



Advanced LIGO Prestabilized Laser System - conceptual design proposal -

Benno Willke

LSC Meeting Livingston, March 2004 LIGO-G040181-00-Z



LIGO AdvLIGO PSL – subsystem layout



9

LIGO Advanced LIGO PSL – requirements

Power / Beamprofile:

- 165W in gausian TEM₀₀ mode
- less than 5W in non- TEM_{00} modes

Drift:

- 1% power drift over 24hr.
- 2% pointing drift

Control:

tidal frequency acuator: +/- 50 MHz range, time constant < 30min
power actuator: BW 10kHz +/-1% range
frequency actuator BW: <20° lag at 100kHz range: 1MHz [DC - 1 Hz] 10kHz [1Hz-100kHz]



LIGO











- detector control software (EPICS)
- data acquisition system
- electrical power and cooling

environment:

- size limit
- electro-magnetic disturbances
- laser safety requirements

reliability:

- meantime between failure
- maintenance intervals and duration













- do we need intermediate power stage
- same rf sidebands for both injection locking stage
- required bandwith of injection locking loops
- how much isolation is needed between different stages





- vacuum required
- loop bandwidth / actuator range
- use injection locking sideband
- thermal loading / finesse / transmission
- do we want to investigate into active beam shaping system



- sensing before or behind PMC
- actuator at high power stage
- bandwidth / range needed

PSL – frequency stabilization







who does what ?



- which group would like to contribute hardware / simulations
- what do we need to do for the design requirement document (due date: 8 April 04)
- who will help to finalize conceptual design
- how much detail do we need in the conceptual design phase
 - characterize the high power laser
 - define and specify actuators for different control loops
 - define and specify sensors for different control loops
 - Simulink models of control loops ??
 - Detailed optical layout (AutoCAD, OptoCAD) ??
 - Interface description (electrical, acoustic, optical)
- who will help in writing the conceptual design document (due date: Jan 05)