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# Analysis of Data from Interferometric Gravitational-wave Detectors

Patrick Brady  
University of Wisconsin-Milwaukee  
for  
LIGO Scientific Collaboration



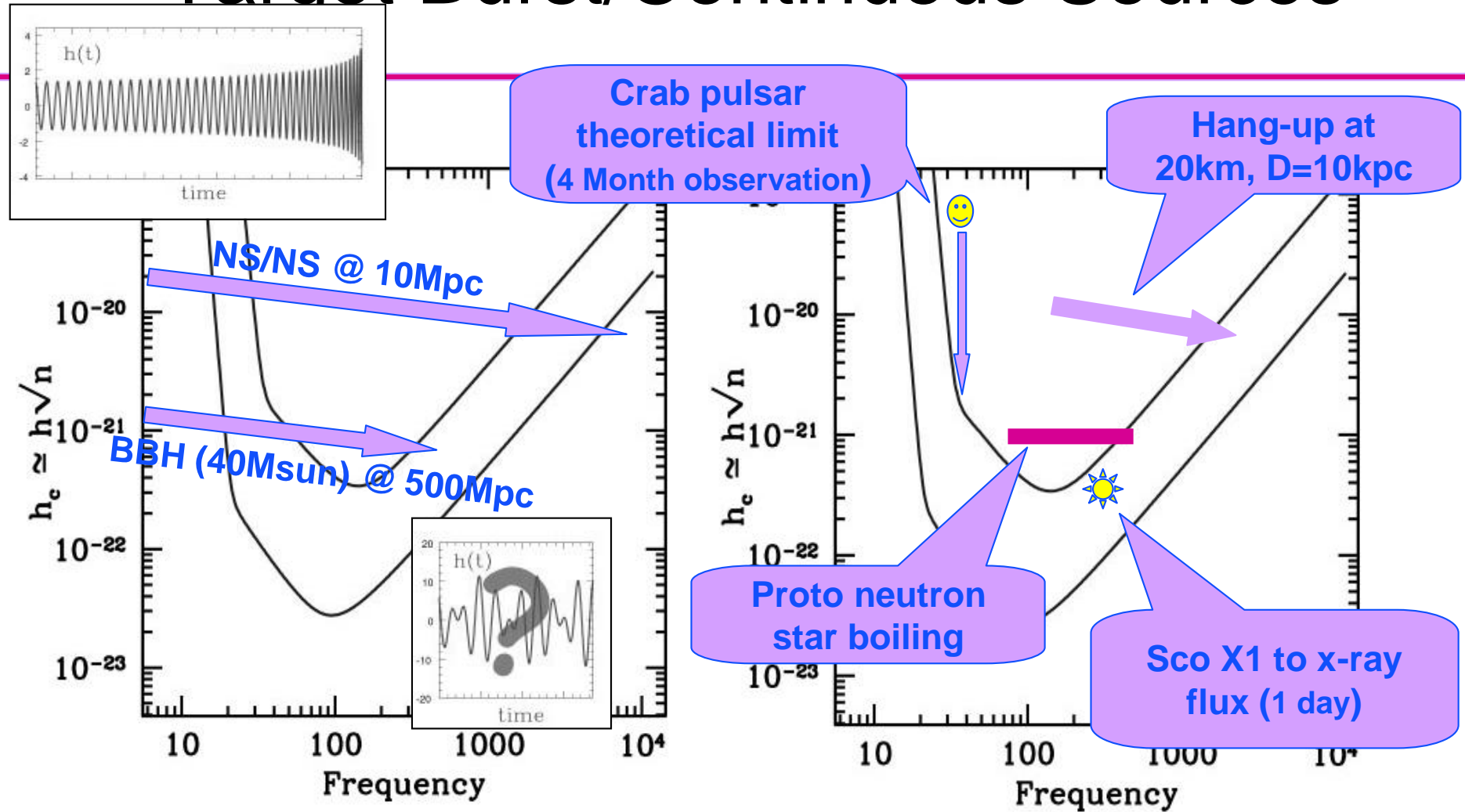
# Waves and Detectors

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- Gravitation
  - » Weaker than Electromagnetism
  - » Radiation from coherent motion of large bodies
  - » Weakness → difficult to detect
  - » Weakness → Universe is transparent to them
- Interferometers
  - » Inherently broadband and multi-directional
  - » Non-Gaussian noise
  - » Non-stationary
  - » Cannot shield from sources → no off-source stats



# Target Burst/Continuous Sources



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# Detection strategies

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- Coherently accumulate power from signal (when in interferometer band) into a single number
- Classic example
  - » Detection of periodic signal in noise by Fourier transform, compare output with expected power due to noise alone.

# Bayesian Optimal Detectors

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- Weinstein & Zubakov, Finn, Finn & Chernoff

$$p(s | h)$$

Depends monotonically on

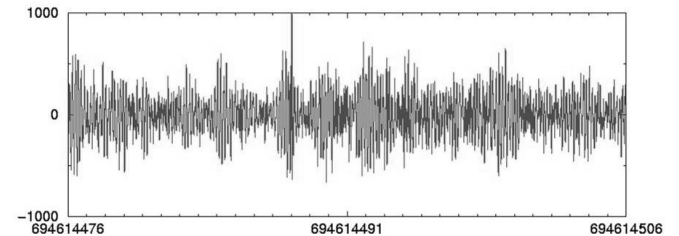
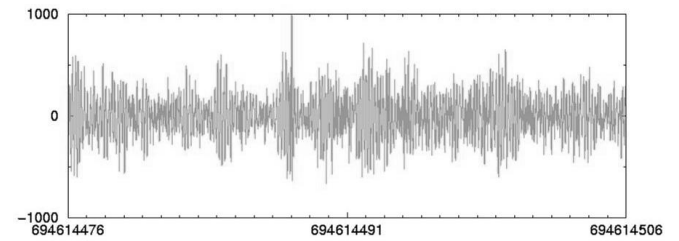
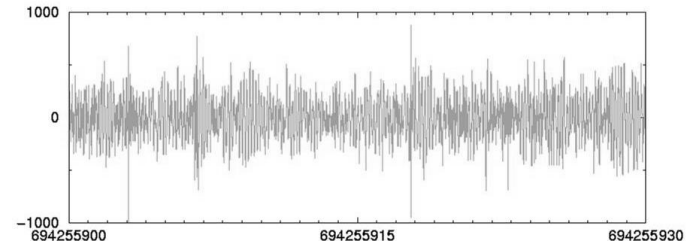
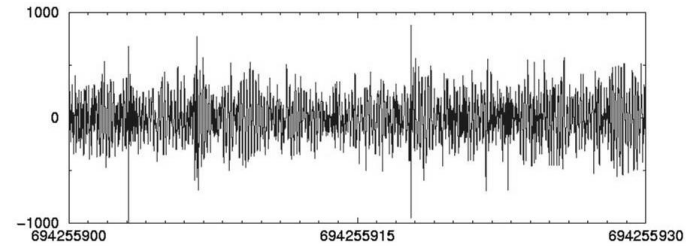
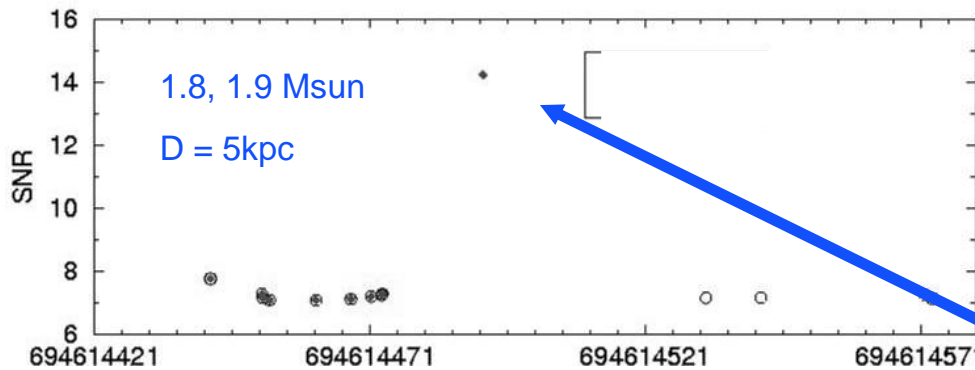
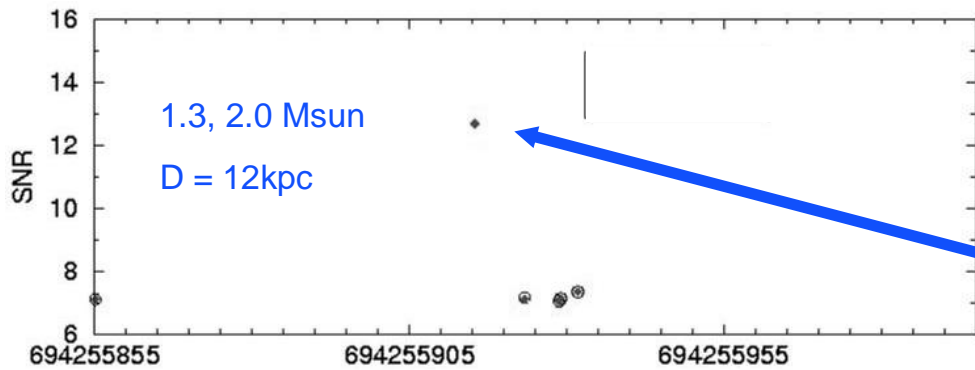
$$\int d\lambda \left( \frac{p(h|s)}{p(h|0)} p[s | \lambda] p[\lambda] \right)$$

- For Gaussian noise and known signal, this gives matched filtering

$$\sum_{k=0}^{N-1} \tilde{s}_k^* \tilde{h}_k / S(f_k)$$

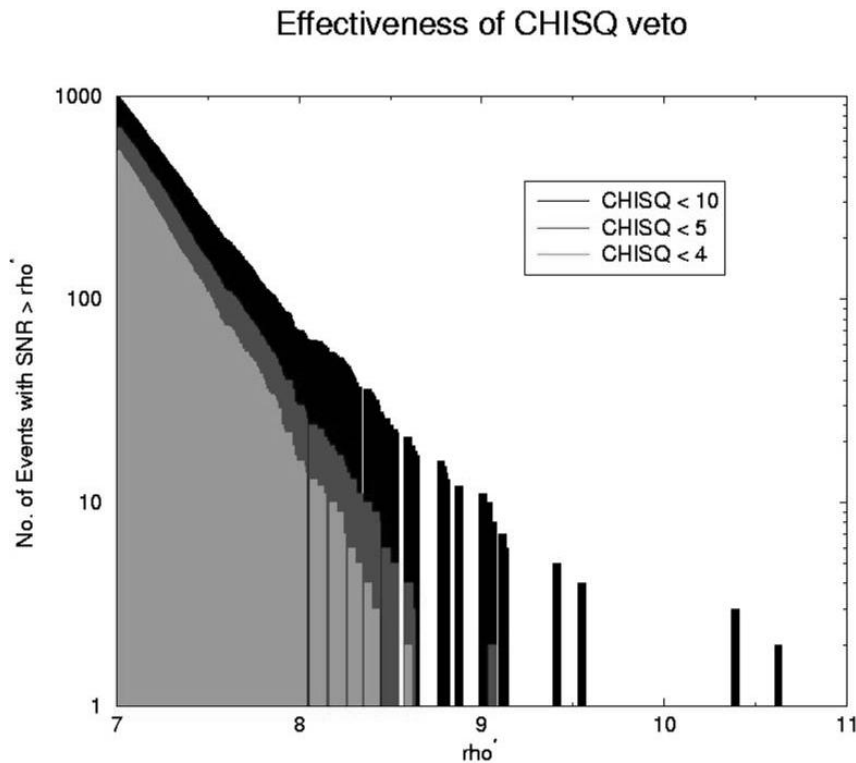


# Testing Detection Methods in Real LIGO (E7) Noise



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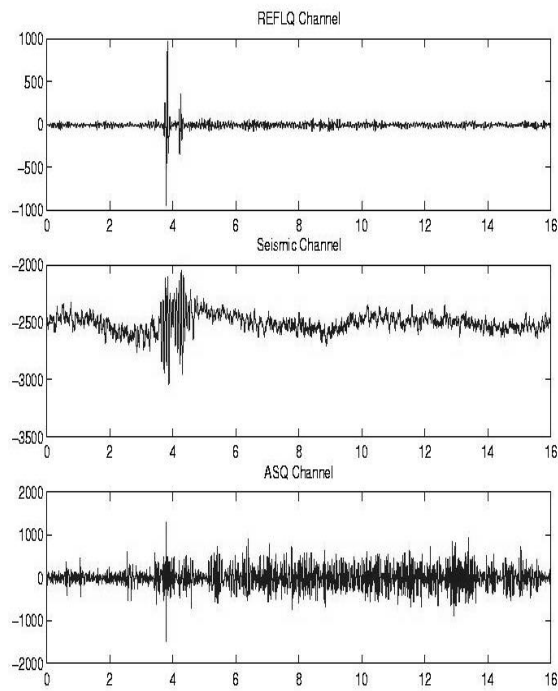
# Dealing with non-Gaussian Noise



- Many mechanisms
- How to deal with them?
  - » Signal based veto: does SNR accumulate as expected?
  - » Originally proposed by Allen, implemented here by Anderson, Brown, and Creighton

# Non-Gaussian Spurions

- Example:
  - » Cattle Guard at LIGO Livingston (Gonzalez, Chickarmane, Saulson during E7)
- How to deal with them?
  - » Auxiliary channels: does spurion show up in other channels?
  - » Coincidence: does signal show up in multiple instruments with appropriate parameters?

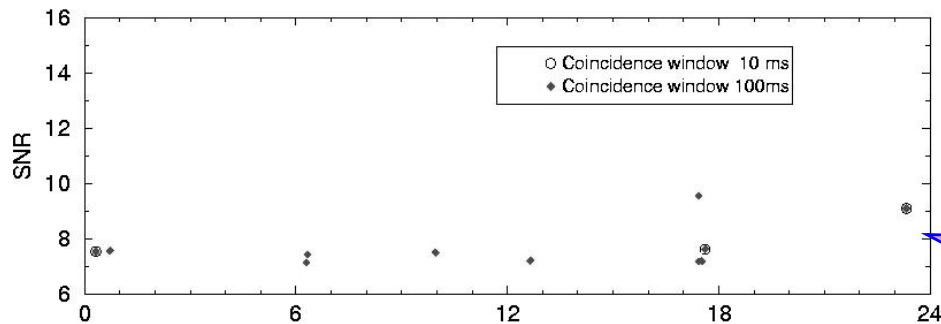
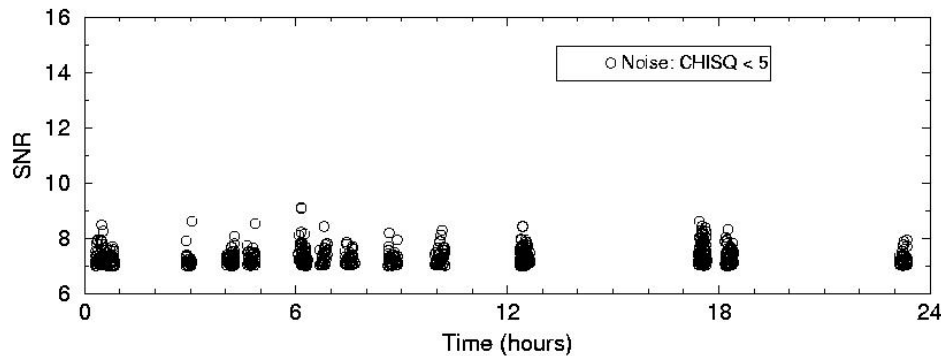


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# Non-Gaussian Spurions

- How to deal with them?
  - » Coincidence: does signal show up in multiple instruments with "same" parameters?



**All candidates vetoed by signal strength consistency**

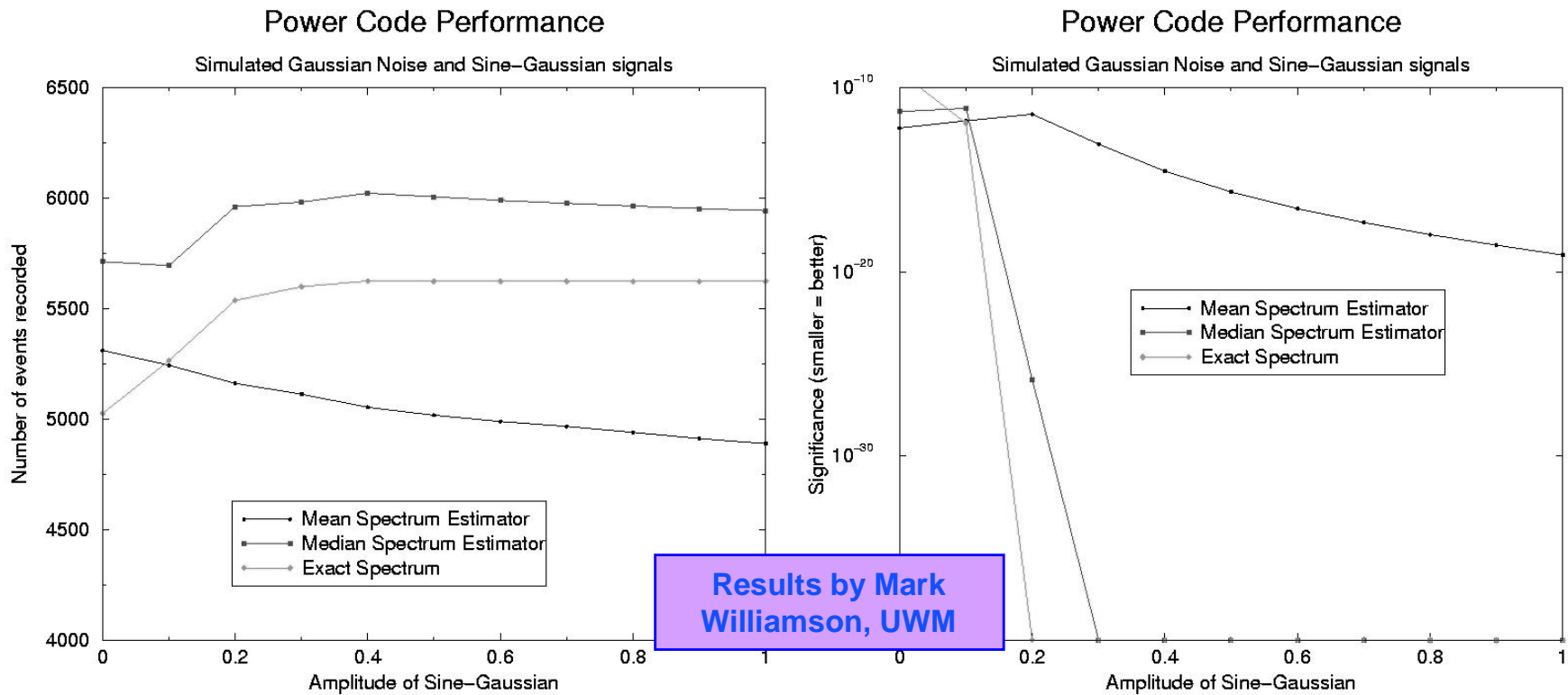
# Non-stationarity

- Instruments are not perfectly stationary
- How to deal with this in data analysis
- First order, notice that search algorithms depend on

$$\tilde{h}(f) / \sqrt{S(|f|)}$$

- Need robust estimator for power spectrum  $S(|f|)$  which
  - » Tracks non-stationarity
  - » Is not biased by non-Gaussian bursts

# Mean versus Median Estimators



# Concluding Remarks

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- Best detection algorithms rely on having some knowledge of expected signals
- Experience is being gained by scientists working with real interferometric data.
- Non-stationarity and non-Gaussianity require supplementing standard algorithms with veto methods
- Inability to go off-source provide interesting difficulties similar to bar detectors
- First analysis results should be available soon