Status of StochMon

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Stochastic Figure of Merit

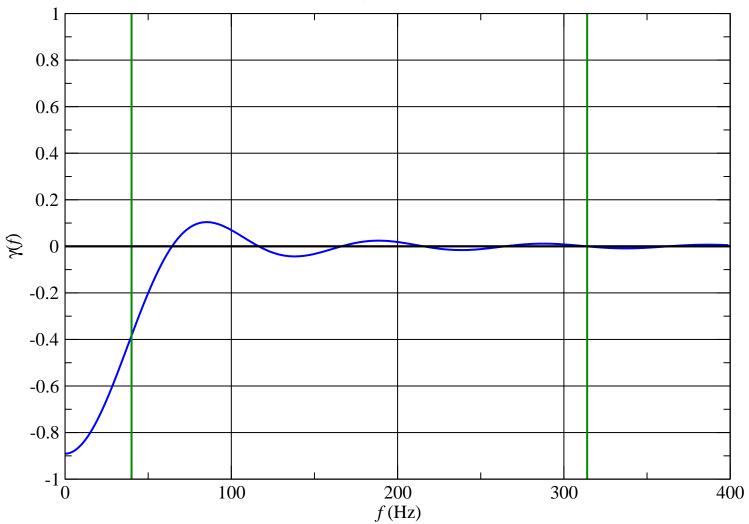
Basis for figure of merit: Assuming flat GW spectrum $(\Omega_{\rm GW}(f)={\rm constant})$, the stochastic background strength we could detect in time T is $\Omega_{\rm S}$:

$$\frac{1}{\Omega_{\rm S}^2} \propto T \left(\int_{f_{\rm min}}^{f_{\rm max}} df \frac{\gamma^2(f)}{f^6 P_1(f) P_2(f)} \right)$$

- Use Ω_s^{-2} instead of Ω_s so sensitivity grows linearly with observation time.
- $P_1(f)$ & $P_2(f)$ are (calibrated) noise PSDs of two detectors
- $\gamma(f)$ is the overlap reduction function (known function of frequency, $\equiv 1$ for H1-H2)

Overlap Reduction Function

LIGO-Livingston / LIGO Hanford



(For correlations between LHO 2km & LHO 4km, $\gamma(f) \equiv 1$)

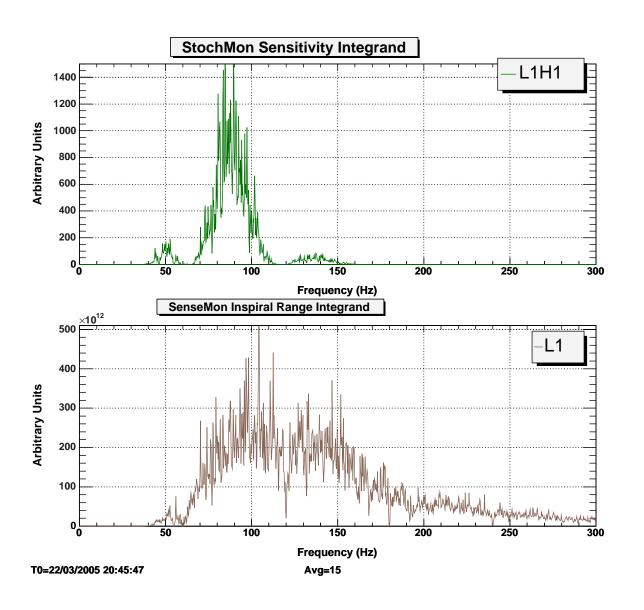
Developments since August

- StochMon now working and running online at both sites
- Overlap reduction function implemented
- StochMon updated to use new EZCalibrate class (thanks to P. Sutton for help)

StochMon in S4

- Versions running online(S4): H1H2 H2H1 H1L1 L1H1
- PSD for first IFO is calculated in real time;
 PSD for second IFO is a "good reference spectrum"
- Present reference spectra taken early in S4 from the output of SenseMonitor and StochMon

StochMon vs SenseMonitor



S4 Benchmark Values

What is a typical FOM for StochMon?

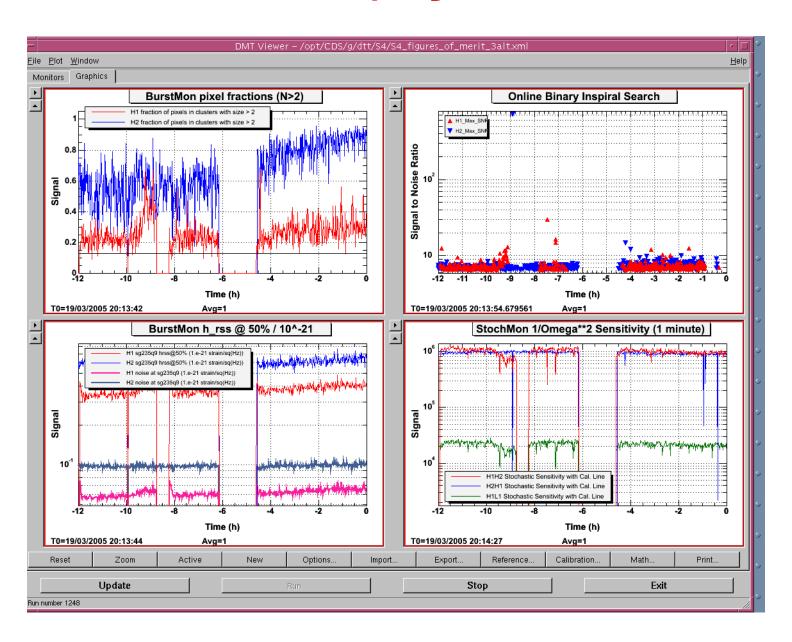
S4 Stochastic sensitivity benchmark values:

StochMon_L1H1 or StochMon_H1L1 \longrightarrow 2.6 \times 10⁴ (using L1_CalPSD_GPS_793481866.txt and H1_CalPSD_GPS_793443300.txt)

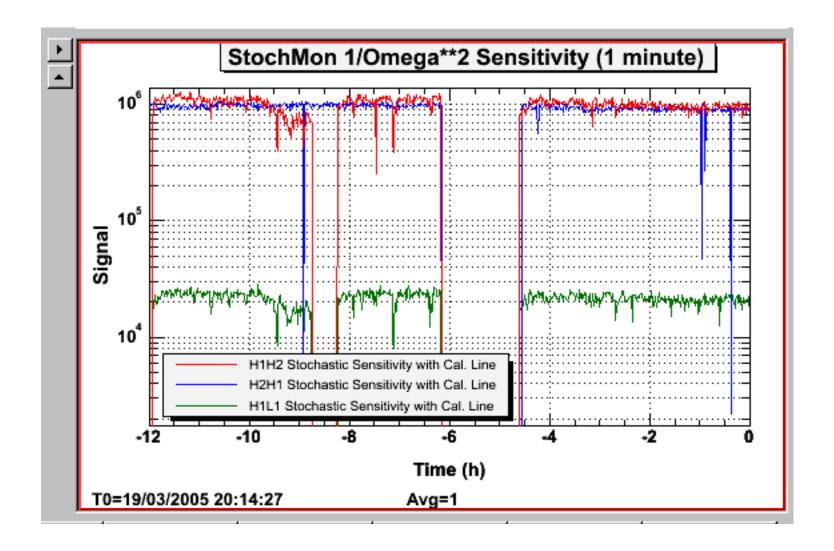
StochMon_H1H2 or StochMon_H2H1 \longrightarrow 1.3 \times 10⁶ (using H1_CalPSD_GPS_793443300.txt and H2_CalPSD_GPS_793481321.txt)

• Running for one year at this noise level, detectable background ($\Omega_{\rm S}$) would be 8.5×10^{-6} (L1/H1) and 1.2×10^{-6} (H1/H2)

Astro FOM Display from Hanford

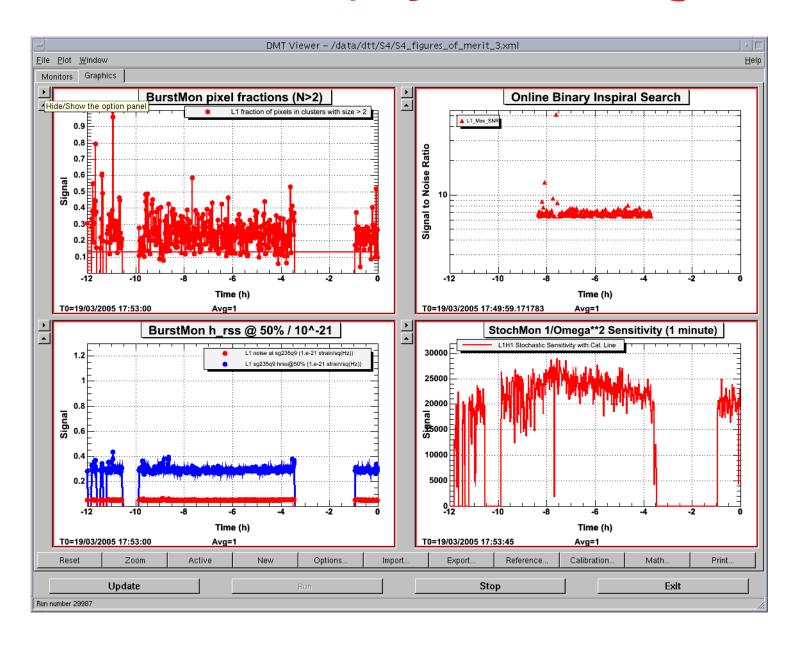


StochMon Traces from Hanford

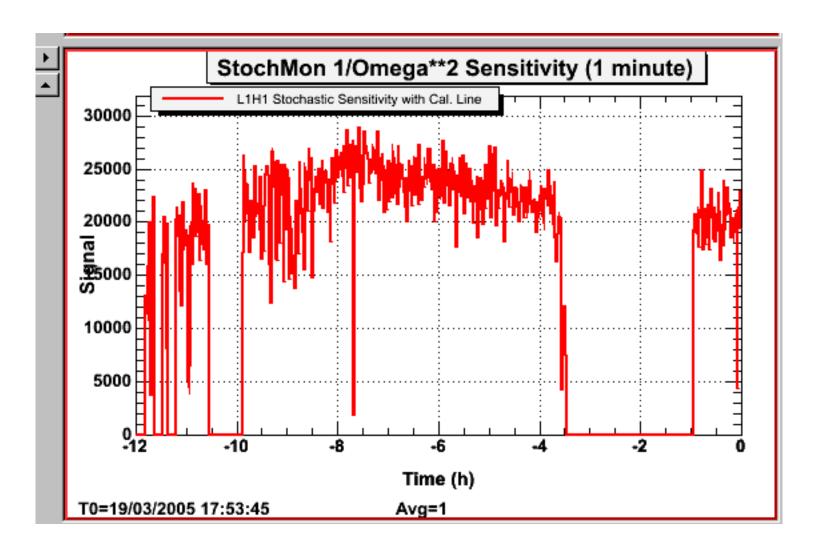


Note: Vertical scale should really be linear

Astro FOM Display from Livingston

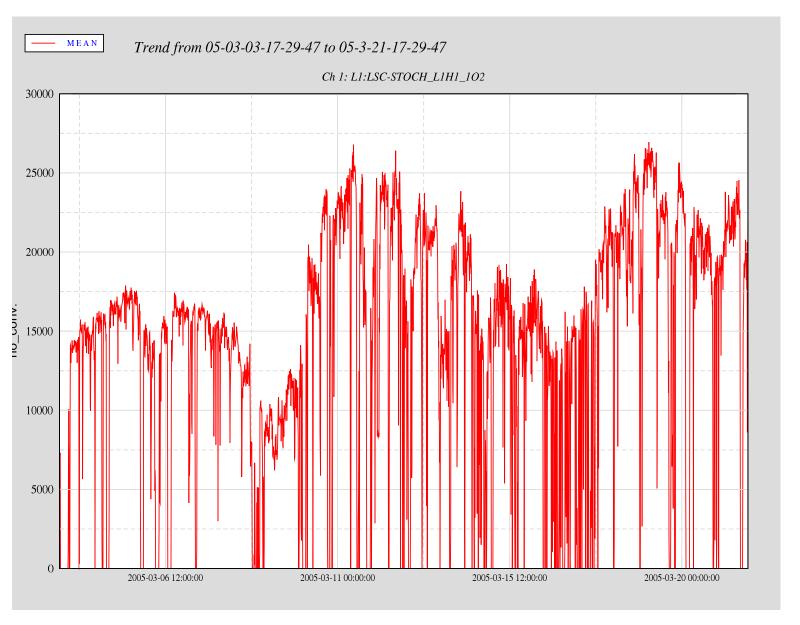


StochMon Trace from Livingston



Note: Area under curve is cumulative sensitivity

Weeks-long Time Series for S4



Planned Enhancements

Clean up (channel names, file parsing, etc)

 More control over output by-products (some redundant with SenseMonitor)

• Output Ω_s as well as $\frac{1}{\Omega_s^2}$

Add functionality to measure both PSDs in real-time