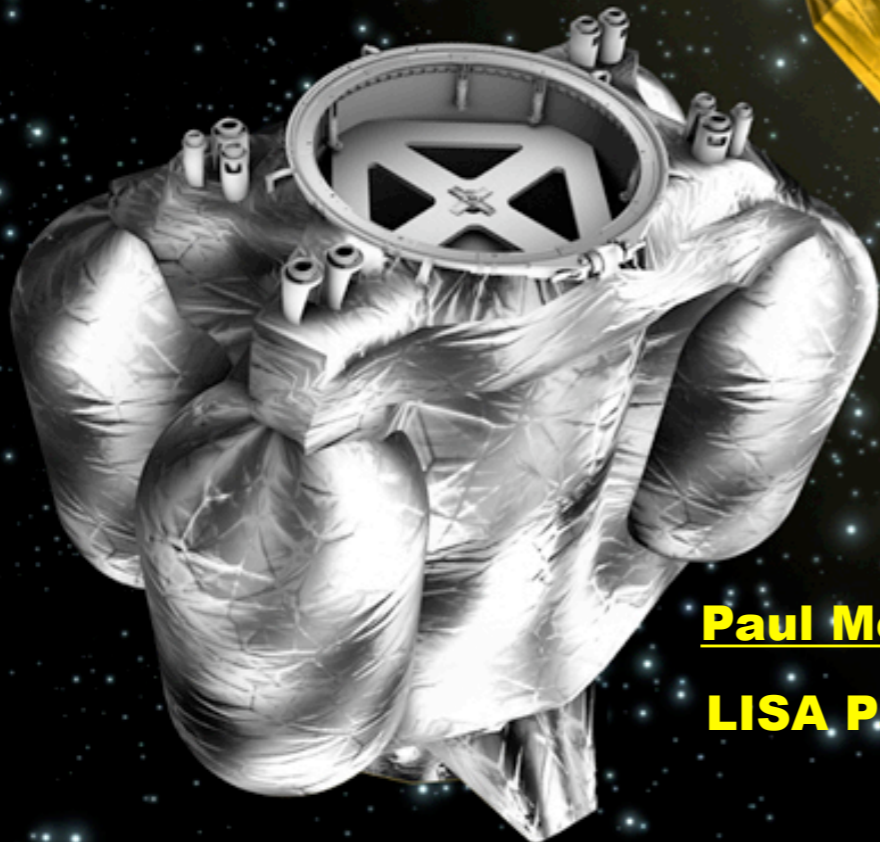




LISA Pathfinder



Paul McNamara for the LPF Team





LISA Pathfinder Project Scientist

GWADW

10th - 15th May 2009

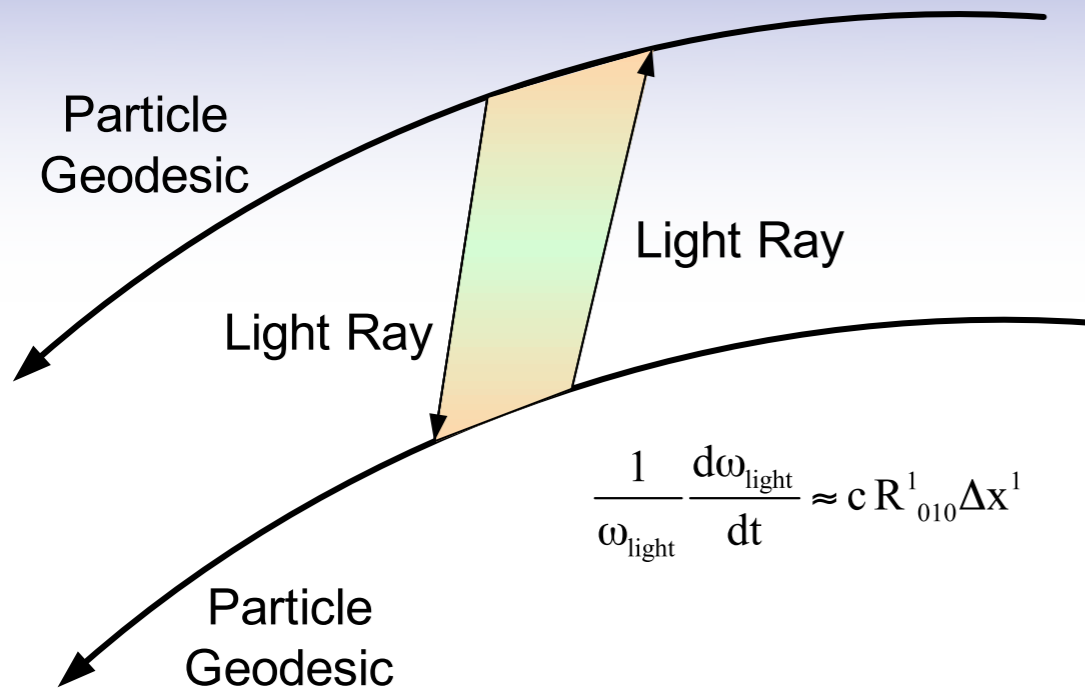
G0900656-v1

Why LISA Pathfinder?

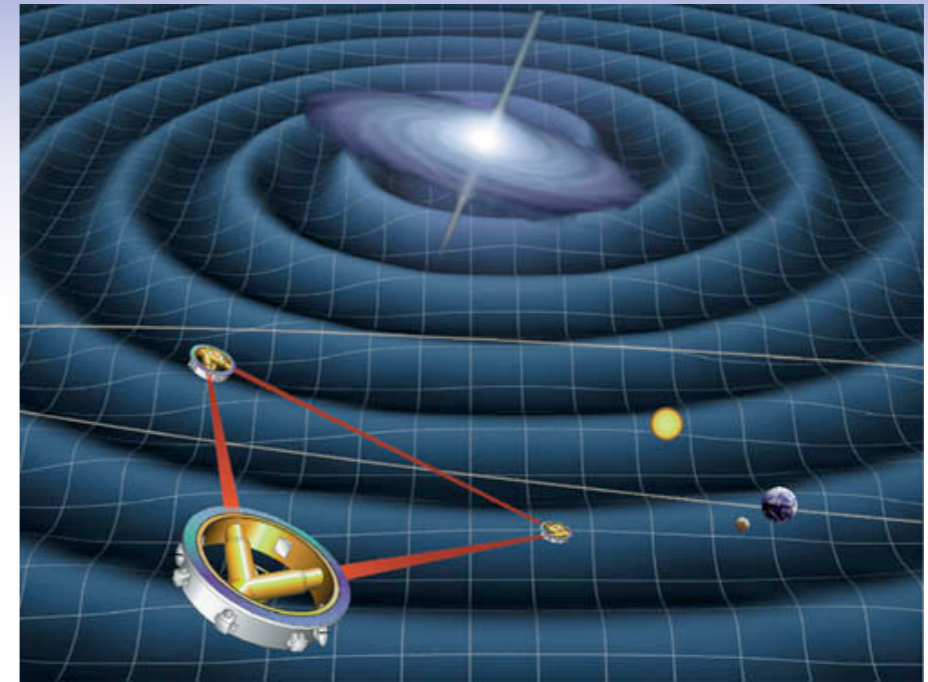
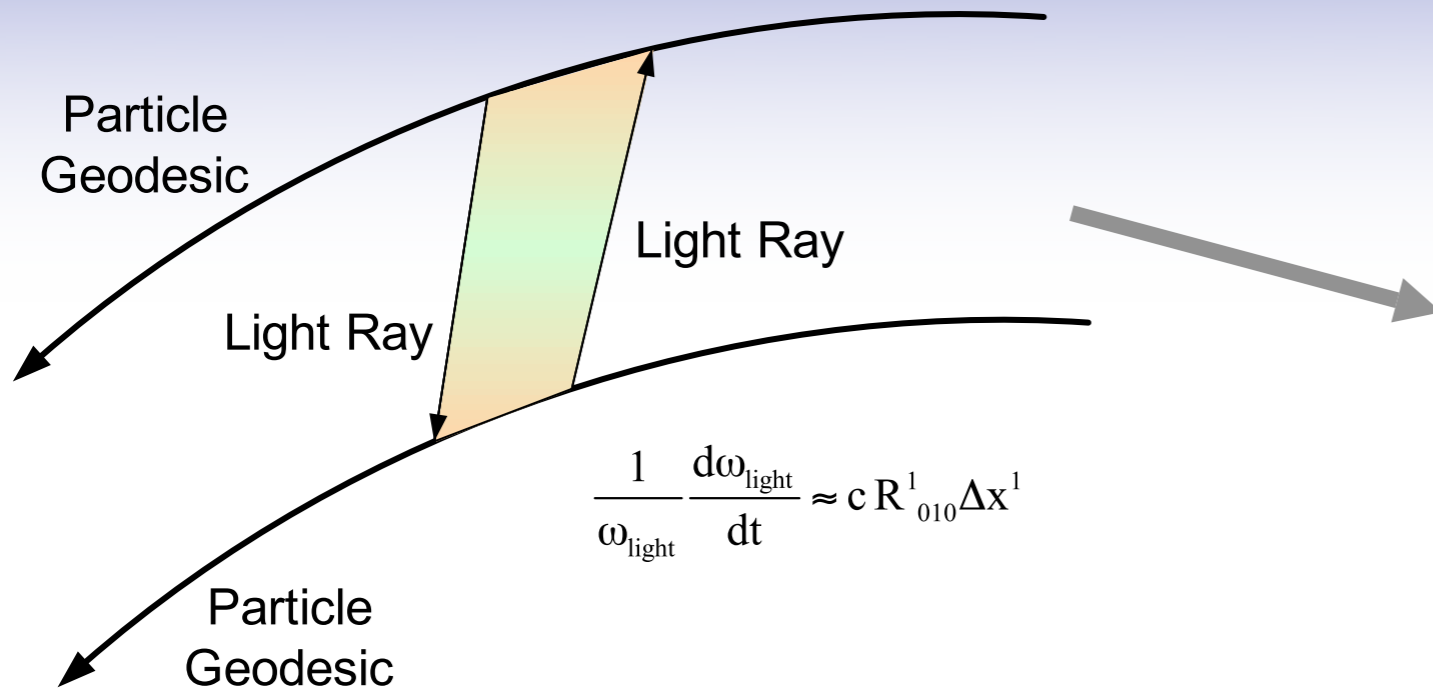
-  The science case for LISA is extremely compelling and has continually been highly ranked by independent review boards
-  However, both ESA and NASA believed that the risk was too high to fly LISA with an unproven measurement concept
-  LISA Pathfinder was instigated by ESA to test the concept of low-frequency gravitational wave detection
-  The LPF development has shown that the technologies required for LISA are difficult, but not impossible
 - LPF has already solved many of the challenges associated with low frequency gravitational wave detection



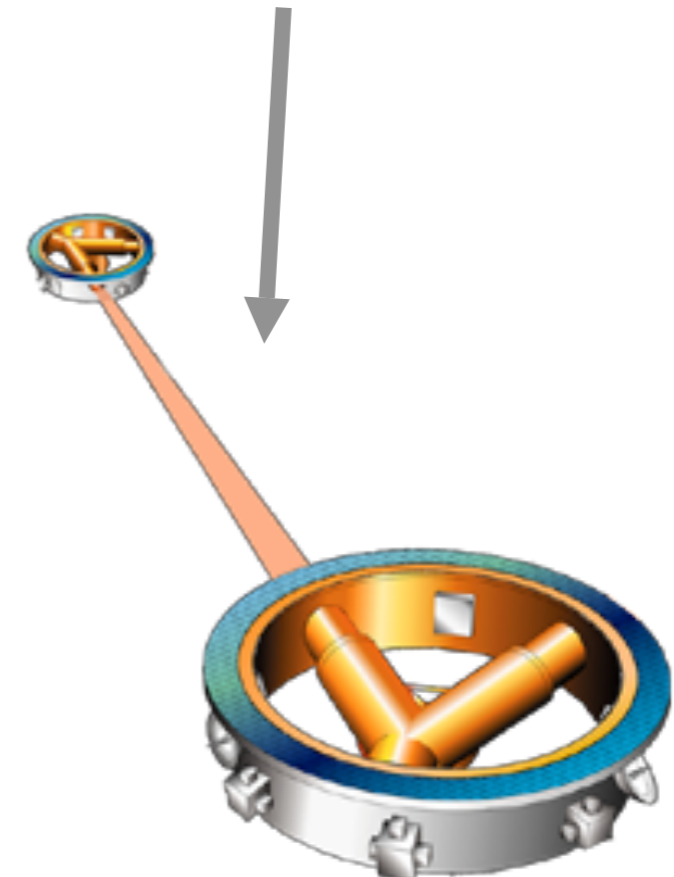
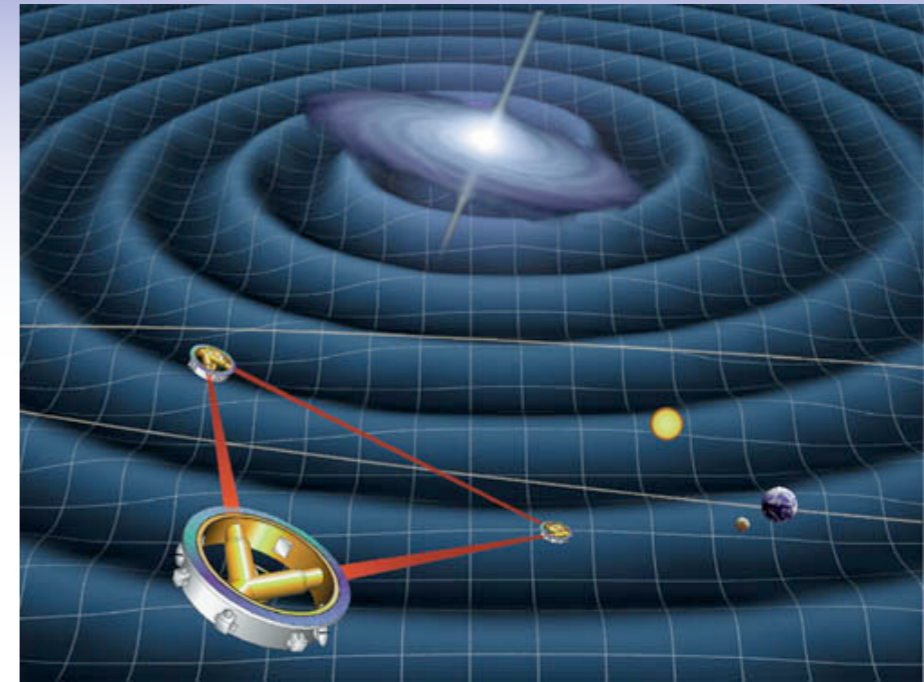
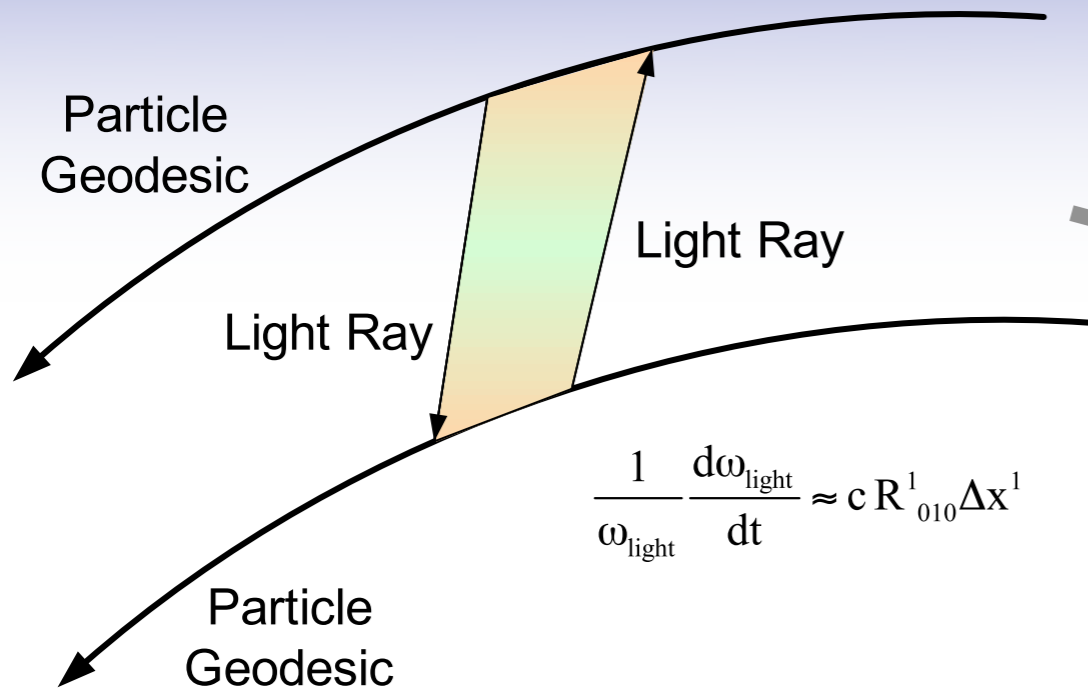
Mission Concept



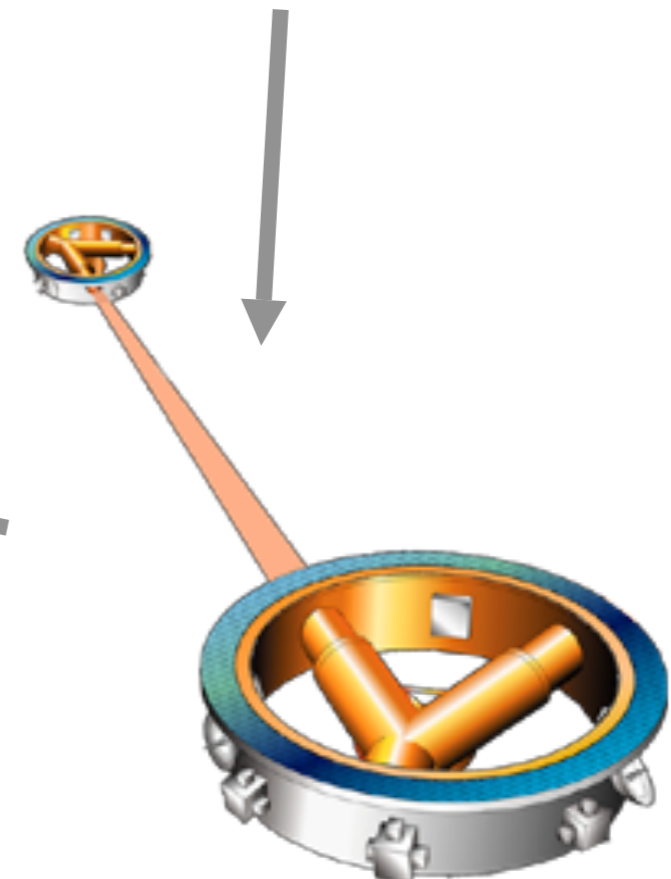
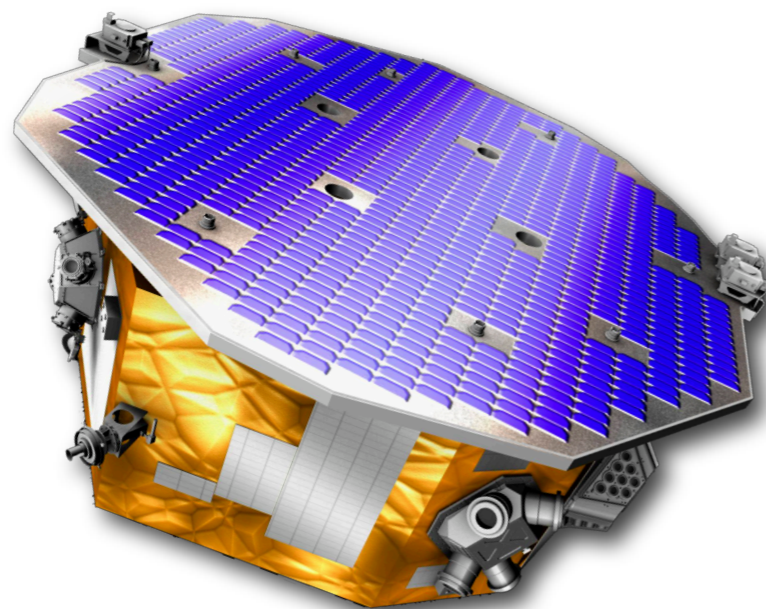
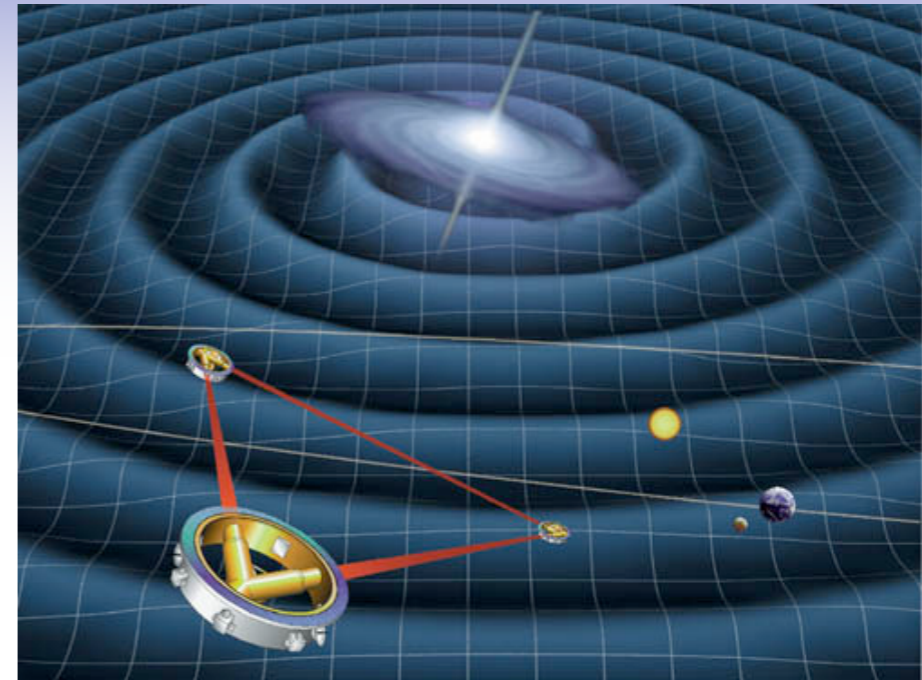
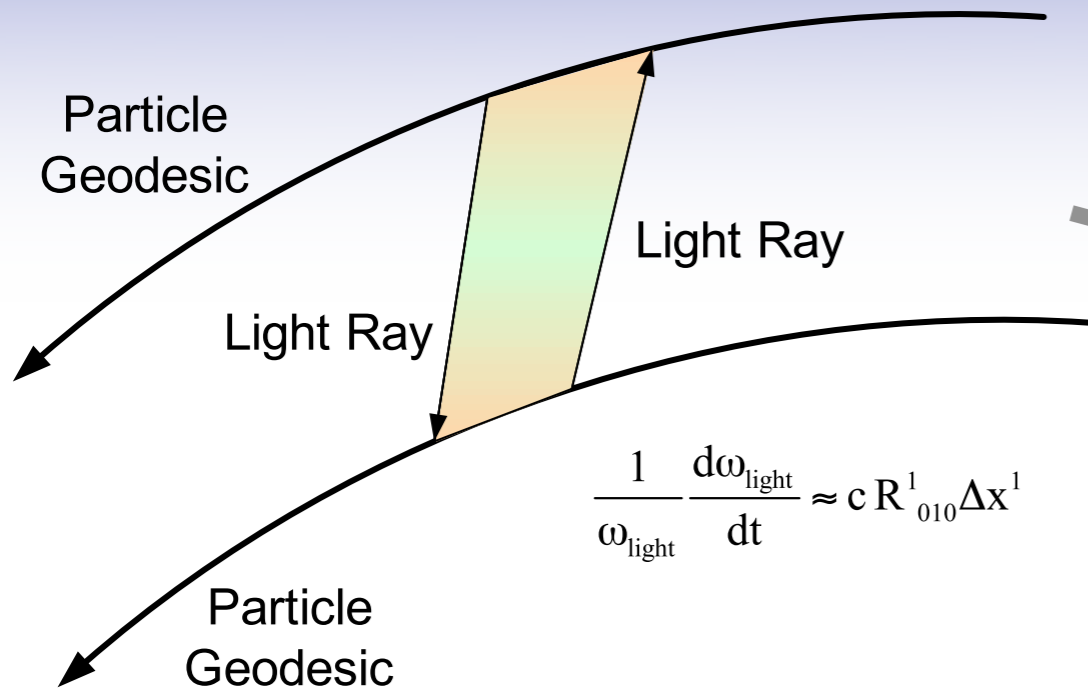
Mission Concept



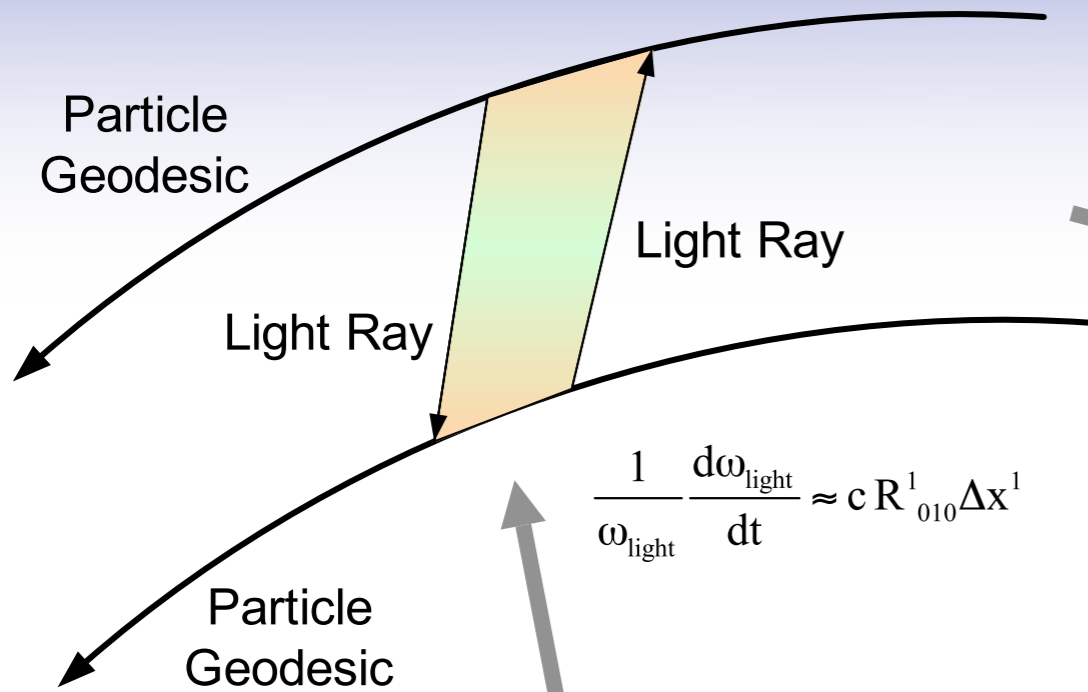
Mission Concept



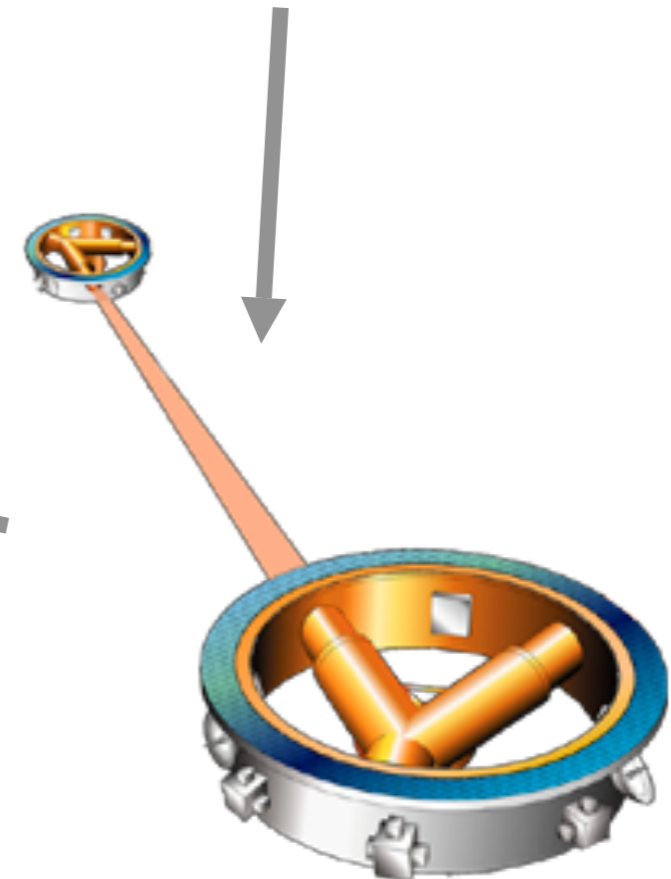
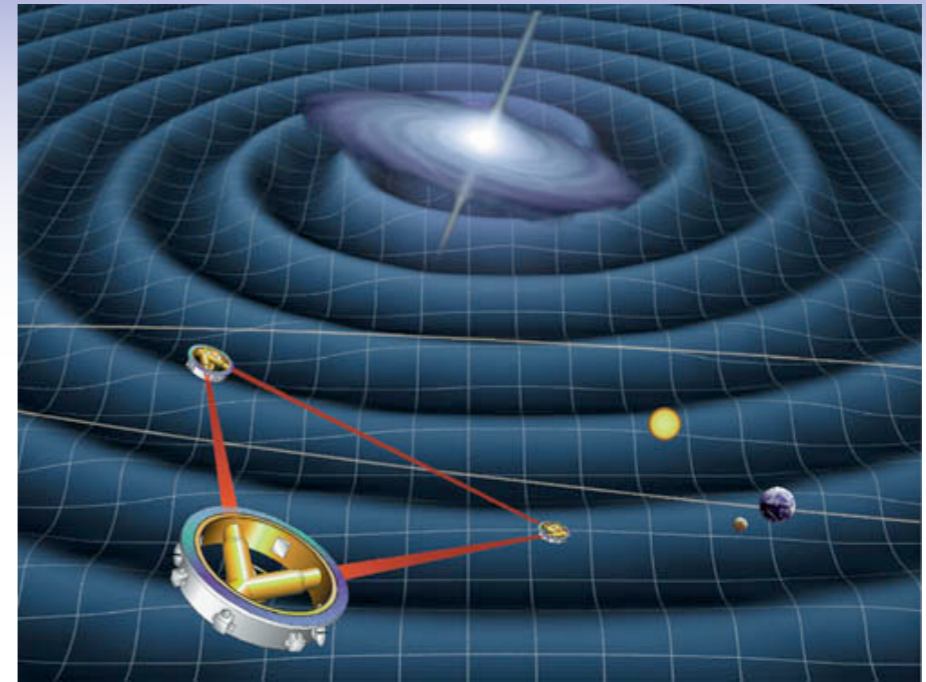
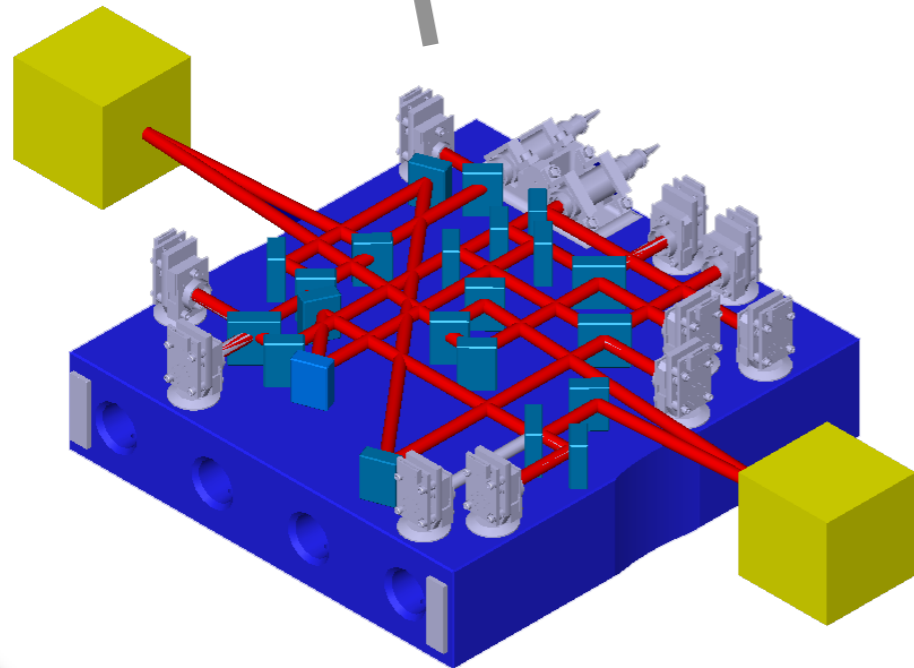
Mission Concept




Mission Concept




$$\frac{1}{\omega_{\text{light}}} \frac{d\omega_{\text{light}}}{dt} \approx c R^1_{010} \Delta x^1$$



LPF Technology

-  The LISA Pathfinder mission will test in flight:
 - Inertial sensors
 - Precision interferometry
 - Micro-Newton propulsion technology
 - Field Emission Electric Propulsion (FEEP)
 - Colloidal thrusters (provided by NASA - JPL)
 - *Drag Free and Attitude Control System (DFACS)*

-  The basic idea of LISA Pathfinder is to squeeze one arm of the LISA constellation from 5 million km to a few tens of cm!
 - Fully tests LISA short arm interferometry




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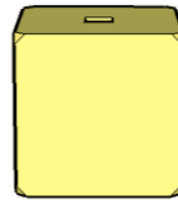
Drag Free and Attitude Control System (DFACS)

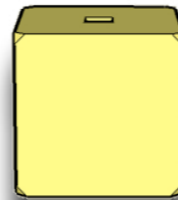
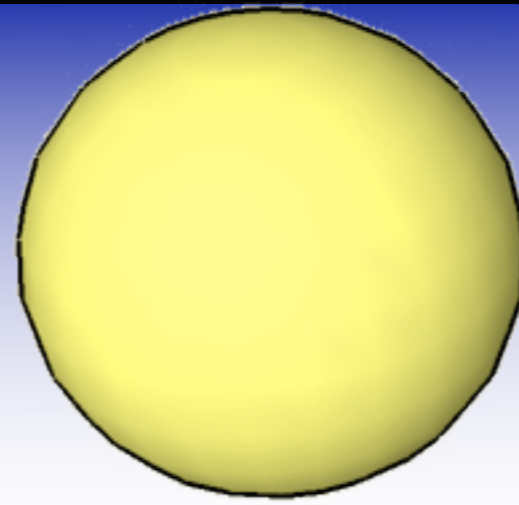
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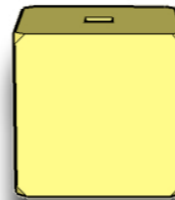
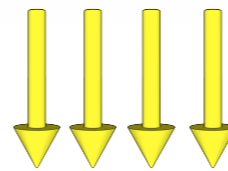
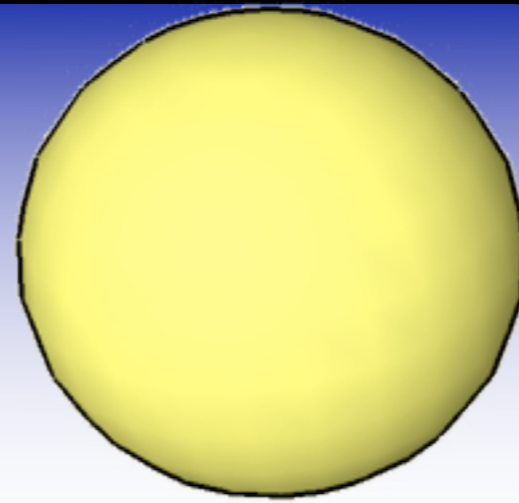
- Fully tests LISA short arm interferometry

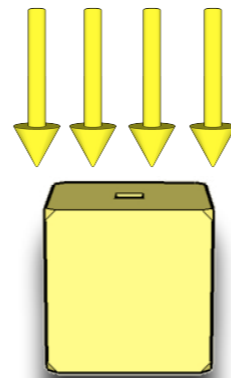
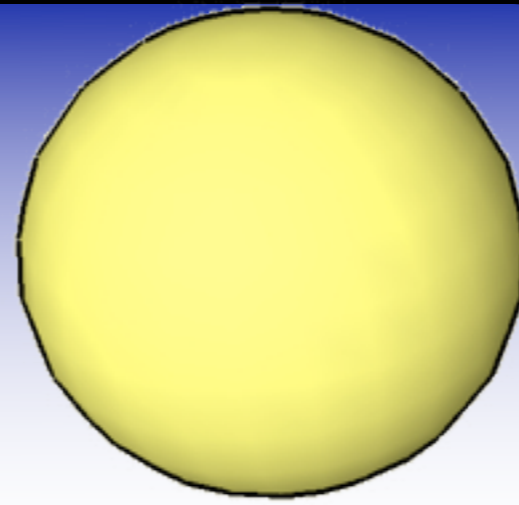


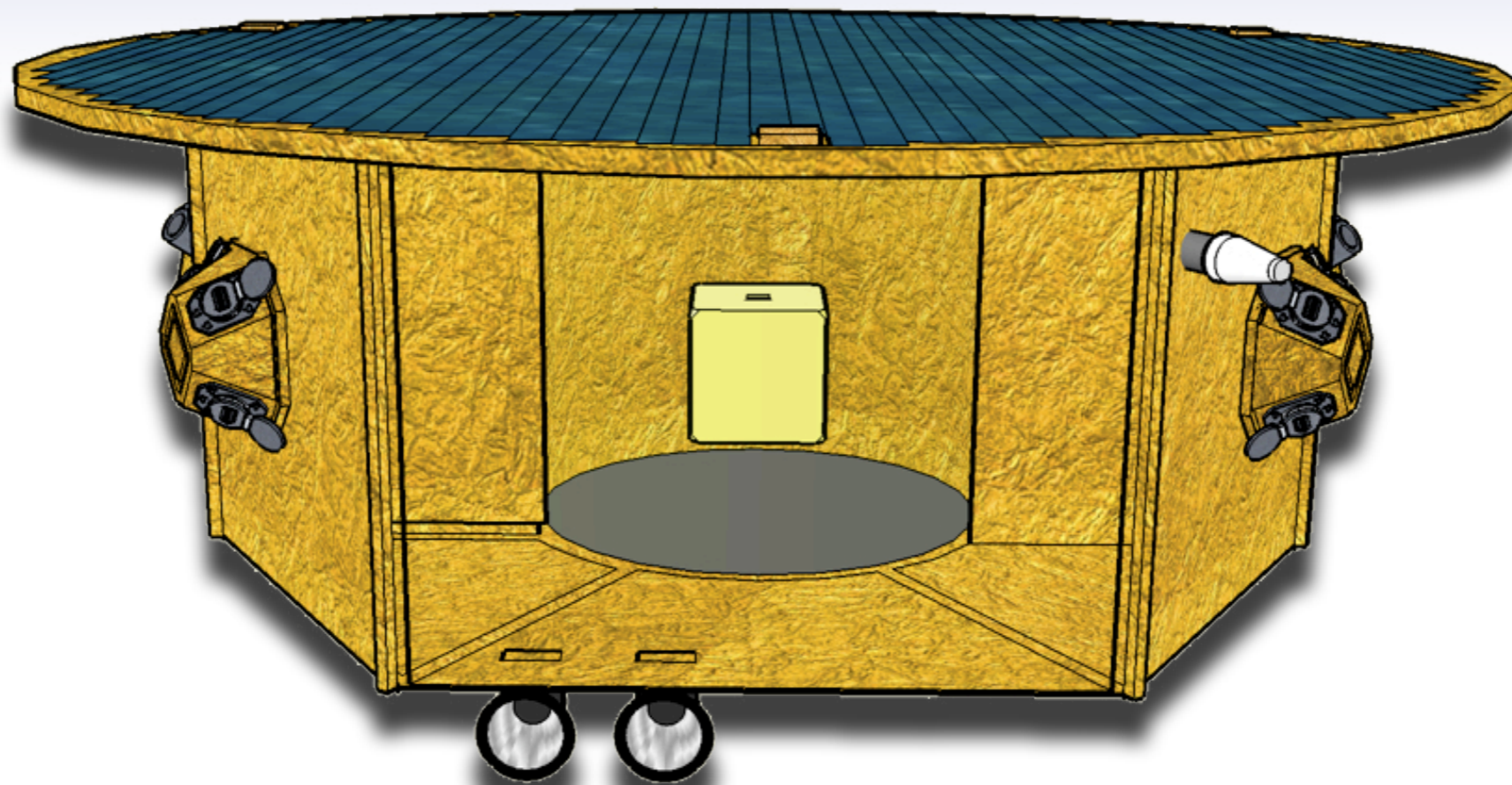
Concept of Drag-Free

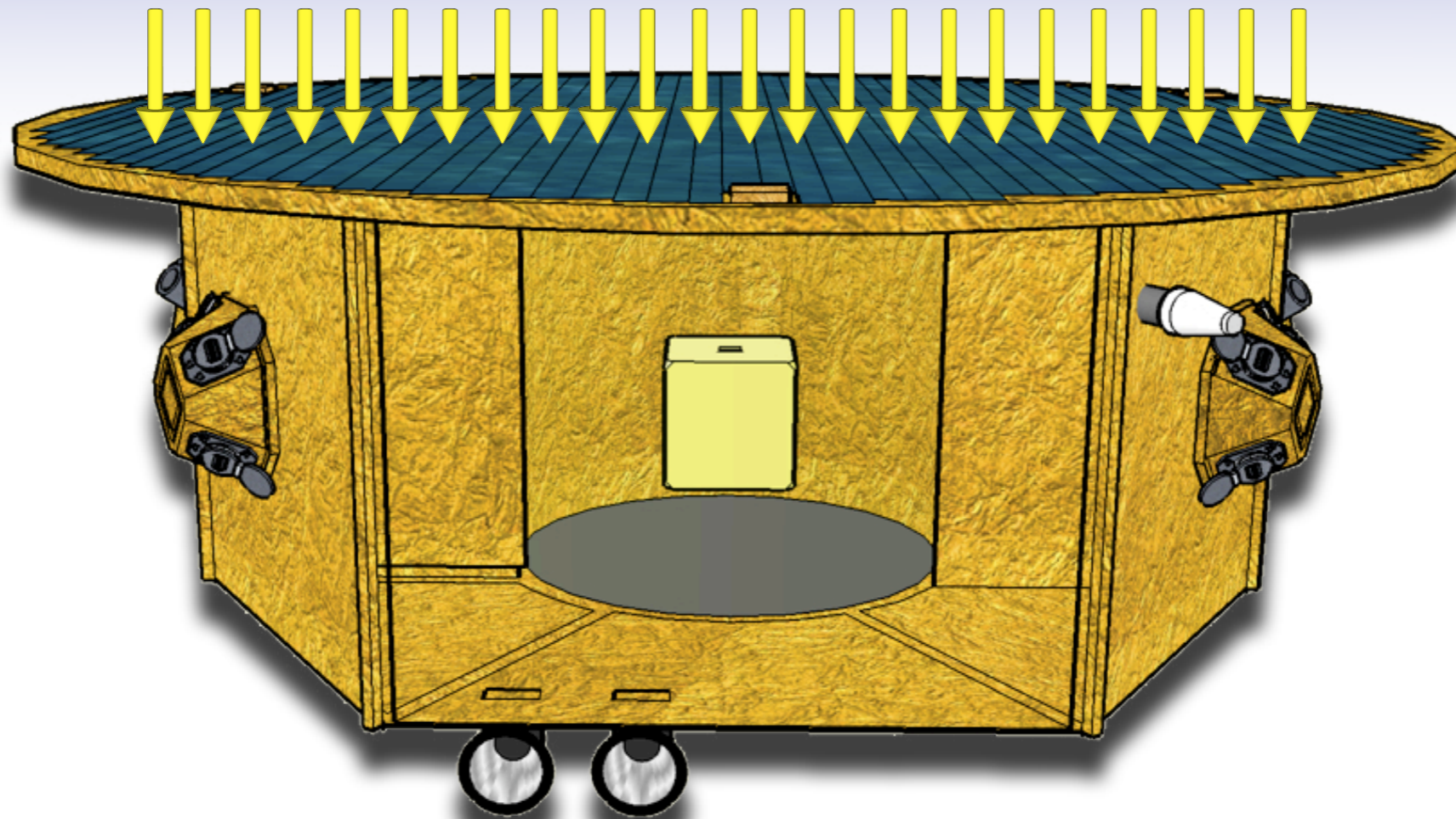


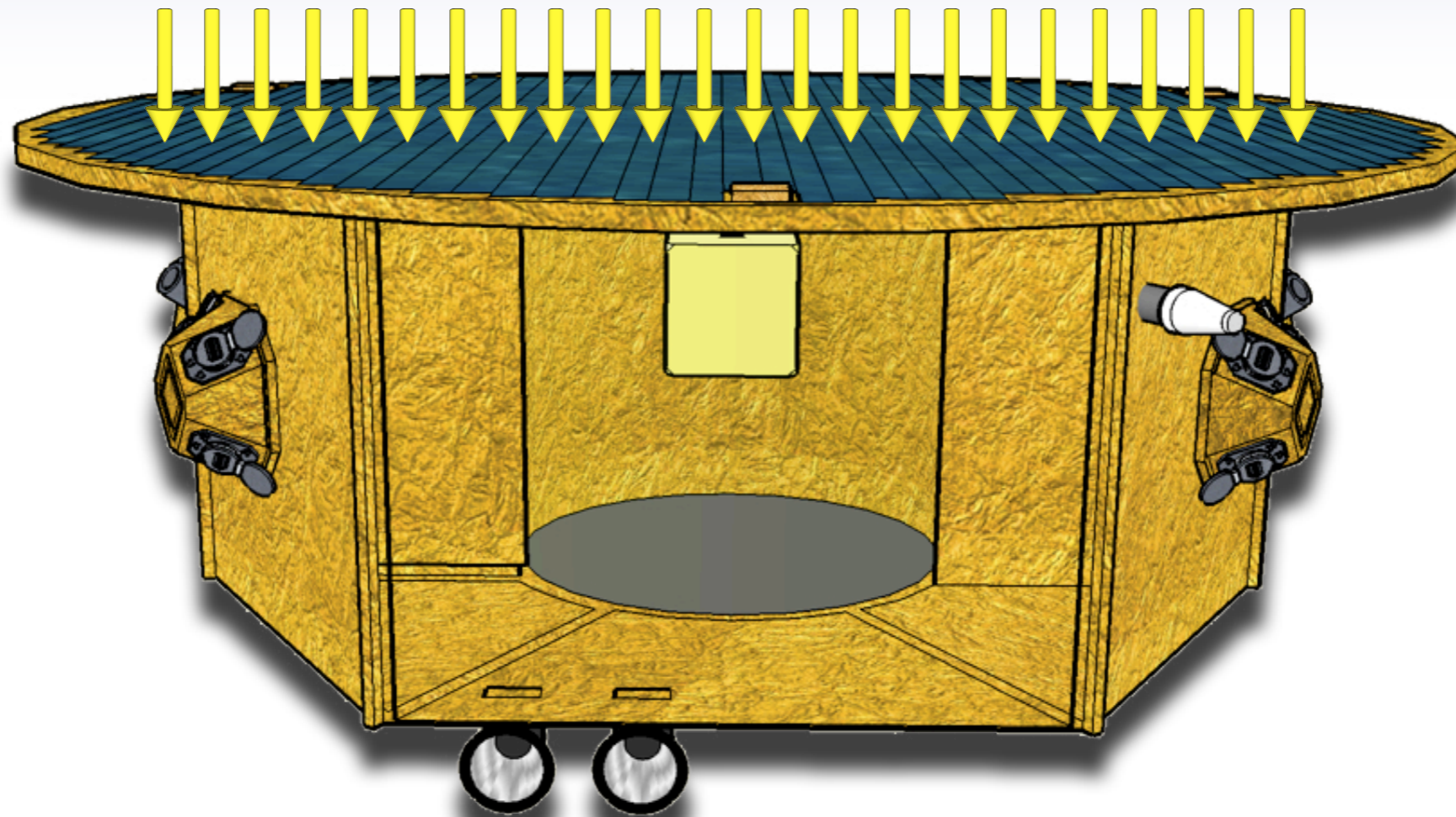


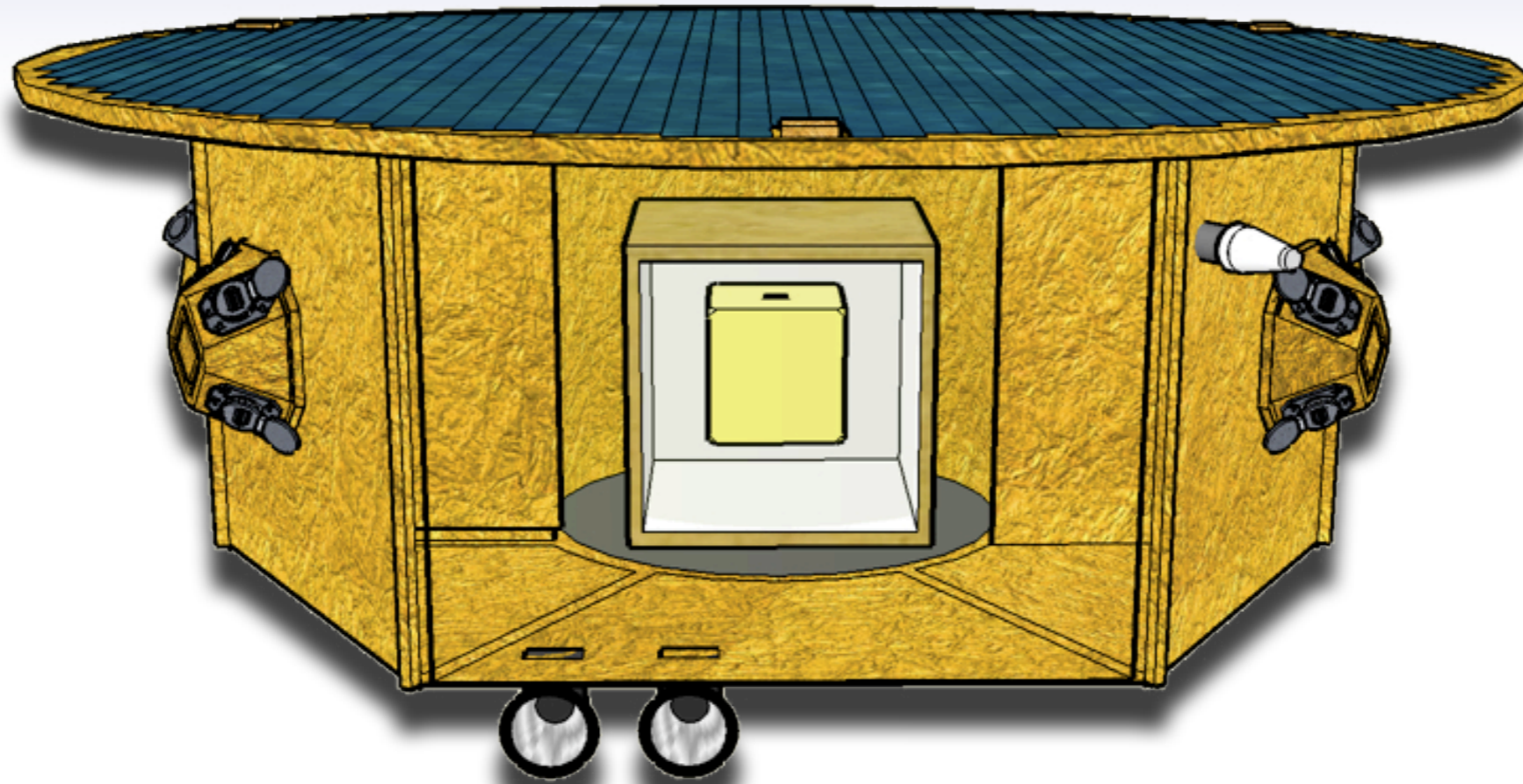


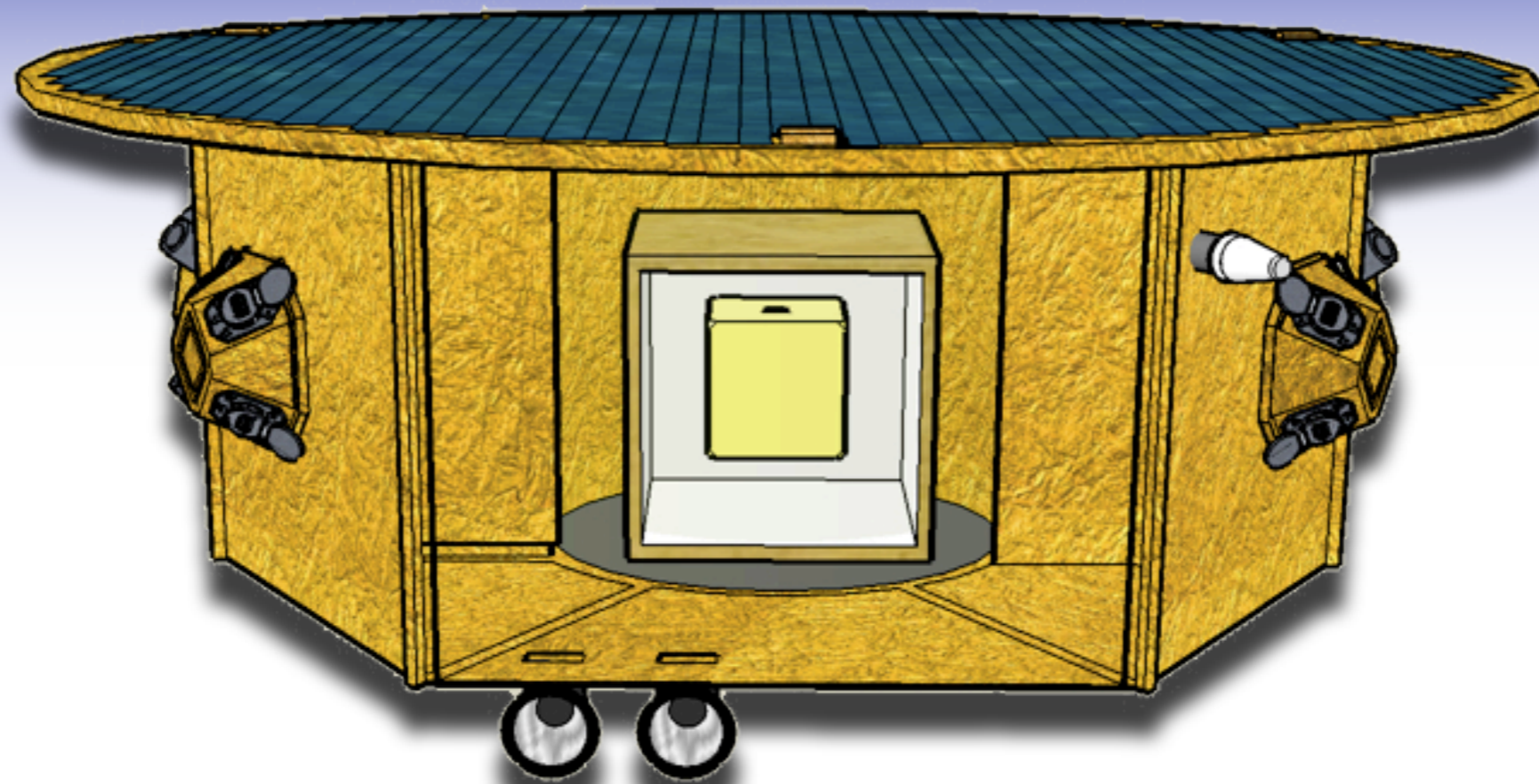


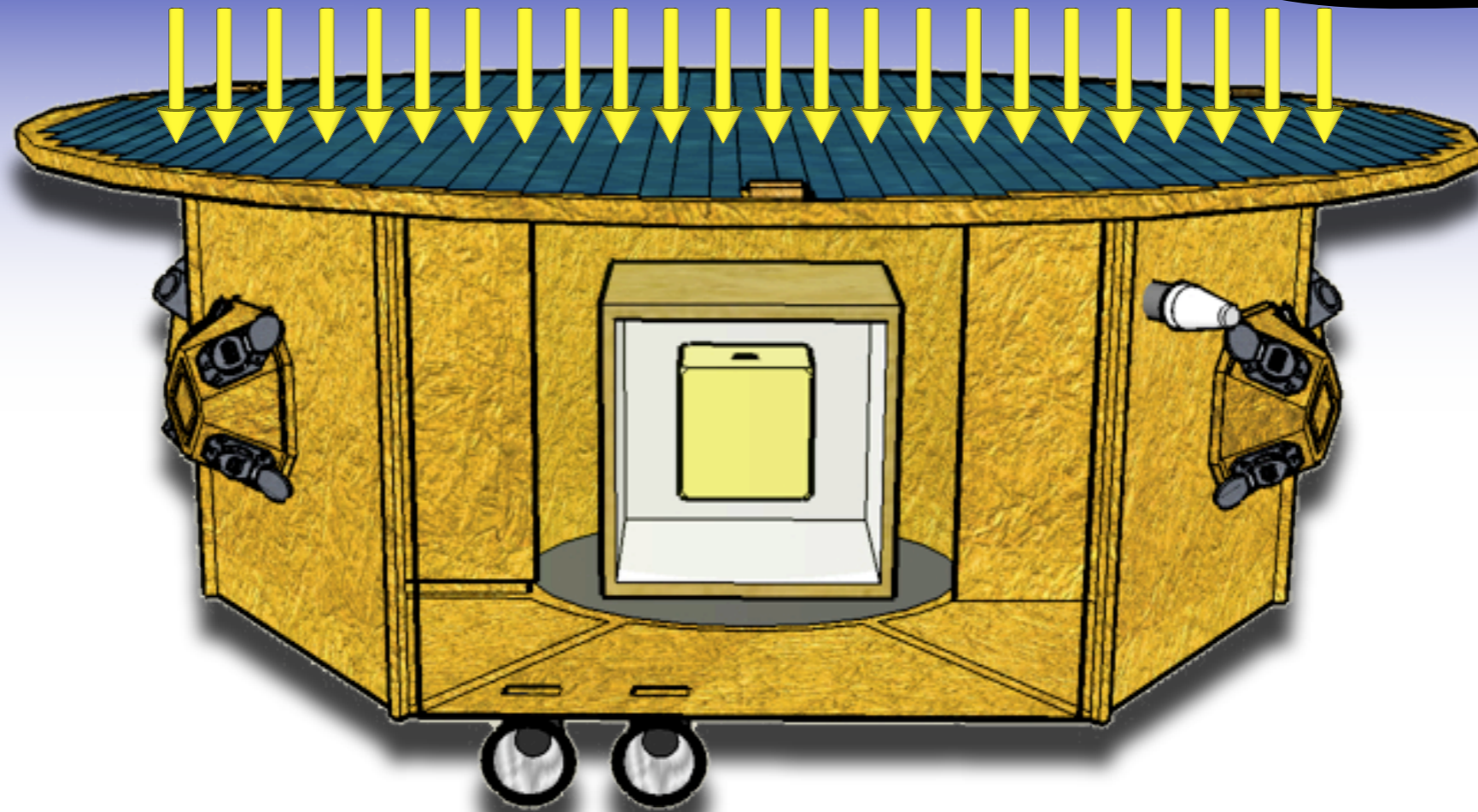




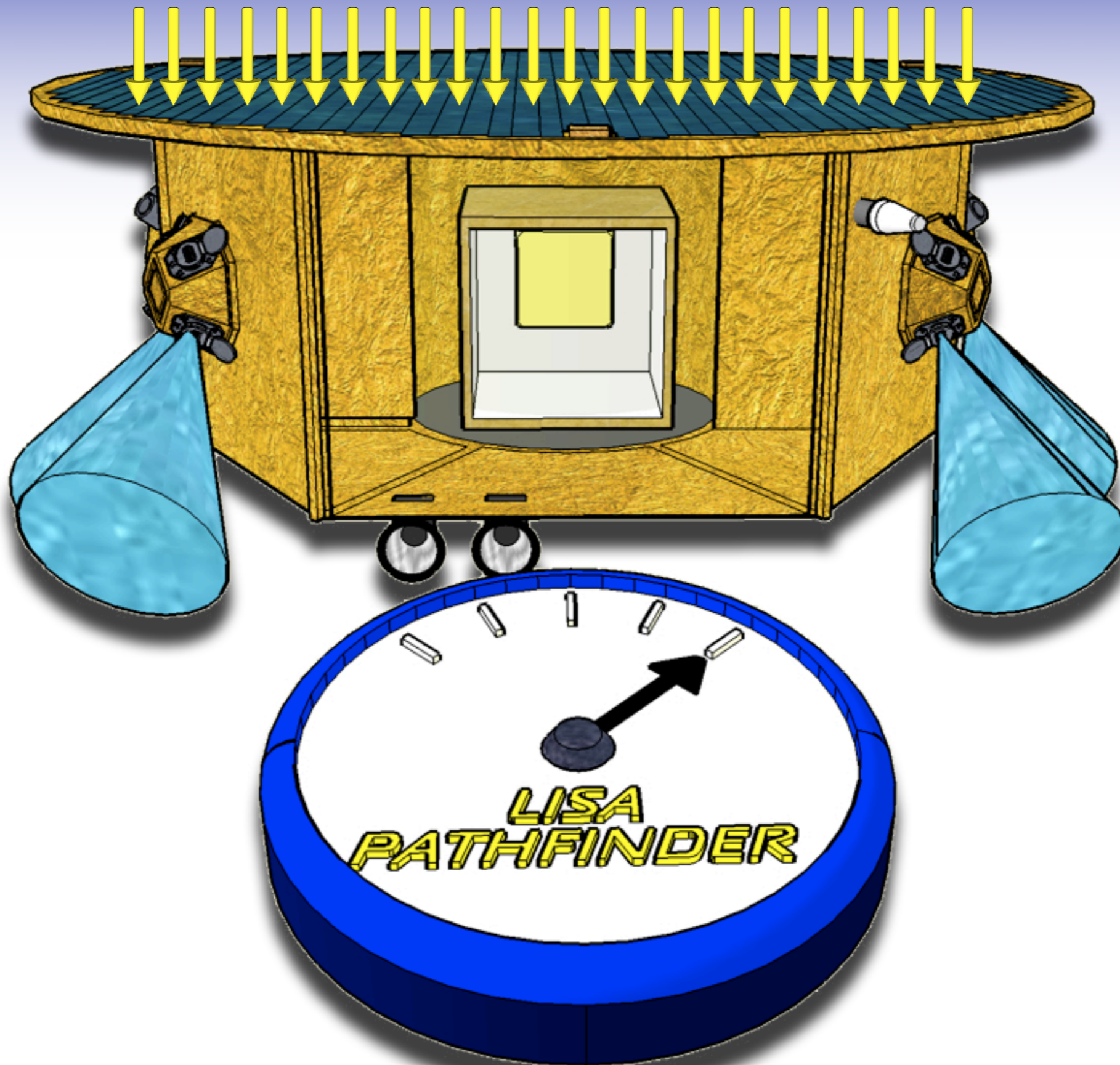














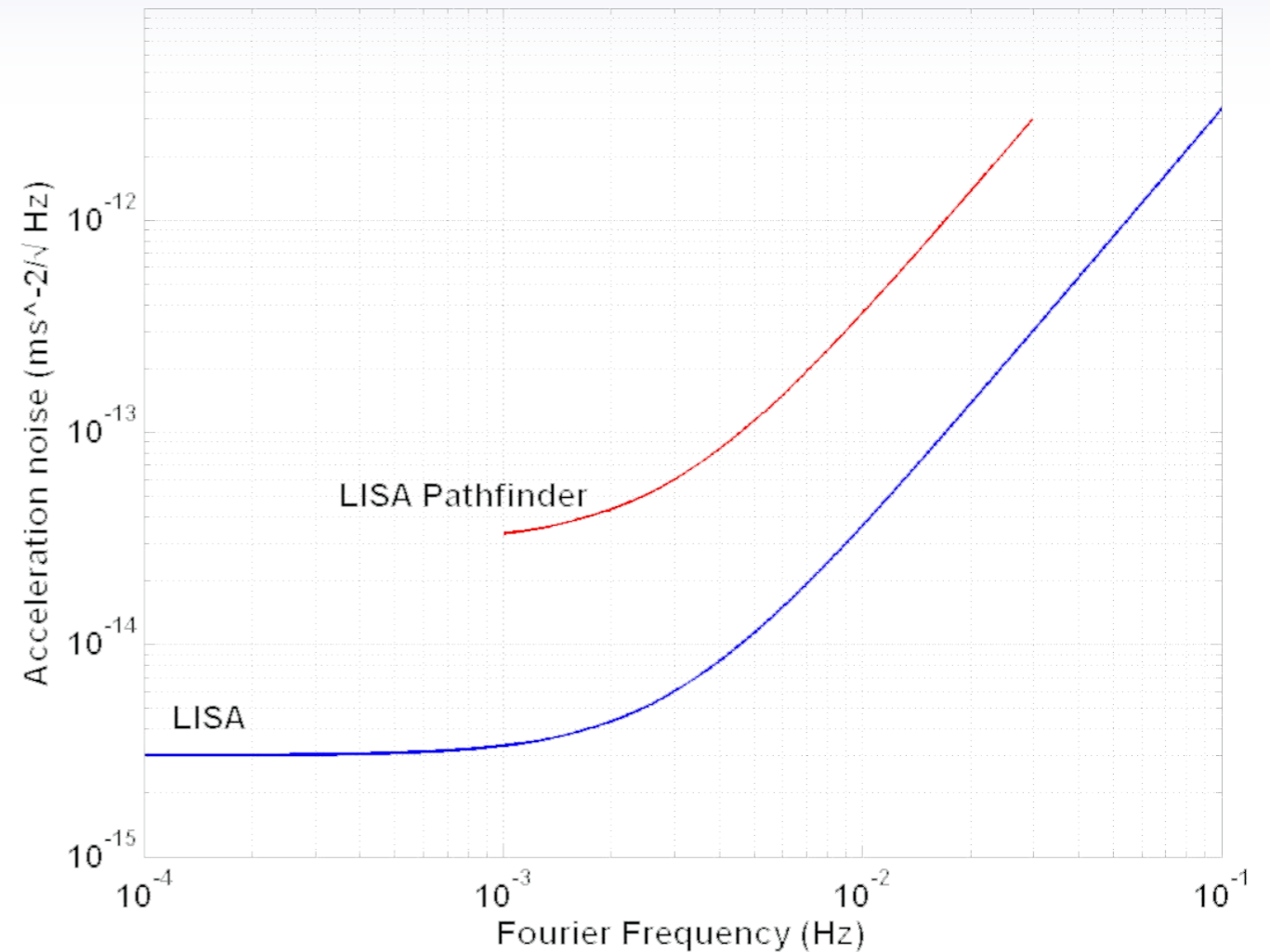
Mission Goal [1]

The primary goal of LISA Pathfinder is to verify that a test mass can be put in pure gravitational free-fall with residual acceleration noise less than


$$S_a^{1/2}(f) \leq 3 \times 10^{-14} \left[1 + \left(\frac{f}{3 \text{ mHz}} \right)^2 \right] \text{ ms}^{-2} / \sqrt{\text{Hz}}$$

over a frequency range of 1-30mHz

Acceleration noise requirements for LISA and LPF

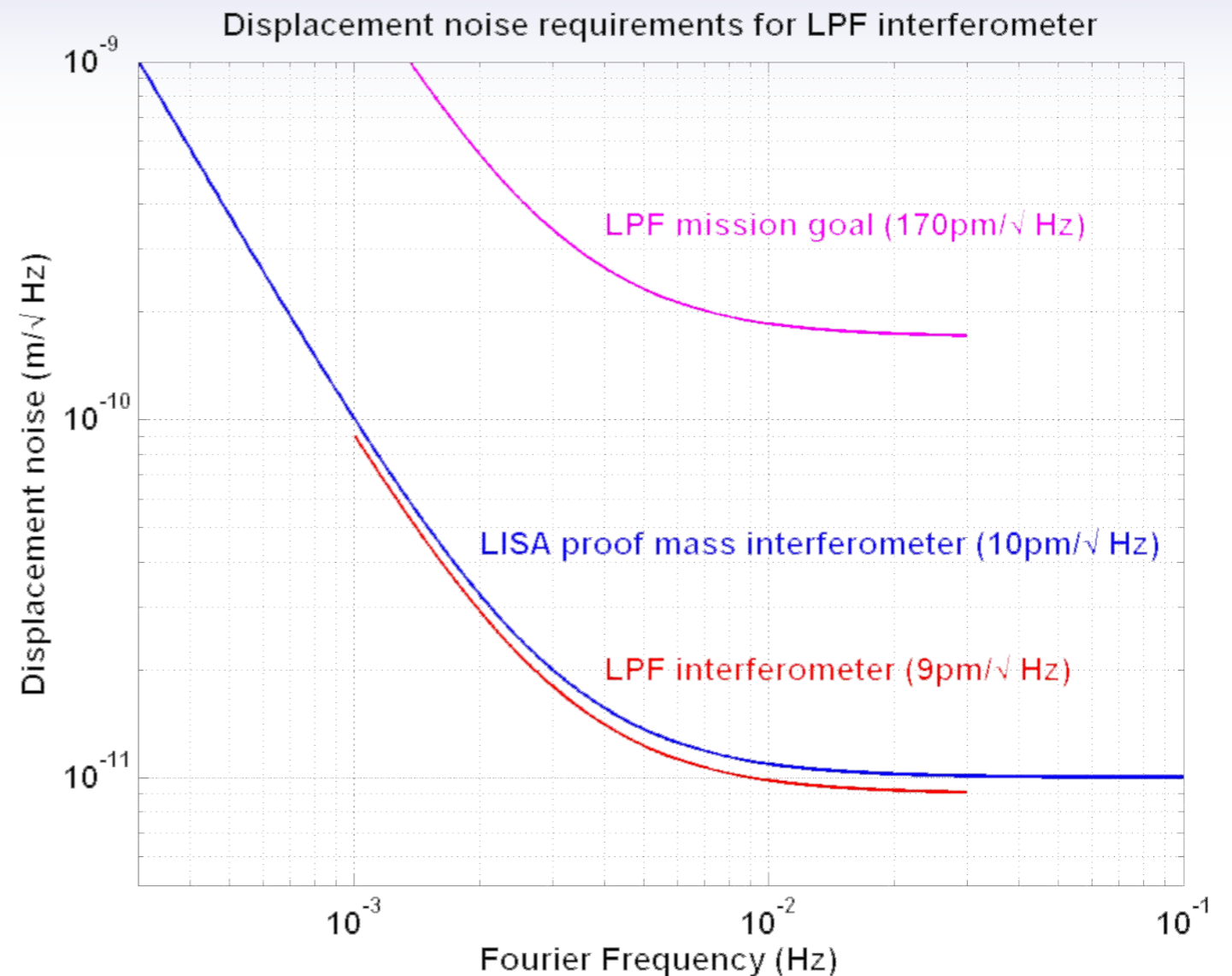


Mission Goal [2]

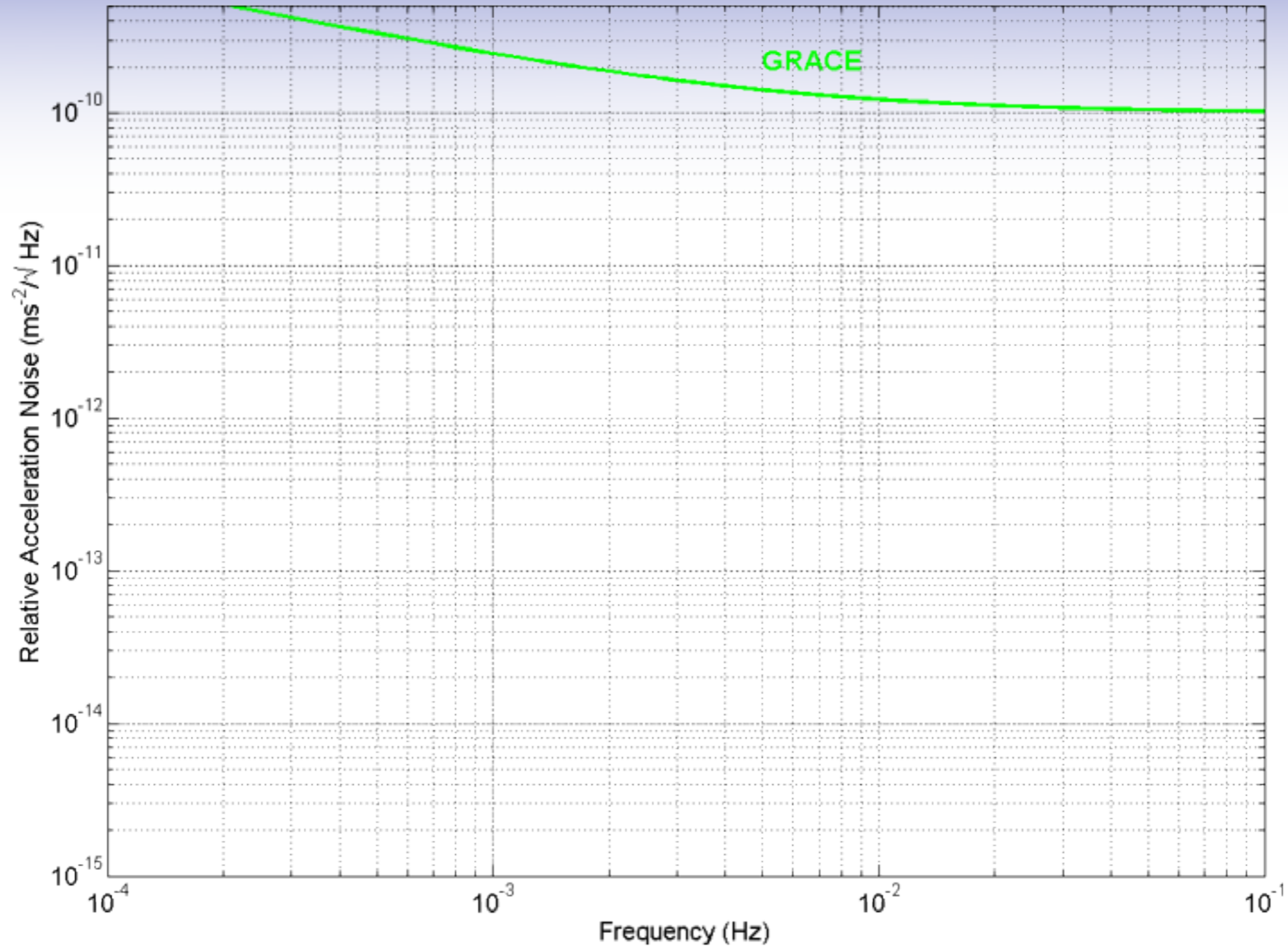
 A secondary goal, which has now become directly relevant to LISA, is to demonstrate laser metrology using free floating mirrors with a displacement sensitivity of

$$S_{\delta x}^{1/2} \leq 9 \times 10^{-12} \left[1 + \left(\frac{3 \text{mHz}}{f} \right)^2 \right] \text{m} / \sqrt{\text{Hz}}$$

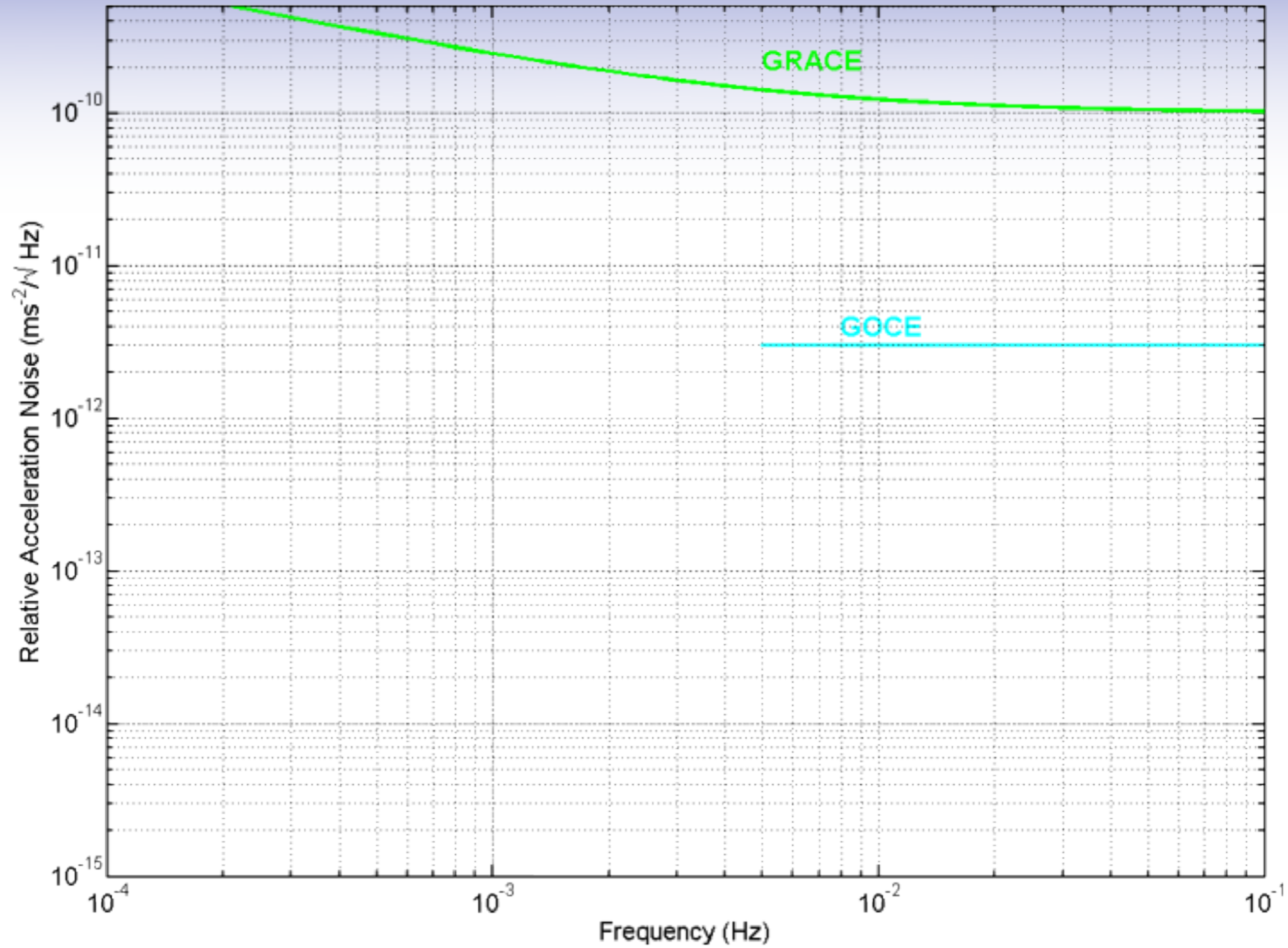
over a frequency range of 1-30mHz



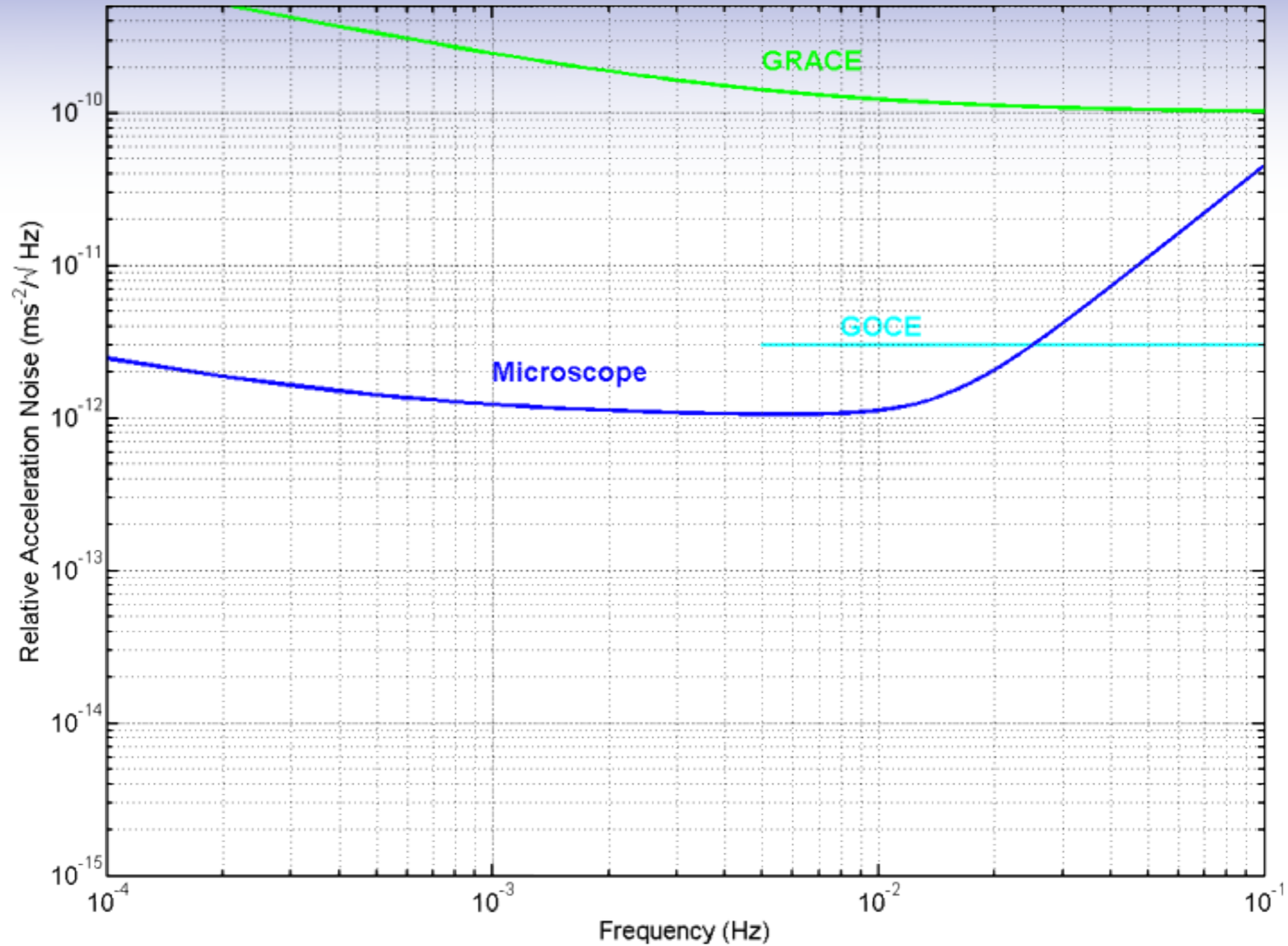
Performance of LPF



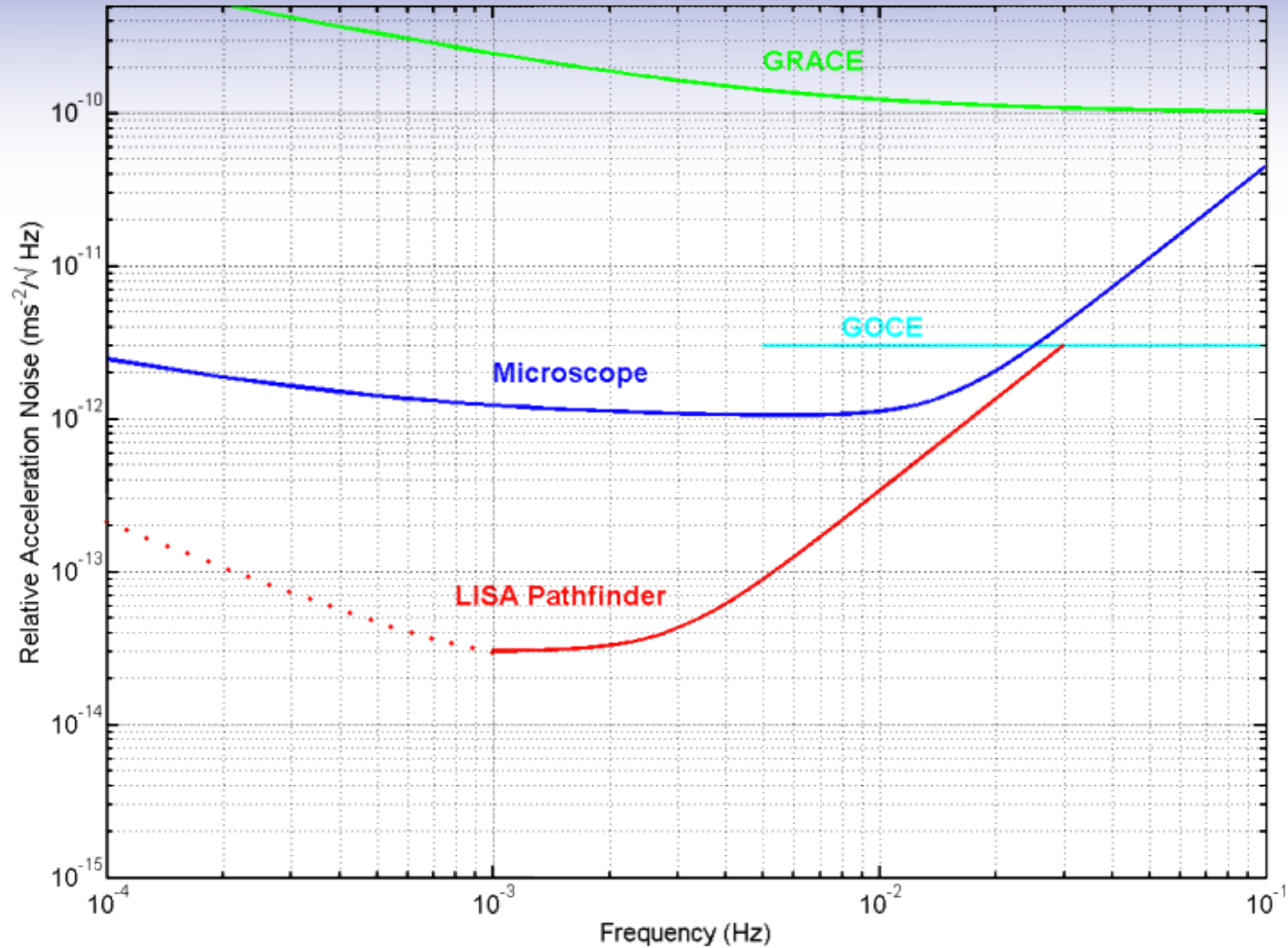
Performance of LPF



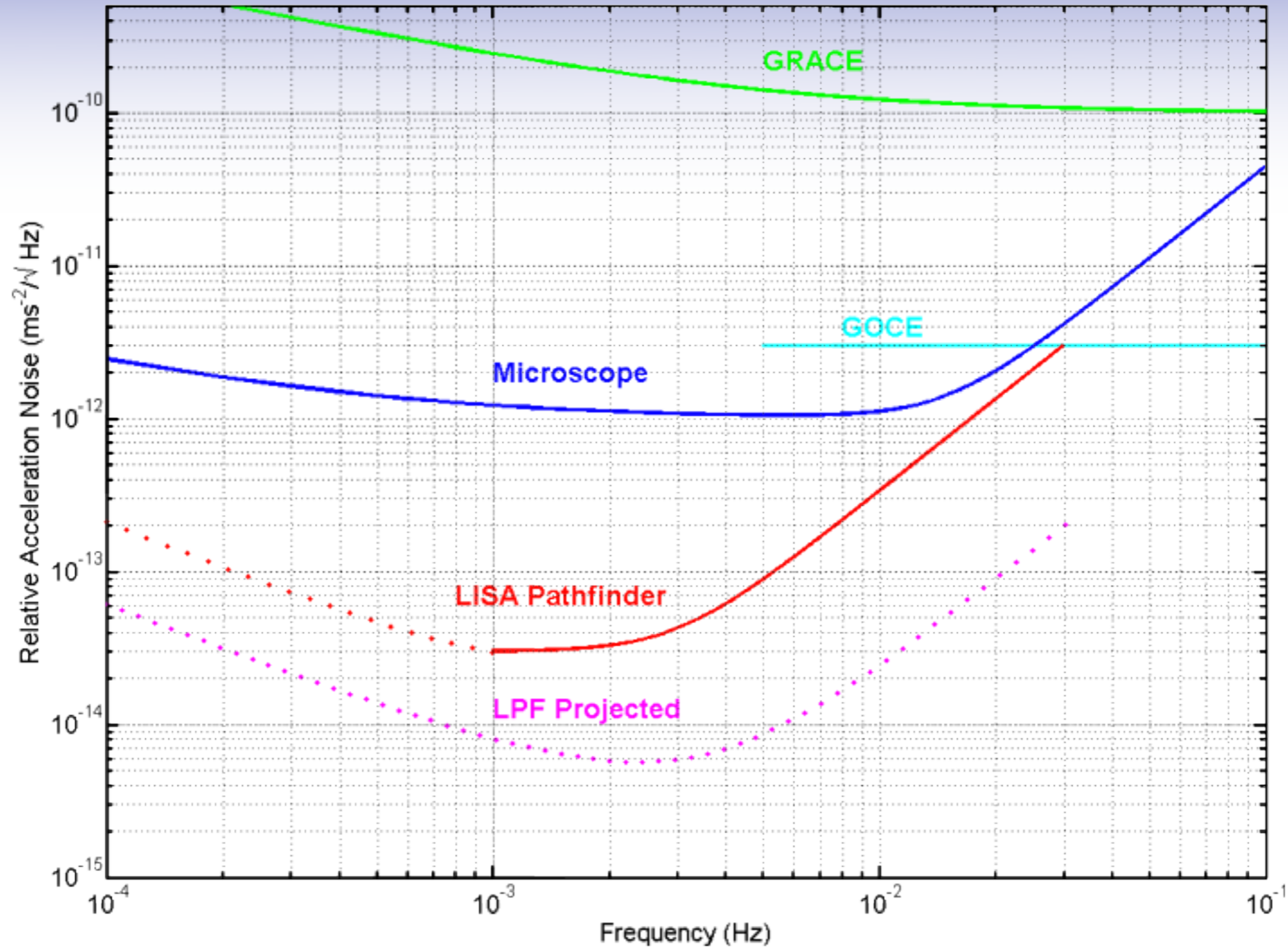
Performance of LPF



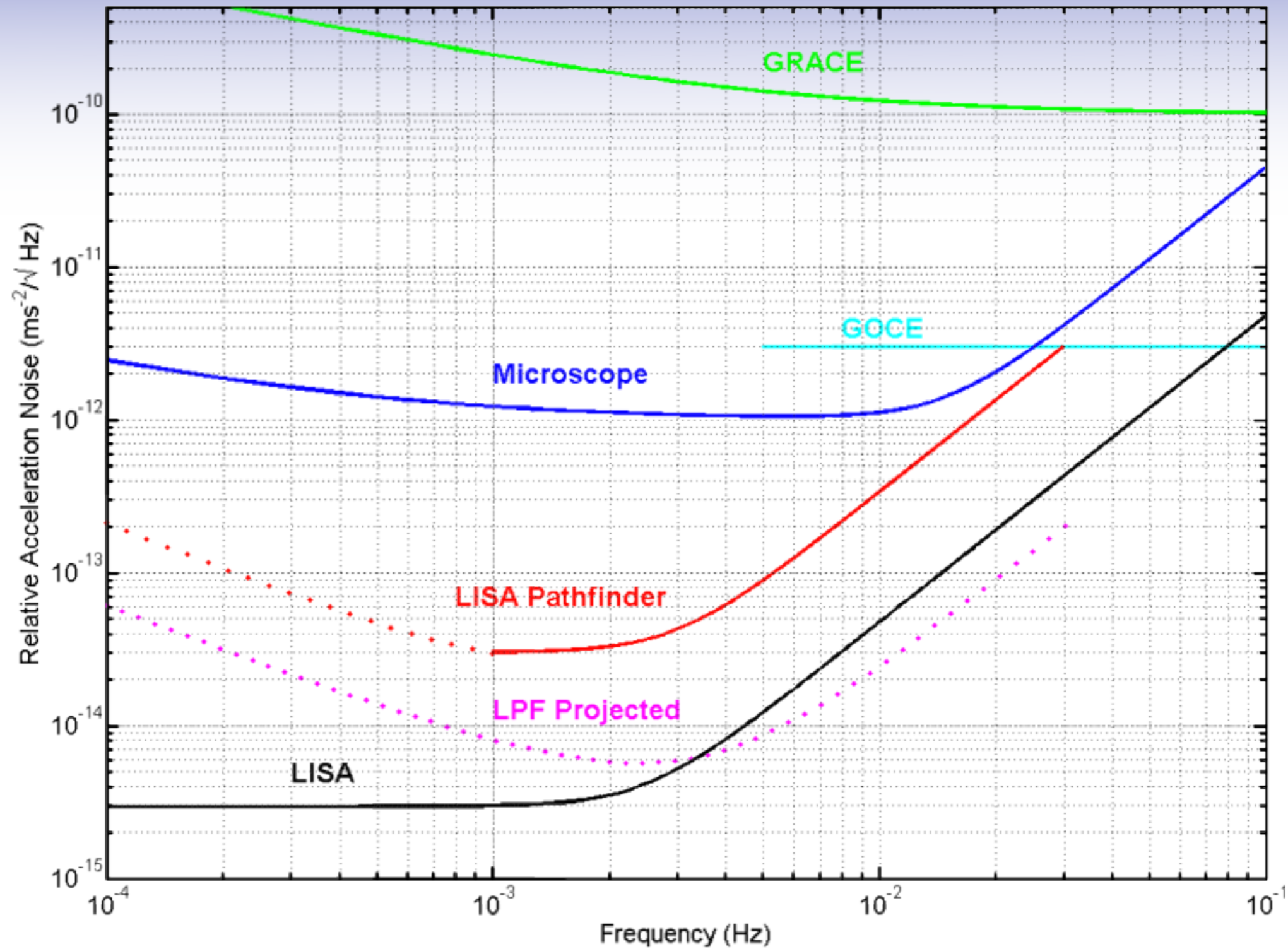
Performance of LPF







Performance of LPF

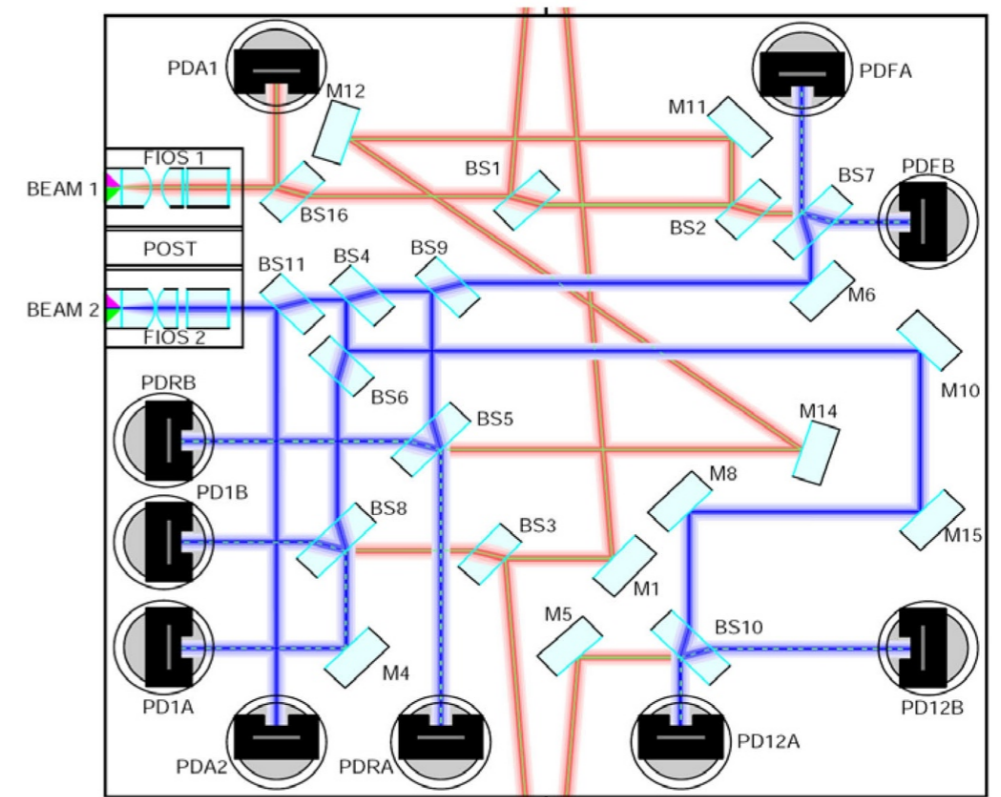
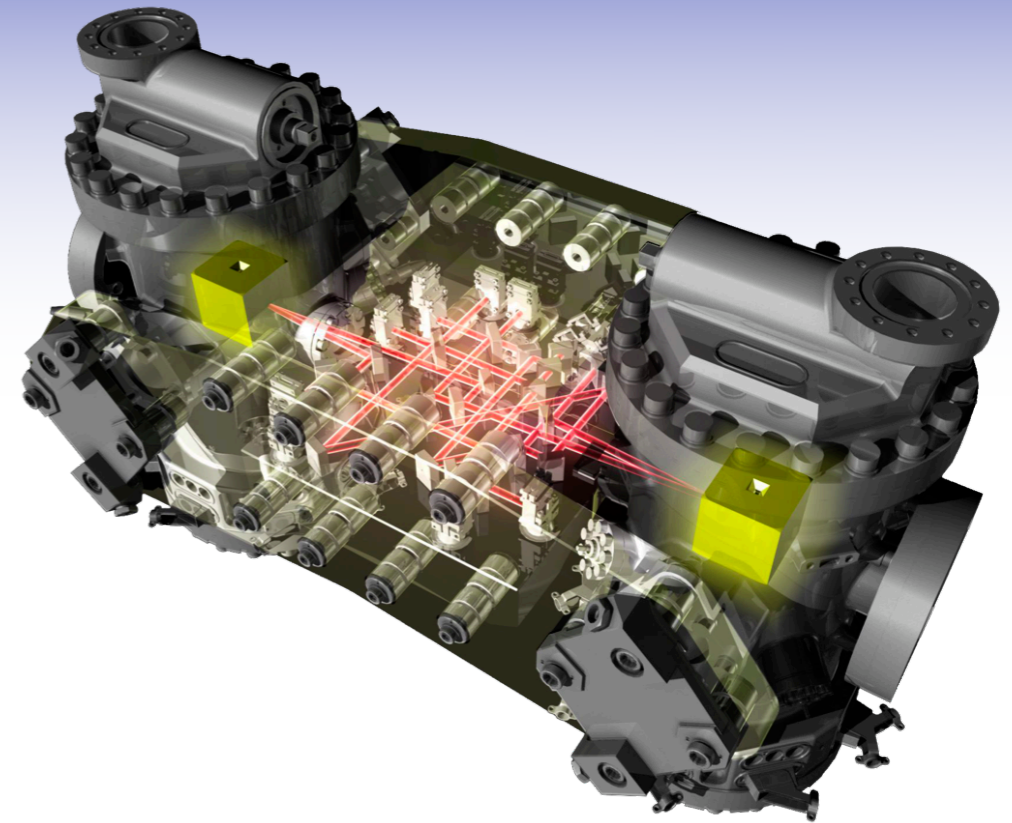


Performance of LPF



LTP Salient Features

- 
 LISA Technology Package (LTP) is the instrument payload of LPF
- 
 Two Au:Pt test masses housed in separate vacuum enclosures
- 
 Relative position of test masses read-out by:
 - Heterodyne laser interferometry on sensitive axis
 - Capacitive sensing on all axes
- 
 Four interferometers on ultra-low expansion optical bench
 - x1, x2-x1, Frequency noise, reference interferometer



LISA Technology Package

- Procurement and manufacture of the LTP funded by European member states and ESA



France:

Laser modulator

Germany:

PI, LTP Architect (Astrium), Laser

Italy:

PI, Inertial Sensor (ISS), Caging Mechanism

Netherlands:

ISS SCOE

Spain:

Data Diagnostics System, Data Management Unit

Switzerland:

ISS Front End Electronics

United Kingdom:

Optical Bench, Phase-meter, Charge Management



Optical Metrology System



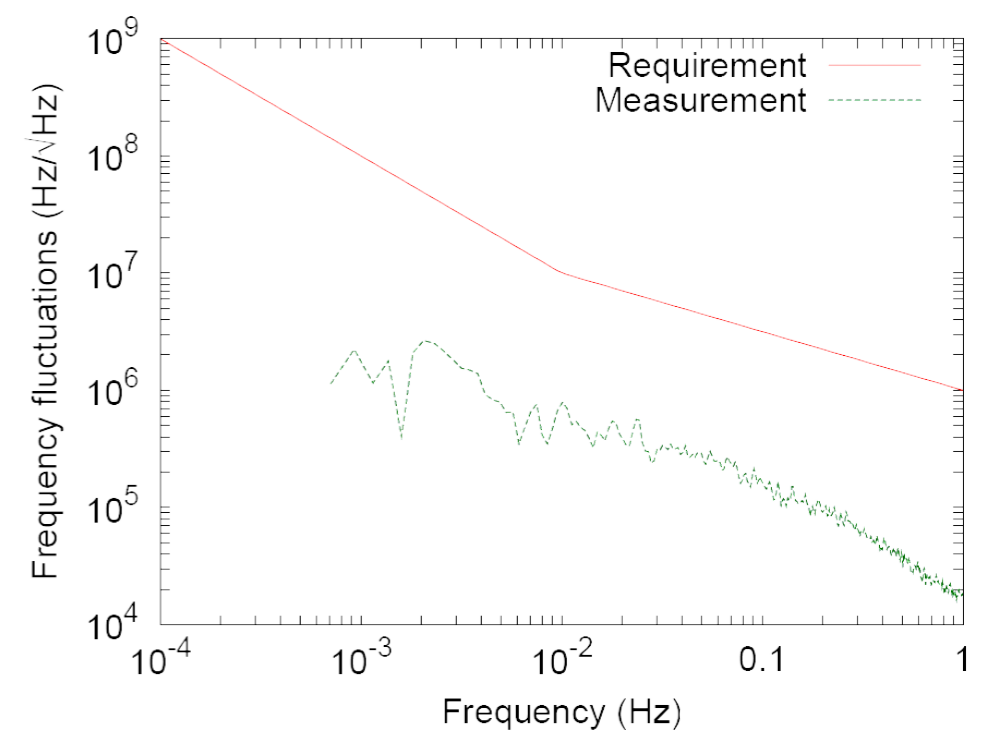
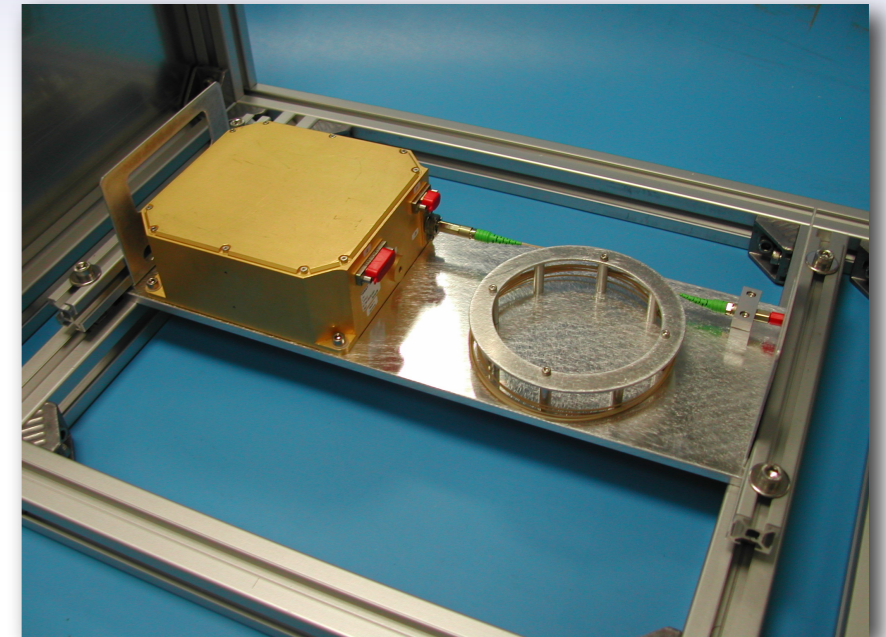
Optical Metrology System

-  The Optical Metrology System (OMS) comprises four main subsystems



Optical Metrology System

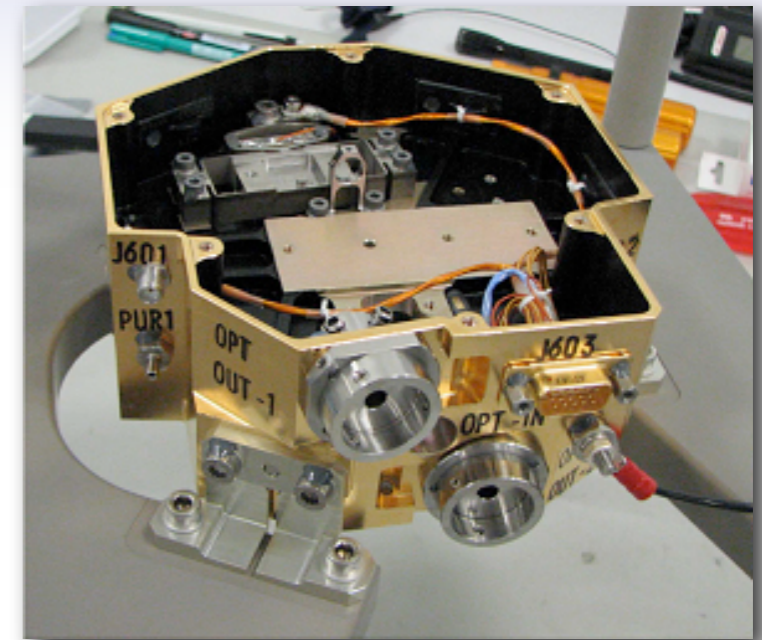
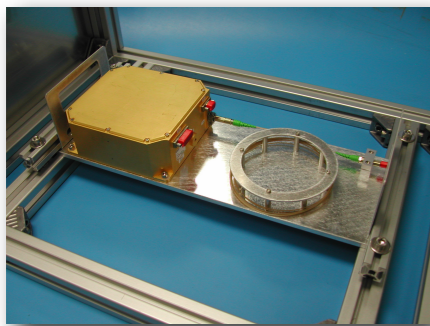
- ✪ The Optical Metrology System (OMS) comprises four main subsystems
 - Reference Laser Unit



Optical Metrology System

 The Optical Metrology System (OMS) comprises four main subsystems

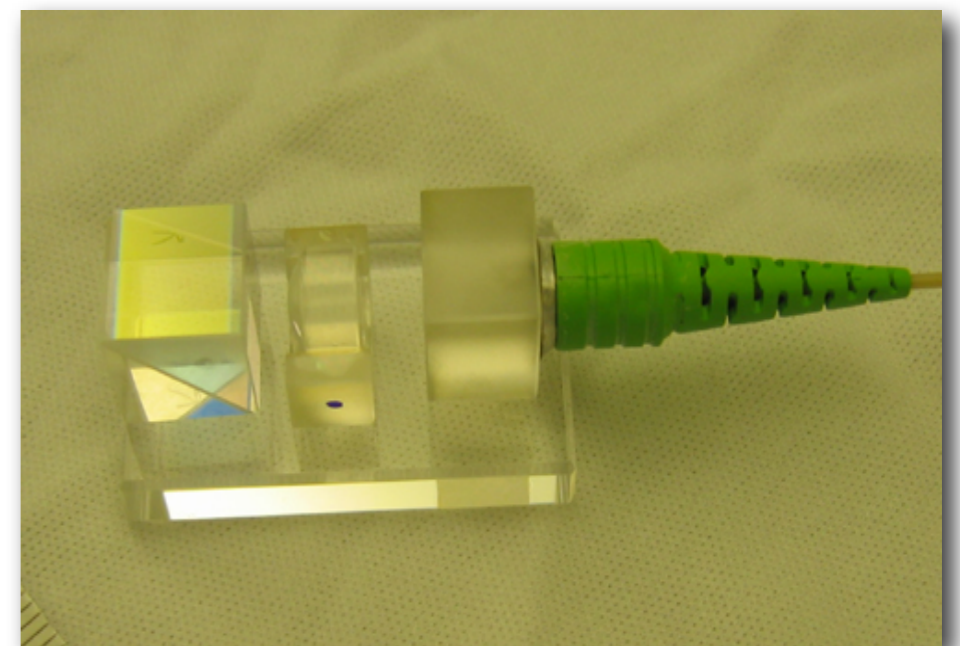
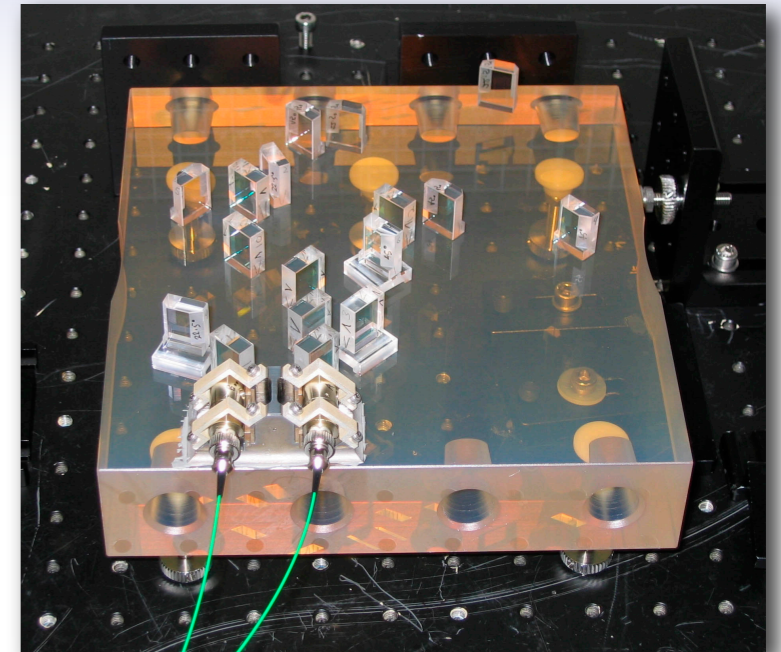
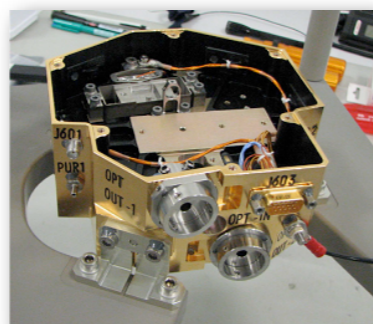
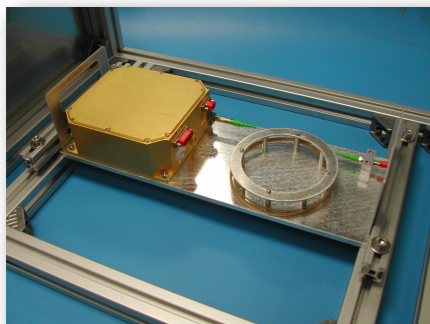
- Reference Laser Unit
- Acousto-Optic Modulator



Optical Metrology System

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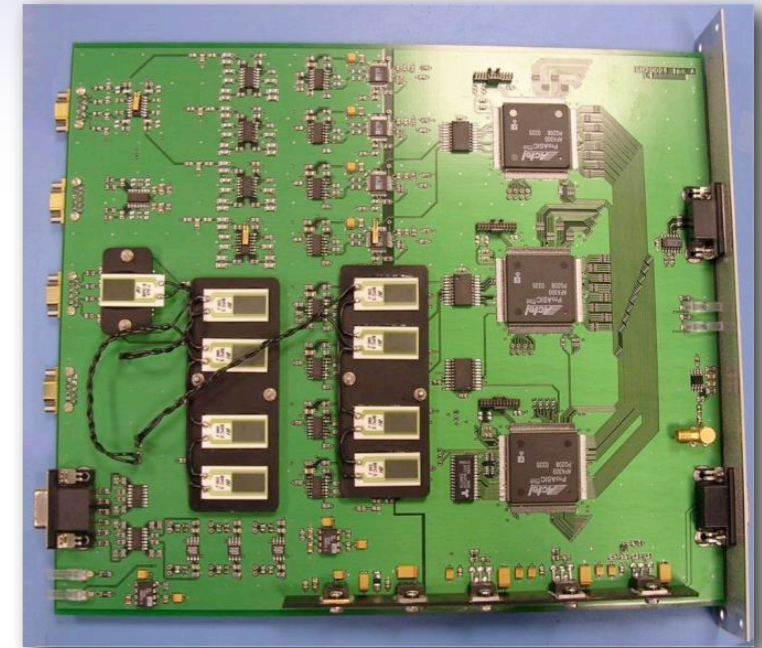
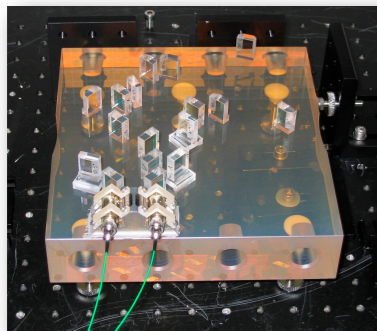
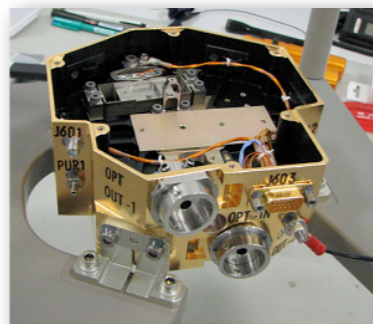
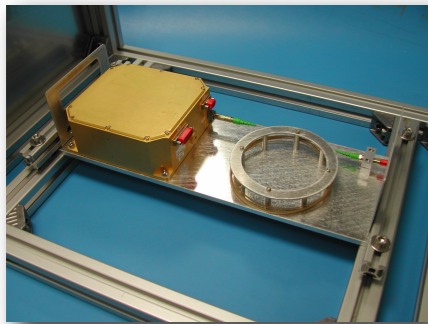
- Reference Laser Unit
- Acousto-Optic Modulator
- Optical Bench



Optical Metrology System

 The Optical Metrology System (OMS) comprises four main subsystems

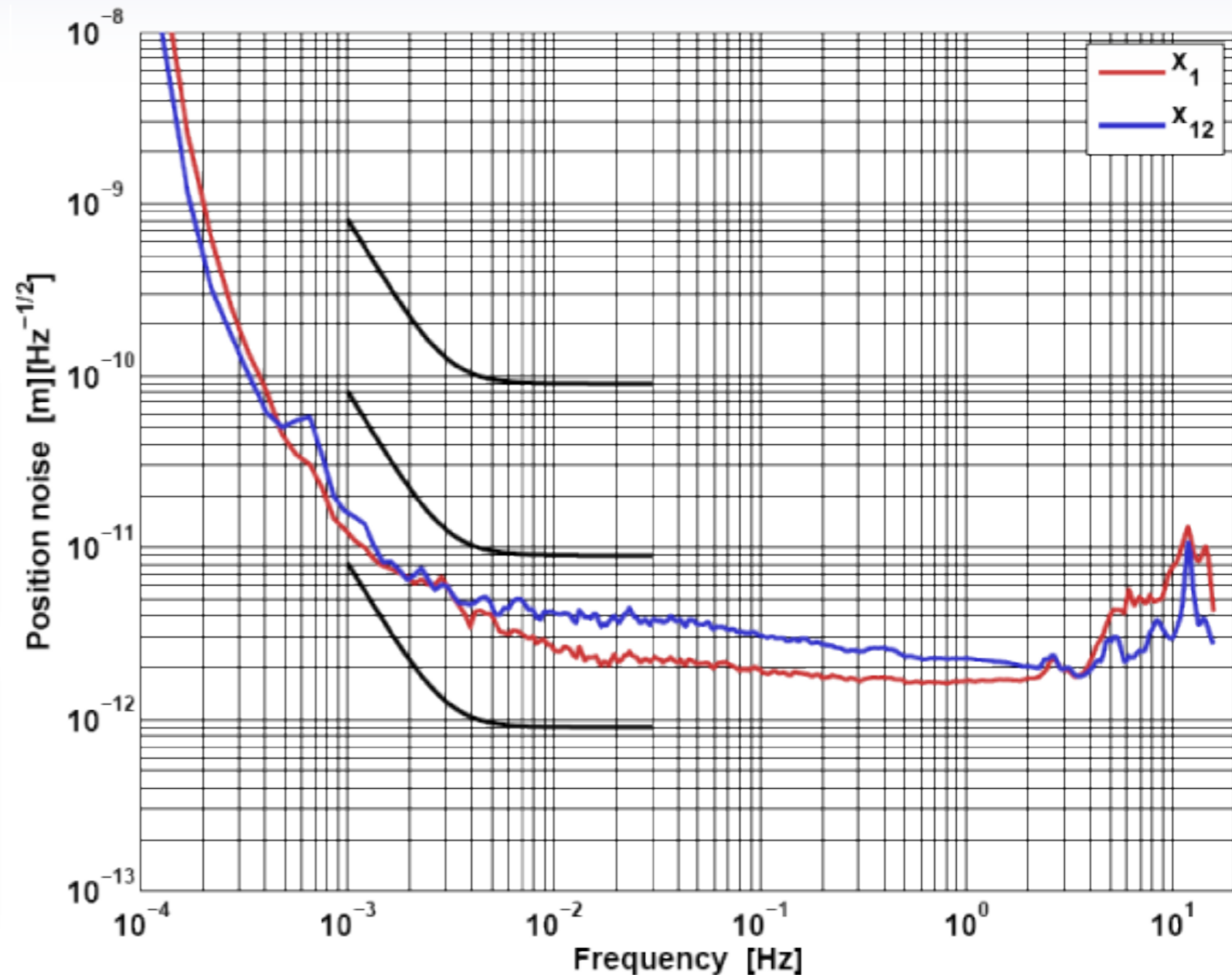
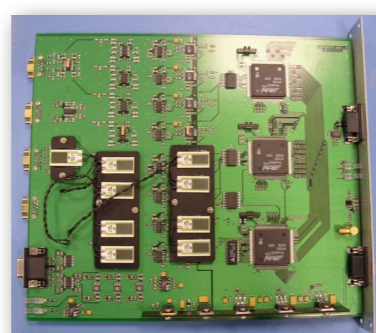
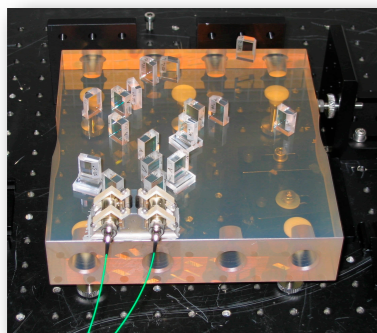
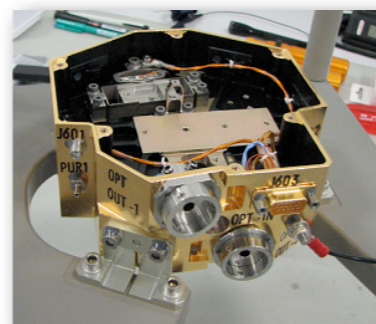
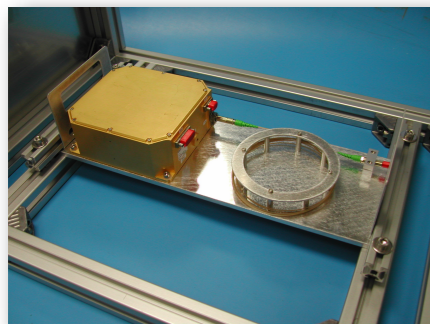
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- Acousto-Optic Modulator
- Optical Bench
- Phase-meter



Optical Metrology System

🚀 The Optical Metrology System (OMS) comprises four main subsystems

- Reference Laser Unit
- Acousto-Optic Modulator
- Optical Bench
- Phase-meter

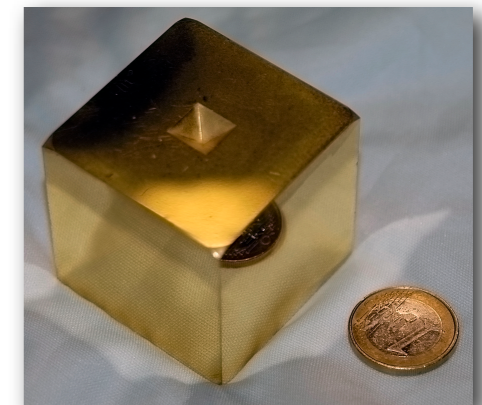
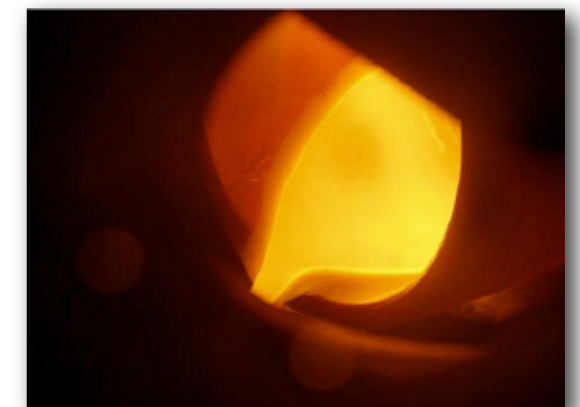
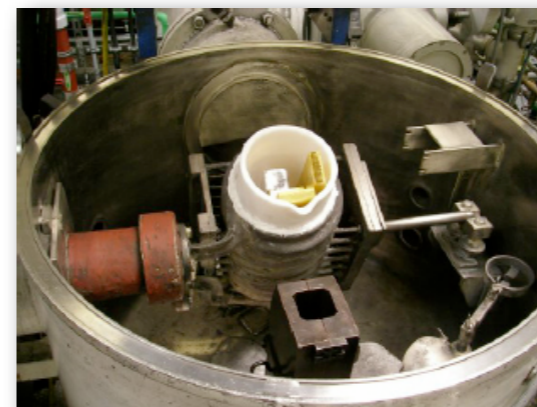
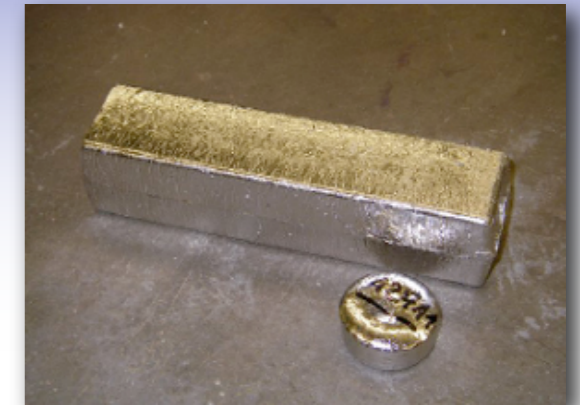


OMS closed loop tests (AEI, Hannover)



Inertial Sensor System

Proof mass

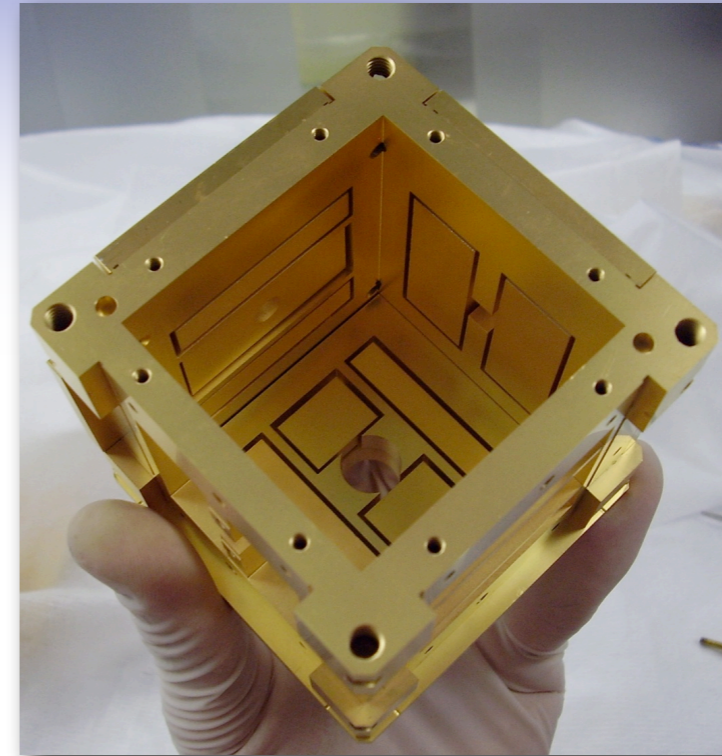


Build stages of the Au:Pt test mass



Inertial Sensor System

- Proof Mass
- Electrode housing**



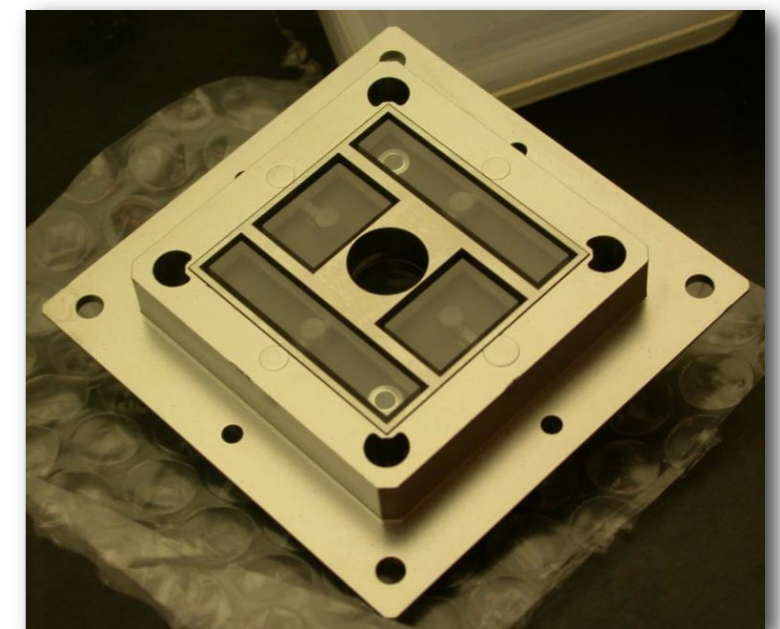
EM Molybdenum electrode Housing



EH Mandrel






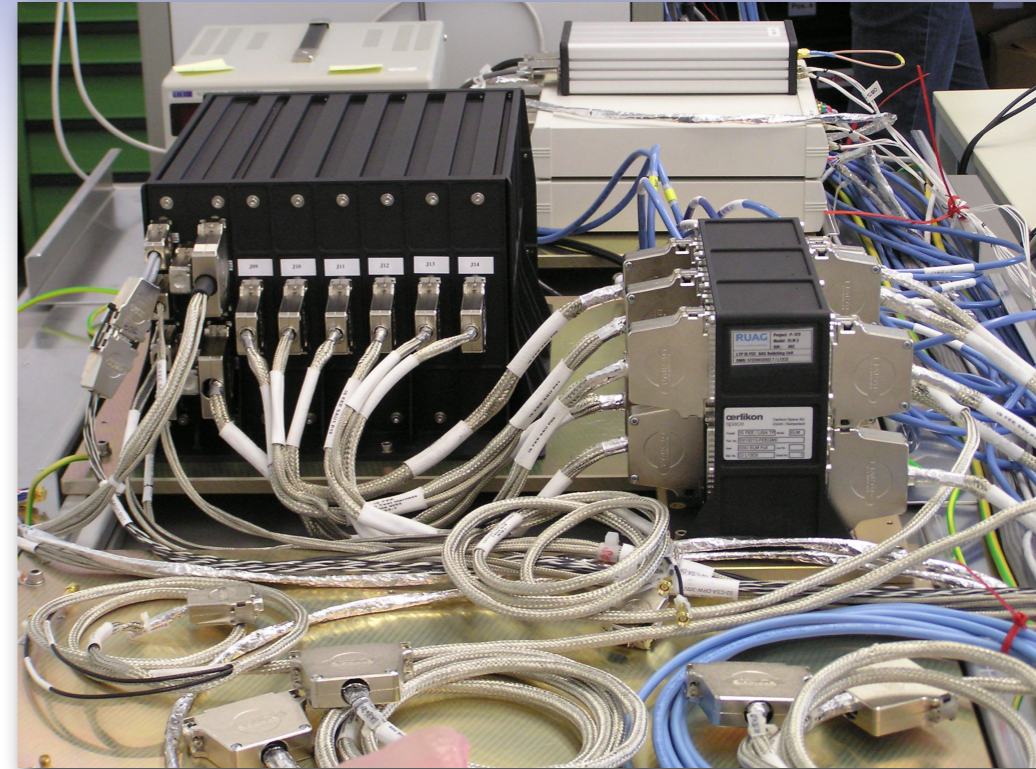
FM x-face Sapphire electrode



Uncoated z-face sapphire electrode in EH wall

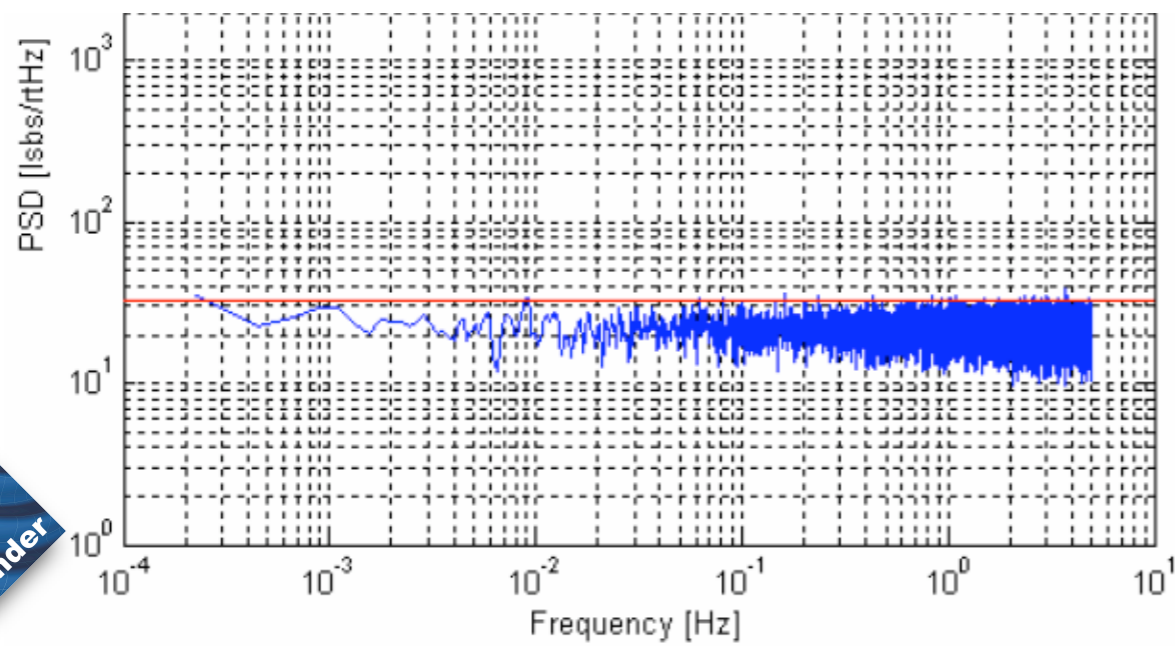
Inertial Sensor System

-  Proof mass
-  Electrode housing
-  **Front end electronics**

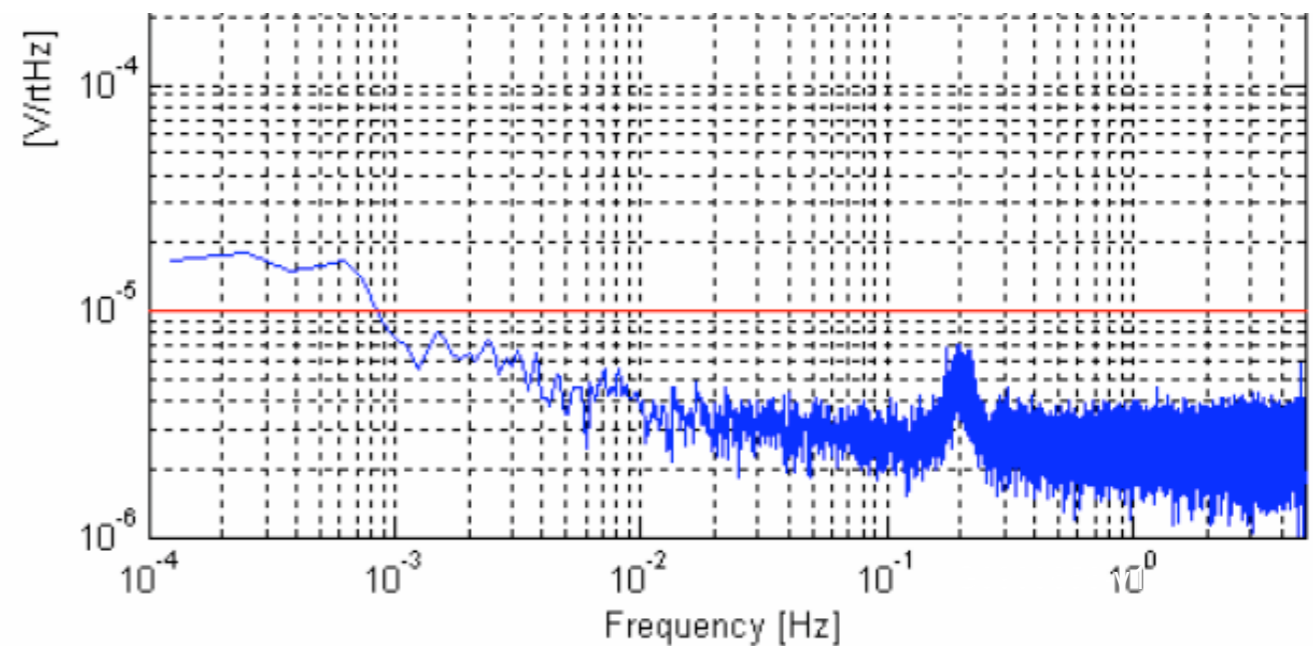


EM ISS FEE and switching unit

Sensing Noise

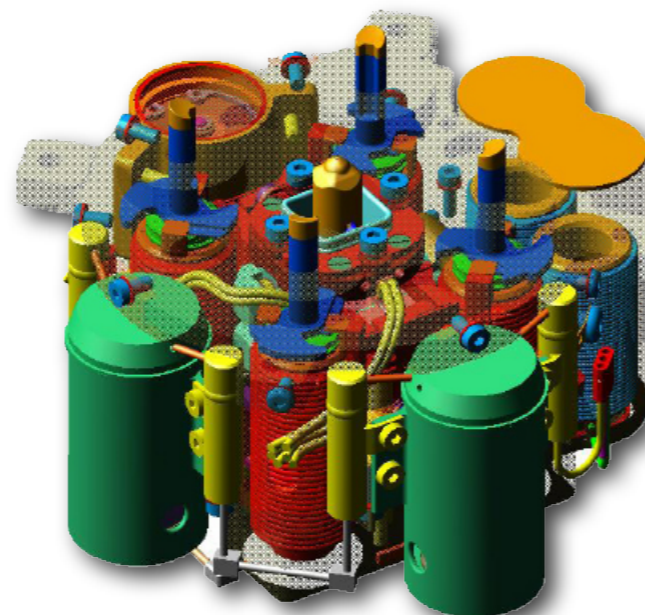
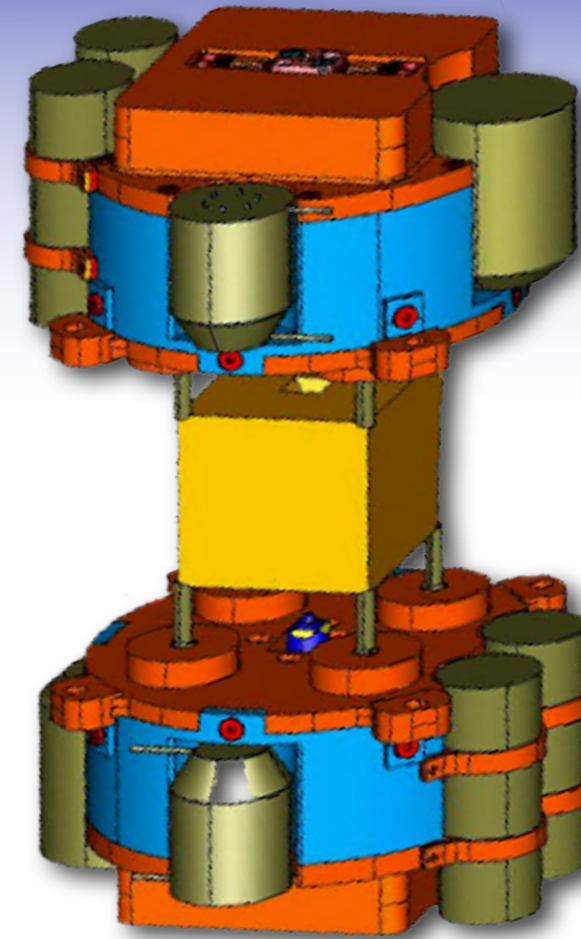


Actuation Noise

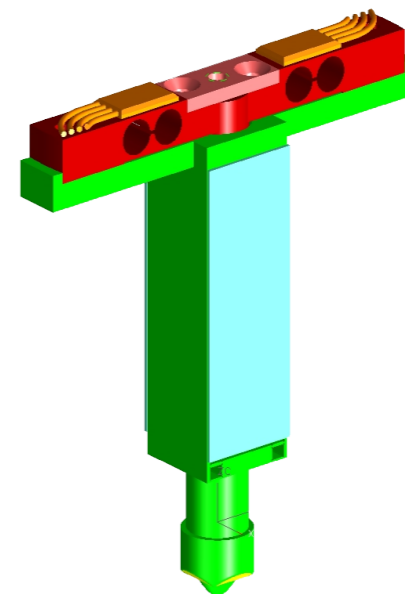


Inertial Sensor System

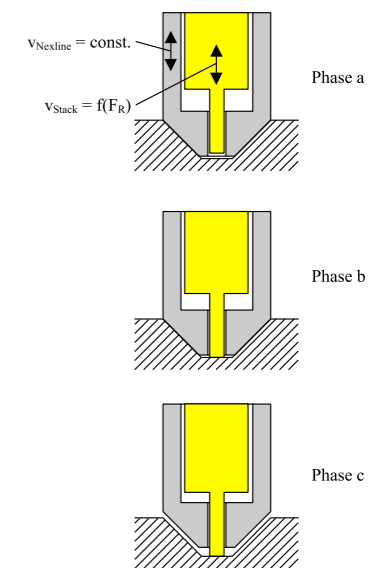
- Proof mass
- Electrode housing
- Front end electronics
- Caging mechanism**



Launch Lock
(3000N)



Positioning Actuator
(100N)

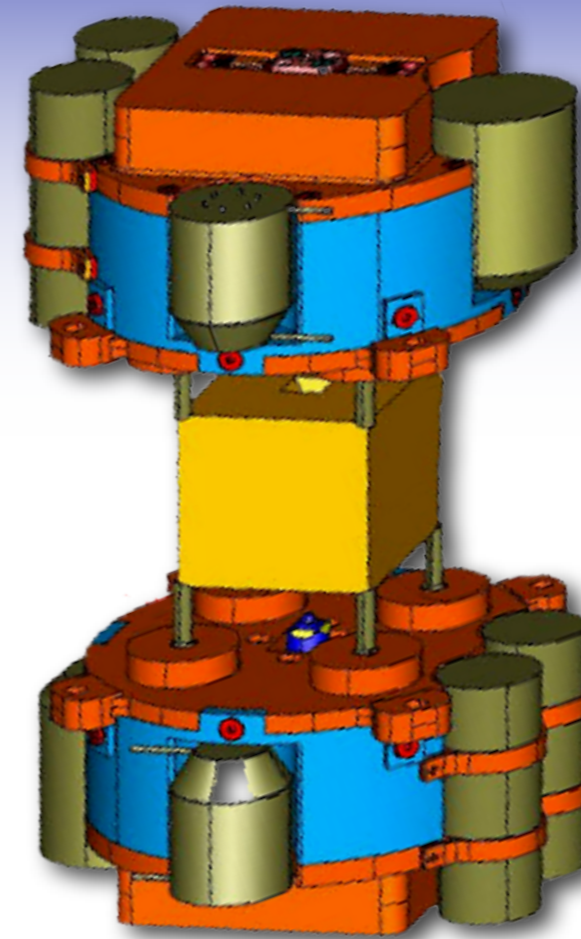


Release Actuator
(10N)

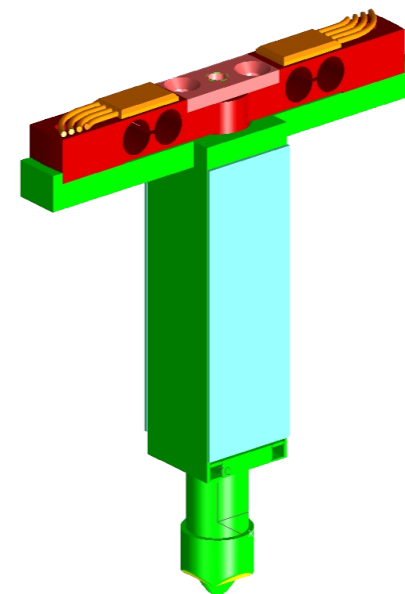
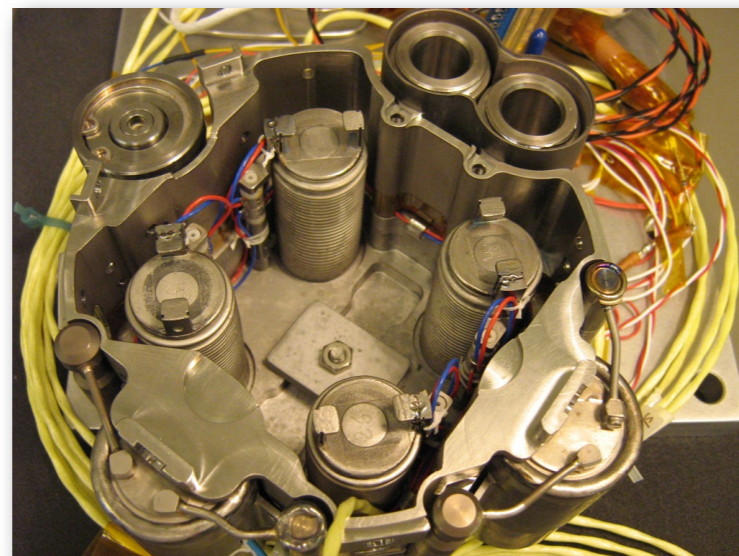


Inertial Sensor System

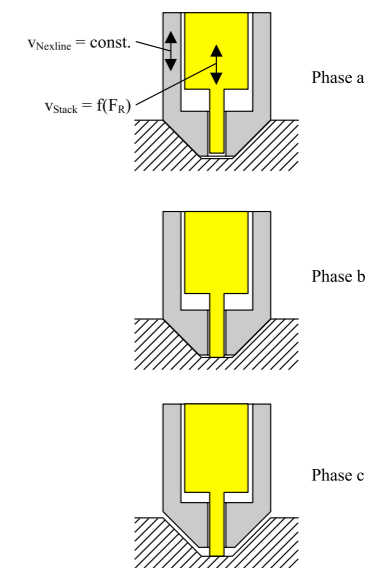
- Proof mass
- Electrode housing
- Front end electronics
- Caging mechanism**



EM Finger



Positioning Actuator
(100N)

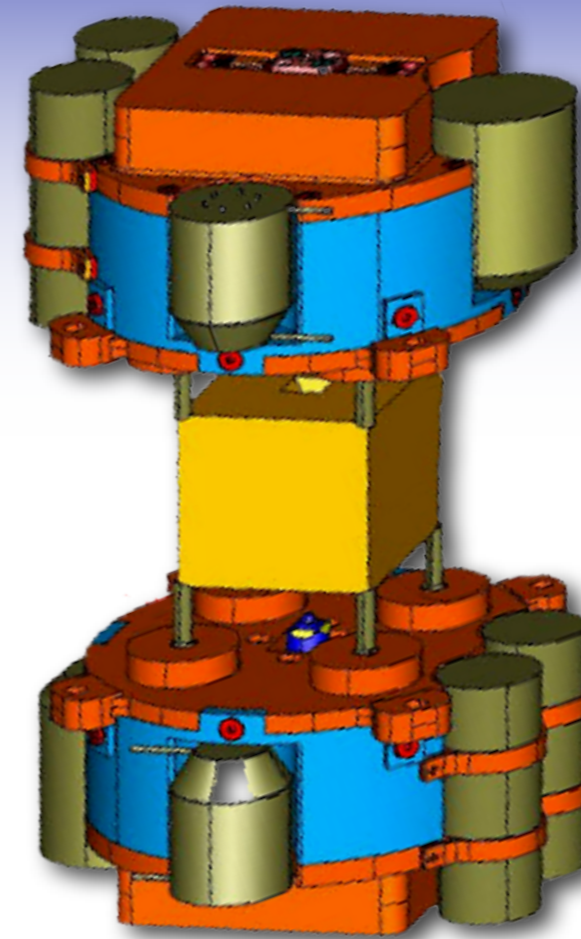


Release Actuator
(10N)

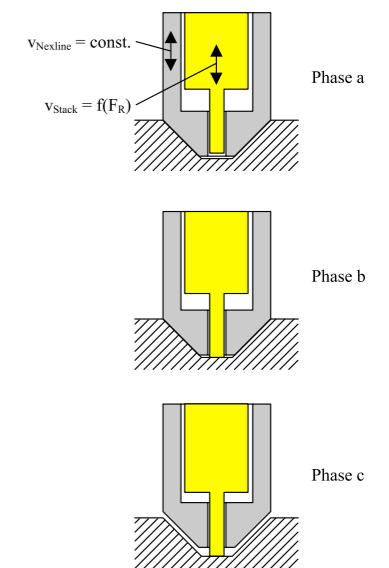
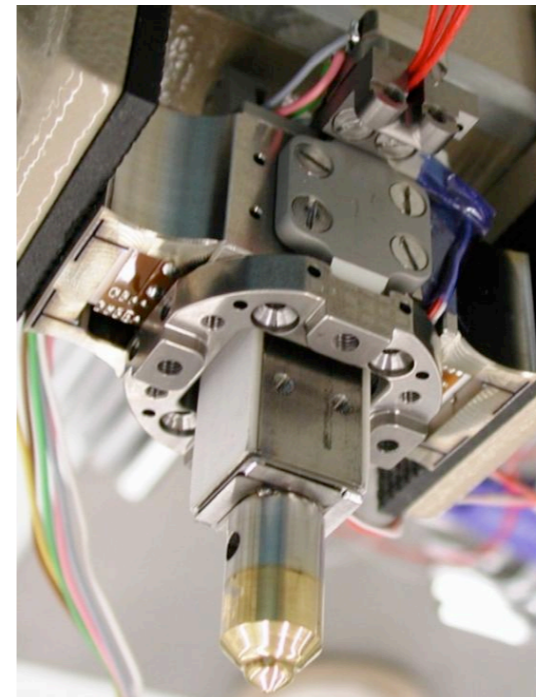
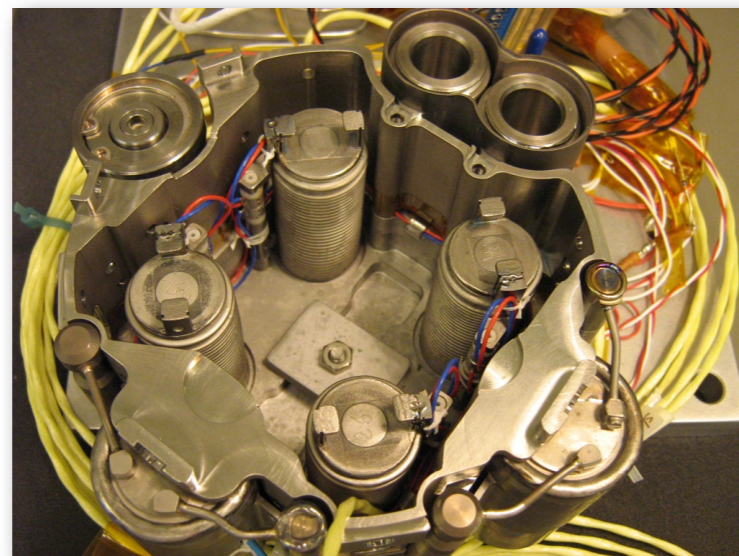


Inertial Sensor System

- Proof mass
- Electrode housing
- Front end electronics
- Caging mechanism**



EM Finger

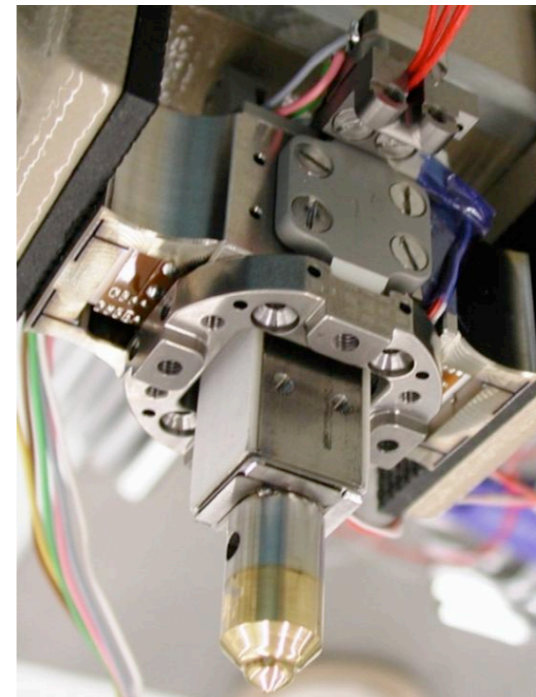
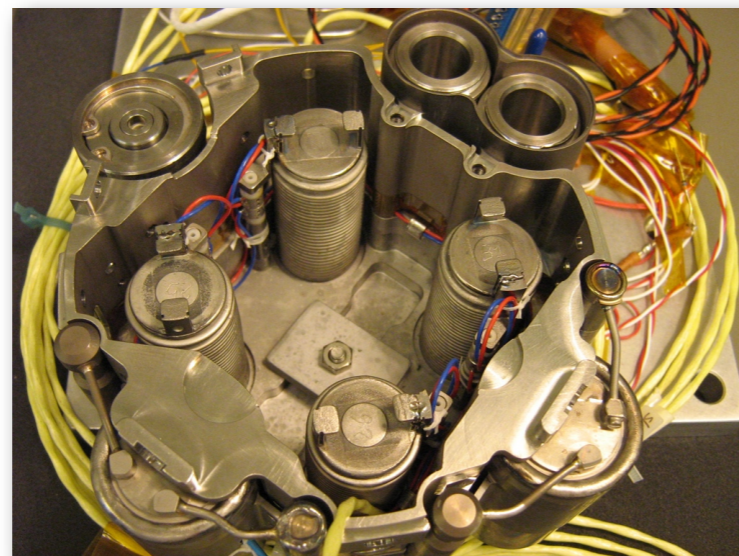
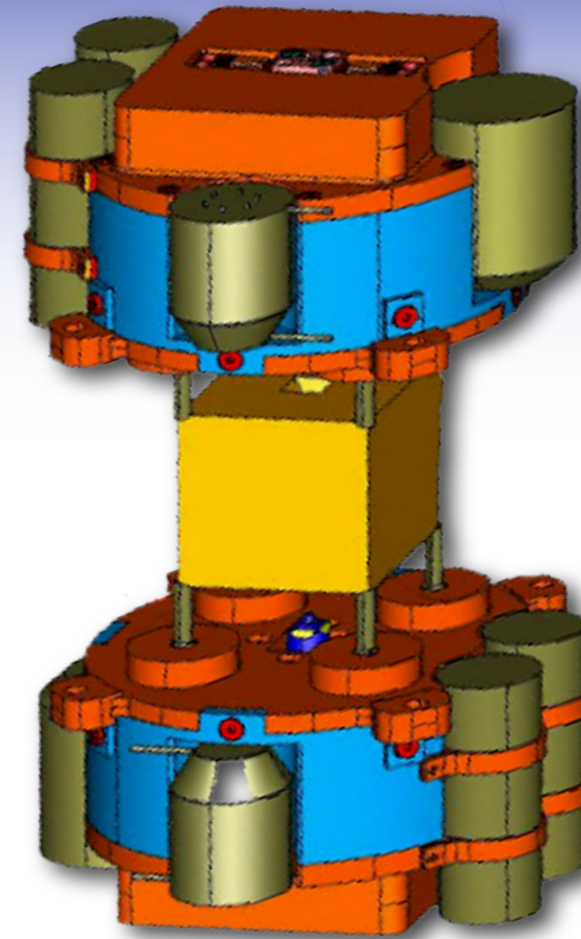


Release Actuator
(10N)



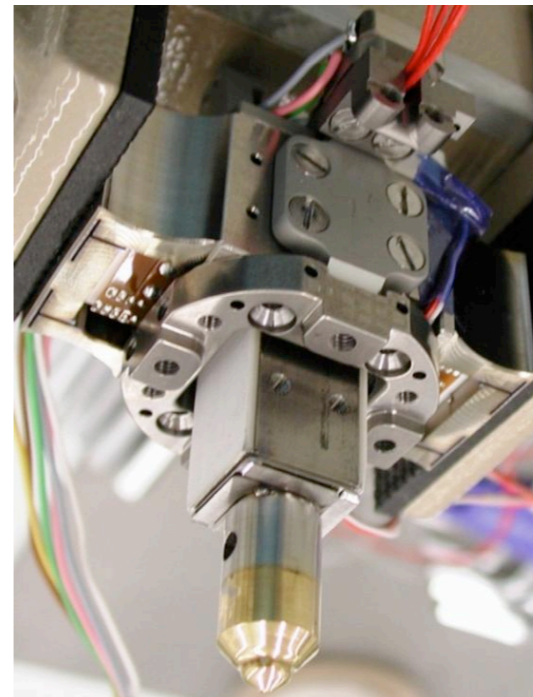
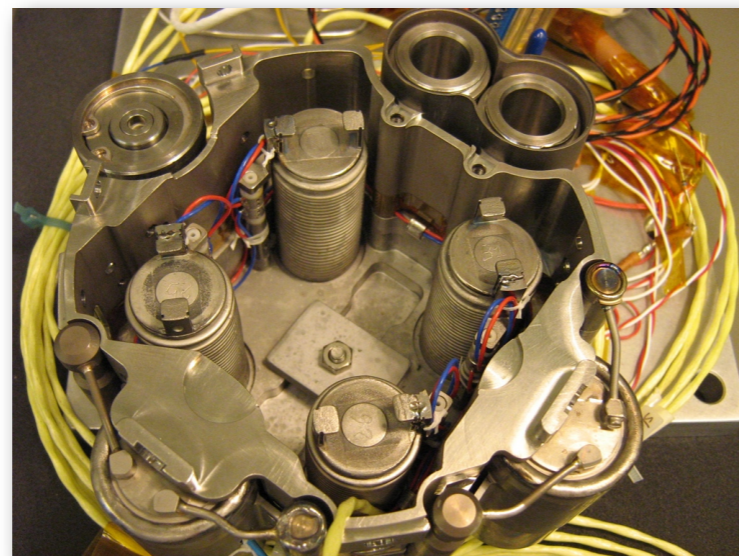
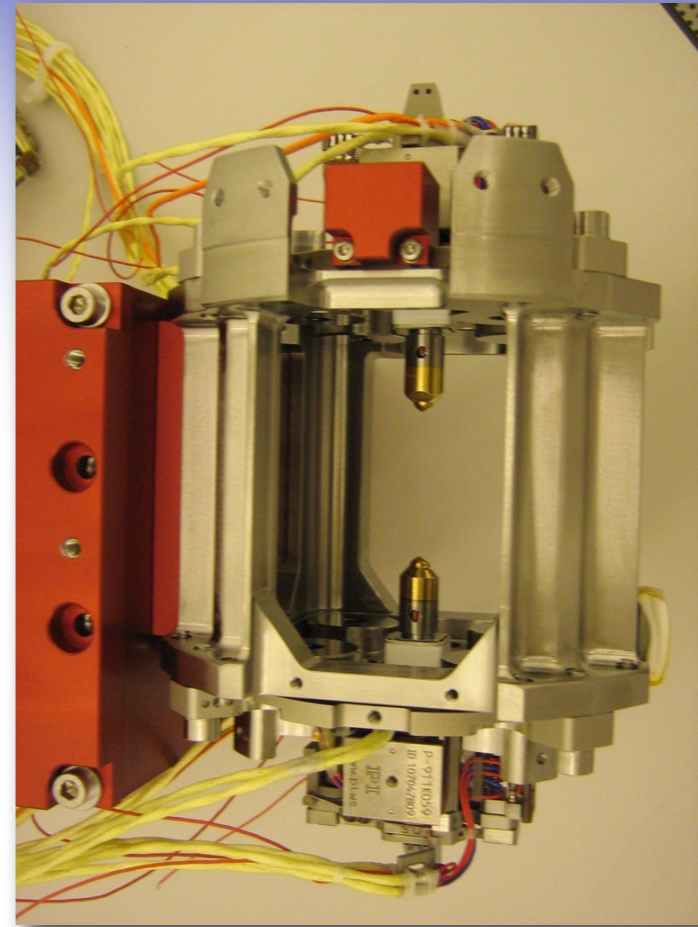
Inertial Sensor System

- Proof mass
- Electrode housing
- Front end electronics
- Caging mechanism**



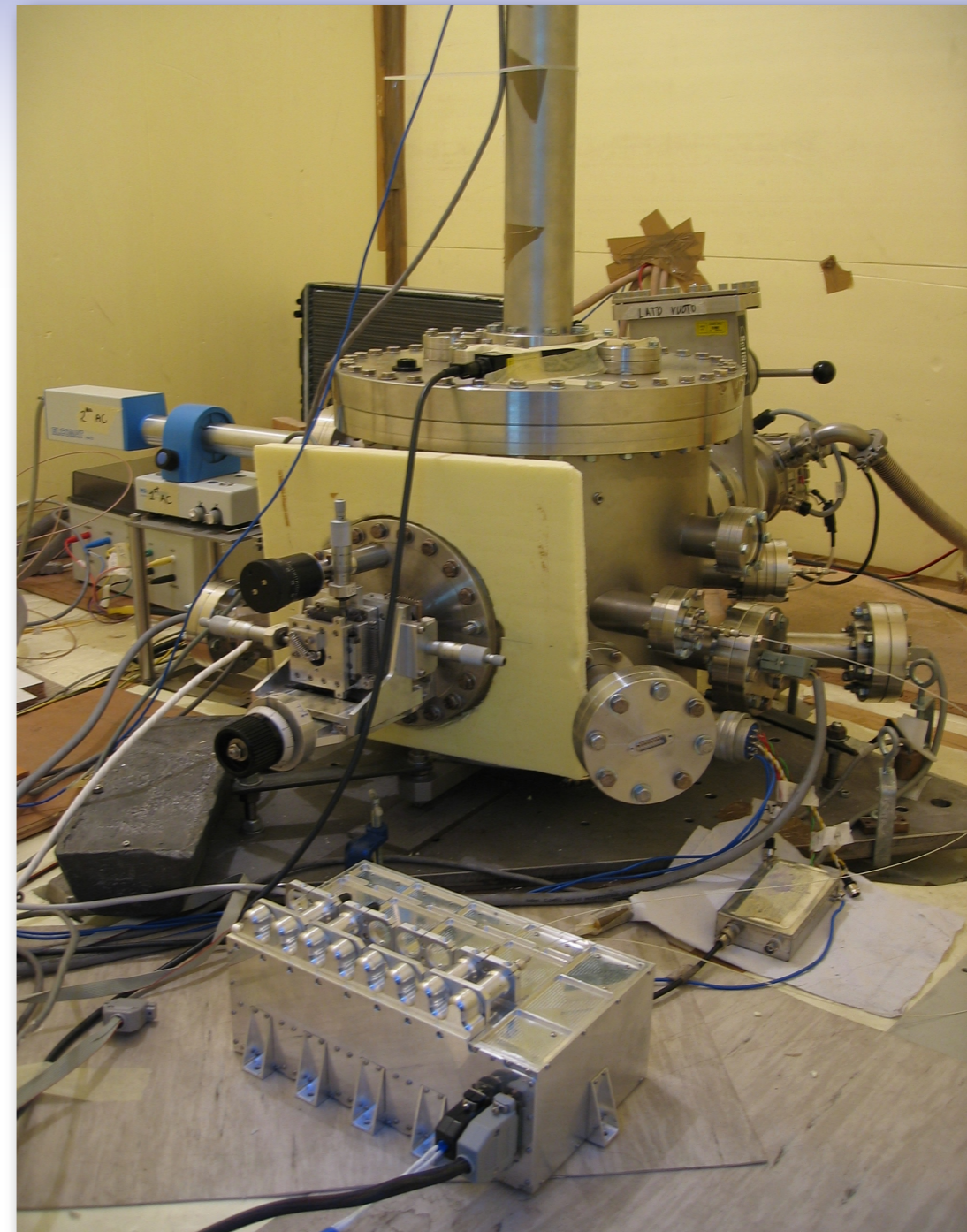
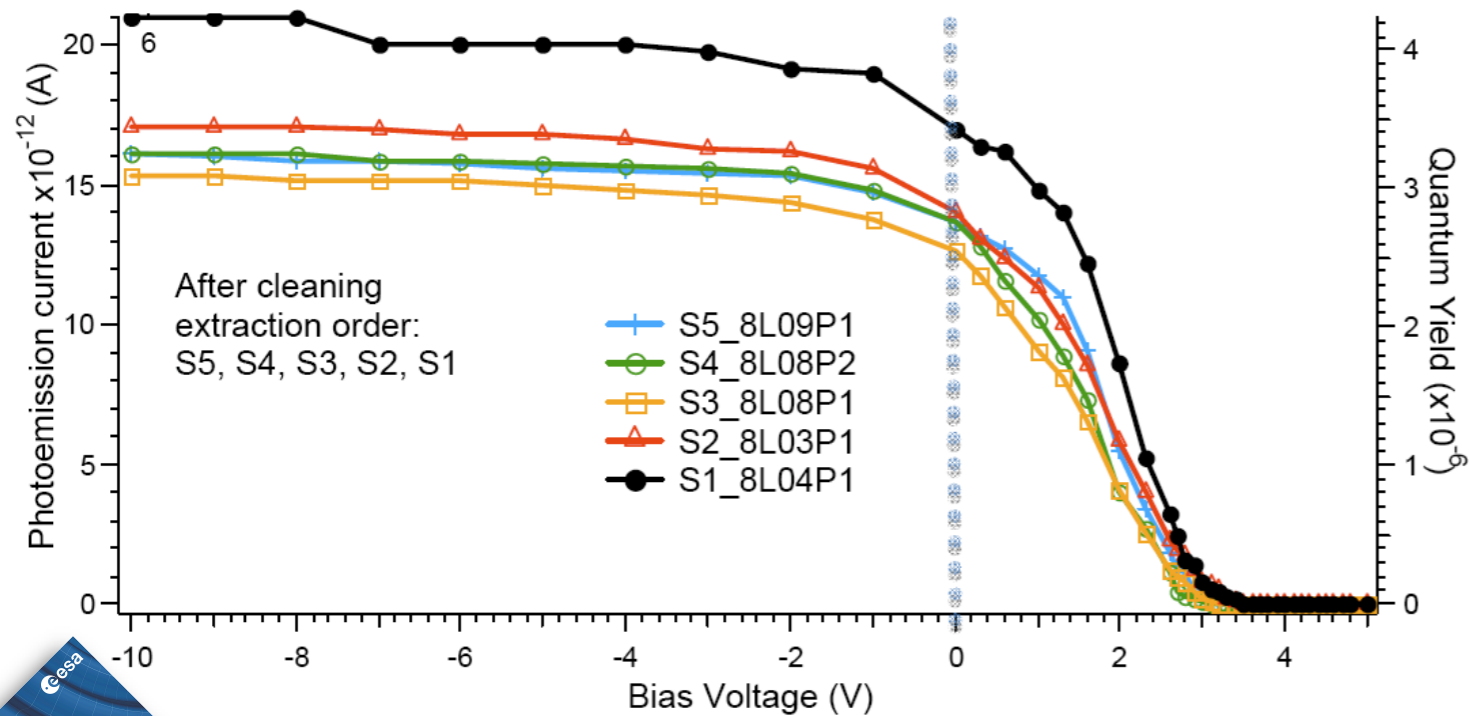
Inertial Sensor System

- Proof mass
- Electrode housing
- Front end electronics
- Caging mechanism**



Inertial Sensor System

- Proof mass
- Electrode housing
- Front end electronics
- Caging mechanism
- UV discharge system**



Charge Management system being tested on torsion pendulum facility

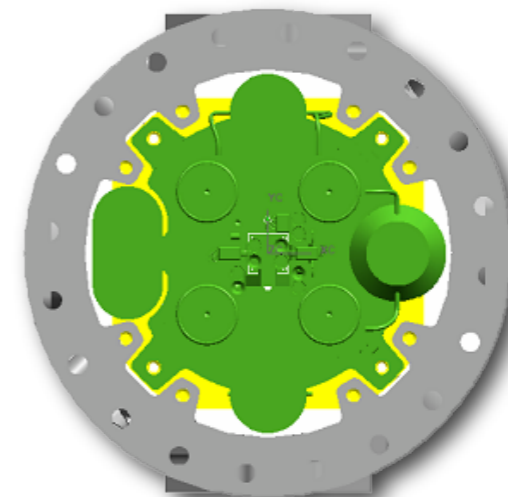


Inertial Sensor System

- Proof mass
- Electrode housing
- Front end electronics
- Caging mechanism
- UV discharge system
- Vacuum System**

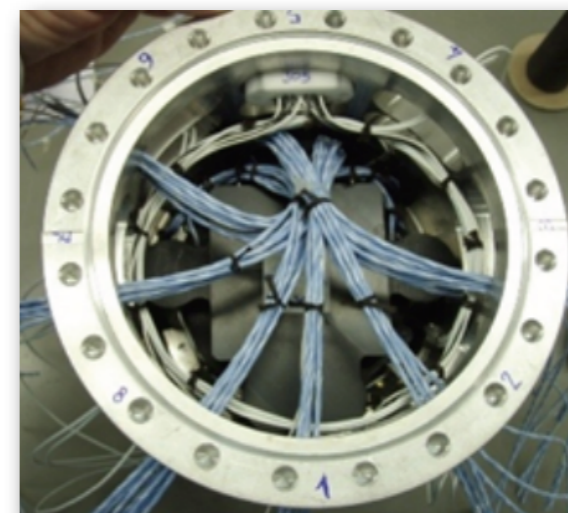
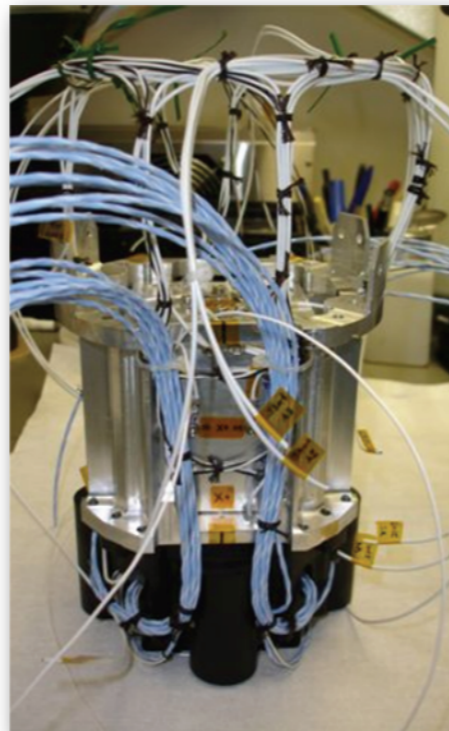
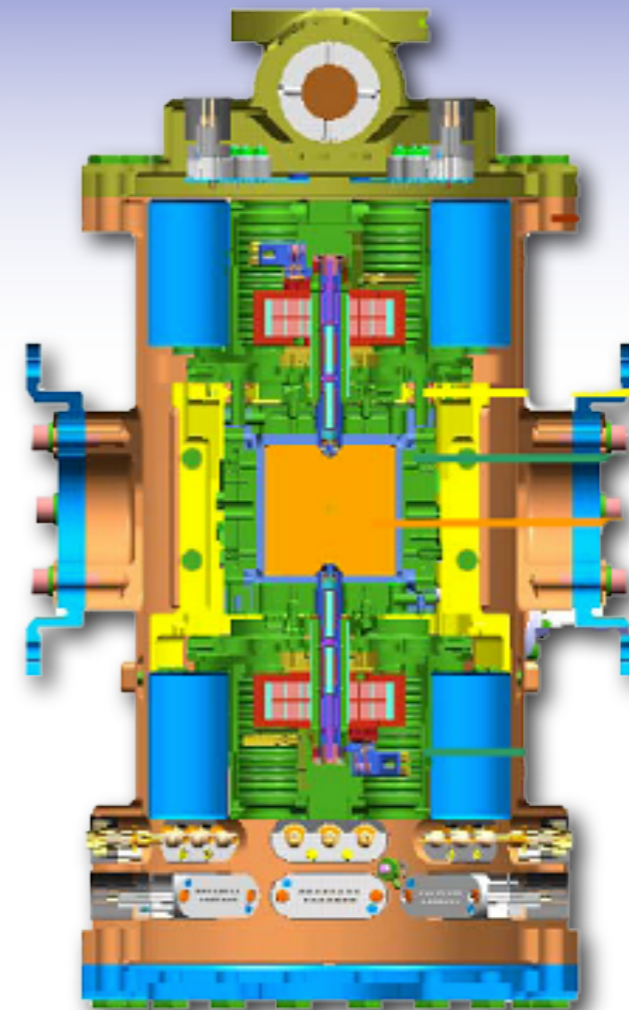


EM Titanium vacuum enclosure



Inertial Sensor System

- Proof mass
- Electrode housing
- Front end electronics
- Caging mechanism
- UV discharge system
- Vacuum System**



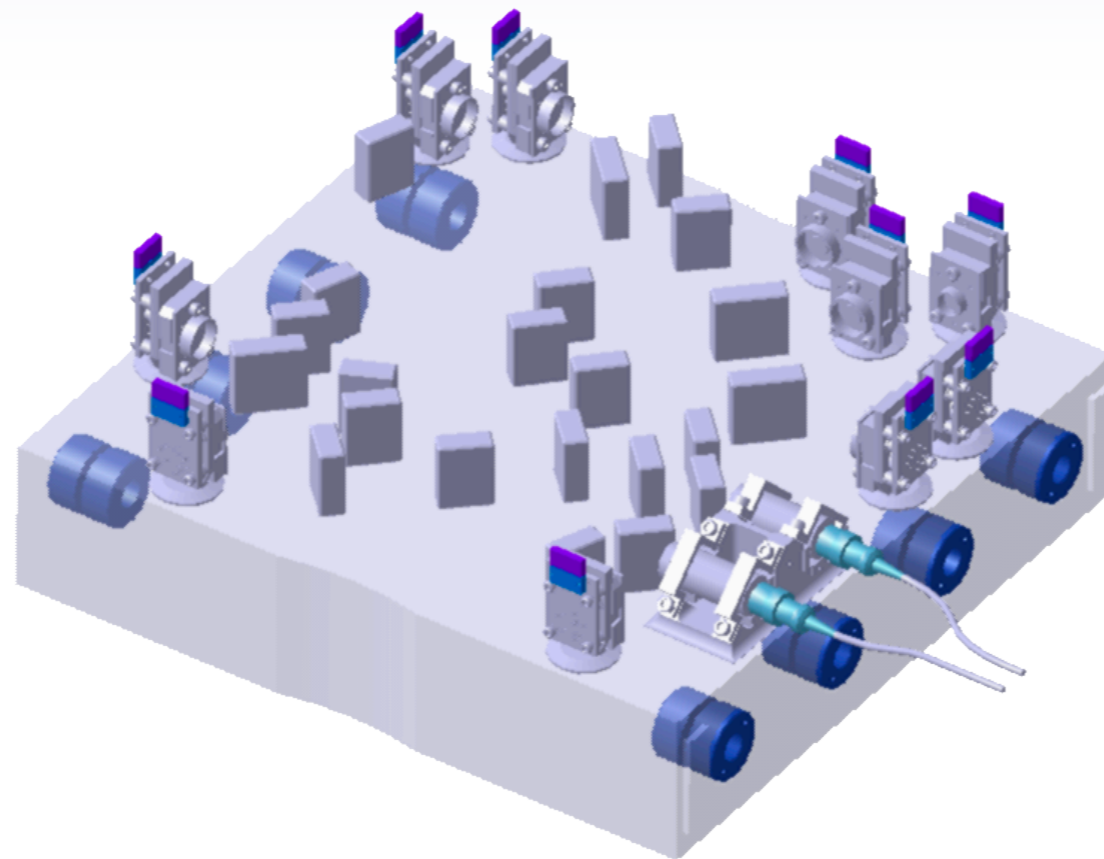
Data Diagnostic Unit

- The Data Diagnostic Unit is the LTP Payload computer
 - ERC32 space qualified processor running at 12MHz!!!
 - Main functions include:
 - TMTC of LTP units
 - Data handling of OMS and auxiliary data
 - Running OMS loops
 - Frequency noise, intensity noise, and optical path length difference
 - Loops running at 100Hz
 - Provide synchronisation clock to LTP units



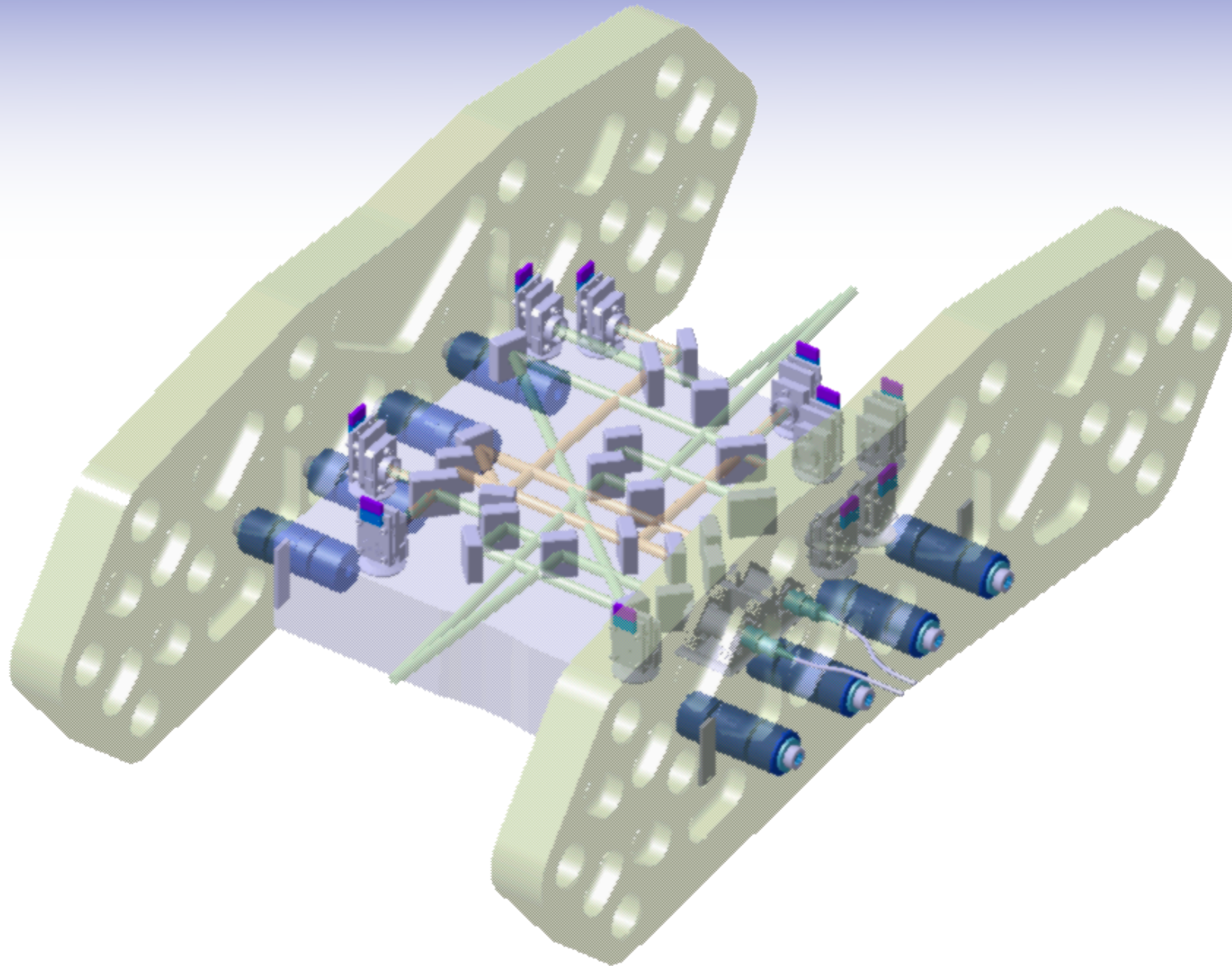
Data Management Unit EQM
(Payload Computer)

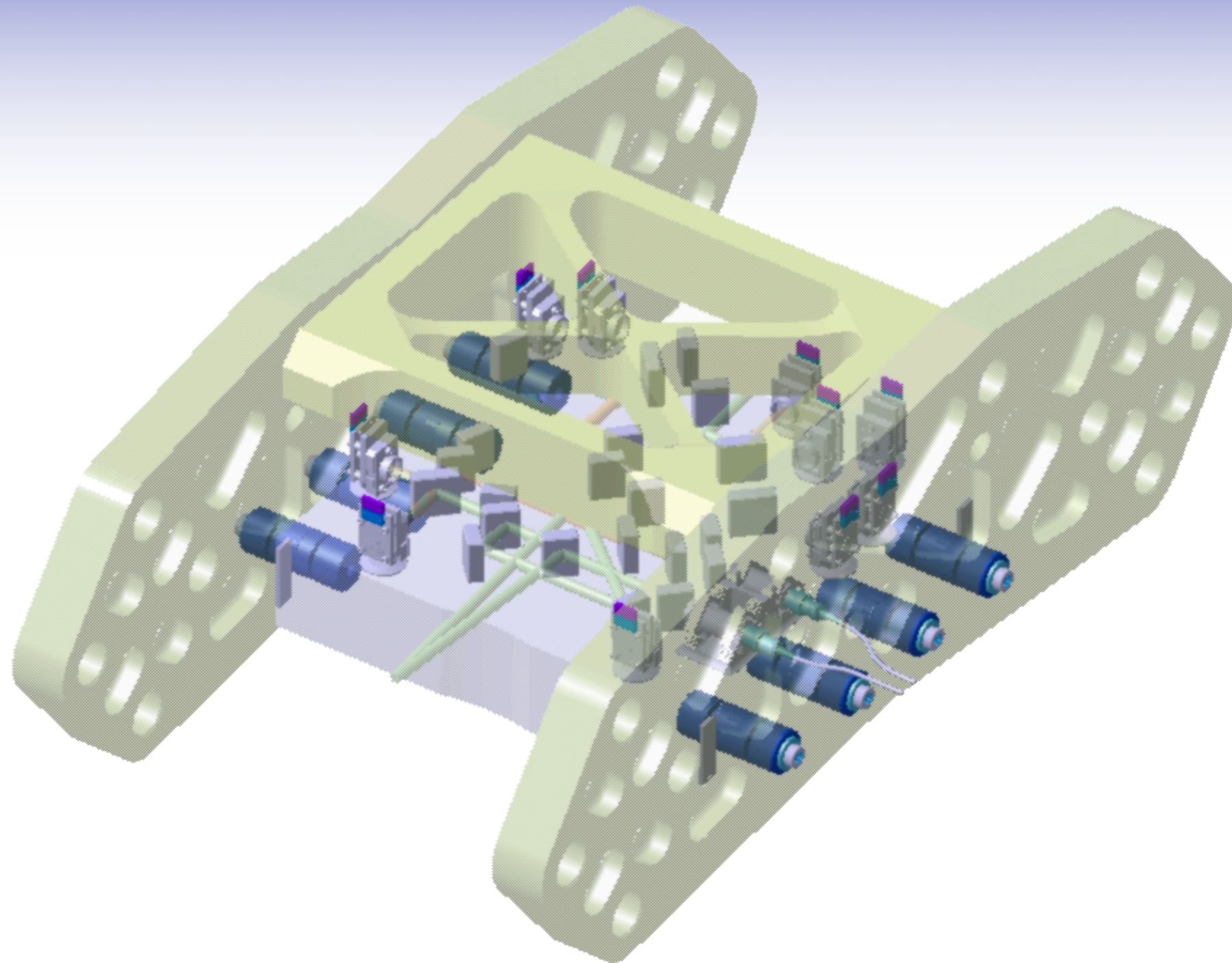
LTP Integration

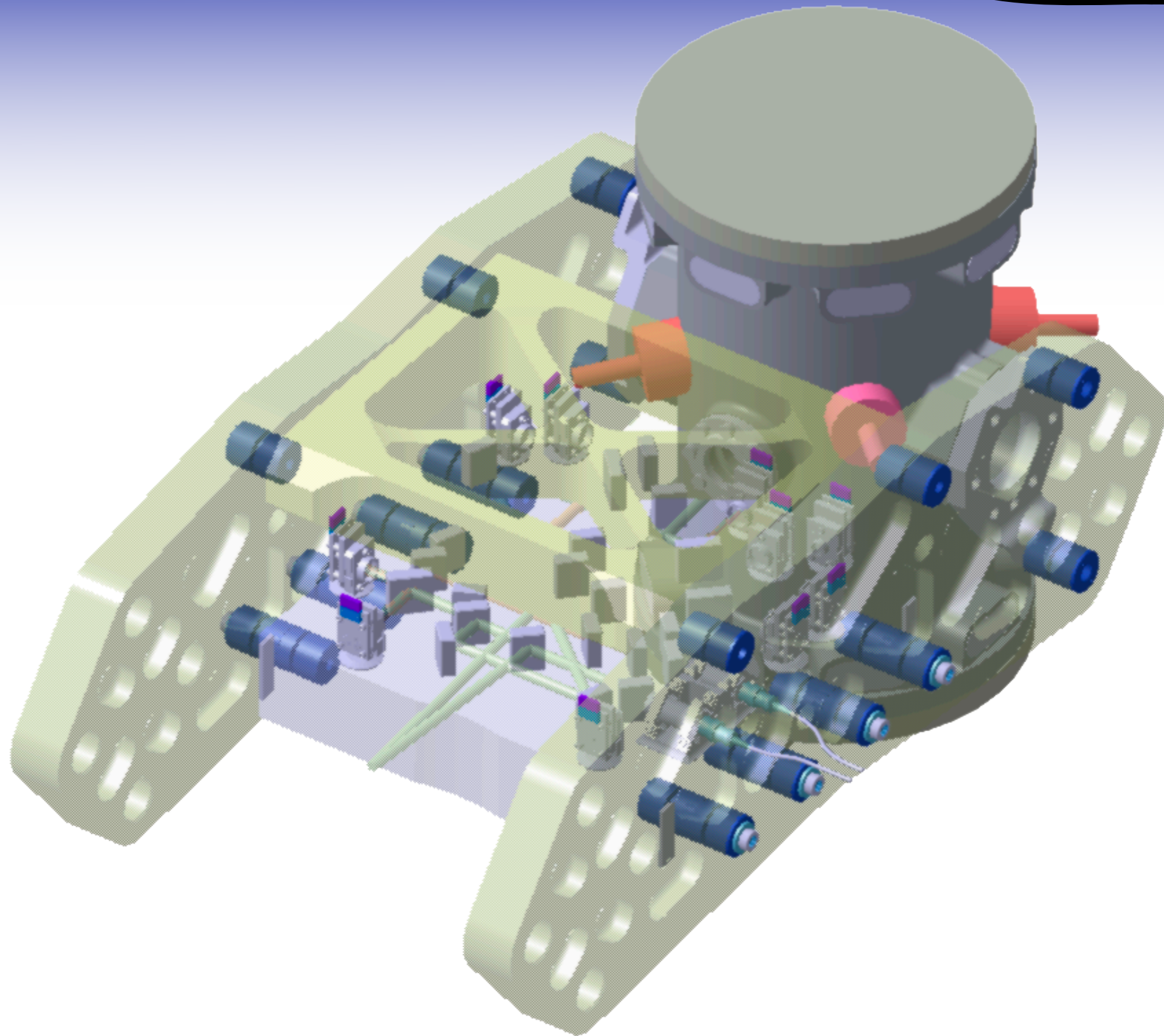


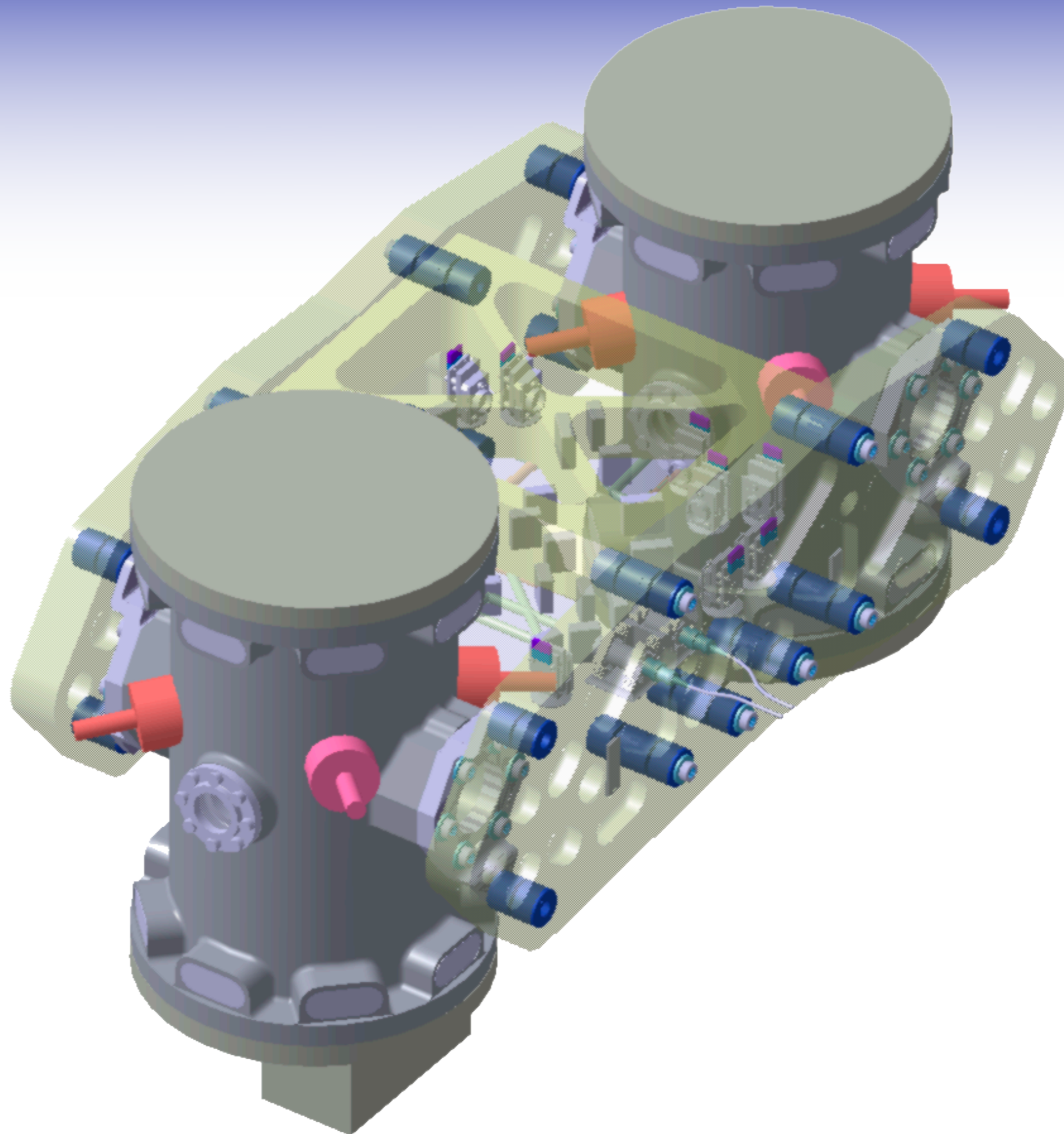
LTP Integration

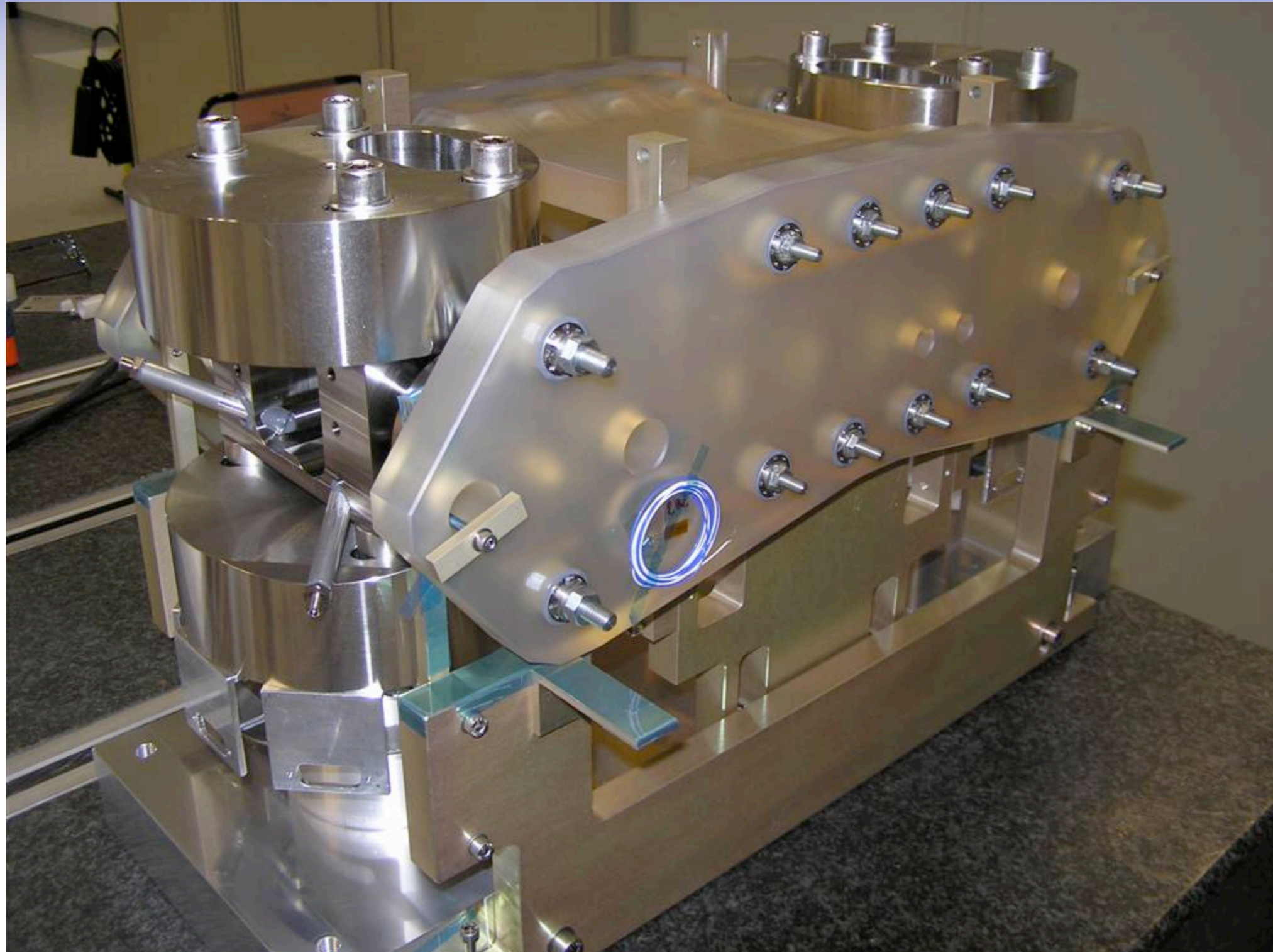


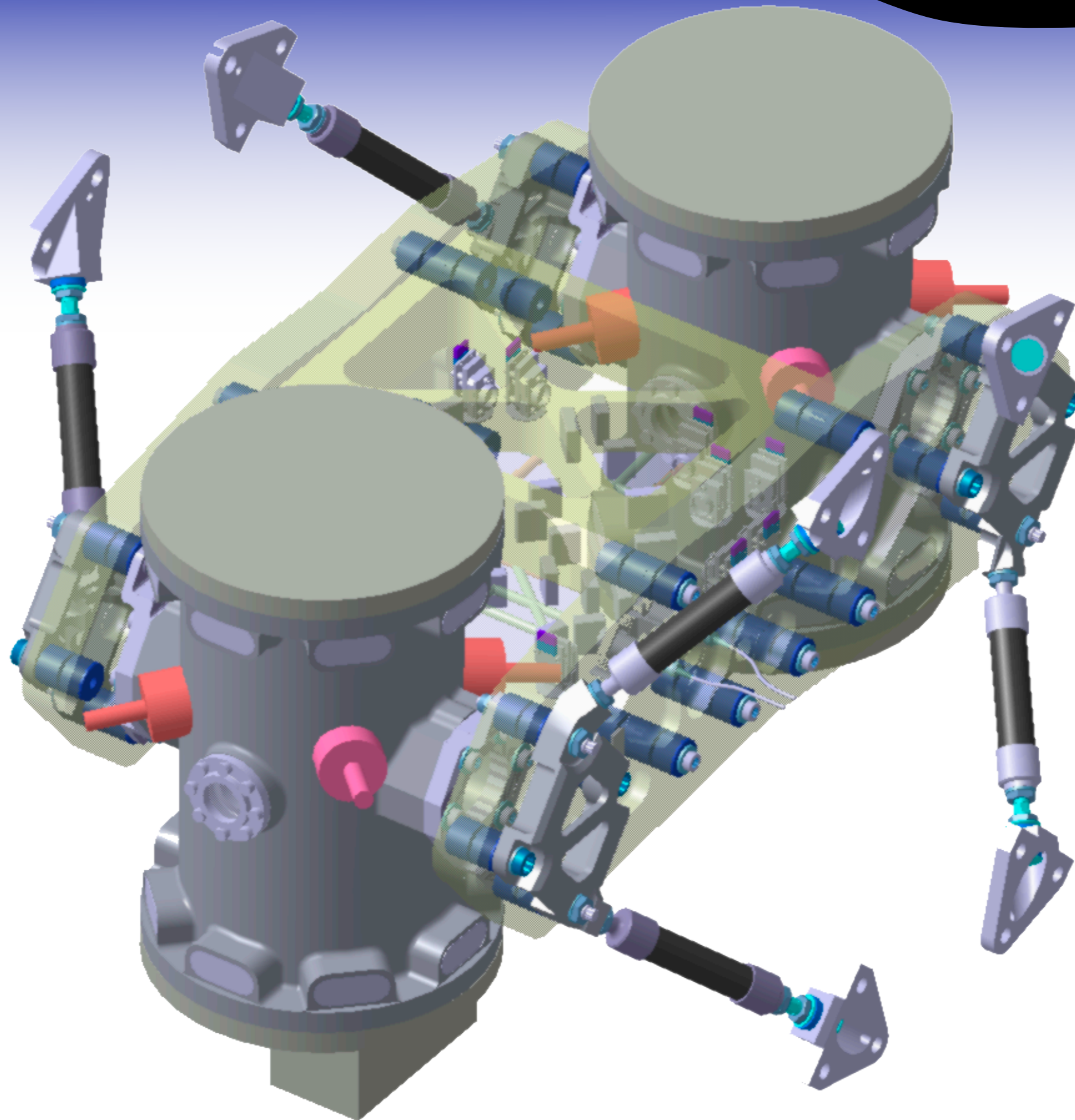


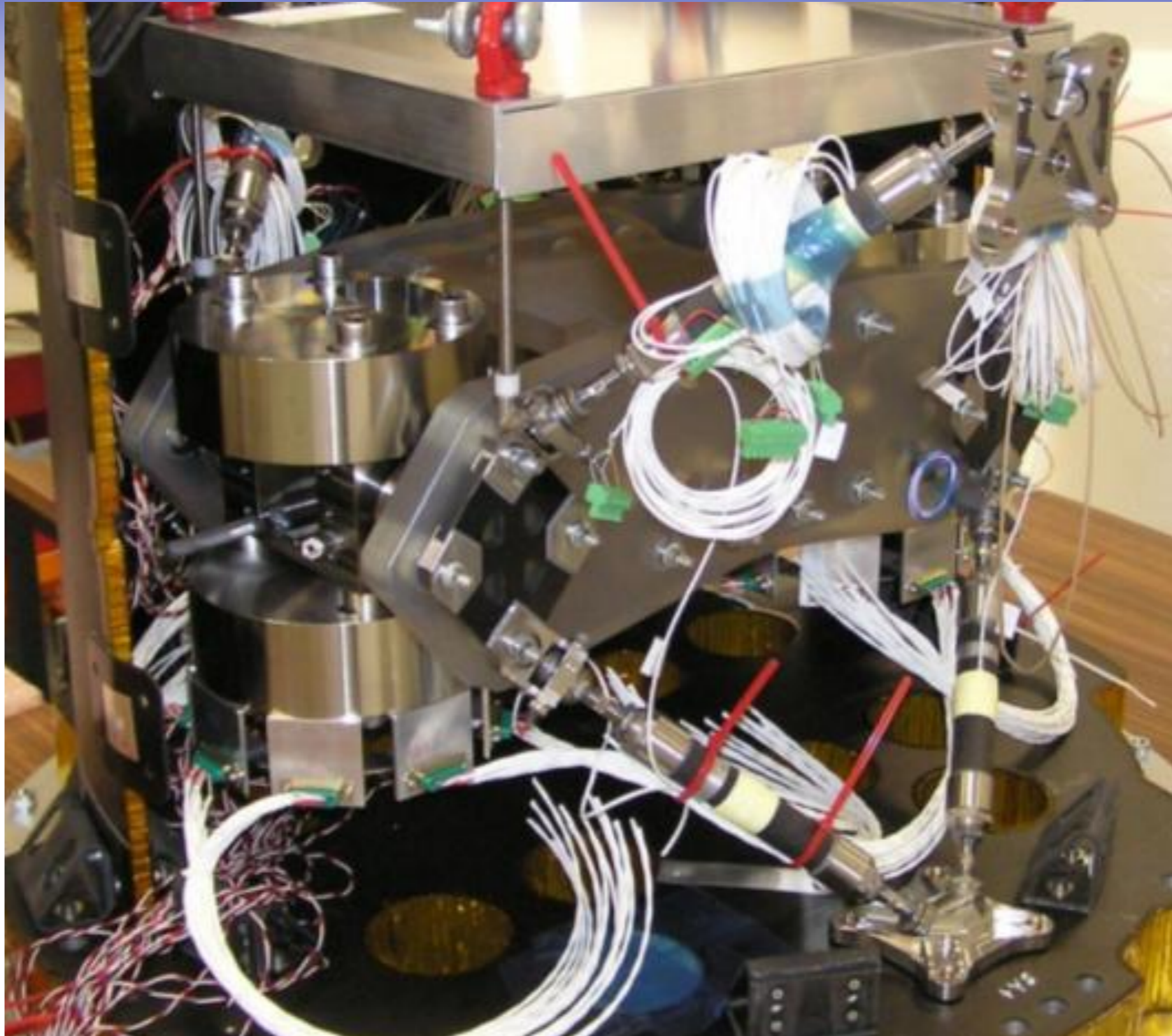


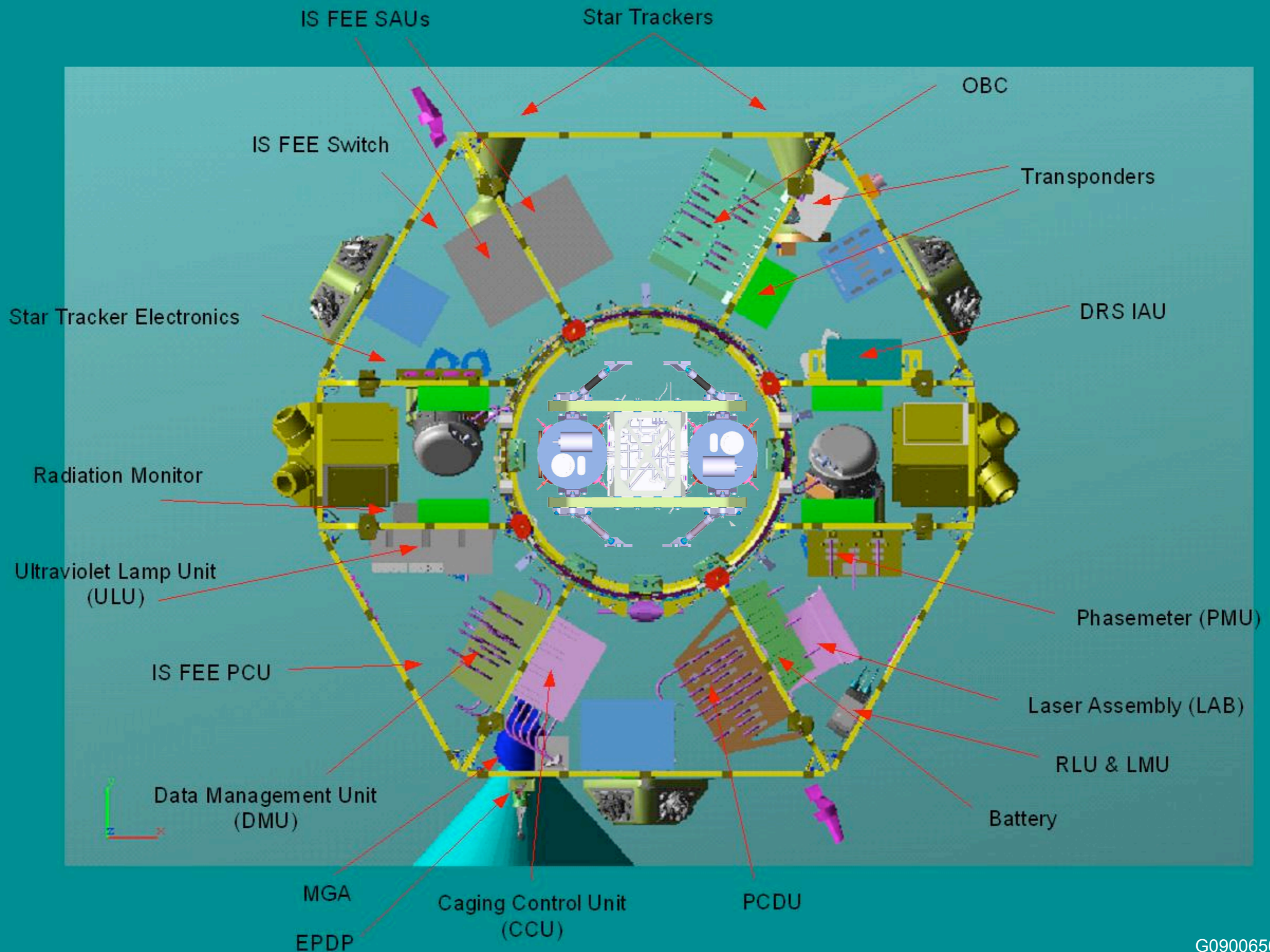


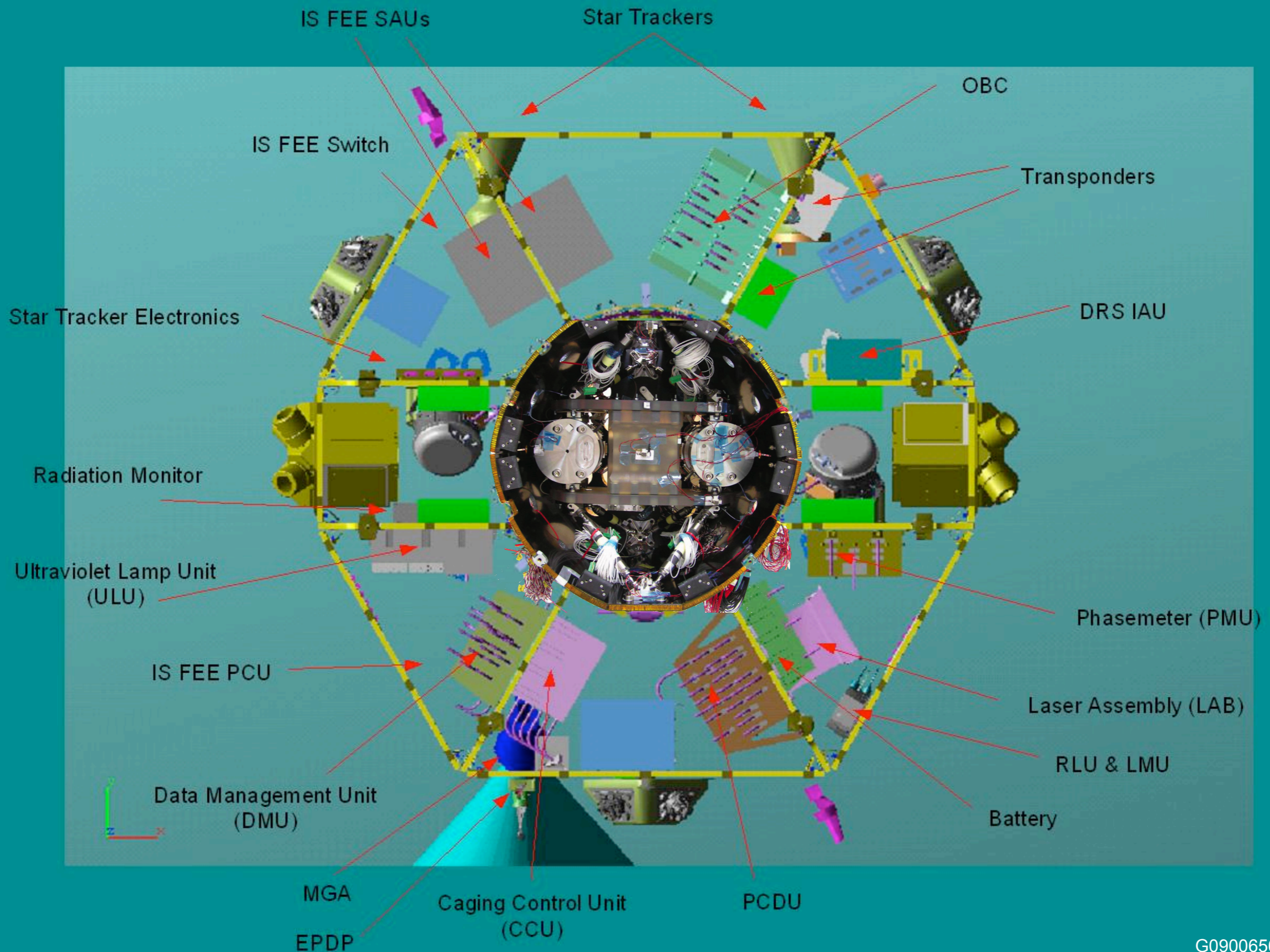














Micro-Newton Thrusters

- 
 LISA Pathfinder will carry two types of μ -Newton thrusters
 - Field Emission Electric Propulsion (FEEPs) [ESA]
 - Colloidal thrusters [NASA]
- 
 Thruster requirements can be summarised as:

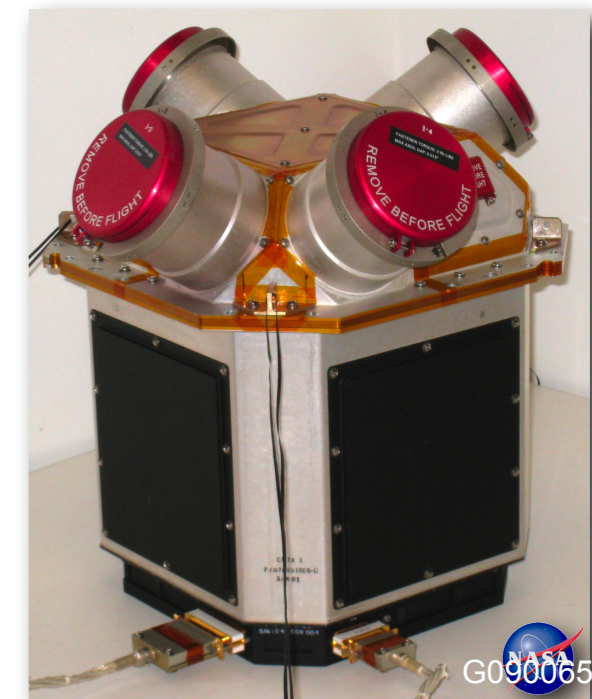
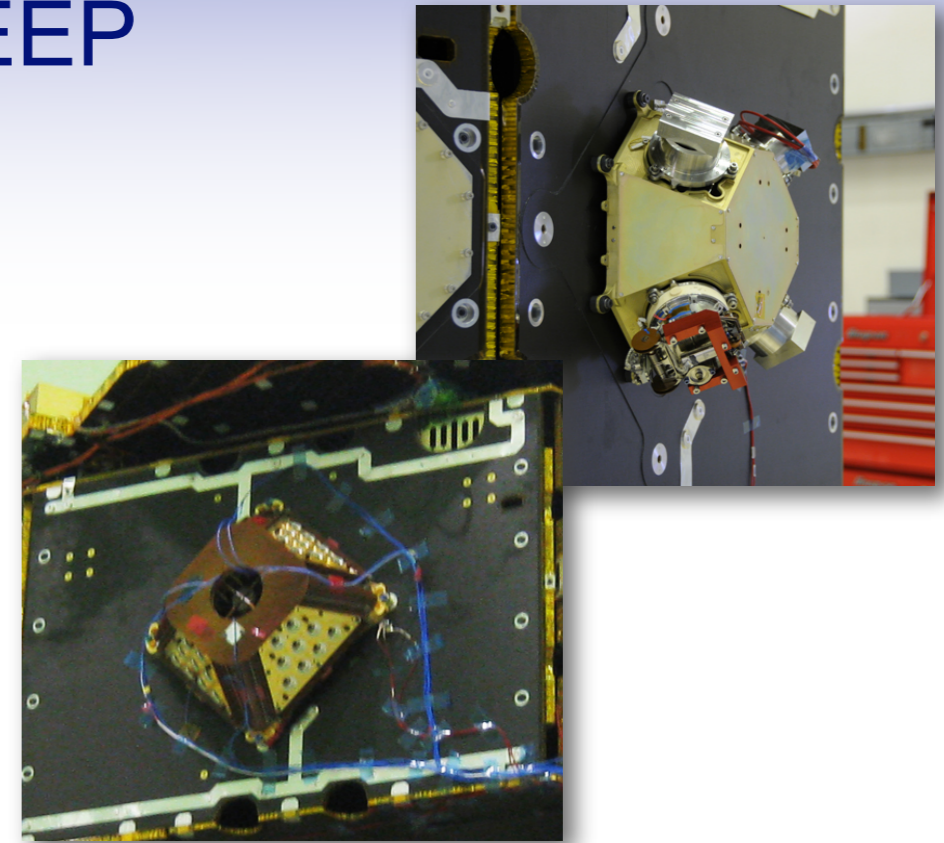
Key Requirement Specification	FEEP	Colloid
Thrust Range	0.3-150 μ N	5-30 μ N
Thrust Precision	<0.1 μ N	<0.1 μ N
Thrust Noise	<0.1 μ N/ $\sqrt{\text{Hz}}$	<0.1 μ N/ $\sqrt{\text{Hz}}$
Response Time	<340 ms	<100 sec
Specific Impulse	>4,000 sec	>150 sec
Cluster Power Consumption (4 thrusters @30 μ N)	55 W	25 W
Cluster Mass (4 thrusters, neutralizer and PCU)	13.7 kg	14.6 kg
Lifetime (Thruster-ON)	250 days	90 days
Total Impulse	2,000 Ns	300 Ns

Note: LISA requires 40,000hours of operation and 4,000N specific impulse

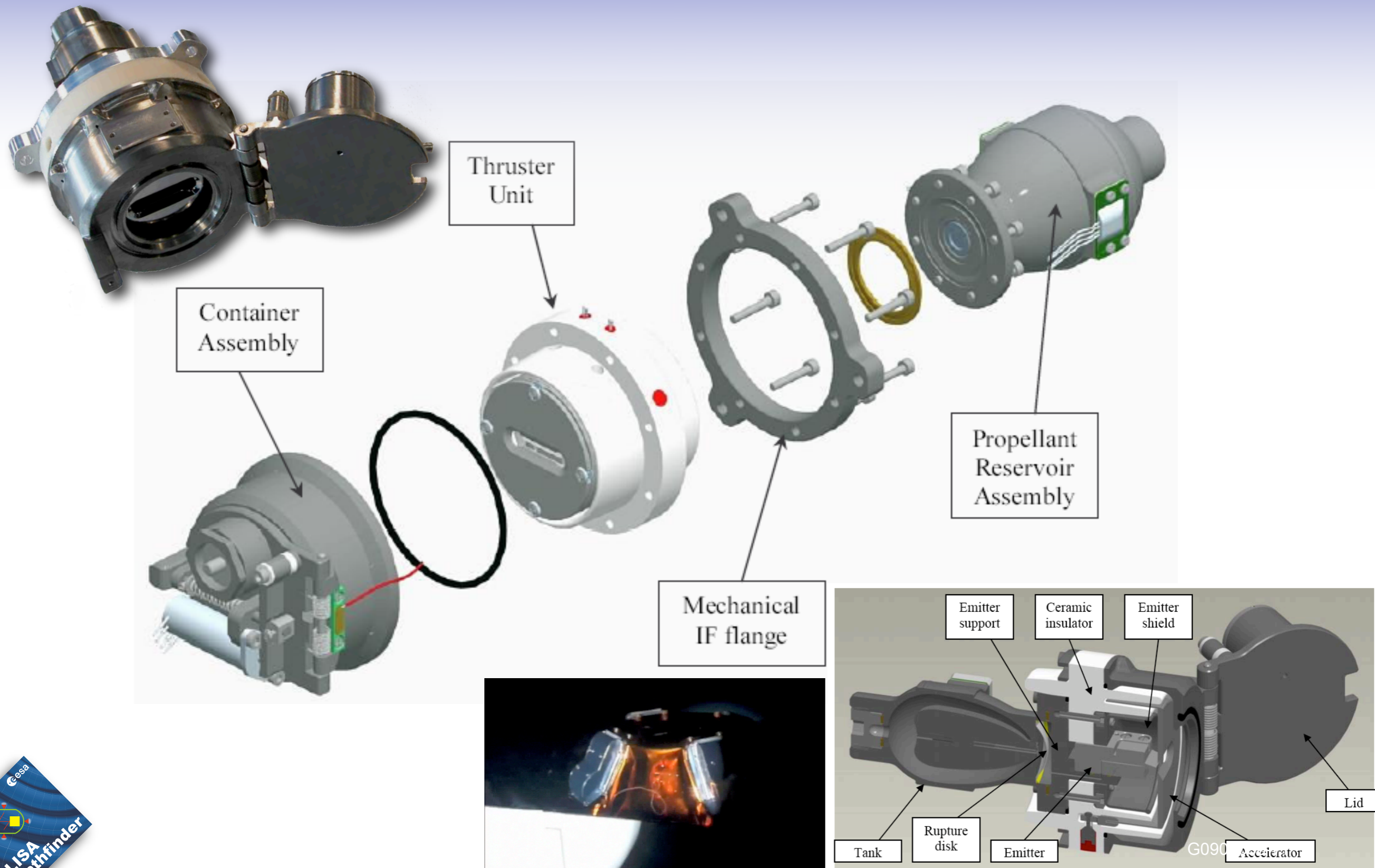


Micro-Newton Thrusters [2]

- Europe are developing two types of FEEP
 - Slit FEEP with Caesium propellant
 - Now been chosen for flight
 - Needle FEEP with Indium propellant
 - Developed as back-up
- Cs FEEP has now demonstrated >3200 hours (860Ns) of operation
 - Flight thrusters are now being built
- NASA Colloidal thruster flight units are complete and are waiting to be shipped to ESA

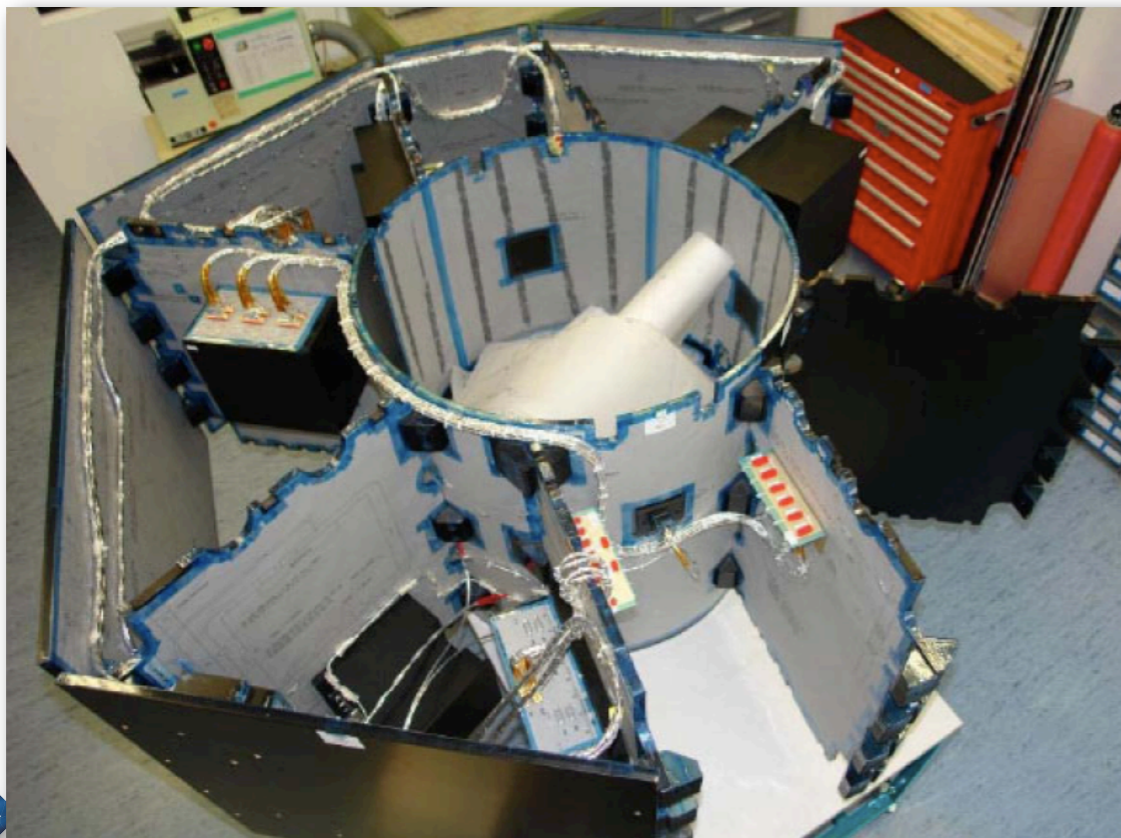


Micro-Newton Thrusters [3]

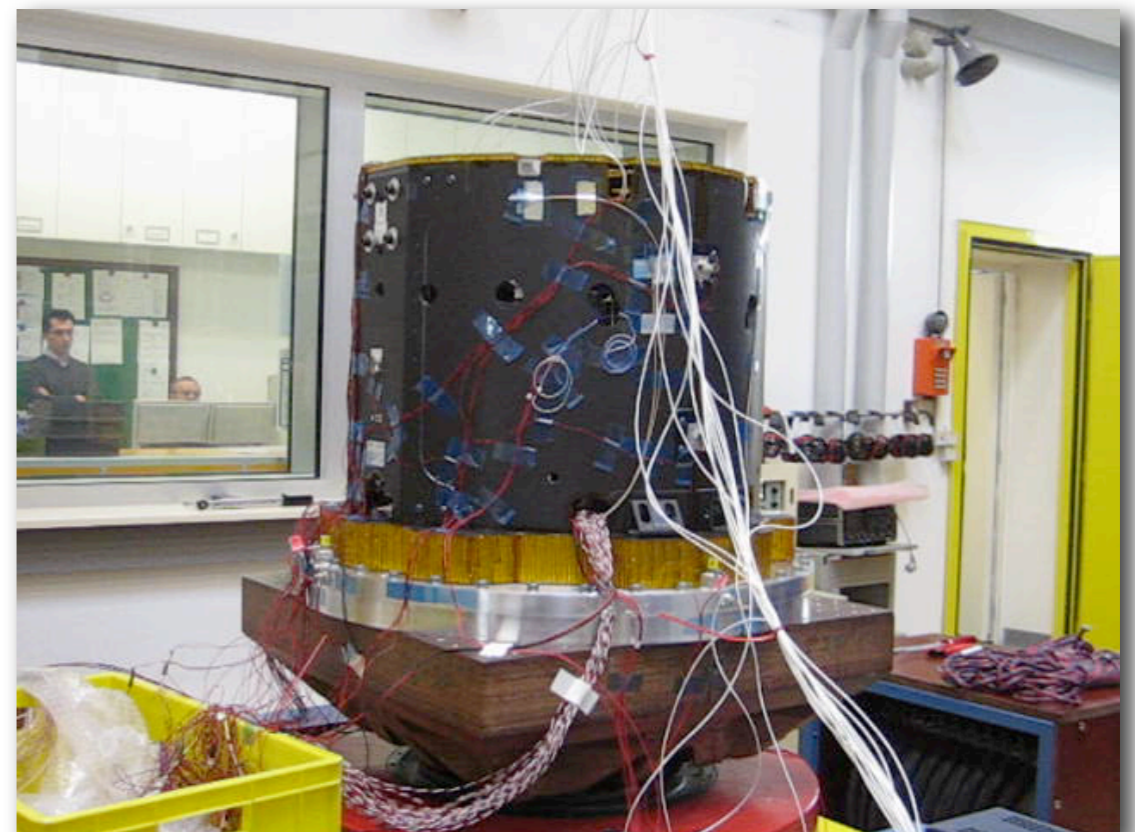


LTP Current Status

- 🪐 LTP successfully passed its Critical Design Review in November 2007
- 🪐 LTP Core Assembly (LCA) passed vibration qualification testing
 - LCA includes LTP, struts and mounting cylinder
- 🪐 ALL LTP FM units are now under manufacture or testing
 - LTP harness will be installed on spacecraft this month!
- 🪐 DFACS has passed CDR and is currently being tested with LTP real time test bed



FM electrical harness check

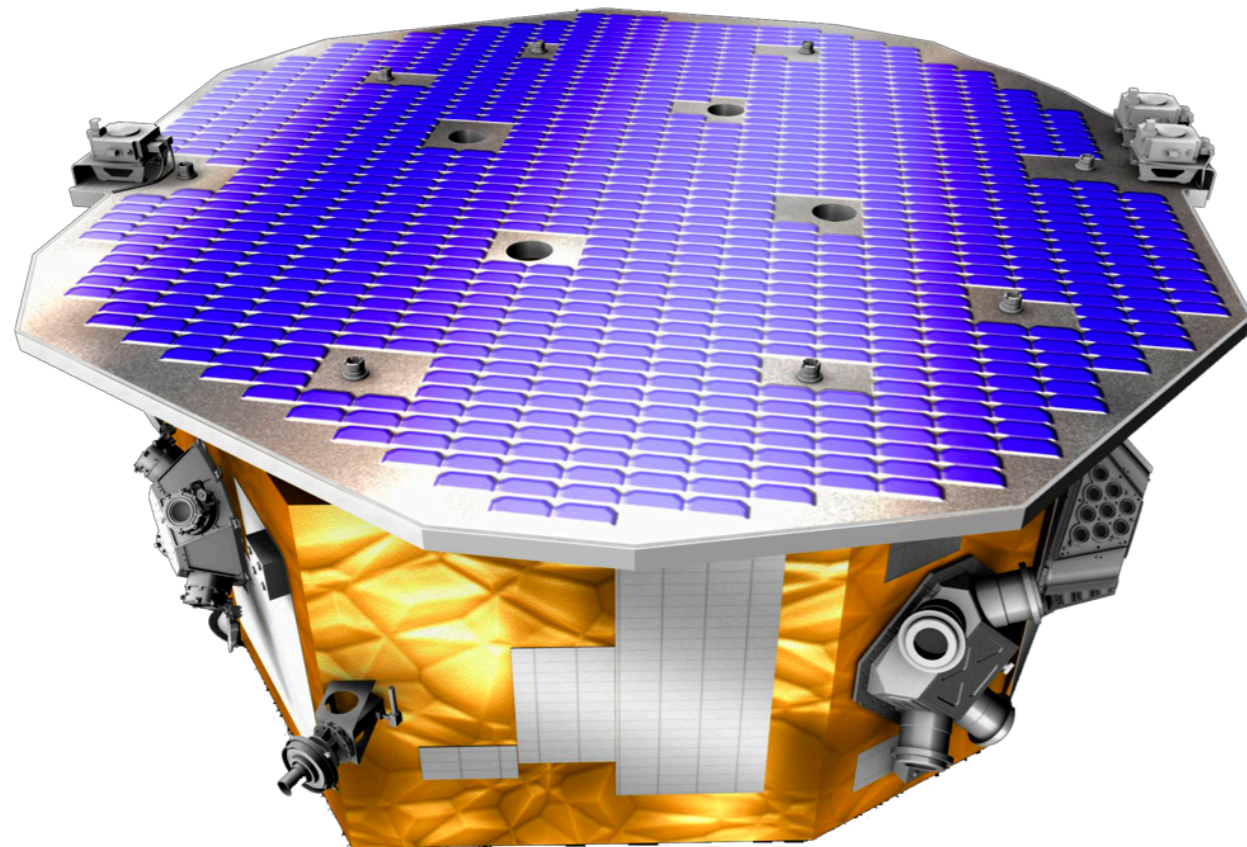


LCA STM vibration test



Spacecraft Flight Hardware

- Integration of electrical harness and e-boxes now starting at LPF Prime Contractor (Astrium UK)
- Both spacecraft and propulsion module have completed structural environmental tests
- Other hardware has been delivered, or is awaiting delivery review



Spacecraft Flight Hardware

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FM Spacecraft structure



Spacecraft Flight Hardware

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FM Spacecraft structure



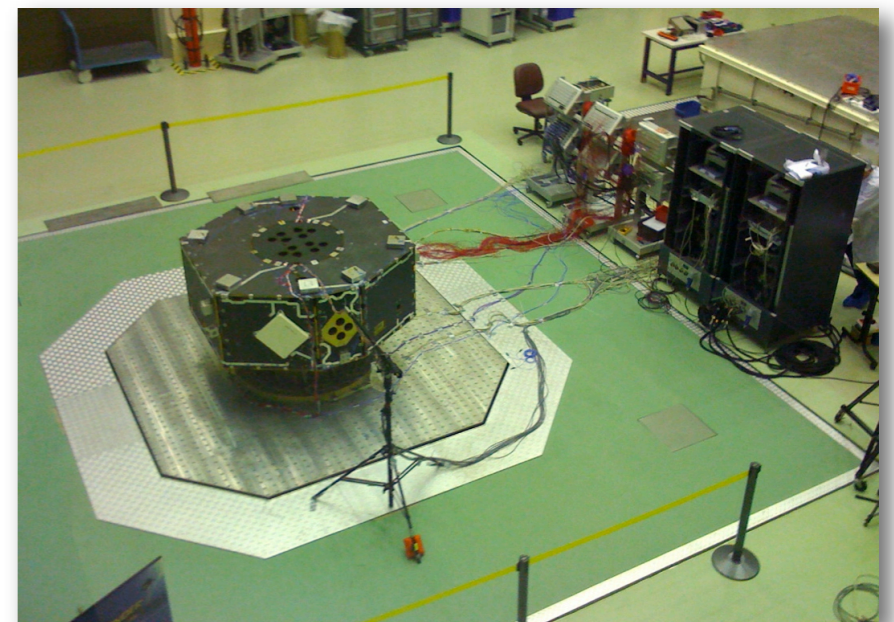
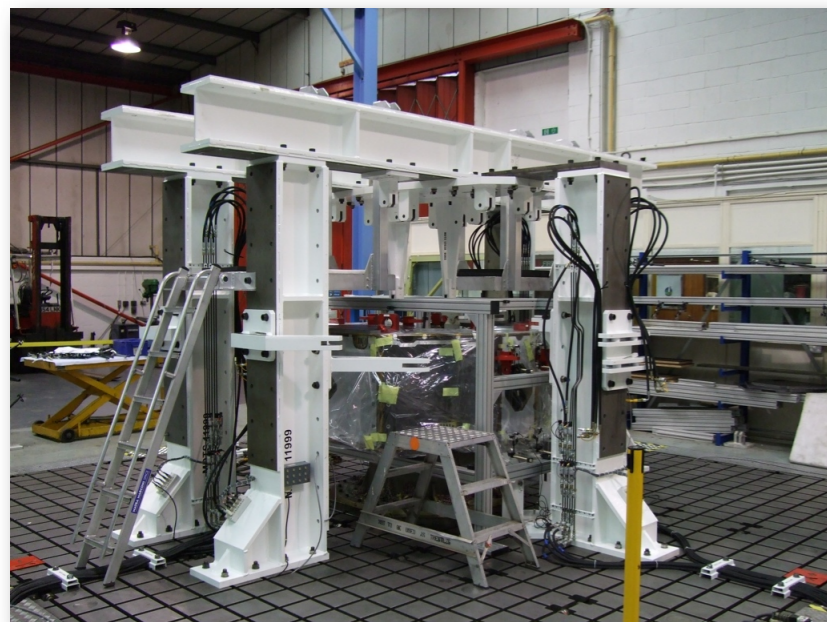
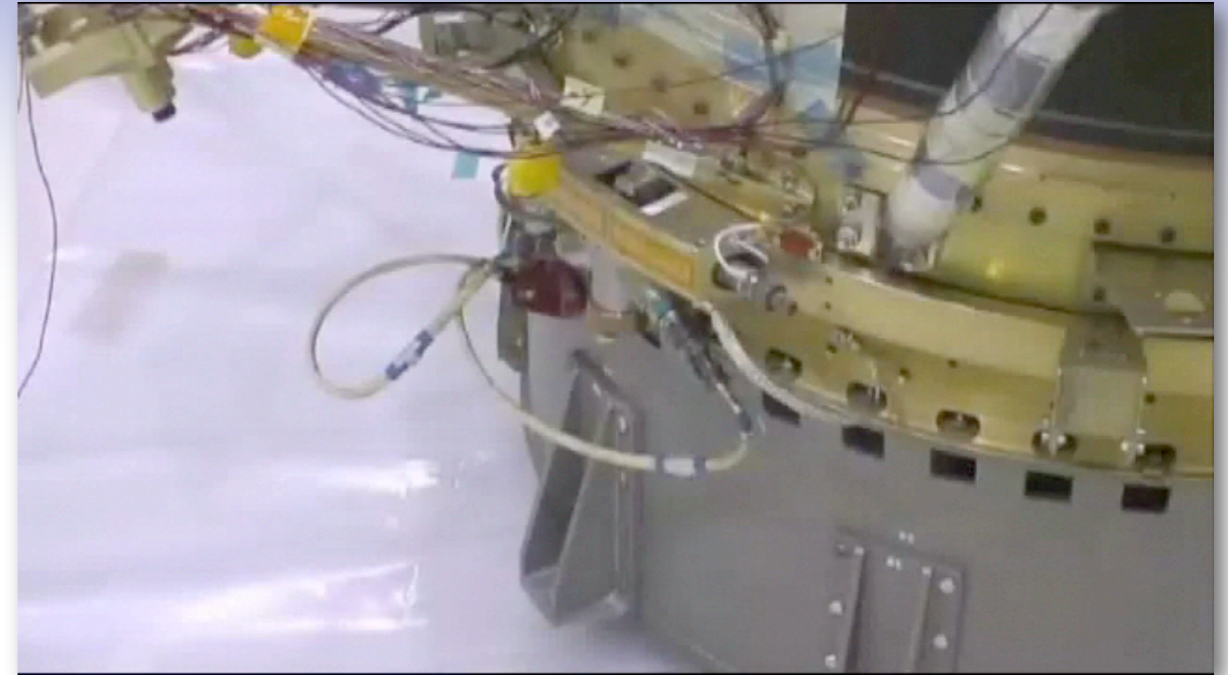
FM Propulsion Module structure



Structural testing

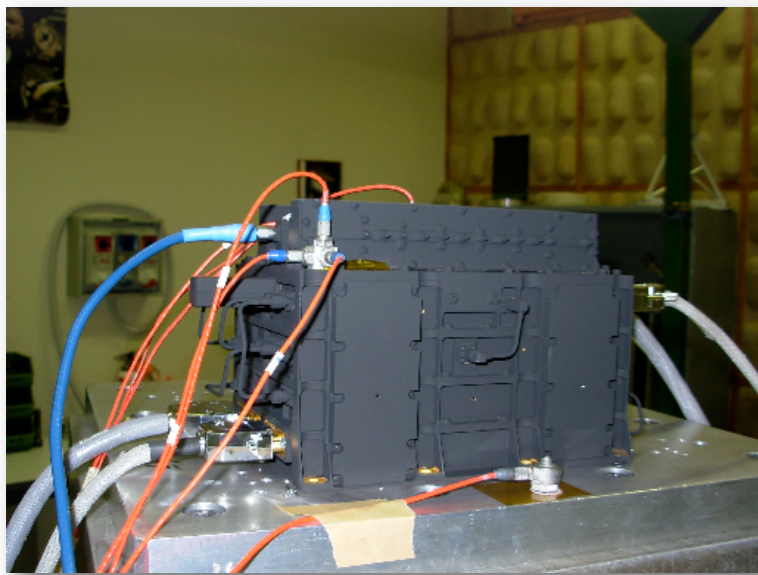
Structural Tests completed:

-  Static load
-  Acoustic
-  Separation Shock
-  Sine Dwell

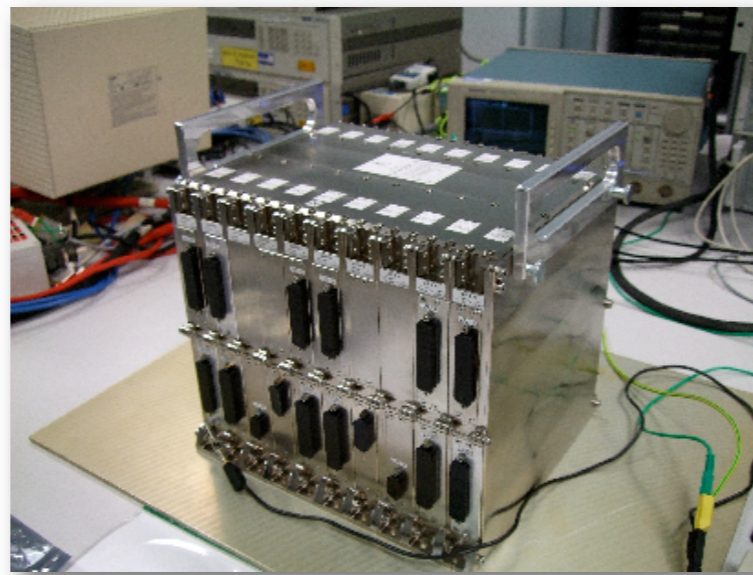


Spacecraft Electrical Systems

- E/QM hardware for OBC, PCDU, and Transponder ready for testbed operations



Transponder



On-board computer



PCDU



Low Gain Antenna

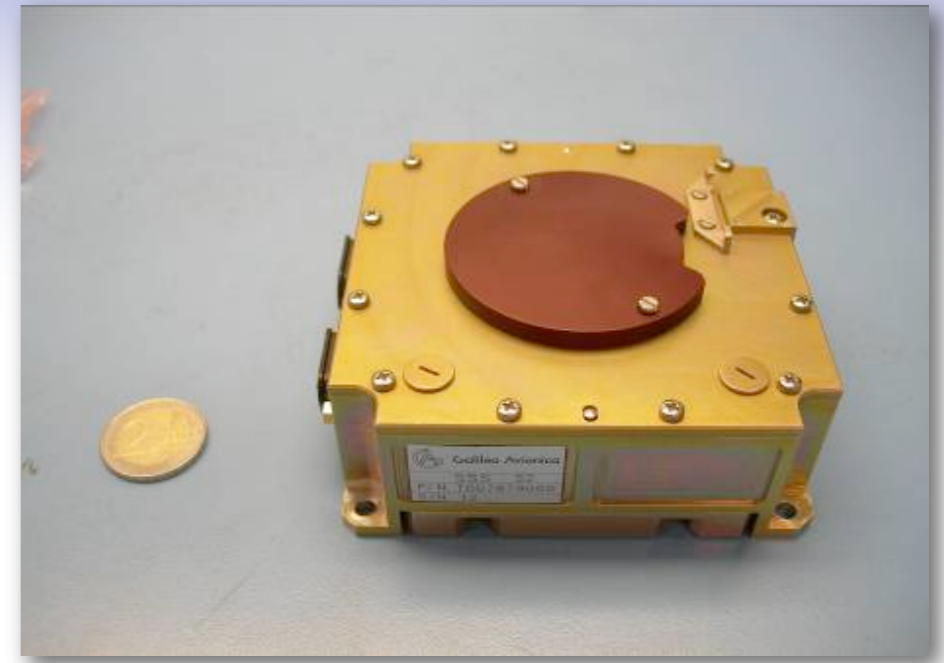


Medium Gain Antenna

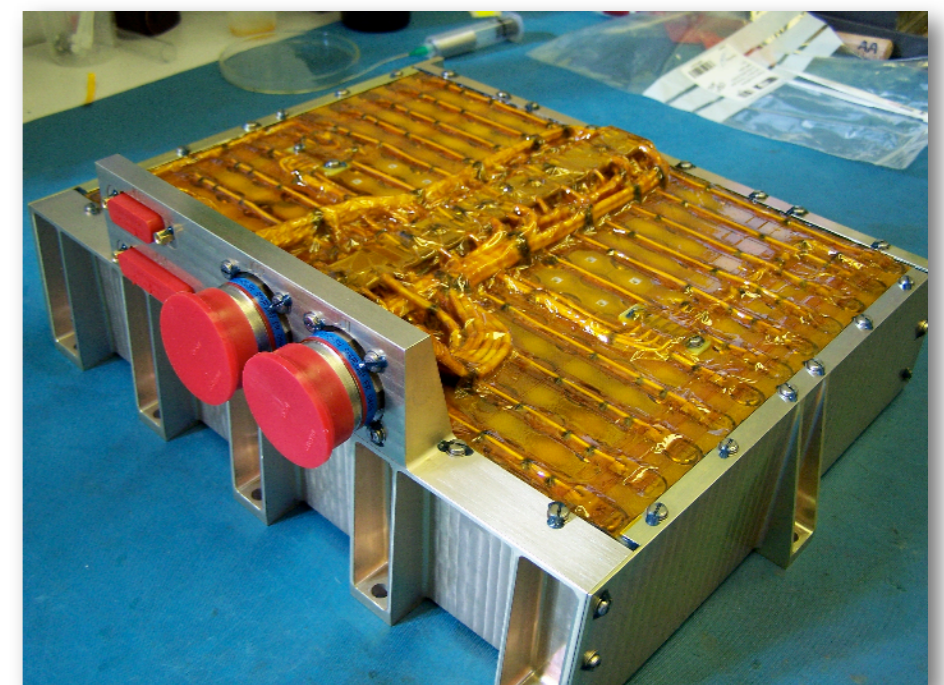
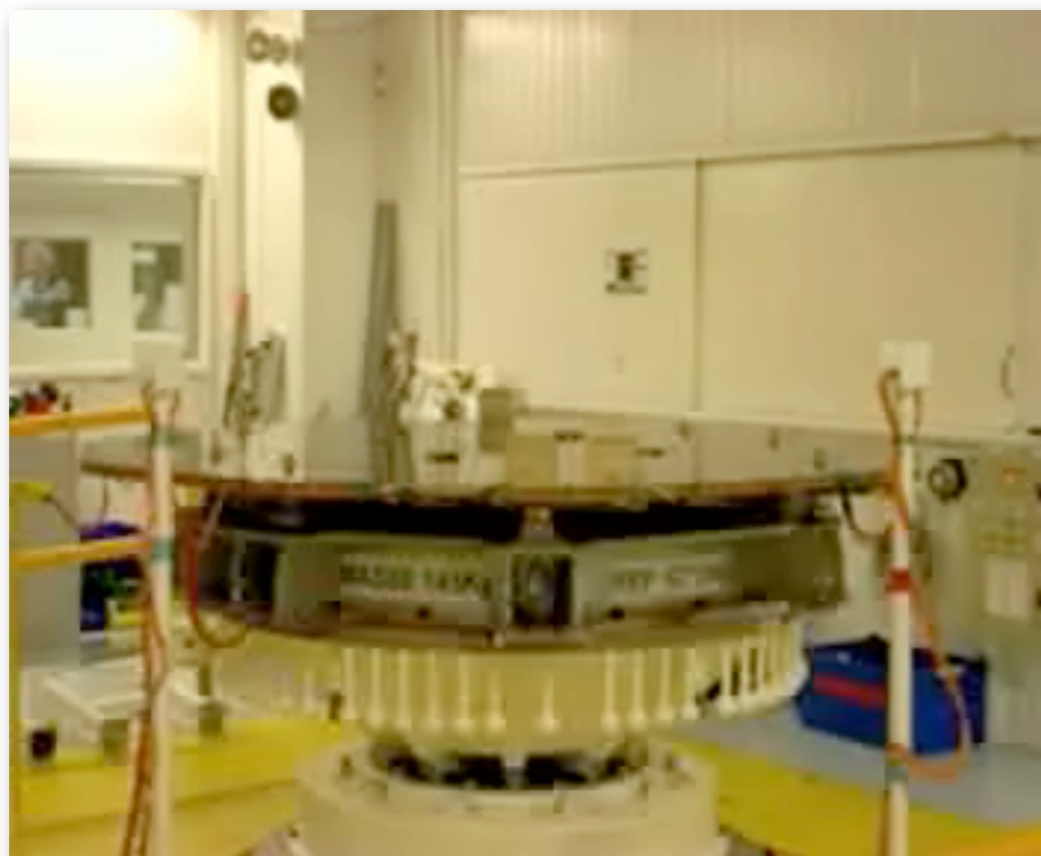


Spacecraft AOCS and Power

- FM sun sensors delivered
- FM battery delivered
- EM star-tracker ready
- FM Gyros ready for delivery
- FM Solar array in test



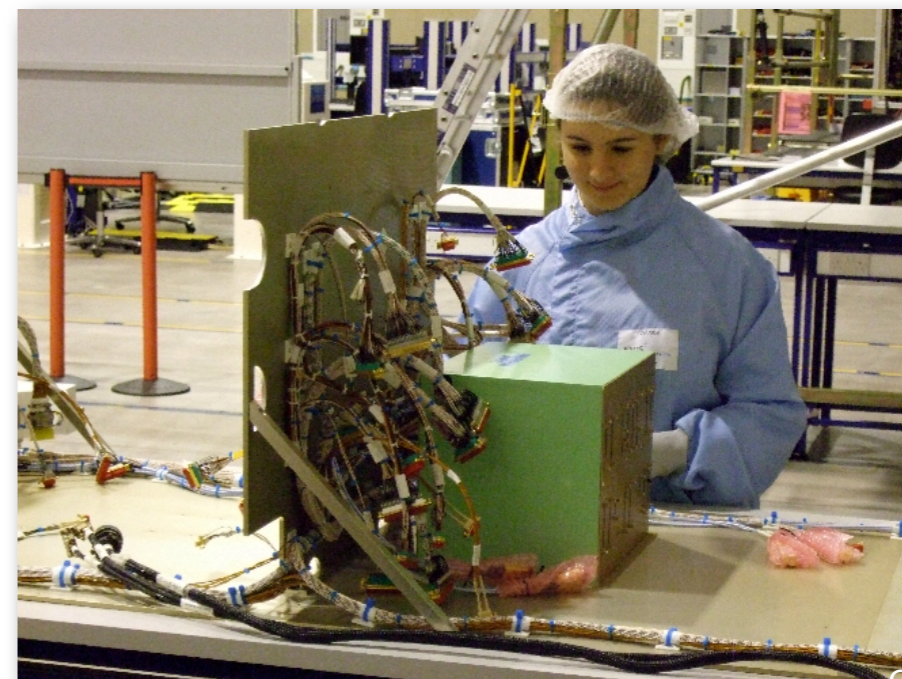
FM Digital Sun Sensor



FM battery

Test Beds

- Fundamental to the development of LISA Pathfinder (and all space missions) is the extensive use of a coherent set of simulators and test beds
 - An SVF and RTB to develop and test the DFACS design
 - In parallel a second SVF and RTB will be configured to develop and test the platform design and AOCS closed loops
 - The second test bed will be further developed to test the FM system including DFACS and AOCS using FM OBC, FM LTP units, DRS Simulator, PCDU and AOCS units.
 - Test will continue using EM units once S/C AIT starts

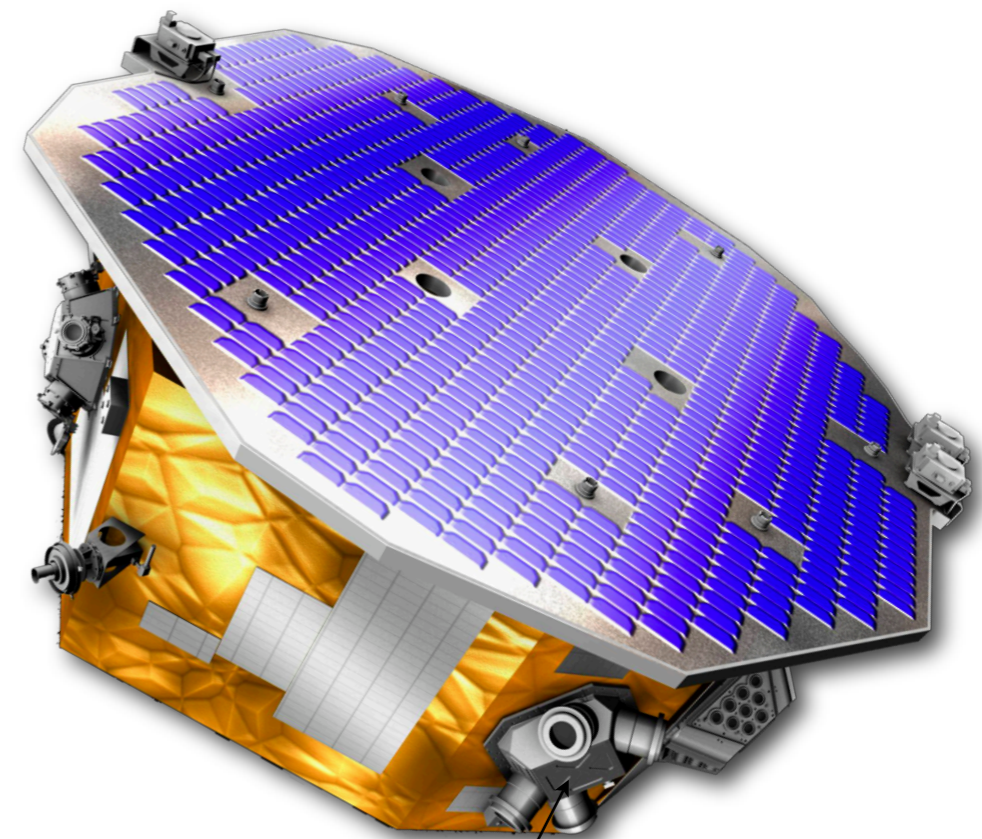


Spacecraft RTB at Astrium UK



Disturbance Reduction System

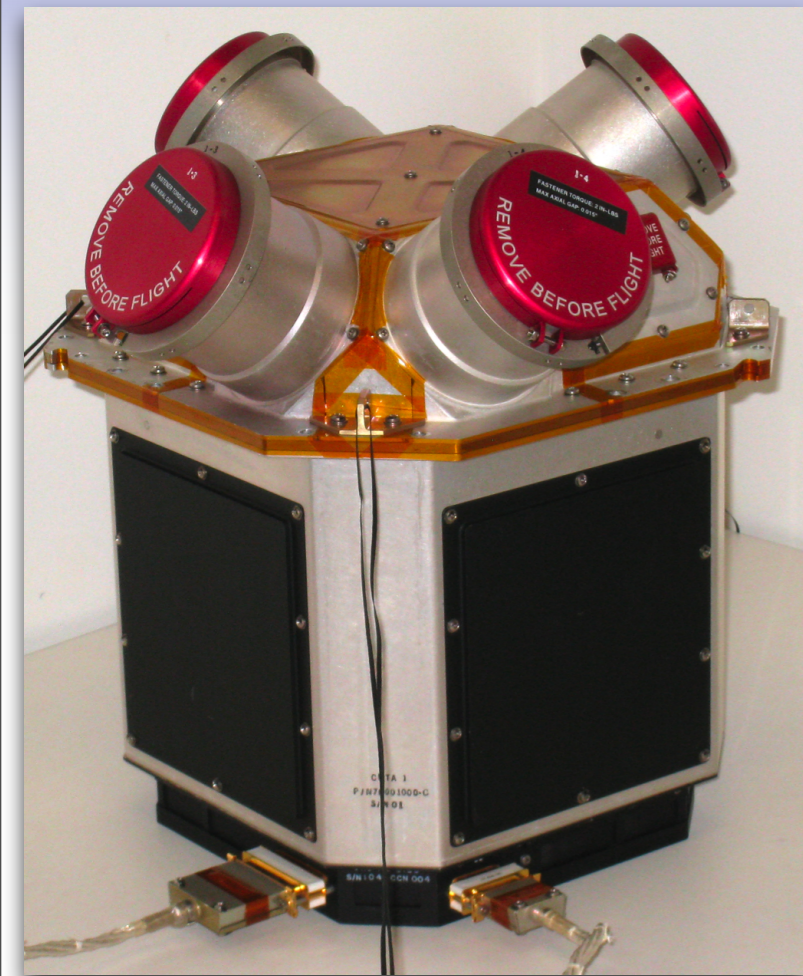
- DRS provided by NASA-JPL
- Originally consisted of LTP like payload (GRS), control law and micro-Newton thrusters
 - Mission was descoped and now consists of processor (control laws) and Colloidal micro-Newton Thrusters
 - DRS will use LTP as its inertial sensor
- ALL DRS flight hardware has been delivered to JPL**
 - Pre-Ship Acceptance Review was held in JPL last year
- Flight Hardware to be delivered to ESA in June!**



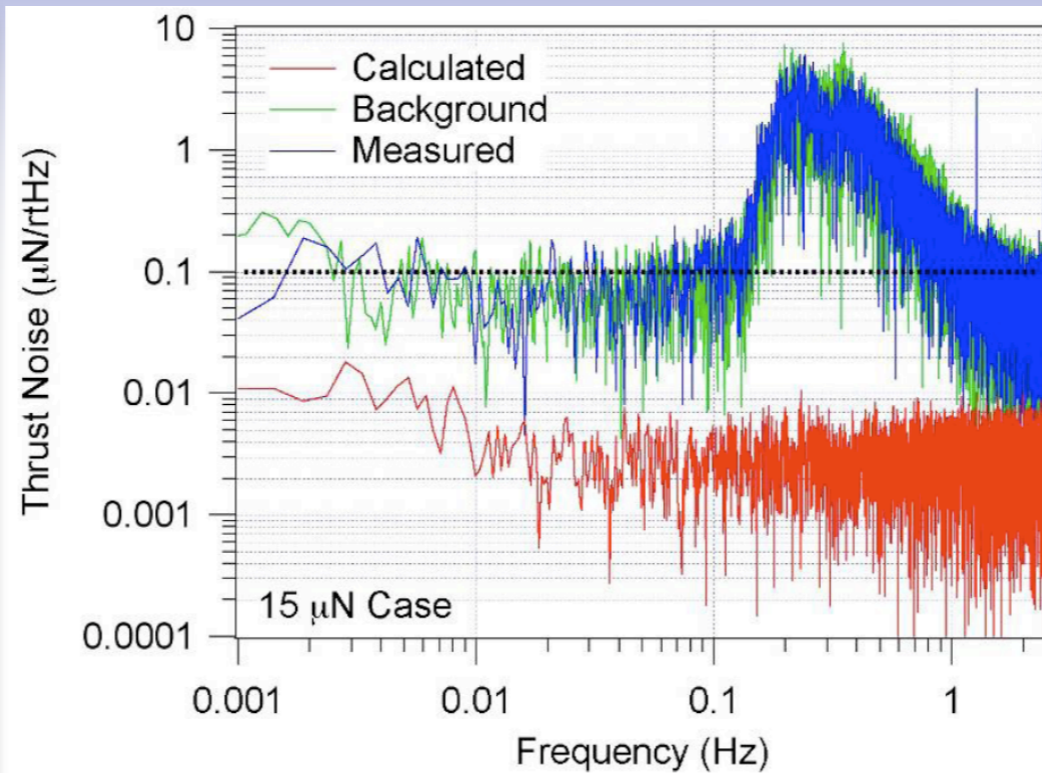
Colloidal micro-Newton thruster



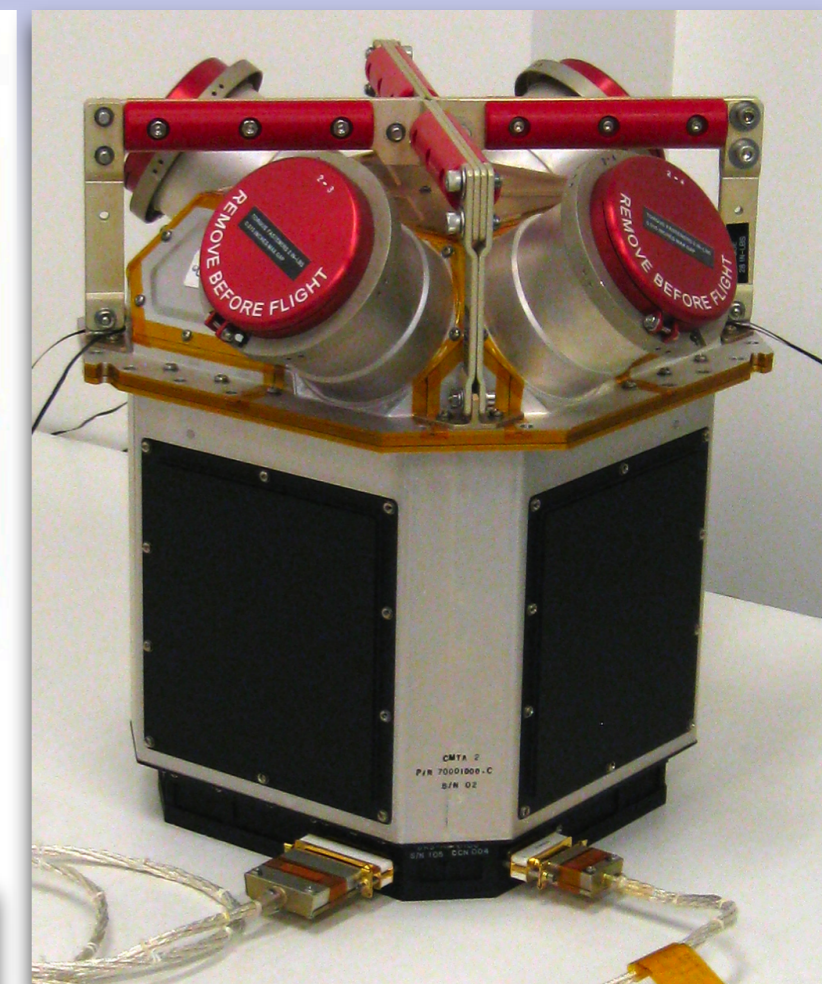
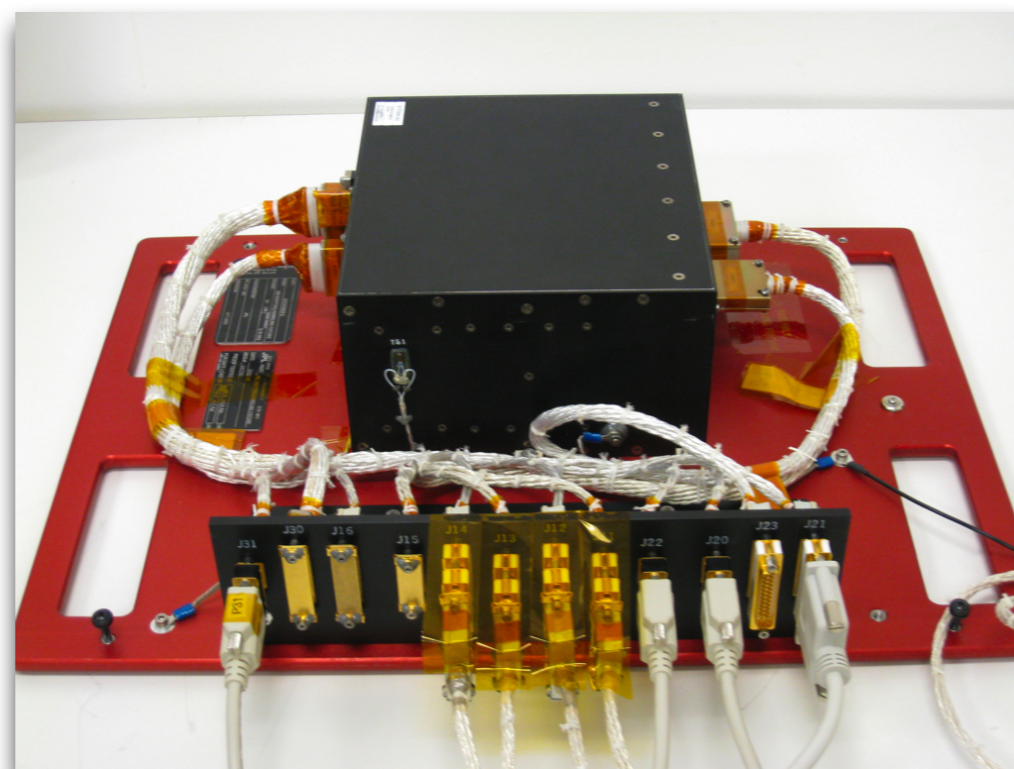
DRS Flight Hardware



Thruster Cluster 1



Integrated Avionics Unit



Thruster Cluster 2



Launcher

Baseline launch vehicle is VEGA

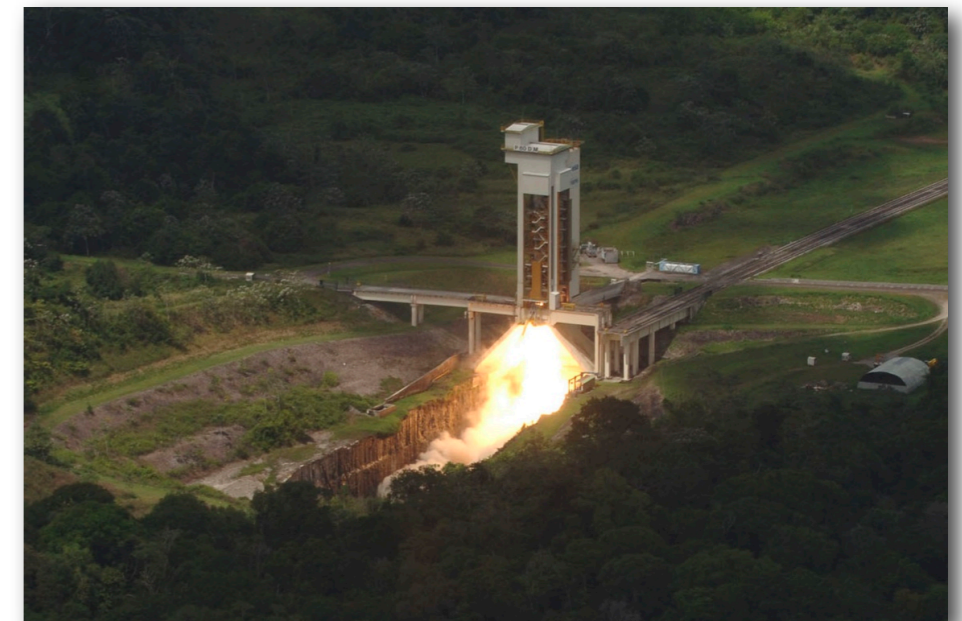
- ESA directive to target European launchers
- Procured from Arianespace
- New launcher
 - LPF scheduled to be on 3rd flight
- Launch from Kourou, French Guiana
 - Latitude 5°

Back-up options considered include

- VEGA into Highly Elliptical Orbit
- Rockot into Highly Elliptical Orbit



Artists impression of VEGA launcher

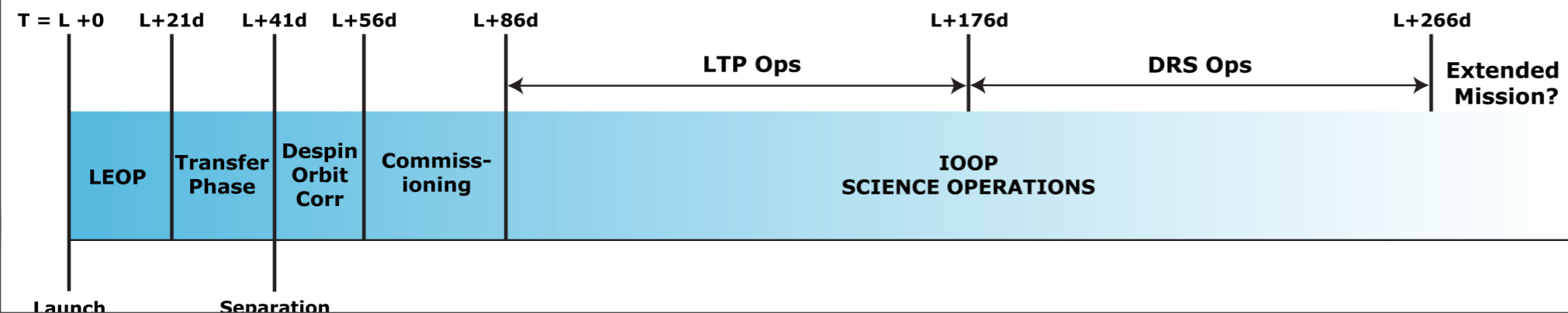
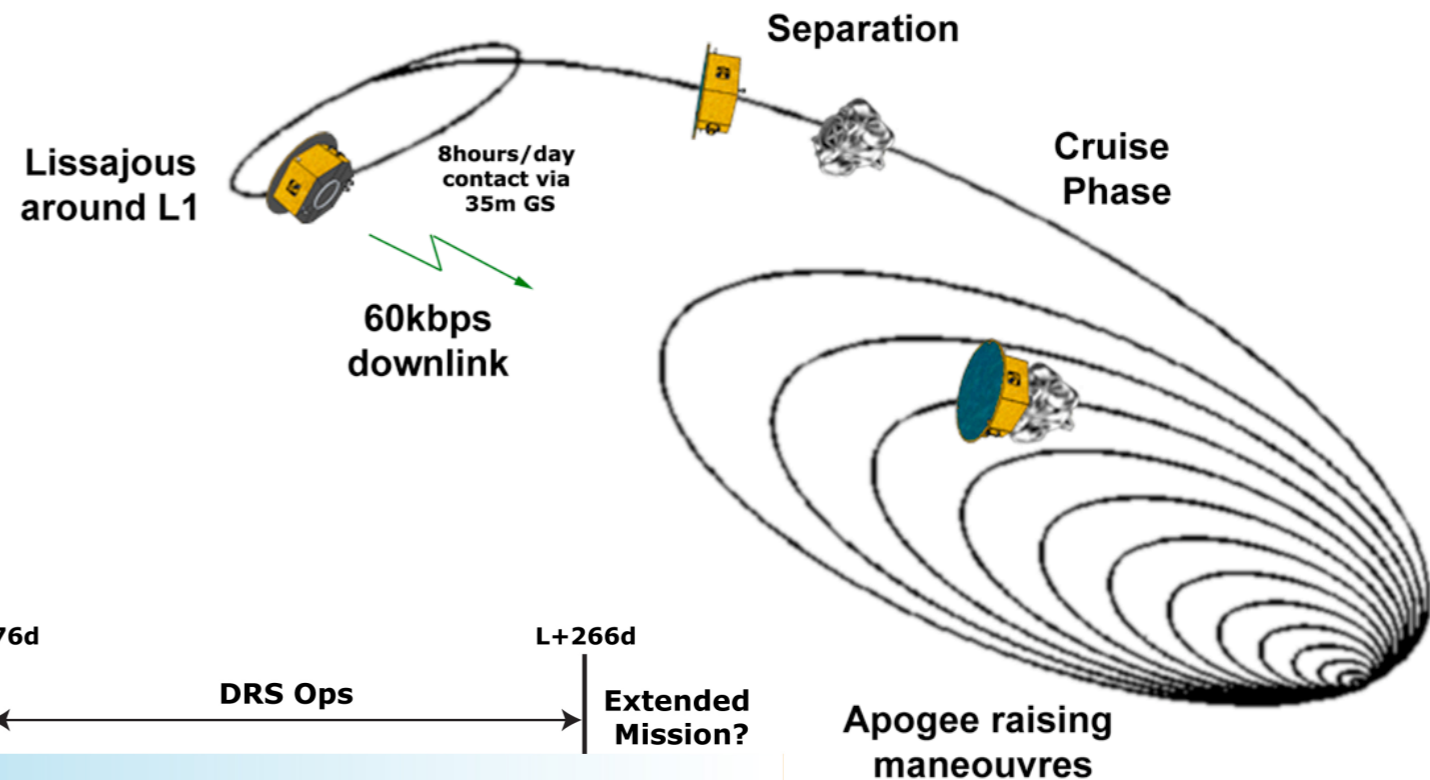


VEGA main engine test



Orbit

- LPF launched into 200x1600km orbit
- 9 apogee raising manoeuvres required to deliver LPF to L1
 - First time so many engines burns have been attempted by ESOC
- Prop module separates during transfer phase
- Final orbit is 500,000x800,000km Lissajous orbit around L1



Apogee raising manoeuvres

Operations

- ✪ Mission Operations controlled from ESOC, Germany
- ✪ 8 hours ground station contact per day
 - 35m ESA Cebreros station
 - Downlink rate of 60kbps
- ✪ Payload commanded via Payload Operation Requests stored in Mission Timeline
 - One POR lasts exactly 24 hours
 - Up to 6 PORs stored on-board at any time
- ✪ Real time commanding only during commissioning and contingency events



G0900656-v1



Conclusions

-  LISA Technology Package and LPF System have passed CDR
 - Flight hardware delivery has started!!
-  Spacecraft integration begins this week!

-  Knowledge gained from LTP/LPF is directly applicable to LISA
-  Additional lessons learned will also be transferred to LISA
 - I&T, ground segment, commissioning

-  Launch of LPF scheduled for mid-2011
 - Initial results available ~3months thereafter



Thank you

- ESA ESTEC
- ESA ESAC
- ESA ESOC
- EADS Astrium UK
- EADS Astrium GmbH
- University of Trento
- Albert Einstein Institute
- University of Glasgow
- University of Birmingham
- Imperial College London
- ETH Zurich
- Institut d-Estudis Espacials de Catalunya
- Universidad Politecnica de Barcelona
- APC Paris
- Laben
- Carlo Gavazzi Space
- ALTA
- ARCS
- Contraves
- Kaiser Threde
- NTE
- SCISYS
- Spacebel
- SRON
- Technologica
- TESAT
- ZARM
- JPL
- NASA Goddard
- BUSEK

