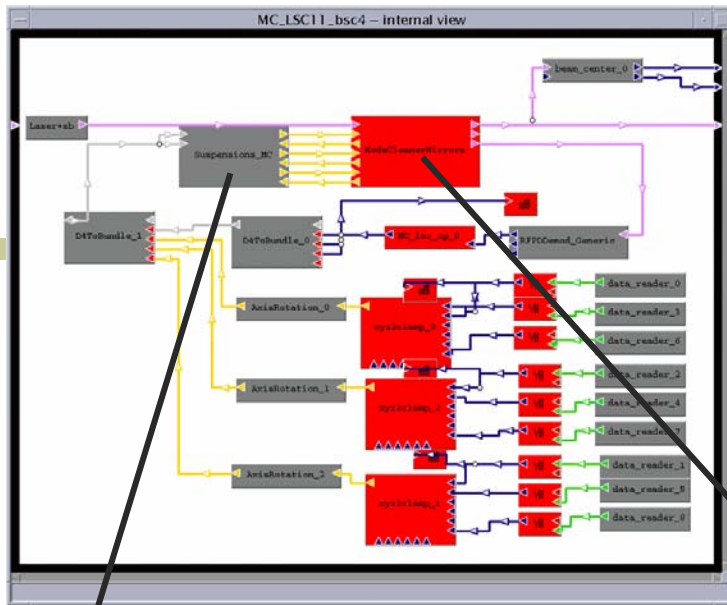


Yaw

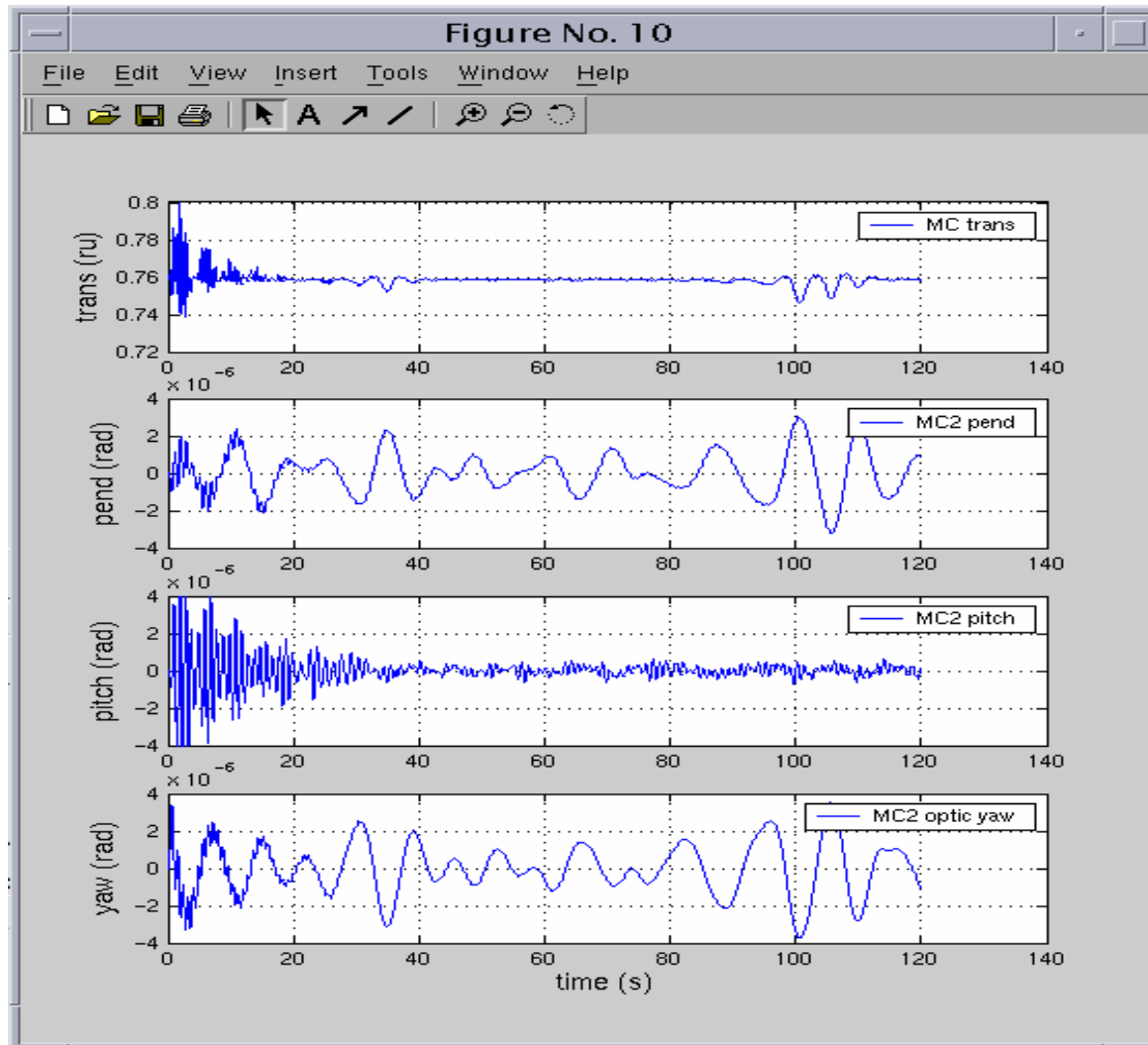
Mode Cleaner



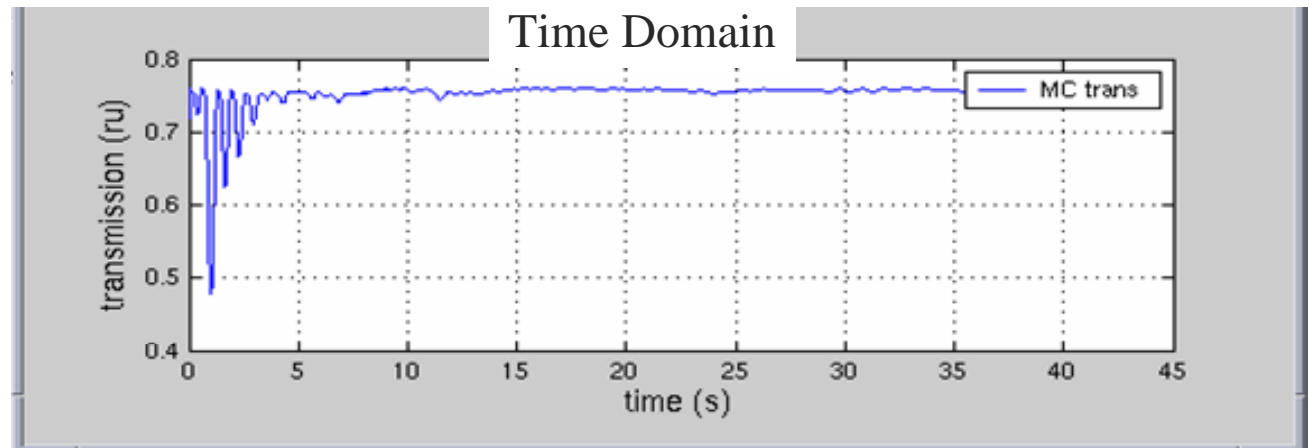
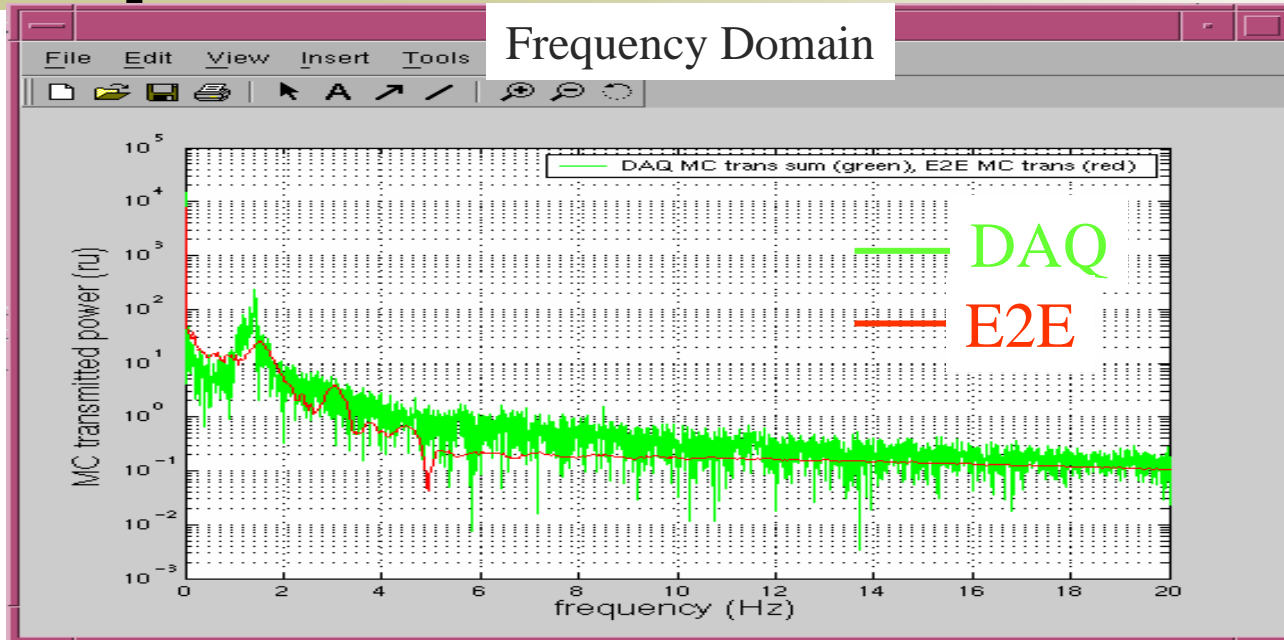
Mode Cleaner Continued



MC Transmission and MC2 motion



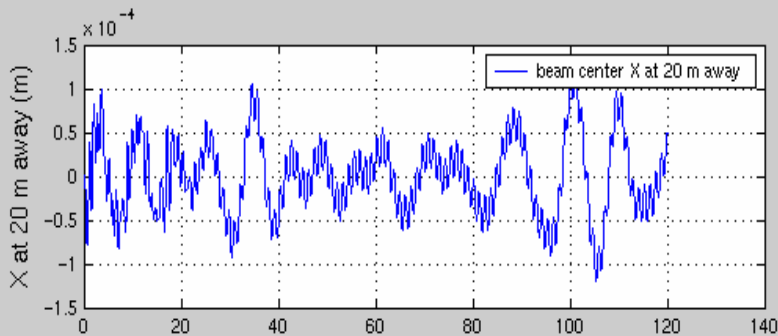
MC Transmitted Power



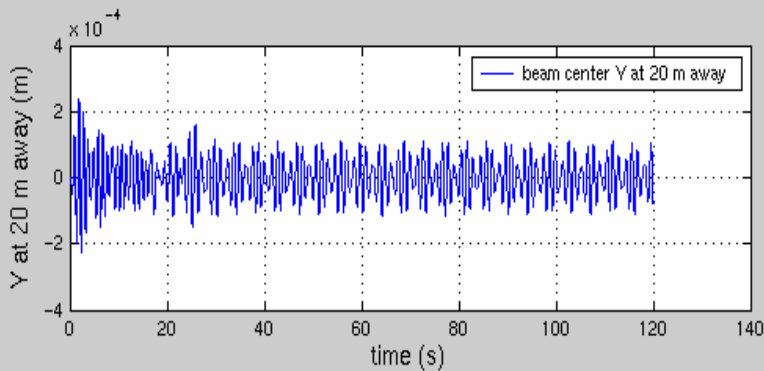
MC Beam Motion

Time Domain

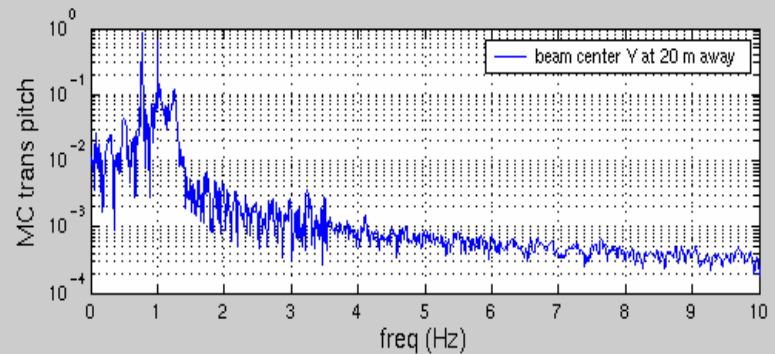
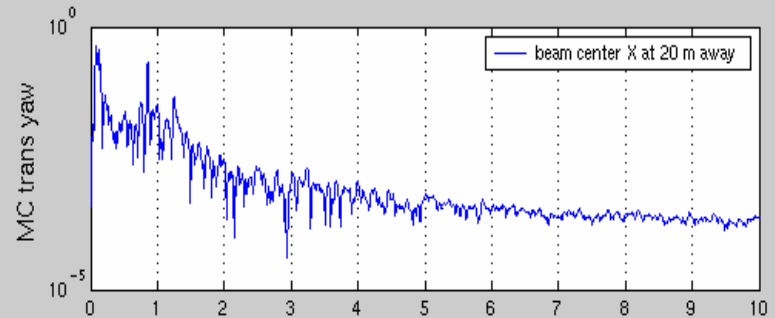
yaw



pitch

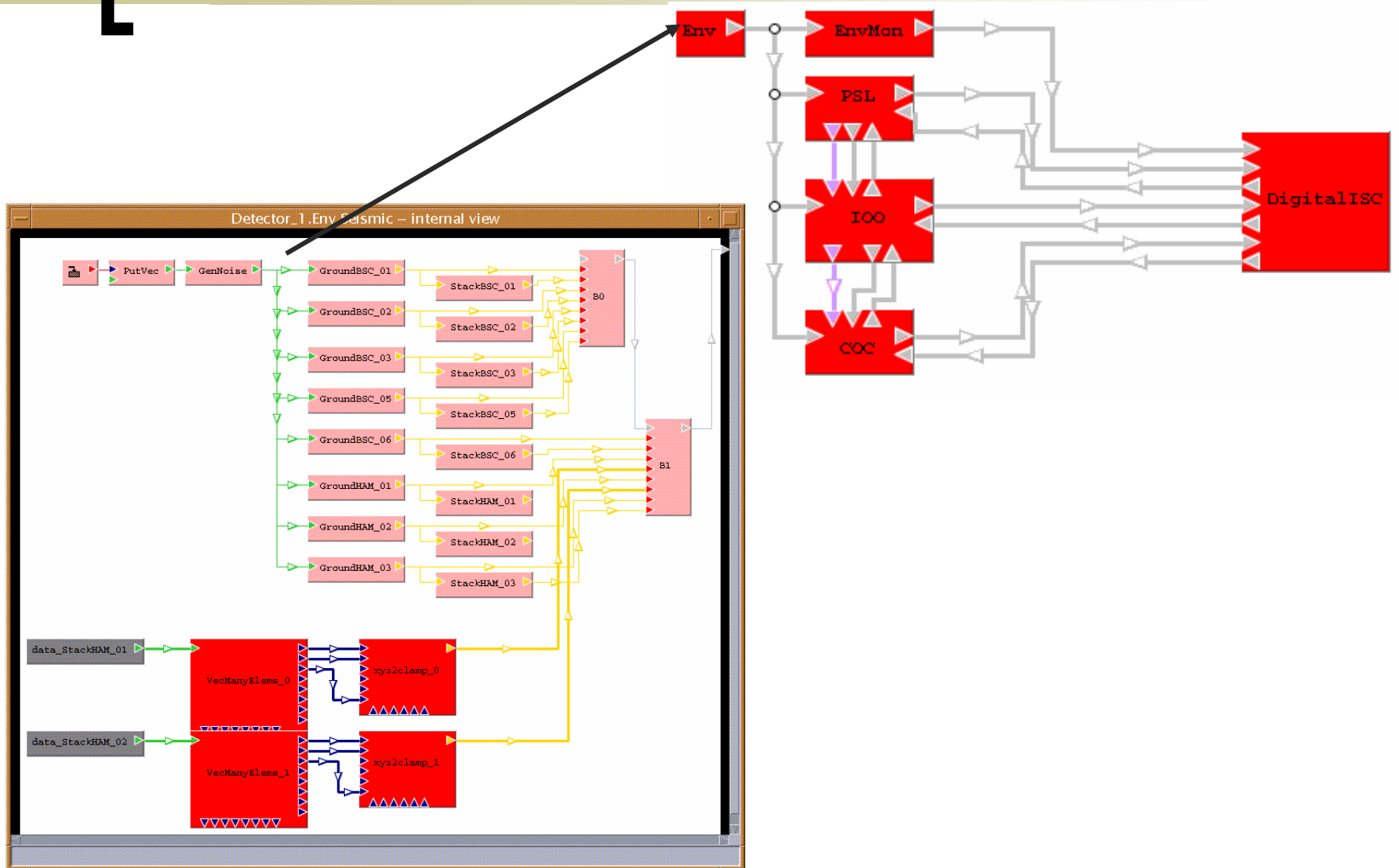


Frequency Domain

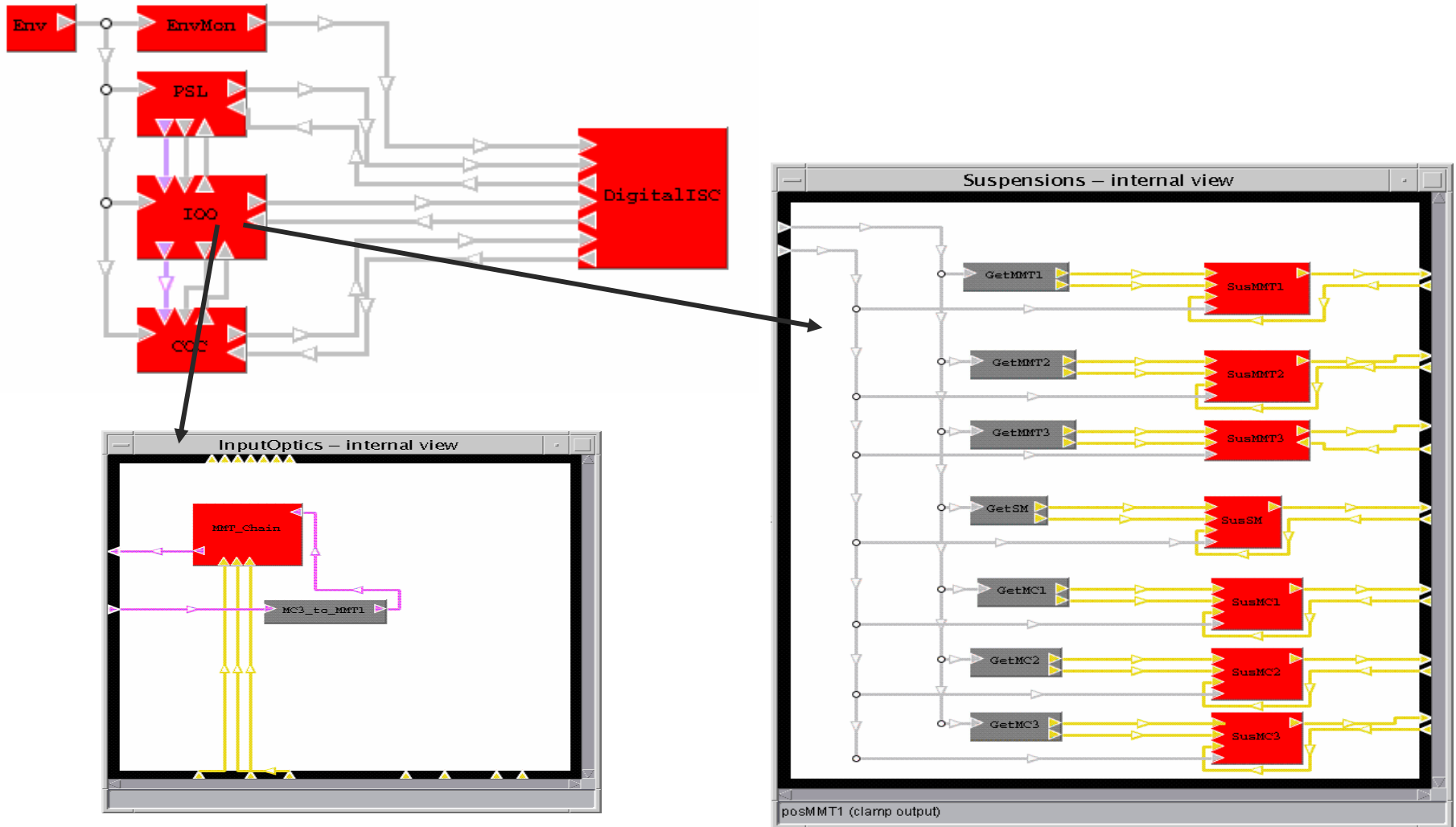


Beam center 20 meters away from MC pitch (lower)

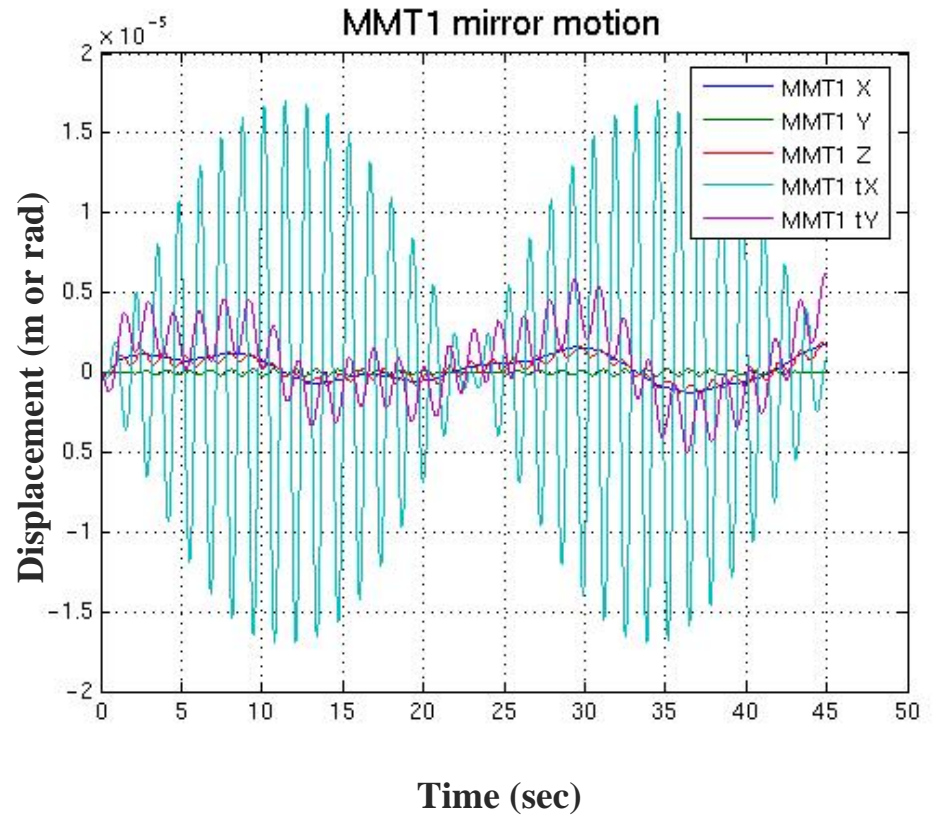
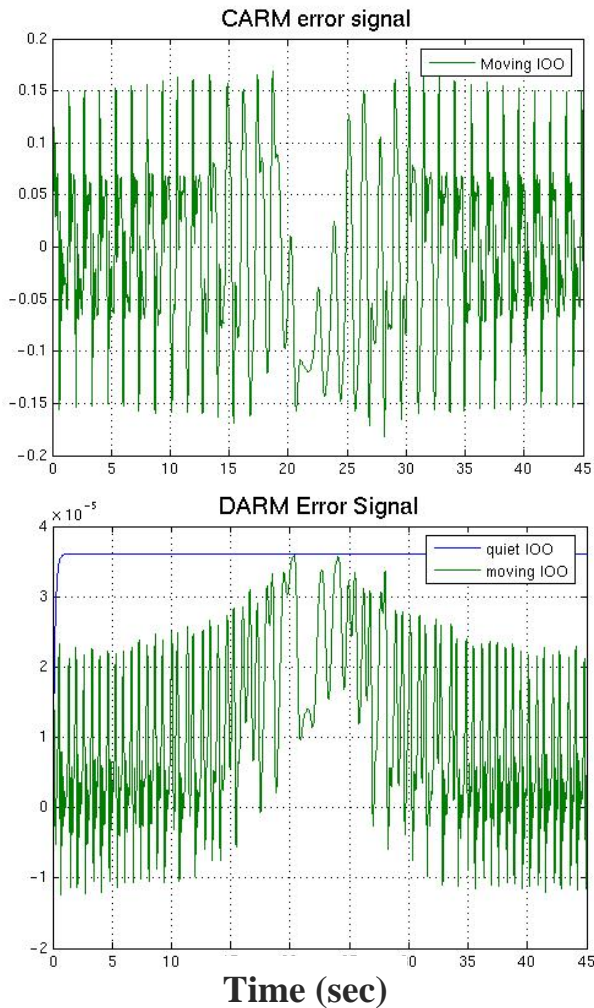
Detector box



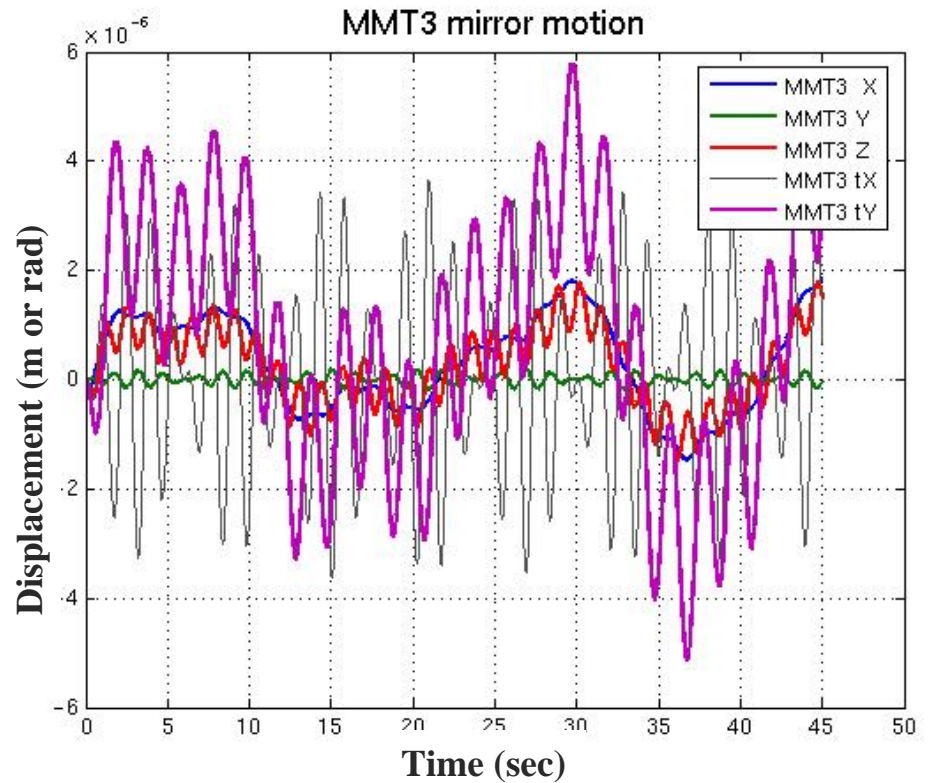
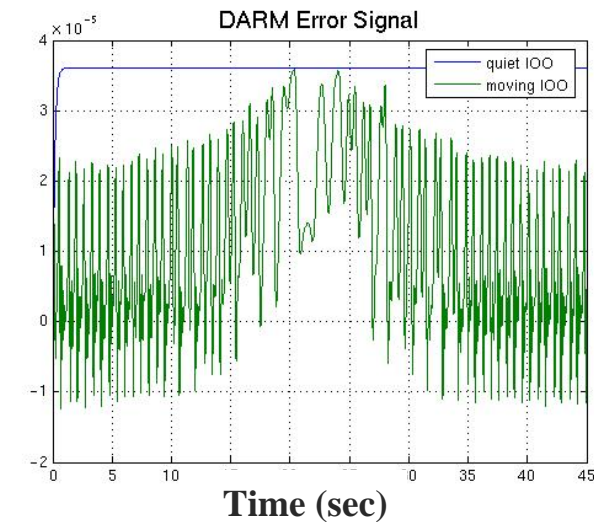
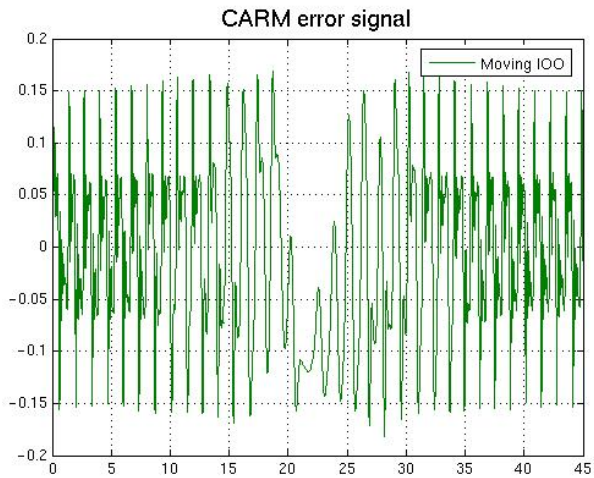
Status of IO box: Contains MMT optics only



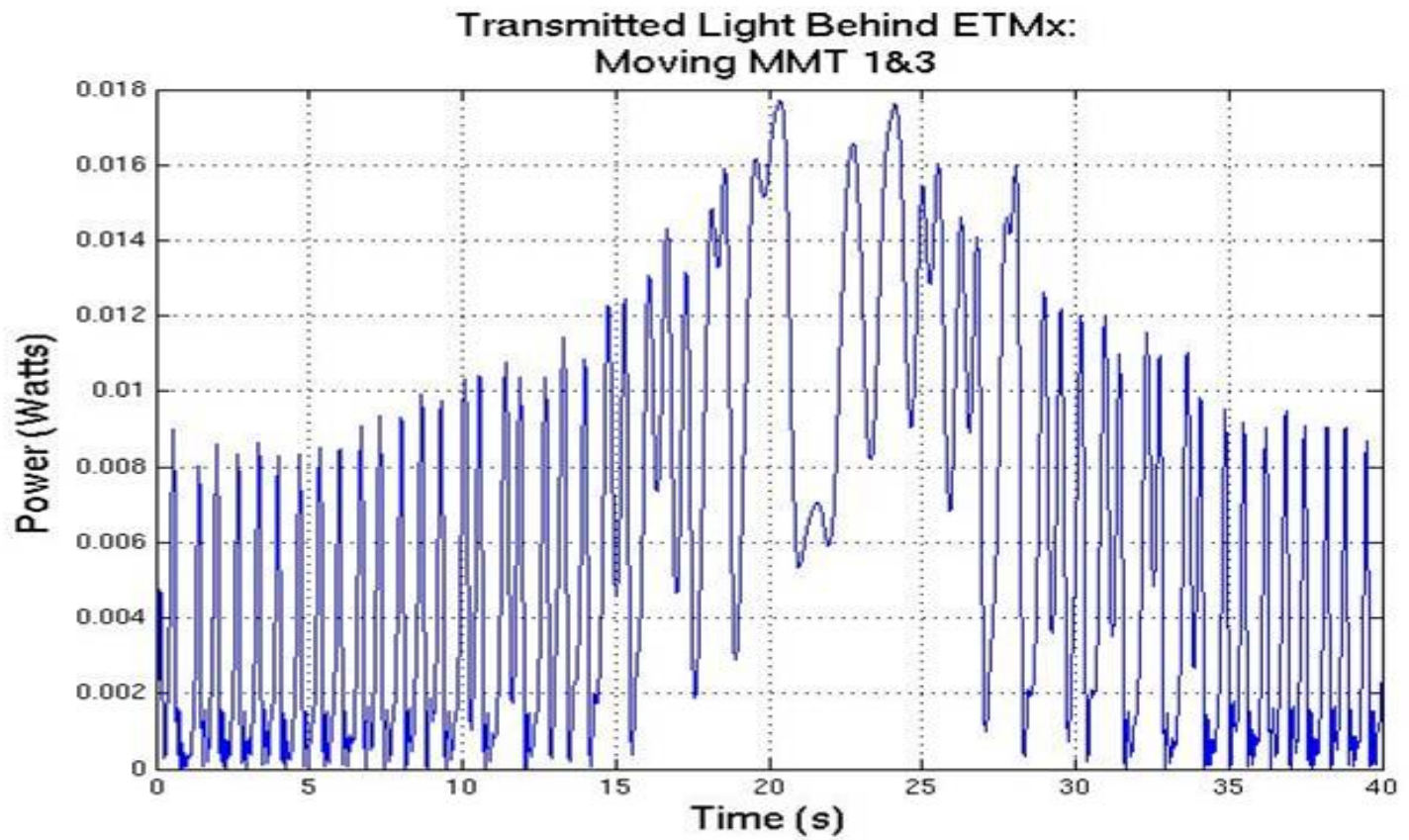
MMT1 motion effect on CARM and DARM error signals



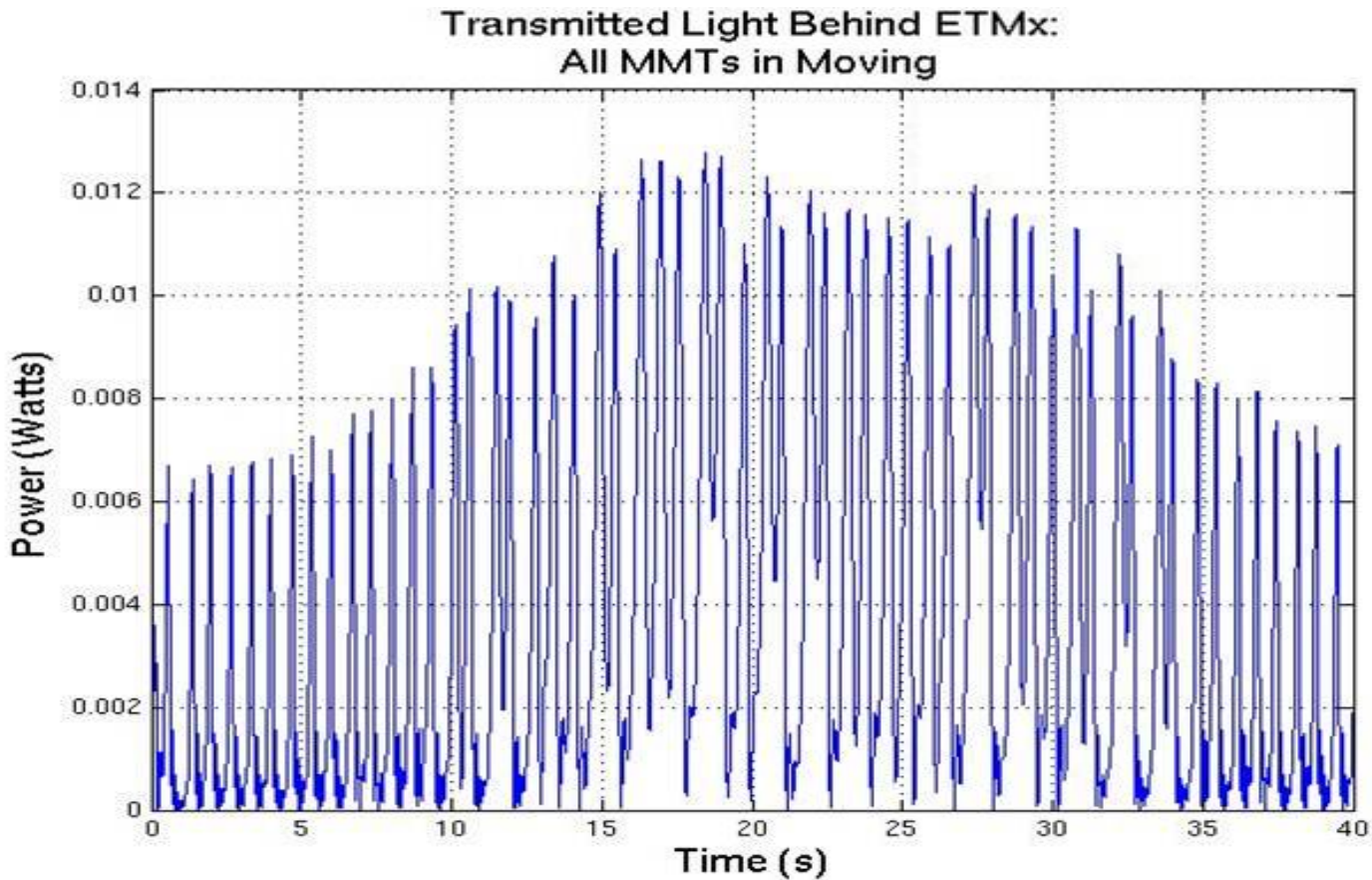
MMT3 motion effect on CARM and DARM



Power Behind ETMx due to MMT1 and MMT3 motion



Power Behind ETMx due to MMT optics motion



[Summary]

- Produced a better representation of the table translational and yaw motion
- Created a Mode Cleaner box with Length Sensing Control
- Put the Mode Matching Telescope into Detector box
- Will continue investigating the effect of table motion on the optic and the resultant beam motion
- Will include Mode Cleaner box in Detector box

Acknowledgements

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