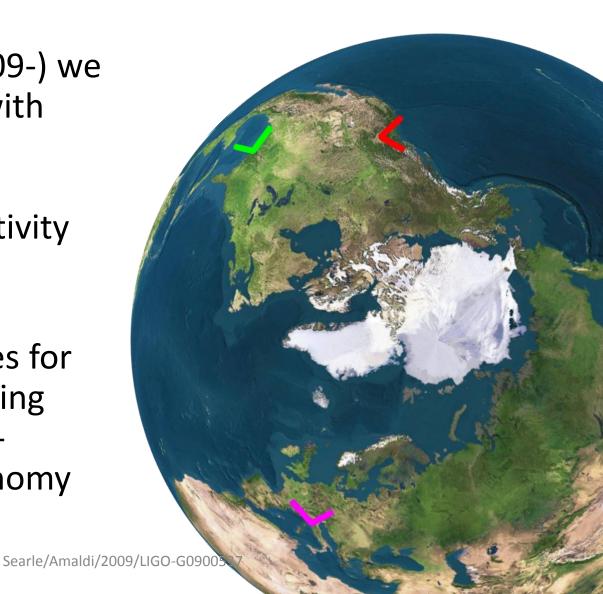
Seeing with three sites

Antony Searle
LIGO Caltech

Three sites

- In S6/VSR2 (July 09-) we have detectors with comparable (and astrophysically interesting) sensitivity at three widely separated sites
- New opportunities for robustness, pointing and thence multimessenger astronomy



New capabilities

- Pointing
 - We have enough information to localize a source on the sky to within a few degrees
- Internal consistency
 - Three detectors over-determine the unknown waveform
 - It is possible to reject glitches on the basis of poor consistency across the interferometers
- To exploit these capabilities requires coherent analysis

Bayesian framework

Idea

- Construct explicit (but uninfomative) models for signals and glitches
- Get back conditional probabilities for the model selection (detection) or pointing problem

Science

- First outlined at last Amaldi meeting
- Searle, Sutton, Tinto & Woan,
 Class. Quant. Grav. 25 (2008)
- Searle, Sutton & Tinto, <u>arXiv:0809.2809</u> (accepted, CQG)

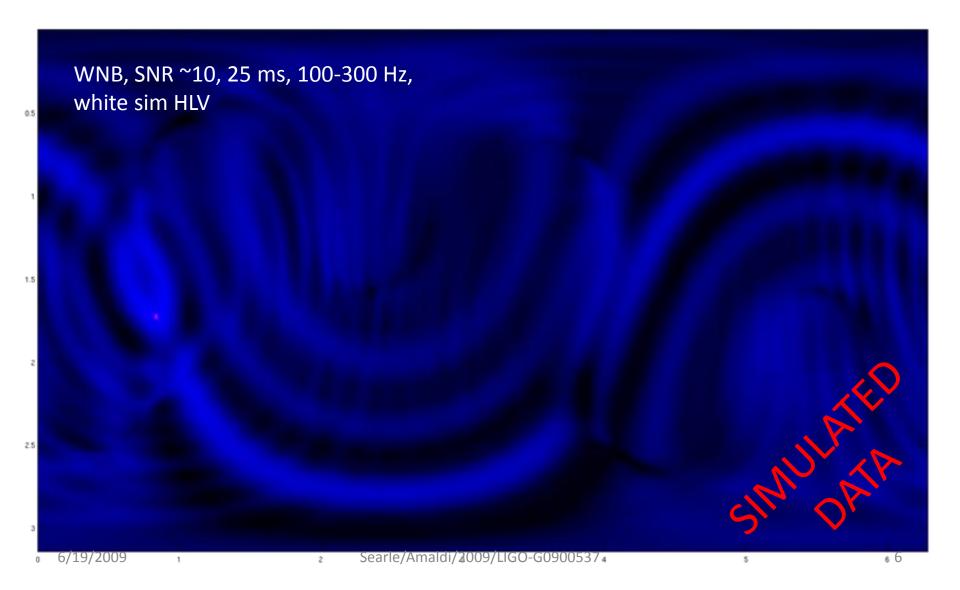
Implementation

- Core library in LAL
- Integrated into Omega and CBC pipelines
- Outputs parameter probability distributions (like MCMC)
- Judicious choices of analytically marginalizable priors for some parameters keeps the analysis cheap
- Fast enough to follow up data around one event per CPU per minute

Process

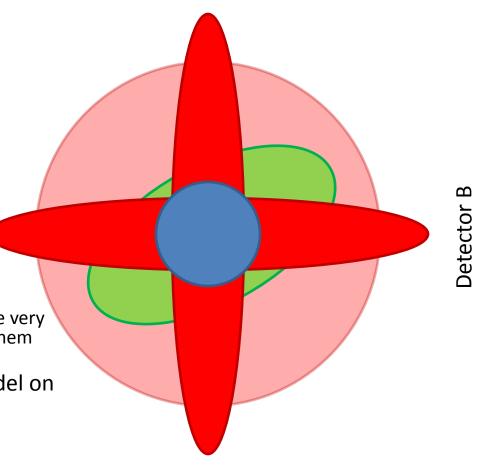
- Given an trigger template and time, we use the matched filter time series z[t] for 1 to 3 sites
 - (i.e. a coincident event found by a regular pipeline; this is a Bayesian followup)
- Produce a conditional posterior probability distribution ("skymap") for the source direction
 - Exactly the right data product for an optical followup
 - Skymaps for orthogonal templates can be combined
 - Cover arbitrary bursts with basis functions
- Produce the conditional posterior probability of a noise burst ("glitch") for each instrument individually

Energy and probability skymaps



Model selection

- The system has three states
 - Colored noise
 - Colored noise + signal
 - Colored noise + glitch
 - Coincident glitches
- Each detector may independently experience a burst of noise
- Uninformative glitch model:
 - Signals and glitches have the same distribution in any single instrument
 - Model selection is then a measure of the inter-site consistency
 - Though the signal and glitch models are very different, Bayesian analysis calibrates them both as probabilities
- In the future, calibrate the glitch model on past observations, like the PSD



Detector A

Roadmap

Now:

- Pointing in Omega and CBC followup pipelines
- Uninformative glitch model in Omega pipeline
- Omega online analysis providing pointing to LUMIN

• Soon:

- Pointing in LLOID
- Uninformative glitch model in CBC followup pipeline and LLOID
- Performance studies with SURF students

Future:

Calibrated glitch model